

## Literature

There is no exact textbook for the material of the lecture. The introduction is most similar to the draft text "*A Course in Machine Learning*" by Hal Daumé III: [http://ciml.info/dl/v0\\_8/ciml-v0\\_8-all.pdf](http://ciml.info/dl/v0_8/ciml-v0_8-all.pdf)

Afterwards, we'll use material from:

- Shai Shalev-Shwartz, Shai Ben-David, "Understanding Machine Learning", 2014.
- Mehryar Mohri, Afshin Rostamizadeh, Ameet Talwalkar "*Foundations of Machine Learning*", 2012.
- Kevin Murphy, "*Machine Learning: A Probabilistic Perspective*", 2012.

## 1 Decision Trees

These are training and test data from the *dating* example in the lecture.

**TRAINING:**

person	eyes	handsome	height	sex	soccer	date?
Apu	blue	yes	tall	M	no	yes
Bernice	brown	yes	short	F	no	no
Carl	blue	no	tall	M	no	yes
Doris	green	yes	short	F	no	no
Edna	brown	no	short	F	yes	no
Prof. Frink	brown	yes	tall	M	yes	no
Gil	blue	no	tall	M	yes	no
Homer	green	yes	short	M	no	yes
Itchy	brown	no	short	M	yes	yes

**TESTING:**

person	eyes	handsome	height	sex	soccer	date?
Jimbo	blue	no	tall	M	no	yes
Krusty	green	yes	short	M	yes	no
Lisa	blue	yes	tall	F	no	no
Moe	brown	no	short	M	no	no
Ned	brown	yes	short	M	no	yes
Quimby	blue	no	tall	M	no	yes

Use the training data to construct decision trees and test them on the test data in the following situations (in cases of ties between attributes, choose by alphabetic order)

- if there had been no attribute "soccer".
- if there had been no attribute "eye color".
- if "Itchy" had the label **no** instead of **yes**.

- if there had been one more training example:

person	eyes	handsome	height	sex	soccer	date?
Ralph	green	no	short	M	yes	no

Assume there were  $D$  additional attributes with random values **yes** or **no** ( $p(\text{yes}) = p(\text{no}) = 0.5$ )?

- What is the probability that the training stops (zero training error) after a single split for  $D = 10$ , for  $D = 100$ , for  $D = 1353$ ?

## 2 Nearest Neighbor Classification

- Find three examples where humans perform (more or less) nearest-neighbor classification. What about  $k$ -NN?
- What are the advantages and disadvantages of  $k$ -NN with  $k > 1$  versus 1-NN.
- What is the error rate of 1-NN when applying it to the *training set*? Is the same true for  $k$ -NN?
- Assume the following tie breaking rule: if there's no unique majority label for  $K$ -NN, use the  $(K-1)$ -decision. Show: for binary classification,  $2K$ -NN classification is identical to  $2K-1$ -NN classification for any  $K \geq 1$ .
- Give an example of a real-life problem where  $K$ -NN classification would fail but a different classifier from the ones we've seen would succeed.

## 3 Capacity & Overfitting

**Definition 1.** We say that a learning system *memorizes* a training set if it can achieve 0 training error, no matter how the training examples were labeled.

**Definition 2.** The *capacity* of a learning system is the largest number of training point that the learning system can *memorize*, or  $\infty$ , if there is no largest number. (Note: for capacity  $K$  it's enough to find any set of  $K$  points that the learner can memorize. This construct makes the definition robust against generate situations, such as multiple identical points, etc.)

a) For  $\mathcal{X} = \mathbb{R}^2$ , what is the *capacity* of decision trees, 1-NN,  $k$ -NN, the perceptron and Boosting? For decision trees, use binary splits along single coordinate exist with arbitrary threshold  $\llbracket x_i \geq \theta \rrbracket$ . For Boosting, use the same checks with output  $\pm 1$  as weak classifiers.

b) Relate their capacity and the effect of *overfitting* observed during decision tree learning.

A more intuitive (but unfortunately not very good) way to measure the capacity of a learning system would be its *number of free parameters*.

