

PHY 316M

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1 Capacitors

$$C = \left| \frac{Q}{V} \right|$$

2 Current

Is the flow of charge in on direction. Current:

$$I = \frac{\Delta Q}{\Delta t} = \frac{\delta Q}{\delta t}$$

Current Density (current per unit area): $J = \frac{I}{A}$

n = charge carrier density, q = charge per carrier, v_d = drift velocity This can give us, $J = nqv_d$

2.1 Ohm's Law

Usually we see Ohm's law in different forms, i.e. for a particular chunk.

Consider some block with volume $A \cdot l$, some source of energy (battery) forces current through by applying an electric field.

For a uniform electric field: $V = E \cdot l$

$$\begin{aligned} J &= \frac{I}{A} \\ &= \sigma E \\ &= \sigma \frac{V}{l} \end{aligned}$$

$$\frac{V}{l} = \frac{1}{\sigma} \frac{l}{A} = \rho \frac{l}{A} = R = \text{resistance}$$

$\frac{V}{l} = R$ Resistance is not resistivity (opposite of current flow of a particular material $[\rho]$) Ohmic material is a material that has a constant slope on Voltage to Current graph. Most common materials like copper behave like this.

Example The resistivity of nichrome wire (heaters, toasters) is $1.5 \times 10^{-6} \Omega m$. If a household voltage of $115V$ is applied across a $0.2mm$ radius wire, $1.0m$ long, what current flows?

$$R = \rho \frac{l}{A} = \rho \frac{l}{\pi r^2} = \frac{1.5 \times 10^{-6} \Omega m \cdot 1.0m}{(\pi (2 \times 10^{-4} m)^2)} = 11.9 \Omega$$

2.2 Model for electric conduction

- electron undergo many rapid collisions when $E = 0$
- when $E \neq 0$, the electrons accelerate between collisions
- $F = ma = qE \Rightarrow a = \frac{qE}{m}$
- $v = v_0 + at = v_0 + \frac{qE}{m}t$

Let τ = average collision time = $R \cdot C$

the $v_d = v_{avg} = \langle v_0 \rangle + \frac{qE}{m}\tau$

so, $J = nqv_d = nq = \frac{qE}{m}\tau = \sigma E$

so conductivity $\sigma = \frac{nq^2\tau}{m}$

Called the Drude model or free electron model

$$\sigma = \frac{nq^2\tau}{m}$$

$$\frac{1}{\sigma} = \rho$$

Example Assume for copper that each atom donates one free electron. What is the average time between collision for electrons in copper.?

Given:

- Density = $8.98 \frac{g}{cm^3}$
- Atomic Weight = $63.54 \frac{g}{mole}$
- $\rho = 1.7 \times 10^{-8} \Omega \cdot m$

$$\tau = \frac{m}{nq^2\rho} = \frac{9.14 \times 10^{-31} kg}{(8.5 \times 10^{22})(1.6 \times 10^{-19})^2 1.7 \times 10^{-8} \Omega m} = 2.5 \times 10^{-14} s$$

2.3 Temperature Dependence of resistivity

- resistivities tabulated for 20 °celsius
- for metals, ρ is higher and T is higher
- α = linear temperature coefficient
- over some range, $\rho = \rho_0(1 + \alpha(T - T_0))$

As T increases, the scattering time decreases due to collisions with vibrating atoms

At higher temperatures the ρ to temperature graph is linear. But at the beginning there is residual resistivity due to impurities.

Semiconductors The number of carriers decreases as the temperature decreases, this means that all the electrons are sticking to their atoms.

