Semantics with Applications Operational Semantics of Extensions of WHILE

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Outline

Introduction

Non-sequential Language Constructs

Blocks and Procedures

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Blocks and Procedures

A Matter of (Semantic) Style

The natural and structural operational semantics of WHILE are equivalent; however:

- for some constructs it is easy to specify the semantics in one style but difficult or even impossible in the other
- some tools or applications are easier to implement in one style

In this lecture we introduce some new constructs in WHILE and illustrate the power and weakness of both operational semantics styles.

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Introduction

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Blocks and Procedures

The abort Statement

abort **stops** the execution of the complete program Note that abort is different from:

- ▶ while true do skip which loops
- ▶ skip since the statement following abort is never executed

We first extend the syntax of WHILE:

```
S \quad ::= \quad x := a \mid \mathtt{skip} \mid S_1 \; ; \; S_2 \mid \mathtt{if} \; b \; \mathtt{then} \; S_1 \; \mathtt{else} \; S_2 \mid \quad \mathsf{while} \; b \; \mathtt{do} \; S \mid \mathtt{abort}
```

The Semantics of abort

We assume that configurations $\langle S, s \rangle$ have been trivially extended to deal with abort.

The intended meaning is that configurations of the form:

$$\langle \mathtt{abort}, \ s \rangle$$

are **stuck**; i.e. a program in such a configuration does not progress any more.

We need to extend the definitions of \rightarrow and \Rightarrow with the appropriate axioms or rules.

No Semantic Definition, No Progress

Indeed, neither rules nor axioms are required to define the semantics of abort!

Since there is no definition for $\langle abort, s \rangle$:

▶ in Natural Semantics we cannot complete a derivation tree for

$$\frac{?}{\langle \mathtt{abort}, \ s \rangle \to ?}$$

in Structural Operational Semantics, the derivation sequence

$$\cdots \Rightarrow \langle \mathtt{abort}, \ s \rangle \Rightarrow ?$$

is stuck

Structural Operational Semantics of abort

The Structural Operational Semantics captures the informal behavior of abort:

▶ abort is not semantically equivalent to skip:

$$\langle \mathtt{abort}, \ s \rangle \neq \langle \mathtt{skip}, \ s \rangle \Rightarrow s$$

abort is not semantically equivalent to while true do skip:

```
\begin{split} &\langle \texttt{while true do skip}, \, s \rangle \\ &\Rightarrow \langle \texttt{if true then (skip; while true do skip) else skip}, \, s \rangle \\ &\Rightarrow \langle \texttt{skip; while true do skip}, \, s \rangle \\ &\Rightarrow \langle \texttt{while true do skip}, \, s \rangle \\ &\Rightarrow \cdots \end{split}
```

Natural Semantics of abort

The Natural Semantics does **not** capture the informal behavior of abort:

▶ abort is not semantically equivalent to skip:

$$\frac{?}{\langle \mathtt{abort}, \ s \rangle \rightarrow ?} \ \neq \ \frac{}{\langle \mathtt{skip}, \ s \rangle \rightarrow s}$$

abort is semantically equivalent to while true do skip:

$$\frac{?}{\langle \texttt{abort}, \; s \rangle \to ?} \; = \; \frac{?}{\langle \texttt{while true do skip}, \; s \rangle \to ?}$$

In both cases the derivation tree cannot be finished.

Natural Semantics versus Structural Operational Semantics

- ▶ if we have no derivation tree for $\langle S, s \rangle \rightarrow s'$, then we cannot tell whether it is because we entered a stuck configuration or a looping execution
- thus in Natural Semantics we cannot distinguish looping from abnormal termination
- on the other hand, in Structural Operational Semantics looping is reflected by infinite derivation sequences and abnormal termination by finite derivation sequences ending in a stuck configuration

Quiz

Is there anything we can do to make **looping** and **abnormal termination** semantically different in natural semantics?

Quiz

Is there anything we can do to make **looping** and **abnormal termination** semantically different in natural semantics?

Yes, we could extend the set of states with some special state to denote that some computation went wrong (i.e. an error final state):

$$T = \mathbf{State} \cup \{\mathbf{Error}\}\$$

and modify the definition of \rightarrow accordingly.

Exercises

Exercise 2.31 We know that the natural semantics and structural operational semantics of WHILE are equivalent. Discuss whether a similar result holds for WHILE extended with abort.

Exercise 2.32 Extend WHILE with the statement

assert b before S

The idea is that if b evaluates to true, then we execute S; otherwise the execution of the complete program aborts. Extend the definition of the structural operational semantics to support this new construct. You are not allowed to rely on the definition of abort. Show that assert true before S is semantically equivalent to S, but assert false before S is equivalent to neither while true do skip nor skip.

The or Statement – Non-determinism

S1 or S2 non-deterministically chooses to execute either S1 or S2. Thus the statement:

yields one and only one of the two final states:

- \triangleright s x = 1, or
- \triangleright s x = 4

We first extend the syntax of WHILE:

$$S \quad ::= \quad x := a \mid \mathtt{skip} \mid S_1 \; ; \; S_2 \mid \mathtt{if} \; b \; \mathtt{then} \; S_1 \; \mathtt{else} \; S_2$$

$$\mid \quad \mathsf{while} \; b \; \mathtt{do} \; S \mid S_1 \; \mathtt{or} \; S_2$$

and then proceed to extend the rules for \rightarrow and \Rightarrow .

