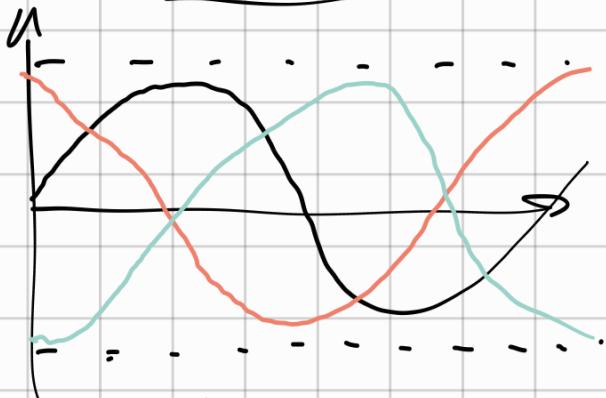


## Commutation:

For A-B-C Frame

### SPWM:



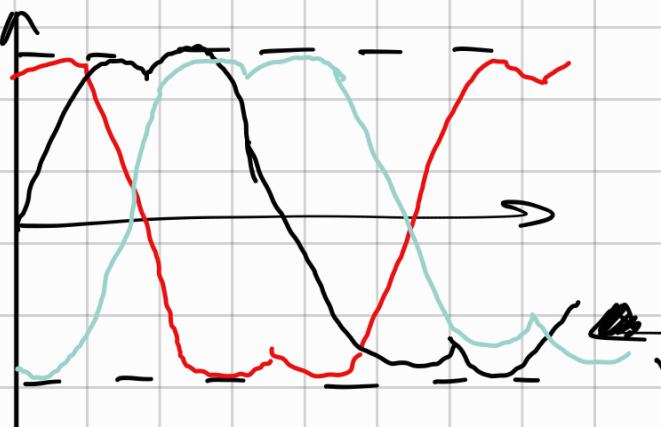
$$I_A = \frac{V_{cnd}}{V_{bus}} \cdot \sin(\theta)$$

$$I_B = \frac{V_{cnd}}{V_{bus}} \cdot \sin(\theta - 120^\circ)$$

$$I_C = \frac{V_{cnd}}{V_{bus}} \cdot \sin(\theta - 240^\circ)$$

④ Net uses the entire Voltage difference available (use 86.6 %)

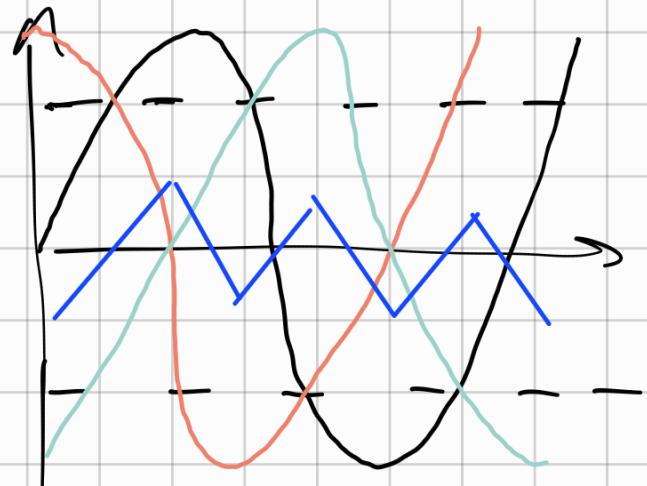
⑤ Six step is this but bit-wise (1/0)



