

Chapter 1 - Introduction

Sections 1.1-2.4 (Versteeg)

ME 2256/MEMS 1256 - Applications of Computational Heat and Mass Transfer

Mechanical Engineering and Materials Science Department
University of Pittsburgh



Student Learning Objectives

Chapter 1 -
Introduction

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At the end of the lecture, students should be able to:

- ▶ Understand the basics of numerics applied to a system of partial differential equations:
 1. Discretization
 2. Basics of grid generation
 3. Solution to a set of algebraic equations
- ▶ Construct the governing constitutive equations (mass, momentum, energy)

Learning Objectives

Preamble

1. Numerics

2. Governing
Equations



- ▶ Consider the heat conduction equation in 1D:

$$\alpha^2 \frac{d^2 T}{dx^2} = \frac{dT}{dt}, \quad 0 < x < L, \quad t > 0$$

- ▶ $T = T(x, t)$
- ▶ The thermal diffusivity, α is the thermal conductivity per the quantity of the density times the specific heat:

$$\alpha(T) = \frac{\lambda(T)}{\rho(T)C_P(T)}$$

- ▶ If the materials properties are invariant with respect to T , an analytic solution exists, if initial and boundary conditions are provided:

$$T(x, 0) = f(x), \quad 0 < x < L$$

$$T(0, t) = A, \quad T(L, t) = B, \quad t > 0$$



- ▶ The is found via separation of variables and is expressed as a series solution:

$$T(x, t) = \sum_{n=1}^{\infty} c_n e^{-n^2 \pi^2 \alpha^2 t / L^2} \sin \frac{n \pi x}{L}$$

$$T(x, 0) = \sum_{n=1}^{\infty} c_n \sin \frac{n \pi x}{L} dx$$

$$c_n = \frac{2}{L} \int_0^L f(x) \sin \frac{n \pi x}{L} dx$$

- ▶ This requires us to sum over a finite value of eigenvalues (n), but a solution is obtainable

Learning Objectives

Preamble

1. Numerics
2. Governing Equations



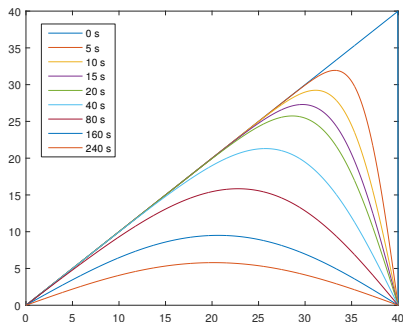
Example #1

- ▶ Consider heat conduction within a rod that has a length of 40 [cm] whose ends at $x=0$ and $x=L$ are kept at 0 °C for all $t>0$.
- ▶ Find the solution for $T(x,t)$, supposing $\alpha^2=1$, with the initial condition $T(x,0)=x$ for $0<x<40$ and plot $T(x,t)$ versus x for $t=5, 10, 15, 20, 40, 80, 160$ and 240 seconds.
- ▶ See the MATLAB code titled “L1Ex1.m” posted on Canvas.



Example #1 Solution

► Thus:



► What happens when $\alpha = \alpha(T)$?

Learning Objectives

Preamble

1. Numerics

2. Governing
Equations



- ▶ The use of numerics does not supersede experiments on physical phenomena.
- ▶ Rather, numerics can be used to design experiments, while simultaneously reducing the number of experiments needed, to gain insight into a particular physics.
- ▶ Numerics can only be used as a predictive tool once the mathematical model and technique is validated against experimental data.
- ▶ The low computational costs of numerics is a major advantage over large-scale experiments, however, there are limitations.



- ▶ Considering the following equation:

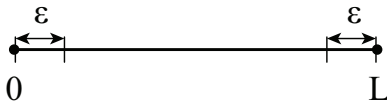
$$\frac{\partial^2 y}{\partial x^2} = f(x), \quad 0 < x < L$$

- ▶ With the following boundary conditions:

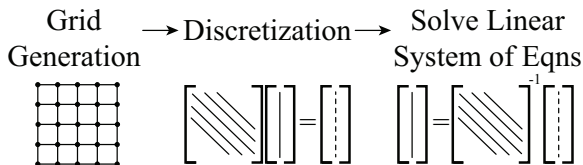
$$\text{at } x = x_0, y = y_0$$

$$\text{at } x = L, y = y_L$$

- ▶ Differential equations are valid within the space of $[\varepsilon, L-\varepsilon]$, i.e. not valid on the boundary, where $\varepsilon \rightarrow 0$.



