

Matthew Massom

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SUMMARY

Highly motivated computer engineering student graduating in December 2019, with knowledge in object-oriented programming, product development, and debugging.

SKILLS

C/C++	Java	Python	Matlab
HTML/CSS	Linux	Git	SQL
Bash	C#	Machine Learning	Visual Studio
Android Studio	Altium	KiCAD	.NET

EDUCATION

Purdue University Northwest

B.S. Computer Engineering

Minor in Computer Science

Hammond, Indiana

Graduating: December 2019

Major GPA: 3.0

- Institute of Electrical and Electronic Engineers – PNW Student Branch
- IEEE PNW Electric Vehicle Grand Prix – Team Leader

EXPERIENCE

Sullair, LLC

Embedded Controls Engineering Intern

Michigan City, Indiana

January 2019 – August 2019

- Developed integrated circuit board hardware for motor controller testing and development
- Expedited various tasks for firmware commissioning through automation with VBA, Python, and C
- Researched component specifications for state-of-the-art controller board development

Sullair, LLC

Electrical Engineering Intern

Michigan City, Indiana

May 2018 – January 2019

- Assessed alternatives to existing components and compiled material lists for future cost reduction.
- Revamped wire harnesses and related components through various methods of troubleshooting.
- Created material lists, schematic drawings, and other technical documents in Siemens Teamcenter and NX

PROJECTS

Predicting Chaotic Systems using Deep Learning and Computer Vision

- Implemented neural networks to predict the outcome of a spin in the game of roulette

Deep Learning Sentiment Analysis

- Examined the use of deep learning in social media sentiment analysis to track patterns such as hate speech

EV Grand Prix Autonomous Car

- Facilitated the planning and groundwork for a competitive autonomous vehicle

AWARDS

Undergraduate Research Grant

- Awarded \$600 for “Using Machine Learning to Predict Outcomes in Chaotic Systems”

Indiana Space Grant Consortium

- Awarded \$600 for “3D Mapping with LiDAR and Stereoscopic Camera”
- Awarded \$600 for “Application of Modern Techniques in Autonomous Racing Vehicle Implementation”