Natural Semantics for or

We add the following two rules:

$$[\operatorname{or}_{\operatorname{ns}}^1] \quad \frac{\langle S_1, \ s \rangle \to s'}{\langle S_1 \ \operatorname{or} \ S_2, \ s \rangle \to s'} \qquad \qquad [\operatorname{or}_{\operatorname{ns}}^2] \quad \frac{\langle S_2, \ s \rangle \to s'}{\langle S_1 \ \operatorname{or} \ S_2, \ s \rangle \to s'}$$

Thus for the configuration

$$\langle x := 1 \text{ or } (x := 2; x := x + 2), s \rangle$$

we have two derivation trees:

$$\begin{split} [\mathtt{or}_{\mathrm{ns}}^1] \quad & \frac{\langle \mathtt{x} := \mathtt{1}, \ s \rangle \to s[\mathtt{x} \mapsto 1]}{\langle \mathtt{x} := \mathtt{1} \ \mathtt{or} \ (\mathtt{x} := \mathtt{2}; \mathtt{x} := \mathtt{x} + \mathtt{2}), \ s \rangle \to s[\mathtt{x} \mapsto 1]} \\ [\mathtt{or}_{\mathrm{ns}}^2] \quad & \vdots \\ & \frac{\langle (\mathtt{x} := \mathtt{2}; \mathtt{x} := \mathtt{x} + \mathtt{2}), \ s \rangle \to s[\mathtt{x} \mapsto 4]}{\langle \mathtt{x} := \mathtt{1} \ \mathtt{or} \ (\mathtt{x} := \mathtt{2}; \mathtt{x} := \mathtt{x} + \mathtt{2}), \ s \rangle \to s[\mathtt{x} \mapsto 4]} \end{aligned}$$

Quiz

How many derivation trees are there for the configuration

$$\langle (\mathtt{while\ true\ do\ skip})\ \mathtt{or}\ (\mathtt{x} := \mathtt{2}; \mathtt{x} := \mathtt{x} + \mathtt{2}),\ s \rangle$$

Quiz

How many derivation trees are there for the configuration

$$\langle (\mathtt{while \; true \; do \; skip}) \; \mathtt{or} \; (\mathtt{x} := \mathtt{2}; \mathtt{x} := \mathtt{x} + \mathtt{2}), \; s \rangle$$

Only one; the while statement above does not terminate.

Structural Operational Semantics for or

We add the following two axioms:

$$[\operatorname{or}^1_{\operatorname{sos}}] \quad \langle S_1 \operatorname{or} S_2, s \rangle \Rightarrow \langle S_1, s \rangle \qquad [\operatorname{or}^2_{\operatorname{sos}}] \quad \langle S_1 \operatorname{or} S_2, s \rangle \Rightarrow \langle S_2, s \rangle$$

Thus for the configuration

$$\langle x := 1 \text{ or } (x := 2; x := x + 2), s \rangle$$

we have two derivation sequences:

$$\langle x := 1 \text{ or } (x := 2; x := x + 2), s \rangle \Rightarrow^{\star} s[x \mapsto 1]$$

and

$$\langle \mathtt{x} := \mathtt{1} \text{ or } (\mathtt{x} := \mathtt{2}; \mathtt{x} := \mathtt{x} + \mathtt{2}), \ s \rangle \Rightarrow^{\star} s[\mathtt{x} \mapsto 4]$$

Quiz

How many derivation sequences are there for the configuration

$$\langle (\mathtt{while \; true \; do \; skip}) \; \mathtt{or} \; (\mathtt{x} := \mathtt{2}; \mathtt{x} := \mathtt{x} + \mathtt{2}), \; s \rangle$$

Quiz

How many derivation sequences are there for the configuration

$$\langle (\mathtt{while \; true \; do \; skip}) \; \mathtt{or} \; (\mathtt{x} := \mathtt{2}; \mathtt{x} := \mathtt{x} + \mathtt{2}), \; s \rangle$$

Two; one finite the other infinite.

Natural Semantics versus Structural Operational Semantics

- ▶ if we do have a derivation tree for $\langle S, s \rangle \rightarrow s'$, then we always chose the *right* branch of execution
- thus in Natural Semantics non-determinism suppresses
 looping, if possible (we can only deal with derivation trees)
- on the other hand, in a Structural Operational Semantics non-determinism does not suppress looping; we deal with both finite and infinite derivations

Exercise

Exercise 2.34 Extend the WHILE language with the statement

random(x)

that changes the value of \mathbf{x} to be any positive natural number. Extend the natural and structural operational semantics to support this statement. Discuss whether \mathbf{random} would be redundant if while were extended with the \mathbf{or} statement as well.

The par Statement – Parallelism

S1 par S2 executes both statements, but the execution can be interleaved.

Thus the statement:

```
x:= 1 par (x:= 2; x:= x+2);
```

yields one and only one of the three final states:

- \triangleright s x = 1, or
- ightharpoonup s x = 3, or
- \triangleright s x = 4

We first extend the syntax of WHILE:

$$S \quad ::= \quad x := a \mid \mathtt{skip} \mid S_1 \; ; \; S_2 \mid \mathtt{if} \; b \; \mathtt{then} \; S_1 \; \mathtt{else} \; S_2$$

$$\mid \quad \mathsf{while} \; b \; \mathtt{do} \; S \mid S_1 \; \mathtt{par} \; S_2$$

and then proceed to extend the rules for \rightarrow and \Rightarrow .

Structural Operational Semantics for par

We add the following rules:

$$\begin{split} [\mathtt{par}_{\mathrm{sos}}^1] & \quad \frac{\langle S_1, \ s \rangle \Rightarrow \langle S_1', \ s' \rangle}{\langle S_1 \ \mathsf{par} \ S_2, \ s \rangle \Rightarrow \langle S_1' \ \mathsf{par} \ S_2, \ s' \rangle} \\ [\mathtt{par}_{\mathrm{sos}}^2] & \quad \frac{\langle S_1, \ s \rangle \Rightarrow s'}{\langle S_1 \ \mathsf{par} \ S_2, \ s \rangle \Rightarrow \langle S_2, \ s' \rangle} \\ [\mathtt{par}_{\mathrm{sos}}^3] & \quad \frac{\langle S_2, \ s \rangle \Rightarrow \langle S_2', \ s' \rangle}{\langle S_1 \ \mathsf{par} \ S_2, \ s \rangle \Rightarrow \langle S_1 \ \mathsf{par} \ S_2', \ s' \rangle} \\ [\mathtt{par}_{\mathrm{sos}}^4] & \quad \frac{\langle S_2, \ s \rangle \Rightarrow \langle S_1 \ \mathsf{par} \ S_2', \ s' \rangle}{\langle S_1 \ \mathsf{par} \ S_2, \ s \rangle \Rightarrow \langle S_1, \ s' \rangle} \end{aligned}$$