Looks something like this

### STW:

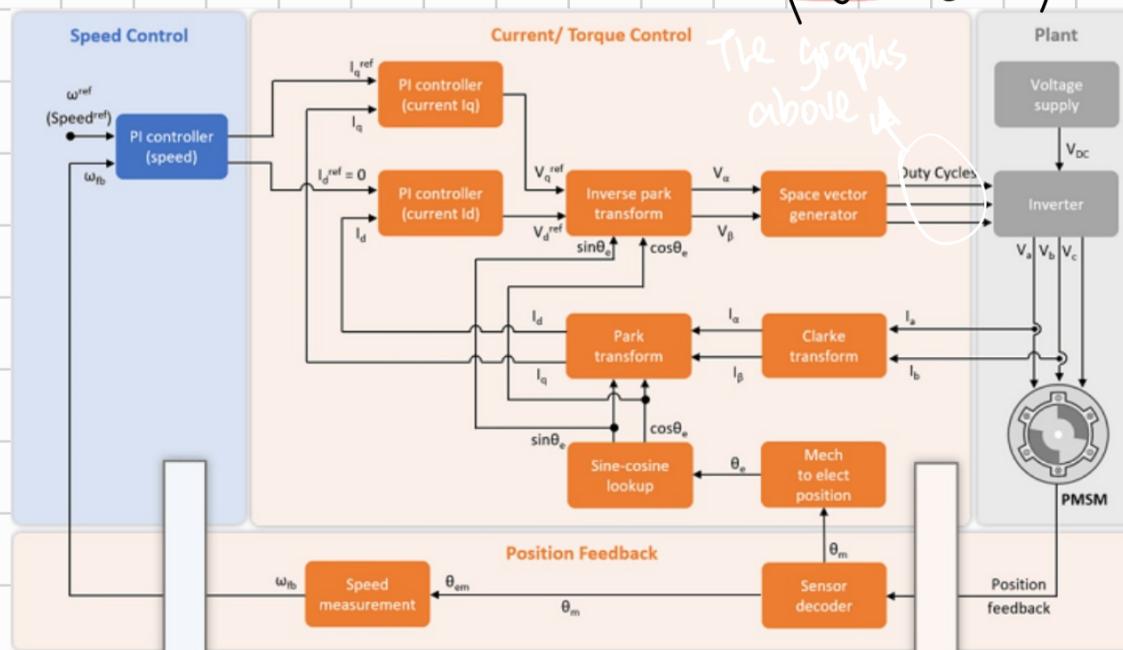
- ④ Take SPWM and increase it by  $\frac{1}{86.6\%} = 1.15$  times



Then fold the extra (what goes over the line) to fit inside the given Voltage. (By adding a triangle CS seen in Blue)

Each peak of the triangle is cut at a point where the voltage goes beyond 100%.

# The control scheme: (Overall)



Park %

$$\begin{bmatrix} d \\ a \\ b \end{bmatrix} = \frac{2}{3} \begin{bmatrix} \cos \theta & \sin(\theta - \frac{2\pi}{3}) & \sin(\theta + \frac{2\pi}{3}) \\ \cos(\theta - \frac{2\pi}{3}) & \cos(\theta + \frac{2\pi}{3}) & 1 \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

Inverse Park %

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta & 1 \\ \sin(\theta - \frac{2\pi}{3}) & \cos(\theta - \frac{2\pi}{3}) & 1 \\ \sin(\theta + \frac{2\pi}{3}) & \cos(\theta + \frac{2\pi}{3}) & 1 \end{bmatrix}^{-1} \begin{bmatrix} d \\ a \\ b \end{bmatrix}$$

Clarke %

$$\begin{bmatrix} \alpha \\ \beta \\ 0 \end{bmatrix} = \frac{2}{3} \begin{bmatrix} 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ 0 & \frac{\sqrt{3}}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

So this aligned with the graphs will give us the desired PWM signal... Or, I'm missing something

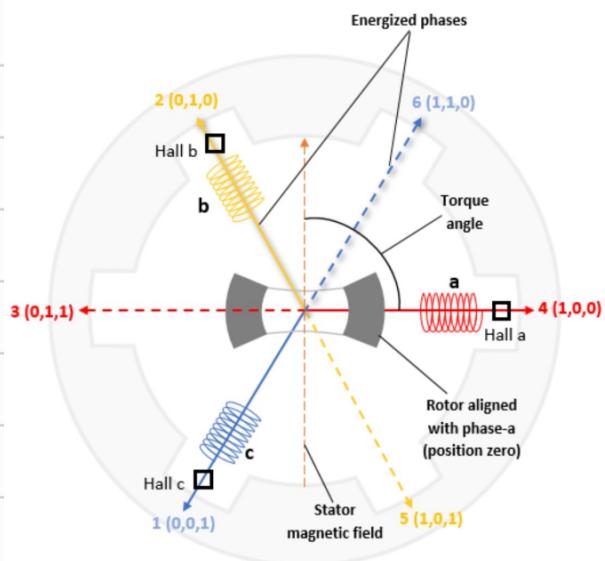
Inverse Clarke %:

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} & 1 \\ -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 1 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ 0 \end{bmatrix}$$

# Electric angle visualization

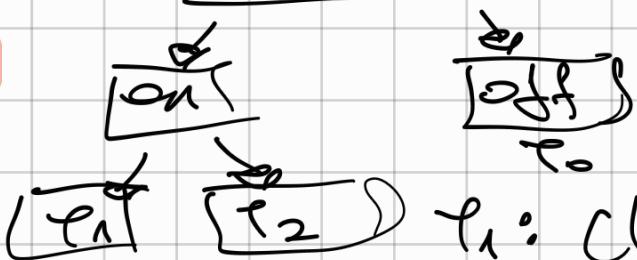
$$\frac{\theta_e}{\theta_m} = NPP$$

So if commutating its easier the rotor angle by the NPP and take the modulo.