3 Resistors in Series and Parallel

Circuit symbol: 

3.1 Resistors in series

For resistors in series the resistivities add

$$R_{tot} = R_1 + R_2 + \dots$$
$$R_{tot} = \frac{V}{I} = \frac{V_1}{I_1} + \frac{V_2}{I_2} = R_1 + R_2$$

The current (I) is the same everywhere too. **Resistors don't add in parallel. Capacitors do.**

$$V = V_1 + V_2$$

The voltage divider

$$V_1 = I \cdot R_1 = \frac{V}{R_1 + R_2} \cdot R_1$$

3.2 Resistors in parallel

For resistors in parallel halve the resistance if two exact resistors are put in parallel

- In parallel have the same voltage across each element
- In parallel also the current divides among branches

$$I = I_1 + I_2 = \frac{V}{R_1} + \frac{V}{R_2} \Rightarrow R_{tot} = \frac{V}{I} = \frac{1}{\frac{1}{R_1} + \frac{1}{R_2}}$$

Superconductors Electrons pair up and when electron jumps to the lattice another electron pulls it right back.

3.3 Resistors Dissipate Energy

Electrons undergo collisions, and give up energy as heat. A steady release of current (I) causes a steady release of energy.

$$\Delta U = \Delta QV$$

Better to discuss the rate, which is really known as:

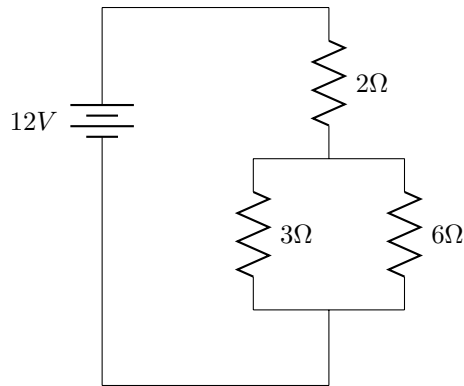
$$\text{Power} = P = \frac{\Delta U}{\Delta t} = \frac{\Delta U}{\Delta t} V = IV$$

$$P = IV = I^2 R = \frac{V^2}{R}$$

This power is also known as Joule heating.

Putting this into practice: many circuits can be analyzed with just Ohm's Law and Resistance.

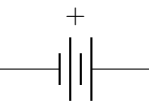
- What is the total power delivered?
- What is the power dissipated in each R ?



$$P_{\text{dissipated in } 3\Omega} = \frac{V_3^2}{R} = \frac{(6V)^2}{3\Omega} = 12W$$

3.4 Direct Current Circuits

Real battery is an ideal \mathcal{E} MF plus intended resistance

Batteries are a source of voltage 

Source of voltage = "electromotive force" = \mathcal{E} MF = \mathcal{E}

$$V = \mathcal{E} - Ir$$

"Open-circuit voltage", where $I = 0$

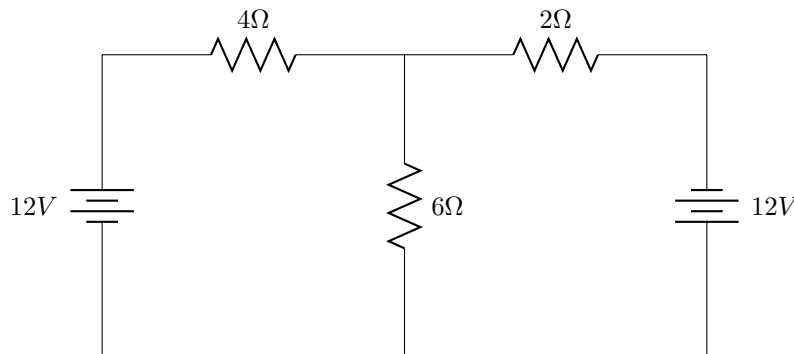
Analysis of circuits Any circuit can be analyzed with Kirchhoffs Rules:

- Junction Rule, algebraic sum of currents into a junction = sum of currents $\Sigma i_{in} = \Sigma i_{out}$
- Loop Rule, algebraic sum of voltages around any closed loop is zero. Where voltage rises are positive (- to +) and voltage drops are negative (+ to -)

For resistors the current direction determines voltage drop(negative)

Example

- What is the current in the 6Ω resistor?
- Is it flowing up or down?



(I) Junction at A: $i_1 = i_2 + i_3$

(II) Loop A: $12V - i_1(4\Omega) - i_3(6\Omega) = 0$

(III) Loop B: $i_3(6\Omega) - i_2(2\Omega) + 12V = 0$

$$i_3 = \frac{-12V}{22\Omega} = -\frac{6}{11}A$$

2 other techniques:

- i) same, except use fictitious “loop currents”
- ii) Source suppressing - can look at effects of sources separately

Next: Circuits with Capacitors will see time-dependent behavior Before “transient phenomena”, look at *Steady-state*: “after a long time”. The capacitor starts acting like the current is 0.