- ightharpoonup execute the first step of either S_1 or S_2 and proceed with remaining par statement
- ightharpoonup complete the execution of either S_1 or S_2 and proceed with the remaining S_1 or S_2 statement

Derivation Sequences for par - Interleaving

For the statement

```
x:= 1 par (x:= 2; x:= x+2);
```

we get up to three derivation sequences, corresponding to three different execution orders of the atomic actions (shown in the next slide).

Example Derivation Sequences - Interleaving

$$\langle \mathbf{x} := 1 \text{ par } (\mathbf{x} := 2; \, \mathbf{x} := \mathbf{x} + 2), \, s \rangle \quad \Rightarrow \quad \langle \mathbf{x} := 2; \, \mathbf{x} := \mathbf{x} + 2, \, s[\mathbf{x} \mapsto \mathbf{1}] \rangle$$

$$\Rightarrow \quad \langle \mathbf{x} := \mathbf{x} + 2, \, s[\mathbf{x} \mapsto \mathbf{2}] \rangle$$

$$\Rightarrow \quad s[\mathbf{x} \mapsto \mathbf{4}]$$

$$\langle \mathbf{x} := 1 \text{ par } (\mathbf{x} := 2; \, \mathbf{x} := \mathbf{x} + 2), \, s \rangle \quad \Rightarrow \quad \langle \mathbf{x} := 1 \text{ par } \mathbf{x} := \mathbf{x} + 2, \, s[\mathbf{x} \mapsto \mathbf{2}] \rangle$$

$$\Rightarrow \quad \langle \mathbf{x} := 1, \, s[\mathbf{x} \mapsto \mathbf{4}] \rangle$$

$$\Rightarrow \quad s[\mathbf{x} \mapsto \mathbf{1}]$$
and
$$\langle \mathbf{x} := 1 \text{ par } (\mathbf{x} := 2; \, \mathbf{x} := \mathbf{x} + 2), \, s \rangle \quad \Rightarrow \quad \langle \mathbf{x} := 1 \text{ par } \mathbf{x} := \mathbf{x} + 2, \, s[\mathbf{x} \mapsto \mathbf{2}] \rangle$$

$$\Rightarrow \quad \langle \mathbf{x} := \mathbf{x} + 2, \, s[\mathbf{x} \mapsto \mathbf{1}] \rangle$$

$$\Rightarrow \quad s[\mathbf{x} \mapsto \mathbf{3}]$$

Natural Semantics for par

We add the following two rules:

$$\begin{split} [\mathtt{par}_{\mathrm{ns}}^1] & \frac{\langle S_1,\ s\rangle \to s', \quad \langle S_2,\ s'\rangle \to s''}{\langle S_1\ \mathtt{par}\ S_2,\ s\rangle \to s''} \\ [\mathtt{par}_{\mathrm{ns}}^2] & \frac{\langle S_2,\ s\rangle \to s', \quad \langle S_1,\ s'\rangle \to s''}{\langle S_1\ \mathtt{par}\ S_2,\ s\rangle \to s''} \end{split}$$

either execute S1; S2 or execute S2; S1

Natural Semantics for par

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either execute S1; S2 or execute S2; S1

Does this work?

Natural Semantics for par

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$$\begin{split} [\mathtt{par}_{\mathrm{ns}}^1] & \frac{\langle S_1,\ s\rangle \to s', \quad \langle S_2,\ s'\rangle \to s''}{\langle S_1\ \mathtt{par}\ S_2,\ s\rangle \to s''} \\ [\mathtt{par}_{\mathrm{ns}}^2] & \frac{\langle S_2,\ s\rangle \to s', \quad \langle S_1,\ s'\rangle \to s''}{\langle S_1\ \mathtt{par}\ S_2,\ s\rangle \to s''} \end{split}$$

either execute S1; S2 or execute S2; S1

Does this work?

Not really, we cannot interleave the executions of S1 and S2

Natural Semantics versus Structural Operational Semantics

- in Natural Semantics, the execution of immediate constituents is an atomic entity thus we cannot express interleaving of computations
- ▶ in Structural Operational Semantics, we concentrate on the small steps of the computation, thus we can easily express interleaving of computations

Exercises

Exercise 2.35 Consider an extension of WHILE that in addition to par also includes the construct:

```
protect S end
```

so that s must be executed as an atomic entity. For example:

```
x:= 1 par protect (x:= 2; x:= x+2) end
```

has only two possible outcomes, namely $s \ x = 1$ or $s \ x = 4$.

Extend the Structural Operational Semantics to support protect and get all the possible derivations for the sentence above.

Can you specify a Natural Semantics for protect?

Exercise 2.36 Specify the Structural Operational Semantics for arithmetic expressions \mathbf{Aexp} where the individual parts of an expression may be computed in parallel. Prove that the new semantics is equivalent to \mathcal{A} .

Outline

Introduction

Non-sequential Language Constructs

Blocks and Procedures

Extending WHILE with Declarations

We now turn WHILE into a block-structured language:

- Blocks contain variable and procedure declarations
- We introduce new concepts:
 - environments for both variables and procedures
 - locations and stores
- ▶ We cover:
 - dynamic and static scope for both variables and procedures
 - recursive and non-recursive procedures

We shall concentrate on the Natural Semantics.

