

Lagrangian's Equations:

$$\frac{\partial}{\partial t} \left(\frac{\partial L}{\partial \dot{q}_i} \right) - \frac{\partial L}{\partial q_i} = 0$$

$$L = T - V = \frac{1}{2} m l^2 \left[2 \dot{\theta}_1^2 + \dot{\theta}_2^2 + 2 \dot{\theta}_1 \dot{\theta}_2 \cos(\theta_1 - \theta_2) \right] + m g l (2 \cos \theta_1 + \cos \theta_2)$$

For θ_1 : $\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}_1} \right) - \frac{\partial L}{\partial \theta_1} = 0$

$$\frac{\partial L}{\partial \dot{\theta}_1} = 2 m l^2 \dot{\theta}_1 + m l^2 \dot{\theta}_2 \cos(\theta_1 - \theta_2) \quad \left(\dot{\theta} = \frac{d\theta}{dt} \therefore \frac{d}{dt} \left(\frac{d\theta}{dt} \right) = \frac{d^2 \theta}{dt^2} = \ddot{\theta} \right)$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}_1} \right) = 2 m l^2 \ddot{\theta}_1 + m l^2 \ddot{\theta}_2 \cos(\theta_1 - \theta_2) - m l^2 \dot{\theta}_2^2 \sin(\theta_1 - \theta_2) \cdot (\dot{\theta}_1 - \dot{\theta}_2)$$

$$\frac{\partial L}{\partial \theta_1} = -m l^2 \dot{\theta}_1 \dot{\theta}_2 \sin(\theta_1 - \theta_2) - 2 m g l \sin \theta_1$$

$$\therefore 2 m l^2 \ddot{\theta}_1 + m l^2 \ddot{\theta}_2 \cos(\theta_1 - \theta_2) - m l^2 \dot{\theta}_2^2 \sin(\theta_1 - \theta_2) \cdot (\dot{\theta}_1 - \dot{\theta}_2) + m l^2 \dot{\theta}_1 \dot{\theta}_2 \sin(\theta_1 - \theta_2) + 2 m g l \sin \theta_1 = 0$$

$$\therefore 2 m l \ddot{\theta}_1 + m l \ddot{\theta}_2 \cos(\theta_1 - \theta_2) - m l \dot{\theta}_1 \dot{\theta}_2^2 \sin(\theta_1 - \theta_2) + m l \dot{\theta}_2^2 \sin(\theta_1 - \theta_2) + m l \dot{\theta}_1 \dot{\theta}_2 \sin(\theta_1 - \theta_2) + 2 m g \sin \theta_1 = 0$$

$$\therefore 2 m l \ddot{\theta}_1 + m l \ddot{\theta}_2 \cos(\theta_1 - \theta_2) + m l \dot{\theta}_2^2 \sin(\theta_1 - \theta_2) + 2 m g \sin \theta_1 = 0$$

$$L = T - V = \frac{1}{2} m l^2 \left[2 \dot{\theta}_1^2 + \dot{\theta}_2^2 + 2 \dot{\theta}_1 \dot{\theta}_2 \cos(\theta_1 - \theta_2) \right] + m g l (2 \cos \theta_1 + \cos \theta_2)$$

For θ_2 :

$$m l^2 \dot{\theta}_1 \dot{\theta}_2 \cos(\theta_1 - \theta_2)$$

$$\frac{\partial L}{\partial \dot{\theta}_2} = m l^2 \dot{\theta}_2 + m l^2 \dot{\theta}_1 \cos(\theta_1 - \theta_2)$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}_2} \right) = m l^2 \ddot{\theta}_2 + m l^2 \ddot{\theta}_1 \cos(\theta_1 - \theta_2) - m l^2 \dot{\theta}_1 \sin(\theta_1 - \theta_2) (\dot{\theta}_1 - \dot{\theta}_2)$$

$$\frac{\partial L}{\partial \theta_2} = m l^2 \dot{\theta}_1 \dot{\theta}_2 \sin(\theta_1 - \theta_2) - m g l \sin \theta_2$$

$$\therefore m l^2 \ddot{\theta}_2 + m l^2 \ddot{\theta}_1 \cos(\theta_1 - \theta_2) - m l^2 \dot{\theta}_1 \sin(\theta_1 - \theta_2) (\dot{\theta}_1 - \dot{\theta}_2) - m l^2 \dot{\theta}_1 \dot{\theta}_2 \sin(\theta_1 - \theta_2) + m g l \sin \theta_2 = 0$$

$$\therefore m l^2 \ddot{\theta}_2 + m l^2 \ddot{\theta}_1 \cos(\theta_1 - \theta_2) - m l^2 \dot{\theta}_1^2 \sin(\theta_1 - \theta_2) + m l^2 \dot{\theta}_1 \dot{\theta}_2 \sin(\theta_1 - \theta_2) - m l^2 \dot{\theta}_1 \dot{\theta}_2 \sin(\theta_1 - \theta_2) + m g l \sin \theta_2 = 0$$

$$\therefore m l \ddot{\theta}_2 + m l \ddot{\theta}_1 \cos(\theta_1 - \theta_2) - m l \dot{\theta}_1^2 \sin(\theta_1 - \theta_2) + m g \sin \theta_2 = 0$$