

Short Paper

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Abstract

This is the abstract.

It consists of two paragraphs.

Introduction

The primary objective of this paper is to develop a low-cost system that can record and categorize track flows through residential neighborhoods.

Methods

To motivate this we provide an example of using repeat photography to classify images of a roadway for the presence of FedEx trucks and buses using TensorFlow, and then demonstrate ways to analyze traffic based on labeled images.

AOI Selection

Although not critical for success in this case, many classification tasks can be improved by restricting the field of view to the area of interest (AOI) that contains the most informative components of an image. In this case any components of the image above the roadway provide no substantive information for the classification task and might throw off the classifier through uninformative changes in lighting, phenology across seasons, or changes in camera placement.

To minimize these issues we apply a multi-stage process to first identify the roadway, then mask out unnecessary image elements. In the first stage, we identify and isolate the yellow road centerline using color selection.

yellow line image

Then yellow lines are then converted to greyscale, and smoothed. These smoothed lines can then be used with a Canny Edge Detector [reference].

grey scale smoothed image

Edges can be defined as the boundary between an object and its background. In its most basic form edge detectors, like Sobel filters, use kernels (moving

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windows) to calculate the difference between adjacent pixels in both the X and Y axis. High gradient values can be treated as lines, and low gradient values are dropped from consideration. Canny edge detection [Canny 1986] goes a few steps further to try to isolate the strongest and most continuous lines. In canny, edges detected by the Sobel kernels are then thinned to be one pixel wide, and then filtered by hysteresis thresholding. Each line is scored by its strength relative to neighboring lines. Then to avoid noise or non-continuous edges, Hysteresis thresholding is applied to return only the most prominent and continuous lines. Thresholds are chosen between the values of zero (no edge) and two hundred (sharp edge). Two thresholds are chosen manually, the first, where all edges with values less than the minimum threshold are dropped completely from consideration. The second upper threshold is more complex, edges with values above the upper threshold are always included, but edges with thresholds between the minimum and maximum thresholds are only included if they touch a line that is above the maximum threshold. As result canny edge detection flexibly identifies strong and continuous lines, while removing ones that are potentially the result of noise or are weak and non-continuous.

<https://www.youtube.com/watch?v=sRFM5IEqR2w>

canny example

Tensor Classifier

Results

Discussion

Text based on elsarticle sample manuscript, see <http://www.elsevier.com/author-schemas/latex-instructions#elsarticle>

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Here are two sample references: Feynman and Vernon Jr. (1963; Dirac 1953).

References

Dirac, P.A.M. 1953. “The Lorentz Transformation and Absolute Time.” *Physica* 19 (1—12): 888–96. doi:[10.1016/S0031-8914\(53\)80099-6](https://doi.org/10.1016/S0031-8914(53)80099-6).

Feynman, R.P, and F.L Vernon Jr. 1963. “The Theory of a General Quantum System Interacting with a Linear Dissipative System.” *Annals of Physics* 24: 118–73. doi:[10.1016/0003-4916\(63\)90068-X](https://doi.org/10.1016/0003-4916(63)90068-X).