The BLOCK Language

We first extend WHILE with blocks containing declarations of local variables. The new language is called BLOCK:

$$S \quad ::= \quad x := a \mid \mathrm{skip} \mid S_1 \; ; \; S_2 \mid \mathrm{if} \; b \; \mathrm{then} \; S_1 \; \mathrm{else} \; S_2$$

$$\mid \quad \quad \mathsf{while} \; b \; \mathsf{do} \; S \mid \mathrm{begin} \; D_V \; S \; \mathrm{end}$$

where D_V is a meta-variable ranging over a new syntactic category \mathbf{Dec}_V of variable declarations:

$$D_V ::= \operatorname{var} x := a; D_V \mid \varepsilon$$

where ε is the empty declaration.

Global and Local Variables in BLOCK

What is the final value of x?

Global and Local Variables in BLOCK

Natural Semantics for Variable Declarations

We consider configurations of the form:

- $ightharpoonup \langle D_V, s \rangle$
- **>** §

and the transition relation \rightarrow_D :

$$\langle D_V, s \rangle \to_D s'$$

the intended meaning is that we update the current state s with new bindings from D_V , obtaining the final state s'.

$$[\operatorname{var}_{\operatorname{ns}}] \quad \frac{\langle D_V, \ s[x \mapsto \mathcal{A}[\![a]\!]s] \rangle \to_D s'}{\langle \operatorname{var} \ x := a; \ D_V, \ s \rangle \to_D s'} \qquad [\operatorname{none}_{\operatorname{ns}}] \quad \langle \varepsilon, \ s \rangle \to_D s$$

Exercise

Build the derivation tree for the declaration:

```
var x:= 1;
var y:= 2;
var x:= 3;
```

Set of Variables Declared in a Block

To define the semantics of variable declarations, we first introduce the function DV computing the set of variables declared in a block:

Generalization of Substitutions on States

Given states s and s' and a set of variables X, $s'[X \longmapsto s]$ denotes a state that is like s' except for variables in X, where it is as specified by s; that is:

$$(s'[X \longmapsto s])x = \begin{cases} s x & \text{if } x \in X \\ s' x & \text{if } x \notin X \end{cases}$$

Exercise. Given

$$s' \mathbf{x} = \mathbf{3}$$
 $s' \mathbf{y} = \mathbf{2}$ $s' \mathbf{z} = \mathbf{1}$ $s' \underline{} = \mathbf{0}$

and:

$$s \mathbf{x} = \mathbf{1}$$
 $s \mathbf{y} = \mathbf{2}$ $s \mathbf{z} = \mathbf{3}$ $s = \mathbf{0}$

compute the values of x, y, z, and w in:

$$s'[\{x, y, z\} \longmapsto s] \quad s[\{x, y, z\} \longmapsto s'] \quad s'[\{w, x\} \longmapsto s]$$

Natural Semantics for BLOCK

The Natural Semantics for BLOCK is identical to that of WHILE, except that we add a new rule for a block with variable declarations:

$$[\mathrm{block_{ns}}] \quad \frac{\langle D_V, \ s \rangle \to_D s', \quad \langle S, \ s' \rangle \to s''}{\langle \mathrm{begin} \ D_V \ S \ \mathrm{end}, \ s \rangle \to s''[DV(D_V) \longmapsto s]}$$

To execute a block from state s:

- 1. add local variables in D_V to s, yielding s'
- 2. execute the body S from s', yielding s''
- 3. restore the variables shadowed in s to their original values

Exercise

Exercise 2.37 Use the Natural Semantics of BLOCK to compute the final state of the statement:

```
begin
   var y:= 1;
   (
     x:= 1;
     begin
       var x:= 2;
       y:= x + 1
   end;
   x:= y + x
  )
end
```

The PROC Language

We now extend BLOCK to include (parameterless) procedure declarations and invocations. The resulting language is called PROC:

```
\begin{array}{lll} S & ::= & x := a \mid \mathtt{skip} \mid S_1 \; ; \; S_2 \mid \mathtt{if} \; b \; \mathtt{then} \; S_1 \; \mathtt{else} \; S_2 \\ & \mid & \mathtt{while} \; b \; \mathtt{do} \; S \mid \mathtt{begin} \; D_V \; D_P \; S \; \mathtt{end} \mid \mathtt{call} \; p \\ \\ D_V & ::= & \mathtt{var} \; x := a ; \; D_V \mid \varepsilon \\ \\ D_P & ::= & \mathtt{proc} \; p \; \mathtt{is} \; S ; \; D_P \mid \varepsilon \end{array}
```

where:

- ightharpoonup p ranges over procedures names \mathbf{Pname}
- $ightharpoonup D_P$ ranges over procedure declarations ${f Dec}_{
 m P}$

PROC and Scope Rules

A binding maps an identifier to a program entity (variable, procedure, etc.)

The **scope** of a binding is the region of the program where it is valid.

The scope can be either **static** or **dynamic**:

- static scope (or lexical) is determined at compile-time, according to the lexical structure of the program
- dynamic scope is determined at run-time, according to the run-time environment

We shall define three different semantics for PROC, differing in the scope rules:

- static scope for variables and procedures
- dynamic scope for variables and procedures
- dynamic scope for variables, static scope for procedures

Scope Rules in Action

The result of the statement below depends on the scope rules:

```
begin
   var x:= 0;
   proc p is x:= x * 2;
   proc q is call p;
   begin
     var x:= 5
      proc p is x:= x + 1;
      call q;
      y:= x
   end
end
```

Static Scope for Variables and Procedures

Assuming static scope for both variables and procedures:

```
begin
   var x:= 0;
   proc p is x:= x * 2;
   proc q is call p;
   begin
     var x:= 5
      proc p is x:= x + 1;
      call q;
     y:= x
   end
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Dynamic Scope for Variables and Procedures

Assuming dynamic scope for both variables and procedures:

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    begin
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    call q;
    y:= x
  end
end
```

Dynamic Scope for Variables, Static for Procedures

Assuming dynamic scope for variables and static for procedures:

```
begin
   var x:= 0;
   proc p is x:= x * 2;
   proc q is call p;
   begin
     var x:= 5
      proc p is x:= x + 1;
      call q;
      y:= x
   end
end
```

Dynamic Scope for Variables, Static for Procedures

Assuming dynamic scope for variables and static for procedures:

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```

The statement

call p

executes the body of a procedure named ${\tt p}.$

The statement

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executes the body of a procedure named p.