4 Magnetism

We saw:

$$F = qv \frac{\mu_0 I}{2\pi r} = 0$$

for \vec{v} tangent to circle. where $\mu_0 = 4\pi \times 10^{-7} \frac{Ns^2}{C^2}$

Rewrite this as

$$\boxed{\vec{F} = q\vec{v} \times \vec{B}}$$

where $\boxed{B = \frac{\mu_0 I}{2\pi r}}$ magnetic field due to a long wire where direction of \vec{B} is tangent to circle.

If also electric force, combination of electric and magnetic force is called “Lorentz Force”

$$\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}$$

$$\vec{F} = q\vec{v} \times \vec{B}$$

- Like \vec{E} , \vec{F} opposite for $+q, -q$
- Depends on \vec{v} : $\vec{F} = 0$ for $\vec{v} = 0$
- Depends on angle: $\boxed{|\vec{F}| = |q|vB\sin\Theta}$
notice $\vec{F} = 0$ for $\vec{v} \parallel \vec{B}$
- Direction $\vec{F} = q\vec{v} \times \vec{B}$ given by right hand rule

Magnetic field does no work because the magnetic force is perpendicular to displacement.

So \vec{B} changes direction of \vec{v} but not its magnitude ($KE = \frac{1}{2}mv^2$)

Unit of $B = \frac{Ns}{Cm} = \text{tesla} = T$ also gauss = $G = 10^{-4}T$

4.1 Evaluating Cross Products

1. Get general equation by expanding determinant $\begin{vmatrix} i & j & k \\ v_x & v_y & v_z \\ B_x & B_y & B_z \end{vmatrix} =$

$$\vec{v} \times \vec{B} = i(v_y B_z - v_z B_y) - j(v_x B_z - v_z B_x) + k(v_x B_y - v_y B_x)$$

2. Just multiply out.
know that $i \times j = k$ and that $j \times i = -k$
5. Magnetic field does no work

4.2 Two ways to Find \vec{B}

1. Ampere's Law: for high symmetry
2. Biot Savart Law

In general we will only look at: center of arcs and circles, or due to straight segments, or on axis of loop.

4.2.1 \vec{B} at the center of a circle

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I d\vec{s} \times \hat{r}}{r^2}$$

$$B = \int dB = \int \frac{\mu_0 I}{4\pi r^2} ds = \frac{\mu_0 I}{2R}$$

Since $r = R$, the integral is constant and is easy to integrate with respect to s .

Also: for a fraction f of a circle $\boxed{\vec{B} = f B_{\text{full circle}}}$

4.2.2 \vec{B} near a finite straight wire

$$d\vec{B} = \frac{\mu_0 I}{4\pi} \frac{d\vec{s} \times \hat{r}}{r^2}$$

$$= \frac{\mu_0 I}{4\pi} \frac{ds \sin\theta}{r^2}$$

1. $\sin\theta = \sin\theta' = \cos\phi$
2. $\cos\phi = \frac{R}{r} \rightarrow r = \frac{R}{\cos\phi}$
3. $\tan\phi = \frac{s}{R} \rightarrow s = R \cdot \tan\phi \rightarrow \frac{R}{\cos^2\phi d\phi}$

$$B = \int dB$$

$$= \int \frac{\mu_0 I \frac{R}{\cos^2\phi} d\phi \cos\phi}{4\pi \left(\frac{R}{\cos\phi}\right)^2}$$

$$= \frac{\mu_0 I}{4\pi R} \int_{-\phi_1}^{+\phi_2} \cos\phi d\phi$$

$$= \frac{\mu_0 I}{4\pi R} \sin\phi \Big|_{-\phi_1}^{+\phi_2}$$

$$= \frac{\mu_0 I}{4\pi R} [\sin\phi_2 + \sin\phi_1]$$

4.2.3 B field due to a square loop of side a

$$B_{\text{loop}}$$

$$\frac{2\sqrt{2}\mu_0 I}{\pi a}$$

4.2.4 B on axis of loop

Off axis components cancel around circle.