- ▶ Thus, a solution to a differential equation is valid both inside the domain and on the boundaries.
- ▶ When creating a numerical solution there are three main building blocks:



- ▶ Grid generation is synonymous to meshing.
- ▶ Discretization is the construction of the mathematical model representing the physics of the problems.



Numerical Solutions to Differential Equations

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1. Numerics

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Equations

- ▶ There are two types of differential equations:
 1. Ordinary Differential Equations (ODEs).
 2. Partial Differential Equations (PDEs).
- ▶ There exist numerous techniques for solving 2nd PDEs
 1. Finite difference → differentiation
 2. Finite element → integration
 3. Finite volume → differentiation+integration
 4. Spectral method
 5. Finite analytic



► Properties of Numerical Solutions

1. Consistency - the extent to which the finite system of algebraic equations approximate the underlying PDE.
2. Stability - errors from any source are not permitted to grow in sequence of numerical procedures → applicable to marching algorithms.
3. Convergence - solution of algebraic expressions approaches true solution of PDE as mesh size tends to zero.



► Types of variables:

1. Conserved - a quantity which is governed by some conservative relationship, e.g. mass, momentum, energy.
2. Primitive - variable that is not conserved, e.g. pressure, temperature, velocity.



- ▶ Goal is to identify, quantify and control numerical error in calculations.
- ▶ Error is present in any approximation, regardless of the numerical techniques employed.
- ▶ When exact mathematical operators are replaced by the approximate algebraic expressions → Truncation Error (TE), for e.g.

$$\frac{dy}{dx} = f(x, y)$$

$$\frac{dy}{dx} \approx \frac{y_{i+1} - y_i}{\Delta x} + \text{H.O.T.}$$

- ▶ When exact numbers are represented as approximate numbers → Round-off Error (RE), for e.g. $\pi=3.14$ vs. $\pi=3.14159...$



- ▶ Let us consider a Taylor series expansion about a point i :

$$y_{i+1} = y_i + \left. \frac{\partial y}{\partial x} \right|_i \frac{\Delta x}{1!} + \left. \frac{\partial^2 y}{\partial x^2} \right|_i \frac{\Delta x^2}{2!} + \left. \frac{\partial^3 y}{\partial x^3} \right|_i \frac{\Delta x^3}{3!} \dots$$

- ▶ The derivative can be re-expressed as

$$\left. \frac{\partial y}{\partial x} \right|_i = \frac{y_{i+1} - y_i}{\Delta x} - \underbrace{\left. \frac{\partial^2 y}{\partial x^2} \right|_i \frac{\Delta x}{2} - \left. \frac{\partial^3 y}{\partial x^3} \right|_i \frac{\Delta x^2}{6} \dots}_{\text{H.O.T represents truncation error}}$$



Example #2

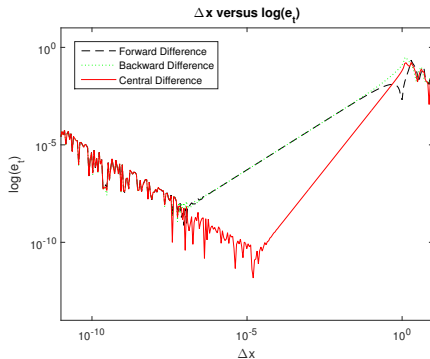
- ▶ Consider the following expression:

$$\frac{\ln(\sin(x)^{\cos(x)})}{x^{1/3}}$$

- ▶ Approximate the derivative at $x=792.93$ using a forward, central and backward difference scheme. Find the optimum Δx and plot the error vs Δx .



Example #2 Solution



- ▶ We see the second order accurate scheme minimizes error of the calculation.
- ▶ Note the slope of the first-order and second-order accurate schemes.