Thus we need somehow to keep track of the association of procedure names \mathbf{Pname} with procedure bodies \mathbf{Stm} .

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A procedure environment env_P is a partial function that given a procedure name $p \in \mathbf{Pname}$ returns the statement $S \in \mathbf{Stm}$ corresponding to its body.

The statement

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Thus we need somehow to keep track of the association of procedure names \mathbf{Pname} with procedure bodies \mathbf{Stm} .

A procedure environment env_P is a partial function that given a procedure name $p \in \mathbf{Pname}$ returns the statement $S \in \mathbf{Stm}$ corresponding to its body.

We introduce the type \mathbf{Env}_P :

$$\mathbf{Env}_P = \mathbf{Pname} \hookrightarrow \mathbf{Stm}$$

thus $env_P \in \mathbf{Env}_P$.

```
begin
    var x:= 0;
    proc p is x:= x + 2;
    proc q is call p;
    begin
        var x:= 5
        proc p is x:= x+1;
        call q;
        y:= x
    end
end
```

What is the value of $env_P \neq ?$

```
begin
    var x:= 0;
    proc p is x:= x + 2;
    proc q is call p;
    begin
        var x:= 5
        proc p is x:= x+1;
        call q;
        y:= x
    end
end
```

What is the value of env_P q?

$$env_P \neq call p$$

What is the value of env_P p?

```
begin
    var x:= 0;
    proc p is x:= x + 2;
    proc q is call p;
    begin
        var x:= 5
        proc p is x:= x+1;
        call q;
        y:= x
    end
end
```

What is the value of env_P q?

$$env_P \neq call p$$

What is the value of env_P p ?

Depends on the scope rules for procedures! Thus different procedure scopes correspond to different ways of managing procedure environments.

Natural Semantics with Procedure Environments

We extend the transition system to take into account procedure environments:

$$env_P \vdash \langle S, s \rangle \rightarrow s'$$

the intended meaning is that we execute S from s and env_P . Axioms and rules for WHILE are simply recast with the new configurations, for example:

$$\begin{split} [\mathtt{skip}_{\mathrm{ns}}] & env_P \vdash \langle \mathtt{skip}, \ s \rangle \to s \\ [\mathtt{comp}_{\mathrm{ns}}] & \frac{env_P \vdash \langle S_1, \ s \rangle \to s', \quad env_P \vdash \langle S_2, \ s' \rangle \to s''}{env_P \vdash \langle S_1; \ S_2, \ s \rangle \to s''} \end{split}$$

Thus env_P is just propagated to where it is needed.

Managing the Procedure Environment

The axioms and rules of WHILE simply propagate env_P to make sure it is available where needed.

We need rules to:

- retrieve the environment (the call statement)
- update the environment (the procedure declarations in begin ... end statements)

The definitions of procedure environment and these rules define the scope rules for procedures.

Dynamic Scope for Variables and Procedures

To define the semantics for a language with **dynamic** scope we need:

- a proper definition of the procedure environment (done)
- a strategy to update the procedure environment (begin ... end)
- ▶ a strategy to retrieve the procedure environment (call)

Updating the Procedure Environment

Given a procedure environment env_P and a procedure declaration D_P the updated procedure environment $\operatorname{upd}_P(D_P,\operatorname{env}_P)$ is defined by:

$$\begin{array}{rcl} \operatorname{upd_P}(\operatorname{proc}\ p\ \operatorname{is}\ S;\ D_P,env_P) &=& \operatorname{upd_P}(D_P,env_P[p\mapsto S]) \\ \operatorname{upd_P}(\varepsilon,env_P) &=& env_P \end{array}$$

The begin ... end Statement

To execute the statement

begin Dv Dp S end

- 1. update the state with variables from Dv
- 2. update the procedure environment with procedures from Dp
- 3. execute s in the updated environment/state
- 4. restore the shadowed variables

$$[\operatorname{block}_{ns}] \quad \frac{\langle D_V, \ s \rangle \to_D s', \quad \operatorname{upd}_{\operatorname{P}}(D_P, env_P) \vdash \langle S, \ s' \rangle \to s''}{env_P \vdash \langle \operatorname{begin} D_V \ D_P \ S \ \operatorname{end}, \ s \rangle \to s''[\operatorname{DV}(D_V) \longmapsto s]}$$

To process variable declarations we are using transitions of the form $\langle D_V,\ s \rangle \to_D s'$ instead of $env_P \vdash \langle D_V,\ s \rangle \to_D s'$. Do we need to take env_P into account to process D_V ? Why?

To process variable declarations we are using transitions of the form $\langle D_V,\ s \rangle \to_D s'$ instead of $env_P \vdash \langle D_V,\ s \rangle \to_D s'.$ Do we need to take env_P into account to process D_V ? Why? No; because variable declarations do not involve procedures. Can you think of an extension to PROC so that transitions of the form $env_P \vdash \langle D_v,\ s \rangle \to_D s'$ are needed?

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The call Statement

To execute the statement

call p

just retrieve the definition of p from the current environment and execute its body.

[call_{ns}]
$$\frac{env_P \vdash \langle S, s \rangle \to s'}{env_P \vdash \langle \text{call } p, s \rangle \to s'}$$
 where $env_P \ p = S$

Note that invoking a non-existing procedure (env_P is a partial function) will abort the execution.

