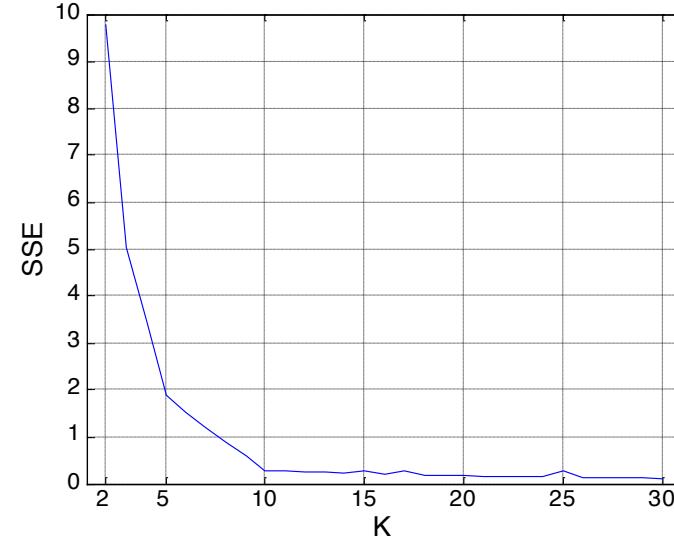
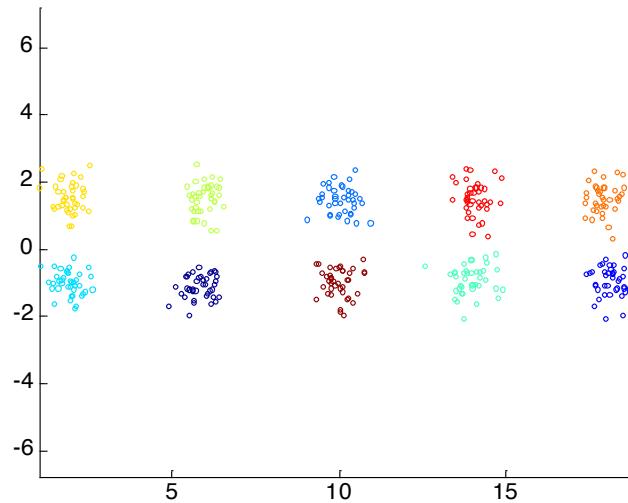


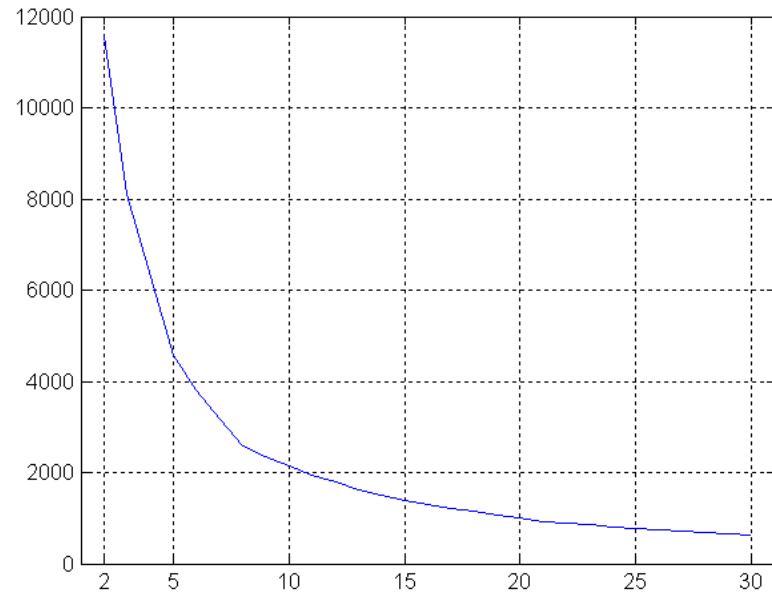
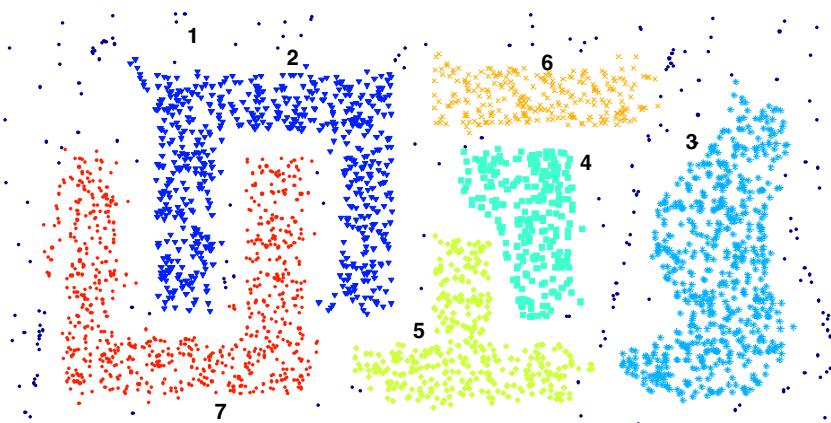
# Internal Measures: SSE