Derivation of General Transport Equation

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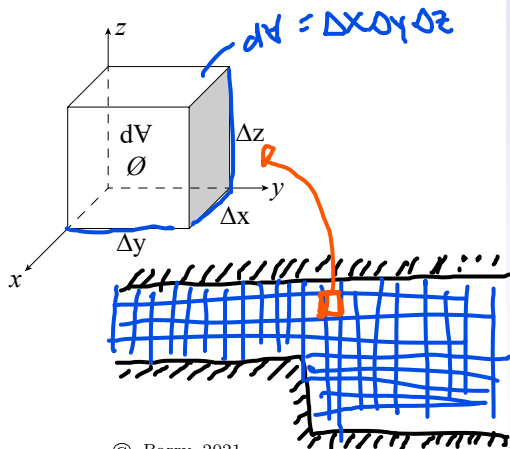
- To illustrate the robustness of the finite-volume method, let's try to derive a generalized transport equation for an arbitrary conserved variable (ϕ)

Learning Objectives

Preamble

1. Numerics

2. Governing
Equations



Accumulation of ϕ

- ▶ Let us consider how a conserved variable, say energy per unit volume (specific ϕ), can change in the C.V. with respect to time

- ▶ Start Time $\rightarrow t$

- ▶ End Time $\rightarrow t + \partial t$

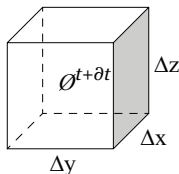
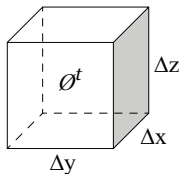
- ▶ ϕ at Start Time:

$$(\rho\phi)^t \Delta x \Delta y \Delta z$$

- ▶ ϕ at End Time:

$$(\rho\phi)^{t+\partial t} \Delta x \Delta y \Delta z$$

- ▶ There are three mechanisms responsible for a change of ϕ in the C.V.



super-time
sub-spatial



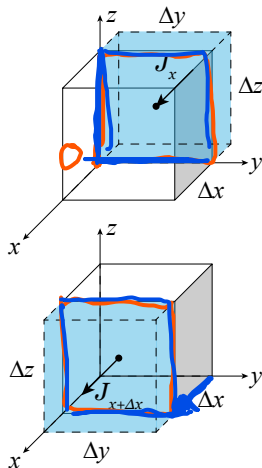
Flux of ϕ

- ▶ Let's define the rate of ϕ leaving a control surface as flux J
- ▶ In the positive x -direction, flux of ϕ entering C.V. over ∂t :

$$\underbrace{(J_x)}_{dA} \underbrace{\Delta y \Delta z \Delta t}_{dA}$$

- ▶ In the positive x -direction, flux of ϕ exiting C.V. over ∂t :

$$\underbrace{(J_{x+\Delta x})}_{dA} \underbrace{\Delta y \Delta z \Delta t}_{dA}$$



Flux of ϕ

- Likewise, in the y and z -directions, we have a flux of ϕ entering the C.V. over ∂t :

$$(J_y) \underline{\Delta x \Delta z \Delta t}$$

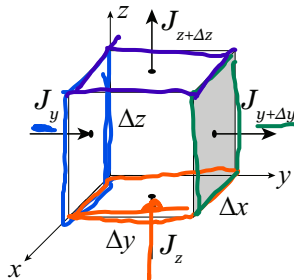
$$(\underline{J_z}) \Delta x \Delta y \Delta t$$

- The flux of ϕ exiting the C.V.:

$$(J_{y+\Delta y}) \underline{\Delta x \Delta z \Delta t}$$

$$(J_{z+\Delta z}) \Delta x \Delta y \Delta t$$

*in
spatial
location*



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1. Numerics

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Equations



Flux of ϕ

conserved quantity

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- To determine the total flux of ϕ into or out of the C.V., we sum like fluxes and combine terms:

$$(J_{x+\Delta x} - J_x) \Delta y \Delta z \Delta t + (J_{y+\Delta y} - J_y) \Delta x \Delta z \Delta t + (J_{z+\Delta z} - J_z) \Delta x \Delta y \Delta t$$

*out positive
in negative*

- Recall the accumulation of ϕ within the C.V. over some ∂t . Thus, the change of ϕ is expressed as:

$$\left[(\rho\phi)^{t+\Delta t} - (\rho\phi)^t \right] \Delta x \Delta y \Delta z$$

- We can relate the change of ϕ in the C.V. over some time ∂t to the net flux of ϕ . For robustness, we also have to consider the generation of ϕ .

