Write Up for P3: Traffic Sign Classifier

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Introduction:

This document is a write up for the 3rd project. As mentioned in the write up template, the objectives are:

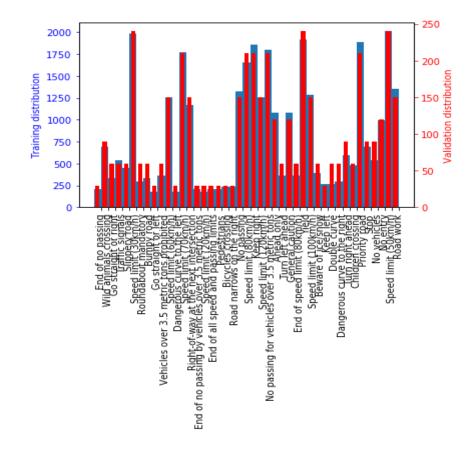
- Load the data set (see below for links to the project data set)
- Explore, summarize and visualize the data set
- Design, train and test a model architecture
- Use the model to make predictions on new images
- Analyze the softmax probabilities of the new images
- Summarize the results with a written report

The submission includes this writeup + code in a single file *Traffic_Sign_Classifier* in ipynb and html format.

Data set summary and exploration

Number of training examples = 34799 Number of testing examples = 12630 Image data shape = (32, 32, 3) Number of classes = 43

Training/ Validation classes histogram



Remarks concerning distribution:

Classes are not equally distributed. On the other side, distribution is similar between training and validation. So as a first approximation, we can use the current training distribution to teach our model.

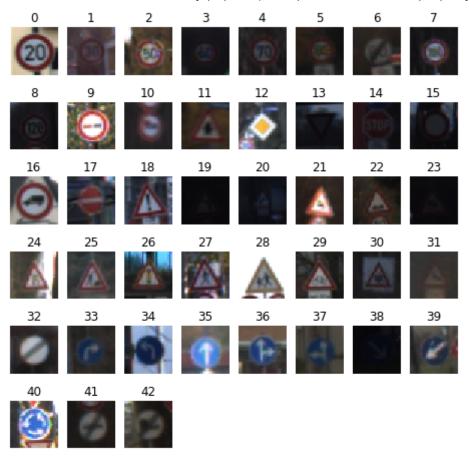
Design and test a model architecture

Preprocessing

Here're the 43 classes, it is interesting to notice that even though color is not a differentiating factor (still an important factor though). That is, no 2 signs are identical in all aspects except color.

⇒ For that reason I change signs to grayscale

Additionally, I scale the data between -1..1 for reasons that are now obvious and that were discussed in the course and many papers (example: "Efficient Backprop" by Yahn Lecun).



Model architecture

| Layer | Description | Output Shape |
|------------------|---|--------------------|
| Input | 32x32x1 scaled | - |
| CONV 3x3 -> ReLU | Stride: 1x1, same padding, filter depth: 16 | N_train x 32x32x16 |
| Max POOL 2x2 | Stride: 2x2 | N_train x 16x16x16 |
| CONV 3x3 -> ReLU | Stride: 1x1, same padding, filter depth: 32 | N_train x 16x16x32 |
| Max POOL 2x2 | Stride: 2x2 | N_train x 8x8x32 |
| FC -> ReLU | | N_train x 120 |
| Dropout 0.8 | | N_train x 120 |
| FC -> ReLU | | N_train x 120 |
| Dropout 0.8 | | N_train x 84 |
| FC -> Softmax | | N_train x 43 |

Model training

Learning rate: 1e-3
Batch size: 64

Optimization: Adam (did not tweak parameters)

Epochs: 15

Approach discussion

To select these parameters, I did several runs displaying both validation error and training error. My approach was first to reach near 100% training accuracy then apply some regularization to increase the validation accuracy.

Training error optimization

Tried increasing the number of layers and filter depth in each layer. For simplicity, I chose a SAME padding followed by Max POOL layer which would divide size by 2. It's easier for me to keep track of image size (in case it gets big!).

⇒ I found that 3 convolutional layers overfit the model so I settled for 2 layers. I also tried different learning rates and found that 1e-3 was best.

Validation error optimization

Whenever I got satisfactory training error with minimum configuration, I tried 2 measures to improve validation error: Early stopping and dropout.

I found that 15 epochs coupled with dropout=0.8 provided good results!

Errors report

Training error: 0.999 Validation error: 0.962 Test error: 0.938

Test model on new images

Classification difficulty for the model discussion

Here're the images found on the web for the german dataset. Corresponding classes from left to right: [1,38,34,18,3,11,12,25]

















To illustrate the difference between the images on the internet and the challenge, I take 2 examples from the chosen classes in the training data. When comparing these images to those collected on the internet, we notice for both images:

- -Different in shape: Maybe due to camera distortion?
- -Difference in blurriness: probably due to the fact that training data were taking from a mounted camera inside a car
- ⇒ Internet images can serve as an additional test for the model's generalization capabilities.





















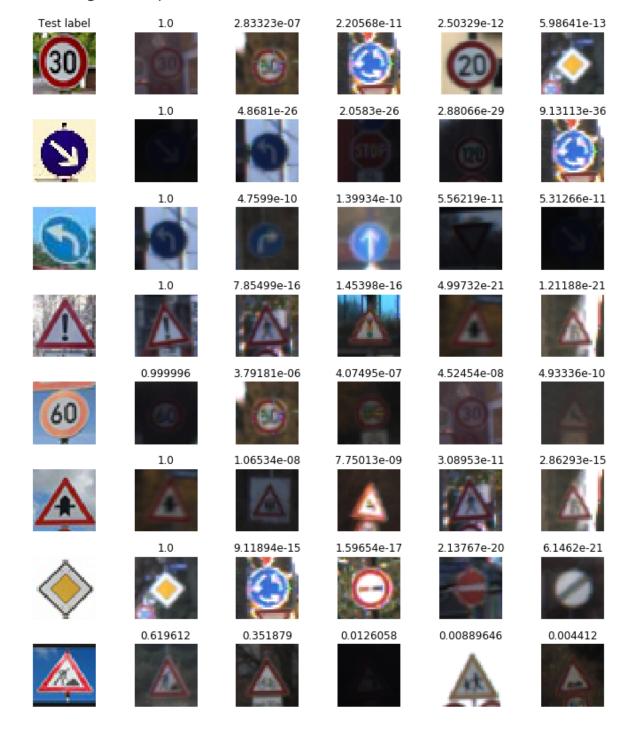
Classification results and significance analysis

Model accuracy on internet data =100%, size =5. This result looks 6.2% different than test accuracy (93.8%, size=12630)

However, this is not statistically significant because test sample size is too small (5 observations). Our new test accuracy given the new data becomes: (1*5+0.938*12630)/(5+12630)=0.938024 which means an impact of **0.0024%**

During the course, it was explained that we need a change of **at least 3%** (if the classes are well balanced) to be significant.

Visualizing model predictions



Discussion

Keeping the same architecture, I believe the model can be further improved in at least 2 ways:

- 1. Batch normalization
- 2. Data augmentation in the training set to balance badly classified classes (confusion matrix)

Additionally, one can try a different architecture (inception for example) or transfer learning. NB: I have written wrote my own NN and CNN from scratch but I was not familiar with tensorflow. After taking this course, I appreciate the ease and efficiency with which one can program such complicated models, thus allowing more time for prototyping!