Then the sections are as follows

## PWM Period



$T =$  Time period  
 $DC =$  Duty cycle

$T_1$ : Closest in clockwise dir.  
 $T_2$ : Closest in CCW dir.  
 $T_0$ : Null between them

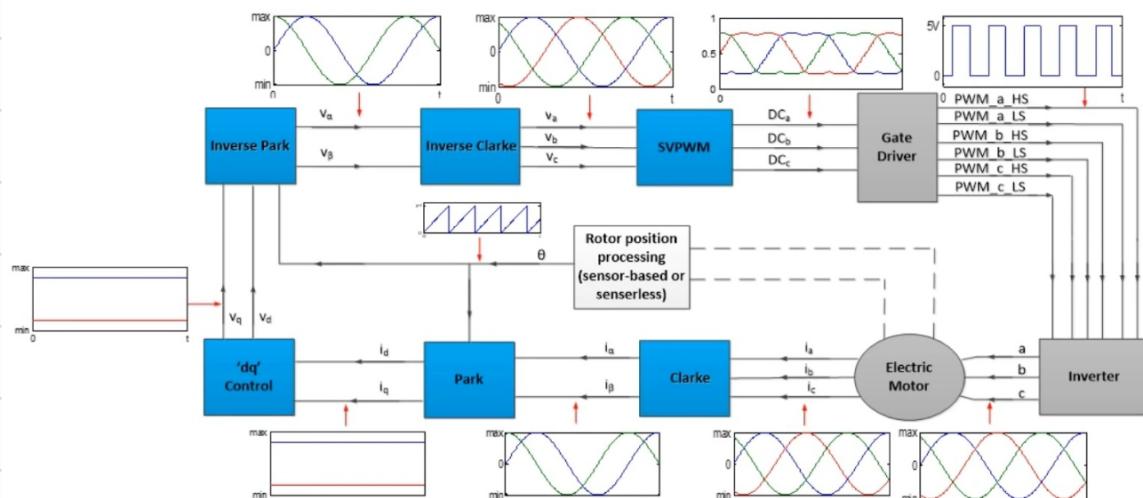
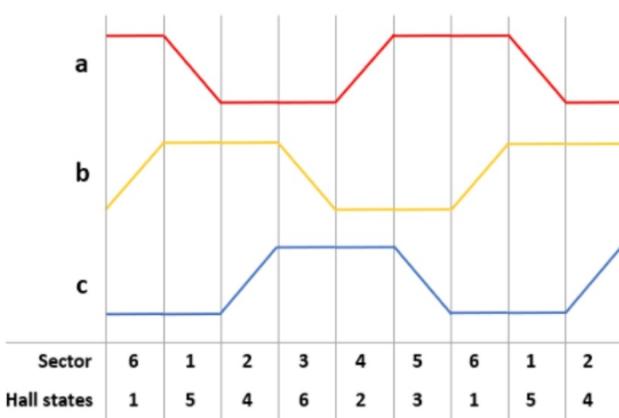
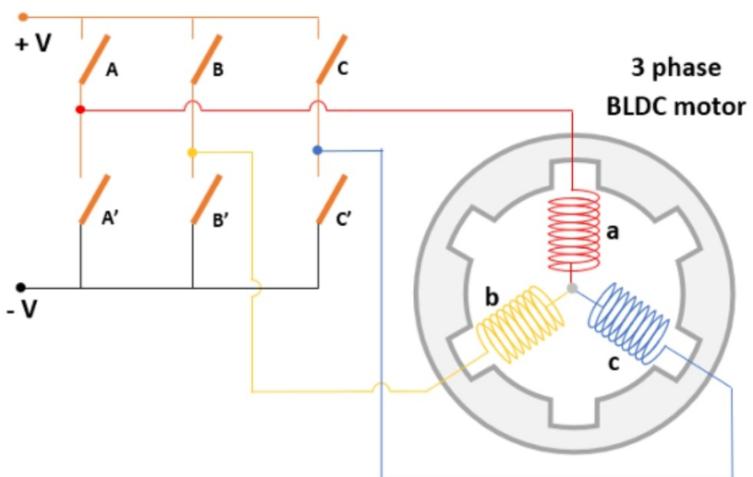
$(I_0, 0, 0S, I_2, 1, +3)$   
choose to make as least possible switches.

## PWM Idea:

$$T_1 = T \cdot DC \cdot \sin(60^\circ - \alpha)$$

$$T_2 = T \cdot DC \cdot \sin(\alpha)$$

$$T_0 = T - T_1 - T_2,$$



so the triangle wave drops it.

$T_{BLDC} \rightarrow 100 [ms]$