RT: $\frac{d\phi}{dt} \big|_{sys} = \frac{\partial}{\partial t} \int_{C.V.} \rho \phi dV + \int_{C.S.} \rho \phi \vec{v} \cdot \vec{n} dA$

conservation \rightarrow



Internal Generation of ϕ

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- ▶ We can also have ϕ generated within our control volume by some volumetric rate (S)
- ▶ Imagine examples of this:
 1. Energy - volumetric heat generation rate (q''')
 2. Species - chemical reaction rate (R)
 3. Momentum - the opposite of generation is dissipation, and friction or viscous dissipation is common in solids and fluids.
- ▶ Let's specify a general volumetric reaction rate:

$$\rightarrow S \Delta x \Delta y \Delta z \Delta t$$

$$\rho \left(\frac{d\vec{v}}{dt} + \vec{v} \cdot \nabla \vec{v} \right) = \underbrace{-\nabla P}_{\text{source}} + \underbrace{\mu \nabla^2 \vec{v}}_{\text{sink}} - \underbrace{\rho \vec{g}}_{\text{source}}$$



Derivation of General Transport Equations

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Preamble

1. Principles

2. Governing
Equation

everything
that can
happen
on and
in dV

- Let's combine all our terms together:

solve for this

$$\begin{aligned} & \left[(\rho\phi)^{t+\Delta t} - (\rho\phi)^t \right] \Delta x \Delta y \Delta z + \left(J_{x+\Delta x} - J_x \right) \Delta y \Delta z \Delta t \\ & + \left(J_{y+\Delta y} - J_y \right) \Delta x \Delta z \Delta t + \left(J_{z+\Delta z} - J_z \right) \Delta x \Delta y \Delta t \\ & = S \Delta x \Delta y \Delta z \Delta t \end{aligned}$$

accumulation
advection
generation

- Simplify by dividing all terms by $\Delta x \Delta y \Delta z \Delta t$

$$\begin{aligned} & \frac{(\rho\phi)^{t+\Delta t} - (\rho\phi)^t}{\Delta t} + \frac{J_{x+\Delta x} - J_x}{\Delta x} + \frac{J_{y+\Delta y} - J_y}{\Delta y} + \dots \\ & \dots + \frac{J_{z+\Delta z} - J_z}{\Delta z} = S \end{aligned}$$

*discretized
variable!!*



Definition of Derivative

- Recall from your calculus classes the definition of the derivative:

spatial — $\left. \frac{\partial y}{\partial x} \right|_x = \lim_{h \rightarrow 0} \frac{y(x+h) - y(x)}{h}$

Handwritten annotations: Δt and Δx in blue and green above and below the limit, and a blue arrow pointing from the ∂x in the derivative to the x in the limit.

- This is applicable to both spatial and temporal terms. Let's do accumulation as an example:

$$\frac{(\rho\phi)^{t+\Delta t} - (\rho\phi)^t}{\Delta t} = \boxed{\frac{\partial}{\partial t}(\rho\phi)}$$



Simplified Transport Expression

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- ▶ Doing this for each term in series yields:

$$\frac{\partial}{\partial t}(\rho\phi) + \frac{\partial J_x}{\partial x} + \frac{\partial J_y}{\partial y} + \frac{\partial J_z}{\partial z} = S$$

- ▶ What are the processes by which ϕ can be transported as J ?

1. Advection - transfer of a conserved quantity by the flow of a fluid.
2. Diffusion - the movement of a conserved quantity through the imposition of a concentration gradient.

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Preamble

1. Numerics
2. Governing Equations

used definition
of a
derivative



Components of Flux

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1. Numerics

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Equations

1. Advection - conserved quantity transported by velocity field:

$$J_{\text{Advection}} = \rho \vec{V} \phi$$

2. Diffusion - conserved quantity transported through material from higher concentration to lower concentration:

$$J_{\text{Diffusion}} = -\Gamma \nabla \phi$$

$\left\langle \frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right\rangle$
diffusivity

3. The total flux is the net sum of the advection and diffusion across each control surface:

$$J_{\text{Total}} = J_{\text{Advection}} + J_{\text{Diffusion}} = \rho \vec{V} \phi - \Gamma \nabla \phi$$



