

# Samir Yitzhak Gadre

616 NE Banner Pl, Seattle, WA 98115  
*Citizenship:* USA  
[sy@cs.columbia.edu](mailto:sy@cs.columbia.edu)

## Research Interests

Self-supervised Learning  
3D Computer Vision  
Robot Learning

## Education

- Sept 2020–Present    **Columbia University**, Computer Science Ph.D. Candidate  
*Advisor:* Professor Shuran Song  
Investigates how agent interaction can improve performance on computer vision tasks like amodal segmentation and pose estimation.  
Interested in representation learning and pretraining.
- Sept 2014–May 2018    **Brown University**, Sc.B. Computer Science w/ Honors  
*GPA:* 3.66, *Computer Science GPA:* 3.94  
*Thesis:* [Teaching Robots Using Mixed Reality](#)  
*Academic Elections:* Sigma Xi  
*Selected Coursework:* Robotics, Reinforcement Learning, Artificial Intelligence, Machine Learning, Probabilistic Methods, Algorithms, Cryptography, Operating Systems, Distributed Systems

## Work Experience

- Feb 2019–Aug 2020    **Microsoft HoloLens**, Software Engineer II  
*Manager:* Dr. Harpreet Sawhney  
Worked on object detection and 6DoF object pose estimation for recently launched [Azure Object Anchors](#).

## Past Research Experience

- May–July 2018    **Brown University**, Robotics Researcher  
*Advisors:* Professors George Konidaris & Stefanie Tellex  
First author on accepted ICRA 2019 paper titled [End-User Robot Programming Using Mixed Reality](#) ([video](#)). Built an Augmented Reality experience to allow users to program robot motion.
- Sept 2017–May 2018    **Brown University**, Honors Candidate  
*Advisors:* Professors George Konidaris & Stefanie Tellex  
Defended a thesis titled [Teaching Robots Using Mixed Reality](#) ([video](#)). Created a Mixed Reality interface to teleoperation an end-effector. Used the interface to train movement primitives for pick-and-place tasks.

May–Aug 2016      **Brown University**, Computer Vision Researcher  
*Advisor:* Professor Benjamin Kimia  
Won an **Undergraduate Teaching and Research Award** to support work on visual odometry and camera pose estimation.

## Teaching Experience

Sept–Present      **Computational Aspects of Robotics**, Graduate Teaching Assistant  
*Taught by:* Professor Shuran Song  
Holds office hours, grades student code submissions, designed a 3D computer vision homework assignment.

Jan–May 2018      **Algorithms & Data Structures**, Teaching Assistant  
*Taught by:* Professor Seny Kamara  
Co-led weekly sections and office hours to help students understand canonical algorithms. Graded code and proofs of correctness.

Sept–Dec 2016      **Object Oriented Programming**, Teaching Assistant  
*Taught by:* Professor Andy van Dam  
Staffed office hours to help students understand object oriented paradigms and debug code. Graded code based on functionality and style.

## Invited Talks

Oct 2018      **University of Washington Robotics Colloquium**, Speaker  
Gave talk titled **Virtual and Mixed Reality Interfaces for Human-Robot Interaction**, which addressed the design and implementation of such interfaces.

## Service

Nov 2020–Present      **Columbia Pre-submission Application Review (PAR)**, Reader  
Provided a helpful round of comments on statement of purpose materials submitted by students intending to apply for Ph.D. admission.

Sept 2014–May 2016      **Outdoor Leadership and Environmental Education**, Mentor  
Mentored 3-5 high school students per year on topics related to college admissions and internships. Taught science workshops.

## Skills

Technical      pytorch, ROS, MoveIt!, Unity, Linux, Windows, python, C, C++, C#

Interests      ultimate frisbee, reading, skiing, house plants

## References

**Prof. Shuran Song**, Columbia University: [shurans@cs.columbia.edu](mailto:shurans@cs.columbia.edu)  
**Dr. Harpreet Sawhney**, Microsoft: [harpreet.sawhney@microsoft.com](mailto:harpreet.sawhney@microsoft.com)  
**Prof. George Konidaris**, Brown University: [gdk@cs.brown.edu](mailto:gdk@cs.brown.edu)