ϕ is the angle at the bottom right of triangle formed by circle and axis

$$r = \sqrt{x^2 + R^2} \quad \text{Using pythagorean theorem}$$

$$\sin\phi = \frac{R}{\sqrt{x^2 + R^2}} \quad \text{So we can define } \sin\phi$$

We only have to integrate along the x components

$$\begin{aligned} dB_x &= dB \sin \phi \\ &= \frac{\mu_0 I ds}{4\pi r^2} \sin \phi \end{aligned}$$

We can say that $\int ds = 2\pi R$ since the radius is constant

$$\begin{aligned} B &= \int \frac{\mu_0 I}{4\pi r^2} \sin \phi ds \\ &= \frac{\mu_0 I R}{4\pi (x^2 + R^2)^{3/2}} \int ds \\ &= \frac{\mu_0 I R^2}{2(x^2 + R^2)^{3/2}} \end{aligned}$$

Also, consider yourself very close to the field, $x \gg R$ $\frac{1}{x^3}$ dipole field

4.3 Motion in a uniform B

$$|\vec{F}| = |q\vec{v} \times \vec{B}| = qvB$$

\vec{F} is \perp to \vec{v} centripetal with accelerations $a_r = \frac{v^2}{r}$ We saw that

$$\begin{aligned} B_{\text{long wire}} &= \frac{\mu_0 I}{2\pi r} \\ B_{\text{solenoid}} &= \mu_0 n I \\ B_{\text{loop center}} &= \frac{\mu_0 I}{2R} \end{aligned}$$

angular velocity $\omega = ?$

$$r = \frac{mv}{qB}$$

Example: Mass Spectrometer *Note: Electrons travel in a semi-circle in a spectrometer* Electrons are accelerated through potential of $10^3 V$ ("a 1 keV electron"). They enter a region of uniform $B = 10^{-2} T$. What is the distance they are displaced?

$$x = 2r = 2 \frac{mv}{qB}$$

Know m, q, B need to find v

$$\begin{aligned} \Delta KE &= \Delta PE \rightarrow \frac{1}{2}mv^2 = eV_0 = \sqrt{\frac{2eV}{m}} \\ x &= 2 \frac{m}{eB} \sqrt{\frac{2eV_0}{m}} = \frac{2}{B} \sqrt{\frac{2mV_0}{e}} = \frac{2}{(10^{-2} T)} \sqrt{\frac{2(9.11 \times 10^{-31})(10^3 V)}{(1.6 \times 10^{-19} C)}} \end{aligned}$$

In practice however, we are given v, B, x to get $\left(\frac{q}{m}\right)$

Example: Velocity Selector region of crossed $\vec{E} + \vec{B}$

All we have to consider is qE -vs- qvB

if $qE = qvB$ then $\boxed{v = \frac{E}{B}}$

4.4 Force on a current

Consider positive charge travelling along x axis with v_0 with a $-\vec{B}\hat{y}$

$$\begin{aligned} F_{\text{on wire}} &= q\vec{v} \times \vec{B} \\ &= \frac{1}{n}\vec{j} \times \vec{B} \\ F_{\text{on wire}} &= (\# \text{ charges})F_{\text{on 1 charge}} \\ &= (nAl)\frac{1}{n}\hat{j} \times \hat{B} \\ &= lA\vec{j} \times \vec{B} \\ &= I\vec{l} \times \vec{B} \end{aligned}$$

Example Net force on a current loop in a uniform \vec{B} is **zero**. This is true for any loop.