Expanding Flux advective term: $\rho \vec{v} \phi$

- Therefore, taking the spatial derivatives of the total flux J yields:

$$\left(\begin{aligned} \frac{\partial J}{\partial x} &= \frac{\partial}{\partial x}(\rho \underline{u} \phi) - \frac{\partial}{\partial x} \left(\Gamma_x \frac{\partial \phi}{\partial x} \right) \\ \frac{\partial J}{\partial y} &= \frac{\partial}{\partial y}(\rho \underline{v} \phi) - \frac{\partial}{\partial y} \left(\Gamma_y \frac{\partial \phi}{\partial y} \right) \\ \frac{\partial J}{\partial z} &= \frac{\partial}{\partial z}(\rho \underline{w} \phi) - \frac{\partial}{\partial z} \left(\Gamma_z \frac{\partial \phi}{\partial z} \right) \end{aligned} \right)$$

$$\frac{\partial}{\partial x} \left(\rho u \phi - \frac{\partial}{\partial x} \left(\Gamma_x \frac{\partial \phi}{\partial x} \right) \right)$$



- ▶ Substituting the expression for the total flux into the general transport equation:

$$\begin{aligned} & \frac{\partial}{\partial t}(\rho\phi) + \frac{\partial}{\partial x}(\rho u\phi) + \frac{\partial}{\partial y}(\rho v\phi) + \frac{\partial}{\partial z}(\rho w\phi) \\ &= \frac{\partial}{\partial x}\left(\Gamma_x \frac{\partial\phi}{\partial x}\right) + \frac{\partial}{\partial y}\left(\Gamma_y \frac{\partial\phi}{\partial y}\right) + \frac{\partial}{\partial z}\left(\Gamma_z \frac{\partial\phi}{\partial z}\right) + S \end{aligned}$$

- ▶ If $\Gamma = \Gamma_x = \Gamma_y = \Gamma_z$, we have isotropic diffusion - the diffusion coefficient Γ is invariant with respect to which direction it is measure.

Learning Objectives

Preamble

1. Numerics

2. Governing Equations



Transport Equation

- In vector form:

$$\underbrace{\frac{\partial}{\partial t}(\rho\phi)}_{\text{Accumulation}} + \underbrace{\nabla \cdot (\rho \vec{V} \phi)}_{\text{Advection}} = \underbrace{\nabla \cdot (\Gamma \nabla \phi)}_{\text{Diffusion}} + \underbrace{S}_{\text{Generation}}$$

- This is the General Scalar Transport Equation
- $\phi \rightarrow$ conserved quantity
- $\Gamma \rightarrow$ diffusion coefficient
- $\rho \rightarrow$ density
- $\vec{V} \rightarrow$ velocity



- ▶ The continuity equation can be formed from the general scalar transport equation such that:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{V}) = S$$

- ▶ The continuity equation states that the rate of mass accumulating in a system must equal the rate of net mass influx.



- ▶ The general scalar transport equation can be formulated in terms of energy, which is expressed in terms of enthalpy, h . In vector form:

$$\frac{\partial}{\partial t}(\rho h) + \nabla \cdot (\rho \vec{V} h) = \nabla \cdot (\lambda \nabla T) + S_h$$

- ▶ Note the diffusion term is expressed in terms of temperature, T , which is not a conserved quantity. Can we transform the energy equation into the general scalar transport equation?



- ▶ From Thermodynamics, we can apply the following $dh = C_P dT$:

$$\frac{\partial \rho h}{\partial t} + \nabla \cdot (\rho \vec{V} h) = \nabla \cdot \left(\frac{\lambda}{C_P} \nabla h \right) + S_h$$

- ▶ Where we make the following transformations:
- ▶ $\phi = h$
- ▶ $\Gamma = \lambda / C_P$
- ▶ $S = S_h$



- ▶ Navier-Stokes (x -direction) for a Newtonian fluid:

$$\frac{\partial}{\partial t}\rho u + \nabla \cdot (\rho \vec{V}u) = \nabla \cdot (\mu \nabla u) - \frac{\partial P}{\partial x} + S_m$$

- ▶ Where we make the following transformations:

- ▶ $\phi = u$

- ▶ $\Gamma = \mu$

- ▶ $S = -\frac{\partial p}{\partial x} + S_m$

- ▶ Note: S will be a “dump” for all terms not diffusion, advection, or accumulation

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