Does this semantics

$$[\operatorname{block}_{ns}] \quad \frac{\langle D_V, \ s \rangle \to_D s', \quad \operatorname{upd}_{\operatorname{P}}(D_V, env_P) \vdash \langle S, \ s' \rangle \to s''}{env_P \vdash \langle \operatorname{begin} D_V \ D_P \ S \ \operatorname{end}, \ s \rangle \to s''[\operatorname{DV}(D_V) \longmapsto s]}$$

$$[\mathtt{call}^{\mathrm{rec}}_{\mathrm{ns}}] \quad \frac{env_P \vdash \langle S, \ s \rangle \to s'}{env_P \vdash \langle \mathtt{call} \ p, \ s \rangle \to s'} \quad \text{where } env_P \ p = S$$

support recursive procedure calls? Why?

Does this semantics

$$[\operatorname{block}_{ns}] \quad \frac{\langle D_V, \ s \rangle \to_D s', \quad \operatorname{upd}_{\operatorname{P}}(D_V, env_P) \vdash \langle S, \ s' \rangle \to s''}{env_P \vdash \langle \operatorname{begin} D_V \ D_P \ S \ \operatorname{end}, \ s \rangle \to s''[\operatorname{DV}(D_V) \longmapsto s]}$$

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support recursive procedure calls? Why?

Yes; procedures must be defined before they are invoked, thus the definition of a recursive procedure is available in env_P when it is called.

Exercises (I)

Exercise 2.38 Consider the following statement of PROC:

```
begin
   proc fac is
      begin
          var z := x;
          if x = 1 then skip
          else (
             x := x - 1;
             call fac;
             y := z * y
      end
     y:= 1;
     call fac
end
```

construct a derivation tree for the execution from state s where s = 3.

Exercises (II)

Exercise 2.39 Use the semantics to verify that the statement:

```
begin
   var x:= 0;
   proc p is x:= x * 2;
   proc q is call p;
   begin
      var x:= 5
      proc p is x:= x + 1;
      call q;
      y:= x
   end
end
```

does indeed assign 6 to y.

To define the semantics for a language with **mixed** scope we need:

- a proper definition of the procedure environment
- a strategy to update the procedure environment (begin ... end)
- ► a strategy to retrieve the procedure environment (call)

Static scope for procedures means that a procedure only knows the procedures that were **already declared** when it itself is declared; thus future re-declarations will not interfere with its semantics.

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A procedure environment env_P is a partial function that given a procedure name $p \in \mathbf{Pname}$ returns a pair with:

- lacktriangle the statement $S \in \mathbf{Stm}$ corresponding to its body, and
- ▶ the procedure environment env_P at the point of declaration (the snapshot)

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- lacktriangle the statement $S \in \mathbf{Stm}$ corresponding to its body, and
- ▶ the procedure environment env_P at the point of declaration (the snapshot)

We introduce the type \mathbf{Env}_P :

$$\mathbf{Env}_P = \mathbf{Pname} \hookrightarrow (\mathbf{Stm}, \mathbf{Env}_P)$$

thus $env_P \in \mathbf{Env}_P$.

Updating the Procedure Environment

Given a procedure environment env_P and a procedure declaration D_P the updated procedure environment $\operatorname{upd}_P(D_P,\operatorname{env}_P)$ is defined by:

$$\operatorname{upd}_{P}(\operatorname{proc} p \text{ is } S; D_{P}, env_{P}) = \operatorname{upd}_{P}(D_{P}, env_{P}[p \mapsto (S, env_{P})])$$

$$\operatorname{upd}_{P}(\varepsilon, env_{P}) = env_{P}$$

Note that the definition is similar to the previous one, but we bind the current environment env_P to p.

Are these definitions circular?

$$\mathbf{Env}_P = \mathbf{Pname} \hookrightarrow (\mathbf{Stm}, \mathbf{Env}_P)$$

$$\begin{array}{rcl} \operatorname{upd_P}(\operatorname{proc}\ p\ \operatorname{is}\ S;\ D_P, env_P) &=& \operatorname{upd_P}(D_P, env_P[p\mapsto (S, env_P)]) \\ \operatorname{upd_P}(\varepsilon, env_P) &=& env_P \end{array}$$

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Not really; procedure environments are built from the bottom up. We start with an empty environment and always build a environment from a strictly smaller environment.

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Not really; procedure environments are built from the bottom up. We start with an empty environment and always build a environment from a strictly smaller environment. However, the corresponding type synonym in Haskell is circular.

The call Statement

To execute the statement

call p

just retrieve the definition of p from the current environment and execute its body S in the recorded environment env_P' .

[call_{ns}]
$$\frac{env'_P \vdash \langle S, s \rangle \to s'}{env_P \vdash \langle \text{call } p, s \rangle \to s'}$$
 where $env_P \ p = (S, env'_P)$

Note that invoking a non-existing procedure (env_P is a partial function) will abort the execution.

Does this semantics

$$[\operatorname{block}_{ns}] \quad \frac{\langle D_V, \ s \rangle \to_D s', \quad \operatorname{upd}_{\operatorname{P}}(D_P, env_P) \vdash \langle S, \ s' \rangle \to s''}{env_P \vdash \langle \operatorname{begin} \ D_V \ D_P \ S \ \operatorname{end}, \ s \rangle \to s''[\operatorname{DV}(D_V) \longmapsto s]}$$

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support recursive procedure calls? Why?

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 where $env_P \ p = (S, env'_P)$

support recursive procedure calls? Why?

No; because the procedure p is **not** available in the recorded environment env'_P .

The call Statement – with Recursive Procedures

We can reconcile static scope for procedures and recursive procedures with the following alternative definition of call:

$$[\mathtt{call}^{\mathtt{rec}}_{\mathtt{ns}}] \quad \frac{env_P'[p \mapsto (S, env_P')] \vdash \langle S, \ s \rangle \to s'}{env_P \vdash \langle \mathtt{call} \ p, \ s \rangle \to s'}$$

where $env_P \ p = (S, env_P')$.

