

1 Complexity, Games, Polytopes and Gale Strings

1.1 Some Complexity Classes

reference - take Papadimitriou (book) for general, then article Megiddo and Papadimitriou (1991) for (T)FNP and Papadimitriou 1994 for PPAD

A *computational problem* is given by the combination of an *input* and a related *output*. A specific input gives an *instance* of the problem.

Computational problems can be classified according to the form of their output. A *decision problems* outputs either “YES” or “NO”. An instance *x function problem*, on the other hand, returns a more generic output *y* that satisfies a given relation $R(x, y)$.

Search problems are function problems that return either an output *y* satisfying a given relation $R(x, y)$ or “NO”, if it’s not possible to find any such *y*. If *y* is guaranteed to exist, the problem is called a *total function problem*. *Counting problems*, finally, return the *number* of *y*’s that satisfy $R(x, y)$; given a problem *R* we denote the associated counting problem $\#R$.

An example of decision problem is: “(input) given a graph, (question) is it possible to find an *Euler tour* for the graph?” A search problem is: “(input) given a graph, (output) return one Euler tour of the graph, or “NO” if no such tour exists.” A total function problem is: “(input) given an Euler graph, (output) return one of its Euler tours.” A counting problem is “(input) given a graph, (output) return the number of its Euler tours.”

Computational problems are also classified according to their *computational complexity*, given by the *reducibility* from each other.

Turing machines: here

Let P_1 be a computational problem. For an instance x of P_1 , let $|x|$ be the the number of bits needed to encode x . P_1 reduces to the problem P_2 in polynomial time, denoted $P_1 \leq_P P_2$, if there exists a polynomial-time reduction, that is, a function $f : \{0, 1\}^* \rightarrow \{0, 1\}^*$ and a Turing machine \mathcal{M}

such that for all $x \in \{0, 1\}^*$

1. $x \in P_1 \iff f(x) \in P_2;$
2. \mathcal{M} computes $f(x);$
3. \mathcal{M} stops after $p(|x|)$ steps, where p is a polynomial.

The complexity class **P** contains all the *polynomially decidable problems*, that is, all problems P such that there exists a Turing machine \mathcal{M} that outputs either “YES” or “NO” for all inputs $x \in \{0, 1\}^*$ of P after $p(|x|)$ steps, where p is a polynomial. Intuitively, a decision problem is in **P** if the answer to its question can be found in a number of steps that is polynomial in the input of the problem. The class **FP** of all the function problems that can be solved in polynomial time is analogously defined.

The class **NP**, *non-deterministic polynomial-time problems*, is the class of problems P such that there exists a Turing machine \mathcal{M} and polynomials p_1, p_2 such that

1. for all $x \in P$ there exists a *certificate* $y \in \{0, 1\}^*$ which satisfies $|y| \leq p_1(|x|);$
2. \mathcal{M} accepts the combined input xy , stopping after at most $p_2(|x| + |y|)$ steps;
3. for all $x \notin P$ there does not exist $y \in \{0, 1\}^*$ such that \mathcal{M} accepts the combined input xy .

Intuitively: a decision problem is in **NP** if it takes polynomial time to verify whether the “certificate solution” y is, indeed, a correct answer to the question posed by the problem.

P

The class **FNP** is defined as the class of binary relations $R(x, y)$ such that there is a polynomial-time algorithm that decides whether $R(x, y)$ holds

for given x, y satisfying $|y| \leq p(|x|)$, where p is a polynomial. If a y as above is guaranteed to exist, the problem belongs to the class **TFNP**. That is, **FNP** and **TFNP** are analogous to **NP**, but they allow for problems of (respectively) function and total function form.

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1.2 Normal Form Games and Nash Equilibria

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1.3 Best Response Polytopes

file: polytopes-subsection

1.4 Cyclic Polytopes and Gale Strings

1.5 The Problem ANOTHER GALE

file: gale-def-subsection

merge in one section "Gale strings" or "CP and GS"?

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