- What's the number of free parameters for a Perceptron in  $\mathbb{R}^2$ ?
- What's the number of free parameters for a decision tree with binary splits and  $L$  leafs?
- Can you find a learning system for  $\mathcal{X} = \mathbb{R}$  and  $\mathcal{Y} = \{-1, +1\}$  that has very few parameters (e.g. just 1) that can still memorize arbitrarily many points?

## 4 Missing Proofs

Complete the proofs that were skipped in the lecture.

- The classifier  $c^*(x) := \operatorname{argmax}_{y \in \mathcal{Y}} p(y|x)$  is identical to the Bayes classifier.

Hint: show that  $\mathcal{R}(c) \geq \mathcal{R}(c^*)$  for an arbitrary classifier,  $c : \mathcal{X} \rightarrow \mathcal{Y}$ .

- For  $\mathcal{Y} = \{-1, +1\}$  the Bayes classifier can be written as

$$c^*(x) = \operatorname{sign} \left[ \log \frac{p(x, +1)}{p(x, -1)} \right], \quad \text{or equivalently} \quad c^*(x) = \operatorname{sign} \left[ \log \frac{p(+1|x)}{p(-1|x)} \right].$$

- For  $\mathcal{Y} = \{-1, +1\}$  and  $\ell(y, \bar{y}) =$ 

$y \setminus \bar{y}$	-1	+1
-1	$a$	$b$
+1	$c$	$d$

the classifier of minimal risk is

$$c_\ell^*(x) = \operatorname{sign} \left[ \log \frac{p(x, +1)}{p(x, -1)} + \log \frac{c-d}{b-a} \right], \quad \text{or equivalently} \quad c_\ell^*(x) = \operatorname{sign} \left[ \log \frac{p(+1|x)}{p(-1|x)} + \log \frac{c-d}{b-a} \right].$$

- Show:  $\theta_z = \frac{1}{n} \sum_{i=1}^n \llbracket z^i = z \rrbracket$  are the maximum likelihood parameters for the multinomial model.

Hint: you will need a Lagrangian multiplier to enforce the constraint  $\sum_z \theta_z = 1$ .

## 5 Practical Experiments I

For the rest of the course and for the final project you will need to create your own implementation of several learning methods, including

- a) *Decision Trees*,      b) *k-Nearest Neighbor* (for  $k \in \{1, 3, 5, 9\}$ ),      c) *Perceptron*  
d) *AdaBoost*,      e) *Naive Bayes*,      f) *Logistic Regression*.

- For a start, pick at least two from a) to d) and implement them in a programming language of your choice.
- Apply them to the following training set:

$$\begin{aligned}x^1 &= (0, 0, 0), & y^1 &= -1, \\x^2 &= (0, 0, 0), & y^2 &= -1, \\x^3 &= (0, 1, 0), & y^3 &= +1, \\x^4 &= (0, 1, 0), & y^4 &= +1, \\x^5 &= (0, 1, 1), & y^5 &= +1, \\x^6 &= (1, 0, 1), & y^6 &= +1, \\x^7 &= (1, 0, 0), & y^7 &= +1, \\x^8 &= (1, 0, 1), & y^8 &= +1, \\x^9 &= (1, 1, 0), & y^9 &= +1.\end{aligned}$$

Plot the curves of complexity-vs-training error, using as complexity measure: a) the number of interior nodes, b)  $k$ , c) the number of passes through the dataset d) the number of boosting iterations

- Test the classifiers on the following examples

$$\begin{aligned}x^{10} &= (1, 1, 1), & y^{10} &= +1, \\x^{11} &= (0, 0, 1), & y^{11} &= -1, \\x^{12} &= (0, 1, 0), & y^{12} &= -1, \\x^{13} &= (0, 1, 1), & y^{13} &= +1\end{aligned}$$

and plot the complexity-vs-test error curves.

- Do the same again, but with  $y^9$  switched from  $+1$  to  $-1$ . How does the trained classifier change? How do the decisions change?

## 6 Practical Experiments II

- Download the *wine* dataset from the homepage.
  - Each row in each file is an example.
  - The first column are the labels, the other 13 columns are features.

Train one of the classifiers you programmed on the *train* part of the data, evaluate it on the *test*, and report the results.