Exercises

Exercise 2.40 Construct a statement that illustrates the difference between the rules [call_{\rm ns}] and [call_{\rm ns}^{\rm rec}]. Validate your claim constructing derivation trees for the execution of the statements from a given initial state.

Exercise 2.41 Use the semantics to verify that the statement:

```
begin
   var x:= 0;
   proc p is x:= x + 2;
   proc q is call p;
   begin
      var x:= 5
      proc p is x:= x + 1;
      call q;
      y:= x
   end
end
```

does indeed assign 10 to y.

Static Scope for Variables and Procedures

To define the semantics for a language with **static** scope we need:

- proper definitions of the procedure and variable environments
- ➤ a strategy to update the variable and procedure environments (begin ... end)
- ► a strategy to retrieve the procedure environment (call)

Variable Environments

A variable environment env_V associates a location with each variable:

$$\mathbf{Env}_V = \mathbf{Var} \to \mathbf{Loc}$$

where \mathbf{Loc} is a set of **locations** or abstract addresses. For the sake of simplicity, we take:

$$\mathbf{Loc} = \mathbb{Z}$$

furthermore, we assume that locations are non-negative.

Stores

A **store** sto associates a value with each location:

$$\mathbf{Store} = \mathbf{Loc} \cup \{ \mathrm{next} \} \to \mathbb{Z}$$

where next is a special token that holds the *next free location* in the store.

We assume a function new:

$$\text{new}: \mathbf{Loc} \to \mathbf{Loc}$$

that given a location l returns the next free location $\mathrm{new}\ l.$ For the sake of simplicity, we take:

new
$$l = l + 1$$

Splitting the State into Variable Environments and Stores

The idea is to replace the state s:

$$s: \mathbf{Var} \to \mathbb{Z}$$

by the function composition:

$$(sto \circ env_V) : \mathbf{Var} \to \mathbb{Z}$$

thus:

$$s = (sto \circ env_V)$$

Reading and Writing Variables

To determine the value of a variable x (s x):

- 1. determine the location $l = env_V x$ associated with x
- 2. determine the value sto l associated with l

To assign a value v to a variable x ($s[x \mapsto v]$):

- 1. determine the location $l = env_V x$ associated with x
- 2. update the store $(sto[l \mapsto v])$ to have sto l = v

Initialization of Variable Environment and Store

When we worked with states in while, we had $s \ _ = 0$. To get a similar initialization:

- ▶ the initial variable environment maps all variables to the location 0
- ▶ the initial store maps next to 1

Is the proposed initialization for PROC:

- ▶ the initial variable environment maps all variables to the location 0
- ▶ the initial store maps next to 1

equivalent to having s = 0 in WHILE?

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- ▶ the initial store maps next to 1

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No; global variables (i.e. non-declared in a block) share the same location and therefore become aliases.

Is the proposed initialization for PROC:

- the initial variable environment maps all variables to the location 0
- ▶ the initial store maps next to 1

equivalent to having s = 0 in while?

No; global variables (i.e. non-declared in a block) share the same location and therefore become aliases.

This is not a problem: in PROC we can get rid of global variables and enclose the whole program in a block with appropriate variable declarations.

Variable Declarations

Both the variable environment and the store are updated by variable declarations.

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Both the variable environment and the store are updated by variable declarations.

The transition system \rightarrow_D is therefore modified to:

$$\langle D_V, \ env_V, \ sto \rangle \rightarrow_D \langle env_V', \ sto' \rangle$$

$$\begin{aligned} & [\text{var}_{\text{ns}}] & & \frac{\langle D_V, \, env_V[x \mapsto l], \, sto[l \mapsto v][\text{next} \mapsto \text{new} \, l] \rangle \, \to_D \, (env_V', \, sto')}{\langle \text{var} \, \, x := \, a; \, D_V, \, env_V, \, sto \rangle \, \to_D \, (env_V', \, sto')} \\ & & & \text{where} \, \, v = \, \mathcal{A}[\![a]\!] (sto \circ env_V) \, \, \text{and} \, \, l = sto \, \, \text{next}} \\ & & & [\text{none}_{\text{ns}}] & & \langle \varepsilon, \, env_V, \, sto \rangle \, \to_D \, (env_V, \, sto) \end{aligned}$$

Table 3.5: Natural semantics for variable declarations using locations

Extended Procedure Environments

We extend the procedure environment env_P to hold the variable environment env_V at the point of declaration (a *snapshot* of the current variables):

$$\mathbf{Env}_P = \mathbf{Pname} \hookrightarrow (\mathbf{Stm}, \ \mathbf{Env}_V, \ \mathbf{Env}_P)$$

and modify the upd_{P} function accordingly:

```
\begin{array}{rcl} \operatorname{upd_P}(\operatorname{proc}\ p\ \operatorname{is}\ S;\ D_P,\ env_V,\ env_P) &=& \operatorname{upd_P}(D_P,env_V,env_P[p\mapsto (S,env_V,env_P)]) \\ & \operatorname{upd_P}(\varepsilon,env_V,env_P) &=& env_P \end{array}
```

Extended Transition System

The transition system is extended to have the form:

$$env_V, env_P \vdash \langle S, sto \rangle \rightarrow sto'$$

thus we get a relation between the initial store and the final store. Most rules and axioms are straightforward: just propagate the variable and procedure environments thus they are available where needed.