Example A current I flows from the origin to $(x, y, z) = (1m, 1m, 0)$ and then straight to $(2m, 0, 0)$. In a uniform field of $\vec{B} = 5T\hat{i}$

$$\begin{aligned} \vec{F}_1 &= (10N)(-\hat{j} + \hat{i}) \\ \vec{F}_2 &= (10N)(-\hat{j} - \hat{i}) \\ \vec{F} &= (20N) - \hat{j} \end{aligned}$$

Example Force on a wire segment due to a large || wire

$$\begin{aligned} B &= \frac{\mu_0 I}{2\pi r} \\ \vec{F} &= I_2 \vec{l} \times \frac{\mu_0 I_1}{2\pi r} \\ &= I_2 \times \frac{l\mu_0 I_1}{2\pi r} \\ \frac{\text{force}}{\text{length}} &= \frac{\mu_0 I_1 I_2}{2\pi r} \end{aligned}$$

Definition: Magnetic Moment

Dipole moment ($\mu = IA$) due to a magnetic loop.

4.5 Torque on a current

We saw: $\vec{F} = I\vec{l} \times \vec{B}$

Magnetic Moment $\vec{\mu} = I\vec{A}$
and for N loops we have $\vec{\mu} = NI\vec{A}$

we also saw that for a loop in uniform $B \rightarrow \vec{F} = 0$. There is no force, but there is a **net torque**.

Torque on a current Loop in a uniform \mathbf{B}

$$\begin{aligned}\vec{\tau} &= \Sigma \vec{r} \times \vec{F} \\ |\vec{\tau}| &= \Sigma r F \sin\theta \\ &= (z) \left(\frac{l}{z}\right) Il B \sin\theta \\ &= Il^2 B \sin\theta \\ &= \mu B \sin\theta \\ \vec{\tau} &= \vec{\mu} \times \vec{B}\end{aligned}$$

Where μ is the magnetic moment and \vec{B} is the magnetic field.

5 Magnetism in Matter

Comes from some sort of current loop in matter. Perhaps an electron traveling around a proton, that is a current loop.

Example Consider the orbiting electron as current:

$$\begin{aligned}I &= \frac{\Delta Q}{\Delta t} = \frac{e}{T} = \frac{e}{(2\pi r)/v} = \frac{e \cdot v}{2\pi r} \\ \mu &= IA = \frac{e \cdot v}{2\pi r} \cdot \pi r^2 = \frac{1}{2} e v r\end{aligned}$$

Recall that angular momentum is $\vec{l} = \vec{r} \times \vec{p}$ and therefore $\boxed{l = mvr}$

$$\mu = \frac{e}{2m} mvr = \frac{e}{2m} l$$

An atom can have many electrons $\vec{L} = \Sigma \vec{l}_i$ and that $\mu = -\frac{e}{2m} \vec{L}$

5.1 Quantum Mechanics

\vec{l} is quantized: $l = 0, \hbar, 2\hbar, \dots$ When $\hbar = \frac{h}{2\pi} = 1.06 \times 10^{-34} J$ where $h = \text{Planck's constant} = 6.63 \times 10^{-34} J$. Ultimately, the spin of atom does not really exist, but it behaves like it is. Its “spin” would be $s = \frac{\hbar}{2}$

Adding total angular momentum $\vec{J} = \vec{L} + \vec{S}$

When $l = \hbar$ we have the smallest possible moment. $\mu = \frac{e\hbar}{2m} = \text{Bohr magneton} = 9.27 \times 10^{-24} J/T$

5.2 Magnetization

Definition Magnetization = $M = \frac{\mu}{(\text{volume})}$ = magnetic moment per unit volume.

The total field In an external field, some moments align and they produce their own field, \vec{B}_{matter} . With our definitions, $B_{\text{matter}} = \mu_0 M$, so the total field $\vec{B} = \vec{B}_{\text{ext}} + \mu_0 \vec{M}$. For many field $\vec{B} \propto \vec{B}_{\text{ext}}$. Really we can say that $\vec{B} = K_m \vec{B}_{\text{ext}}$ where K_m = magnetic permeability or just the permeability constant.

Vacuum $K_m = 1$

Diamagnet in most materials $K_m - 1 \approx 10^{-6} - 10^{-4} \approx -10^{-5}$ because they have closed shells

Ferromagnet $K_m \gg 1$ have locked moments due to Pauli exclusion principle.

Superconductors Type I superconductors have a $K_m = 0$, which means they shield the external field.

