### Chapter 3 - Fluid Statics

Lecture 6 Section 3.4

Introduction to Fluid Mechanics

Mechanical Engineering and Materials Science University of Pittsburgh  $\begin{array}{c} {\rm Chapter} \ 3 \ \hbox{-} \ {\rm Fluid} \\ {\rm Statics} \end{array}$ 

MEMS 0071

Learning Objectives

Force on Submerged Curved Surfaces



### Student Learning Objectives

 $\begin{array}{c} {\rm Chapter} \ 3 \ \hbox{-} \ {\rm Fluid} \\ {\rm Statics} \end{array}$ 

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Learning Objectives

.4 Hydrostatic orce on Submerged ourved Surfaces

Students should be able to determine the:

- magnitude of a force acting on a submerged curved surface;
- direction of a force acting on a submerged curved surface;
- ▶ the line of action of a force acting on a submerged curved surface.



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- The only difference in deriving the formulation for the resultant force  $F_R$  acting on a curved surface is that our pressure force is acting per unit normal at every infinitesimally small dA
- Looking at a sphere, each normal vector  $\vec{n}$  will vary slightly as you move along the surface.





- To rectify this, we integrate over  $d\overline{A}$  instead of dA, and it is also helpful to break  $F_R$  down into x- and y- components,  $F_x$  and  $F_y$
- Therefore, replacing dA with  $d\vec{A}$ ,  $F_R$  now becomes a vector expression:

$$d\vec{F}_R = -Pd\vec{A}$$

Note the minus sign - when we previously evaluated  $F_R$ , it was a magnitude (hence no sign), and now it acts against  $\vec{n}$ 

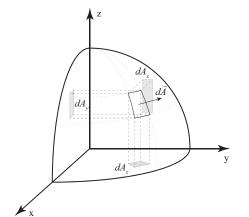


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3.4 Hydrostatic Force on Submerged Curved Surfaces

Notice how we *project* each component of the differential area on the x-y, y-z and z-x axes.





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3.4 Hydrostatic Force on Submerged Curved Surfaces

Since  $\vec{F}_R$  is a vector, we can write it in terms of the x-,y- and z- components (magnitude and direction):

$$\vec{F}_R = \vec{F}_x + \vec{F}_y + \vec{F}_z = F_{Rx}\hat{i} + F_{Ry}\hat{j} + F_{Rz}\hat{k}$$

► Integrating our force vector:

$$\int d\vec{F}_R = -P \int d\vec{A} \implies \vec{F}_R = -P \int_A d\vec{A}$$

We know the force vector has three components (x,y,z) and that the area has three components  $(A_x,A_y,A_z)$ 



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3.4 Hydrostatic Force on Submerged Curved Surfaces

If we multiply our force vector by the unit normal vector (vector dot product):

$$x: \quad F_{Rx} = \vec{F}_R \cdot \hat{i}$$

$$y: \quad F_{Ry} = \vec{F}_R \cdot \hat{j}$$

$$z: \quad F_{Rz} = \vec{F}_R \cdot \hat{k}$$



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3.4 Hydrostatic Force on Submerged Curved Surfaces

▶ Integrating each direction of the force vector:

$$x: F_{Rx} = -\int_{A} P d\vec{A} \cdot \hat{i} = -\int_{A} P dA_{x}$$

$$y: F_{Ry} = -\int_{A} P d\vec{A} \cdot \hat{j} = -\int_{A} P dA_{y}$$

$$z: F_{Rz} = -\int_{A} P d\vec{A} \cdot \hat{k} = -\int_{A} P dA_{z}$$

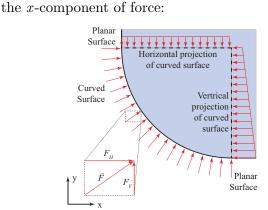
Note how the x-component of the force is the pressure acting on the x-component of the differential area (i.e. projection of dA onto the y-z plane), and the like for the remaining components



If we consider a purely 2-D case (x,y), lets look at

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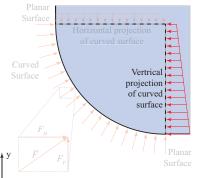




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3.4 Hydrostatic Force on Submerged Curved Surfaces

If we project  $d\vec{A}$  onto the vertical (y-z) plane, we see that the force (magnitude and line of action) is equal to the hydrostatic force as would be acting on a purely vertical plate (projection)





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3.4 Hydrostatic Force on Submerged Curved Surfaces

This means (using H to designate horizontal force):

$$F_{Rx} = F_H = P_c A$$

▶ i.e. the horizontal force acting on a curved surface is equivalent to the force on a vertically submerged planar surface

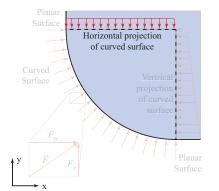


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3.4 Hydrostatic Force on Submerged Curved Surfaces

Similarly, the vertical force,  $F_{Ry}=F_V$ , ignoring atmospheric pressure (assuming it is acting on the free surface and other side of the surface of interest not in contact with the fluid)





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 $\triangleright$   $F_V$  is merely the weight of the fluid above the surface  $(P=\rho gh, hdA_z=d\forall)$ :

$$F_{Ry} = F_v = \int_A P dA_z = \int_A \rho g h dA_z = \int_A \rho g dV = \rho g V = F_V$$



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► Therefore, we have the following equations to use on a curved surface in 2-D space:

$$F_{Rx} = F_H = P_c A$$

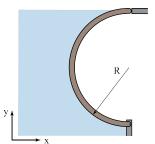
$$R_{Ry} = F_V = \rho g \forall$$

$$F_R = \sqrt{F_H^2 + F_V^2}$$



▶ There is semi-circular sluice gate as depicted below. The semi-circle has a radius of 3 [m], hinged at the bottom, and it 4 [m] long. Determine:

- 1.  $\vec{F}_R$
- 2. the force on the pin, as well as the top of the gate.



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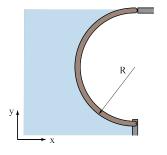


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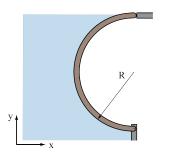
Solution:





Solution:





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Solution:

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Solution:

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