The Assignment (:=) and skip Statements

```
[\mathrm{ass_{ns}}] \qquad env_V, env_P \vdash \langle x := a, sto \rangle \to sto[l \mapsto v] where: l = env_V \ x \quad \text{and} \quad v = \mathcal{A}[\![a]\!](sto \circ env_V) [\mathrm{skip_{ns}}] \qquad env_V, env_P \vdash \langle \mathtt{skip}, sto \rangle \to sto
```

The Sequential Composition (;) Statement

 $[\mathrm{comp}_{\mathrm{ns}}]$

$$\frac{\textit{env}_V, \textit{env}_P \vdash \langle S_1, \textit{sto} \rangle \rightarrow \textit{sto'} \quad \textit{env}_V, \textit{env}_P \vdash \langle S_2, \textit{sto'} \rangle \rightarrow \textit{sto''}}{\textit{env}_V, \textit{env}_P \vdash \langle S_1; S_2, \textit{sto} \rangle \rightarrow \textit{sto''}}$$

The if then else Statement

$$[if_{ns}^{tt}] \qquad \frac{env_V, env_P \vdash \langle S_1, sto \rangle \rightarrow sto'}{env_V, env_P \vdash \langle if \ b \ then \ S_1 \ else \ S_2, sto \rangle \rightarrow sto'}$$

where:

$$\mathcal{B}[\![b]\!](sto\circ env_V)=\mathbf{tt}$$

$$[if_{ns}^{ff}] \qquad \frac{env_V, env_P \vdash \langle S_2, sto \rangle \to sto'}{env_V, env_P \vdash \langle if \ b \ then \ S_1 \ else \ S_2, sto \rangle \to sto'}$$

$$\mathcal{B}[\![b]\!](sto \circ env_V) = \mathbf{ff}$$

The while Statement

 $[\text{while}_{\text{ns}}^{\text{tt}}]$

$$\frac{\mathit{env}_V, \mathit{env}_P \vdash \langle S, \mathit{sto} \rangle \to \mathit{sto}' \quad \mathit{env}_V, \mathit{env}_P \vdash \langle \mathsf{while} \ \mathit{b} \ \mathsf{do} \ S, \mathit{sto}' \rangle \to \mathit{sto}''}{\mathit{env}_V, \mathit{env}_P \vdash \langle \mathsf{while} \ \mathit{b} \ \mathsf{do} \ S, \mathit{sto} \rangle \to \mathit{sto}''}$$

where:

$$\mathcal{B}[\![b]\!](sto \circ env_V) = \mathbf{tt}$$

 $[\text{while}_{\text{ns}}^{\text{ff}}]$

$$env_V, env_P \vdash \langle \mathtt{while}\ b\ \mathtt{do}\ S, sto \rangle \rightarrow sto$$

$$\mathcal{B}[\![b]\!](sto\circ env_V) = \mathbf{ff}$$

The Block (begin ... end) Statement

 $[block_{ns}]$

$$\frac{\langle D_V, env_V, sto \rangle \rightarrow_D (env'_V, sto') \quad env'_V, env'_P \vdash \langle S, \ sto' \rangle \rightarrow sto''}{env_V, env_P \vdash \langle \texttt{begin} \ D_V \ D_P \ S \ \texttt{end}, sto \rangle \rightarrow sto''}$$

$$env'_P = \operatorname{upd}_P(D_P, env'_V, env_P)$$

Compare:

$$\frac{\langle D_V, env_V, sto \rangle \rightarrow_D (env'_V, sto') \quad env'_V, env'_P \vdash \langle S, sto' \rangle \rightarrow sto''}{env_V, env_P \vdash \langle \mathsf{begin} \ D_V \ D_P \ S \ \mathsf{end}, sto \rangle \rightarrow sto''}$$

where:

$$env'_P = \operatorname{upd}_P(D_P, env'_V, env_P)$$

to:

$$\frac{\langle D_V,\ s\rangle \to_D s', \quad \operatorname{upd}_{\operatorname{P}}(D_P, env_P) \vdash \langle S,\ s'\rangle \to s''}{env_P \vdash \langle \operatorname{begin}\ D_V\ D_P\ S \text{ end},\ s\rangle \to s''[\operatorname{DV}(D_V) \longmapsto s]}$$

What happened to $[DV(D_V) \longmapsto s]$?

Compare:

$$\frac{\langle D_V, env_V, sto \rangle \to_D (env'_V, sto') \quad env'_V, env'_P \vdash \langle S, sto' \rangle \to sto''}{env_V, env_P \vdash \langle \mathsf{begin} \ D_V \ D_P \ S \ \mathsf{end}, sto \rangle \to sto''}$$

where:

$$env'_P = \operatorname{upd}_P(D_P, env'_V, env_P)$$

to:

$$\frac{\langle D_V, s \rangle \to_D s', \quad \operatorname{upd}_{\mathcal{P}}(D_P, env_P) \vdash \langle S, s' \rangle \to s''}{env_P \vdash \langle \operatorname{begin} D_V D_P S \text{ end}, s \rangle \to s''[\operatorname{DV}(D_V) \longmapsto s]}$$

What happened to $[DV(D_V) \longmapsto s]$?

It is not needed since variables can only be accessed through the variable environment env_V . Note that the static semantics leaves garbage in the store.

The call Statement – Non-recursive Procedures

 $[call_{ns}]$

$$\frac{env'_V, env'_P \vdash \langle S, \ sto \rangle \rightarrow sto'}{env_V, env_P \vdash \langle \texttt{call} \ p, sto \rangle \rightarrow sto'}$$

$$env_P \ p = (S, env'_V, env'_P)$$

The call Statement – Recursive Procedures

$$[\mathrm{call}_\mathrm{ns}^\mathrm{rec}]$$

$$\frac{\mathit{env'}_V, \mathit{env'}_P[p \mapsto (S, \mathit{env'}_V, \mathit{env'}_P)] \vdash \langle S, \mathit{sto} \rangle \to \mathit{sto'}}{\mathit{env}_V, \mathit{env}_P \vdash \langle \mathit{call} \ p, \mathit{sto} \rangle \to \mathit{sto'}}$$

$$env_P p = (S, env'_V, env'_P)$$

Exercises

Exercises 2.42 to 2.47 (old, on-line edition) Exercises 3.12 to 3.17 (new edition)