Magnetic Susceptibility $\chi_m = K_m - 1$ $\boxed{\frac{\mu_0 M}{B_{ext}}}$

5.3 Hall Effects

5.3.1 Hall effect

is used for measuring the charge carrier density n (or, for known n , can measure B or map B)

Consider a current I and a $\vec{v} \perp \vec{B}$

Carrier experience $\vec{F} = q\vec{v} \times \vec{B}$, deflect and build up on surface with their transverse electric field balances magnetic force until $qE_t = qv_d B$

We measure the (transverse) “Hall Voltage” $V_H = E_t d$

Use current density $j = \frac{I}{A} = \frac{I}{dl} = nqv_d \rightarrow v_d = \frac{I}{nqdl}$ (1) and $F_e = F_m \rightarrow E_t = v_d B \rightarrow v_d = \frac{E_t}{B}$ (2)

Due to (1) and (2) we can say $\frac{E_t}{B} = \frac{I}{nqdl}$ and $V_H = E_t d \rightarrow \frac{V_H}{Bd} = \frac{I}{nqdl} \rightarrow \boxed{n = \frac{IB}{V_H qd}}$

5.3.2 Motional EMF

This gives us Magnetic Flux and Faraday’s Law

Instead of a current producing a Hall Voltage, we can just $\vec{v} \perp \vec{B}$. Ions are stuck, but electrons can move, until $qE_t = qvB$ and get a transverse voltage. Called a **motional EMF**. $\boxed{\mathcal{E} = E_t l = Blv}$. We will see many ways to get EMF by “sweeping past B field”

5.4 Faraday’s Law

5.4.1 Preparation

$\mathcal{E} = Blv$

Before looking at Faraday’s Law define Magnetic Flux $\Phi_m = \int \vec{B} \cdot d\vec{A} = \vec{B} \cdot \vec{A} = BA \cos \theta$. We will be interested in “flux through a current loop”.

Example A long solenoid with current I and n turns/meter, radius R_2 contains a loop of radius $R_1 \perp$ to solenoid axis. Find flux through loop. Remember: $\boxed{B_{\text{solenoid}} = \mu_0 n I}$.

$$\Phi_m = \int \vec{B} \cdot d\vec{A} = \vec{B} \cdot \vec{A} = BA = (\mu_0 n I)(\pi R_1^2)$$

Will only get an induced voltage if something is moving though.

Example A rectangular loop is ?? in plane of a long wire carrying current I . From wire to one end of rectangle is a , and to other end is b . Remember that B is not uniform.

$$\Phi_m = \int \vec{B} \cdot d\vec{A} = \int_{\vec{B} \perp \vec{A}} B dA = \int_a^b \frac{\mu_0 I}{2\pi r} l dr = \frac{\mu_0 I l}{2\pi} \int_a^b \frac{1}{r} dr = \frac{\mu_0 I l}{2\pi} \ln(b/a)$$

5.4.2 Content

A changing magnetic flux induces a current/voltage around a loop. If Φ_m is the flux through surface then the voltage around that surface is

$$\mathcal{E} = -\frac{\partial \Phi_m}{\partial t}$$

If N loops on a coil then

$$\mathcal{E} = -N \frac{\partial \Phi_m}{\partial t}$$

Example A loop of wire with resistance R is partly in a region of uniform B and is pushed in at a constant v . What happens?

$$\Phi = BA = Blx$$

Farady: $\mathcal{E} = \frac{d\Phi}{dt} = -\frac{d}{dt}Blx = Bl\frac{dx}{dt} = -lv$. If loop is closed, current flows. $I = \frac{\mathcal{E}}{R} = -\frac{Blv}{R}$. Energy dissipated: $P = I^2R = \frac{B^2l^2v^2}{R}$. Another view: $\vec{F} = I\vec{l} \times \vec{B} = I; B = \frac{Blv}{R}lB$ Hence we can say $P = Fv = \frac{B^2l^2v^2}{R}$

The sign in Faraday's Law The “-” in the equation for \mathcal{E} is called **Lenz' Law**, which states that induced current opposes the change in flux.