- Clusters in more complicated figures aren't well separated
- Internal Index: Used to measure the goodness of a clustering structure without respect to external information
  - SSE
- SSE is good for comparing two clusterings or two clusters (average SSE).
- Can also be used to estimate the number of clusters



# Internal Measures: SSE

- SSE curve for a more complicated data set



**SSE of clusters found using K-means**

# Framework for Cluster Validity

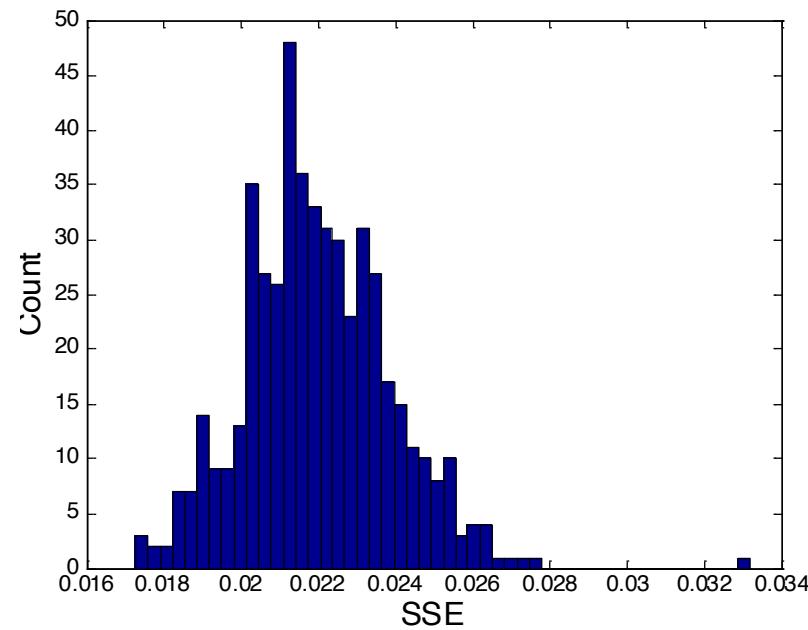
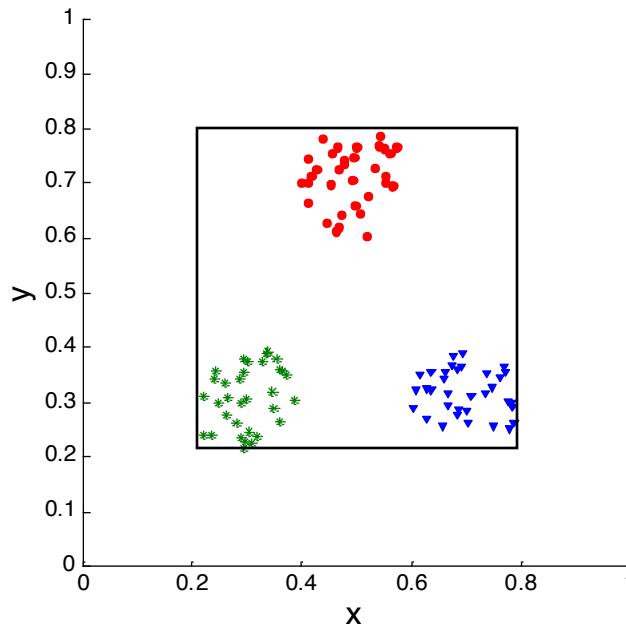
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- Need a framework to interpret any measure.
  - For example, if our measure of evaluation has the value, 10, is that good, fair, or poor?
- Statistics provide a framework for cluster validity
  - The more “atypical” a clustering result is, the more likely it represents valid structure in the data
  - Can compare the values of an index that result from random data or clusterings to those of a clustering result.
    - ◆ If the value of the index is unlikely, then the cluster results are valid
  - These approaches are more complicated and harder to understand.
- For comparing the results of two different sets of cluster analyses, a framework is less necessary.
  - However, there is the question of whether the difference between two index values is significant

# Statistical Framework for SSE

## ● Example

- Compare SSE of 0.005 against three clusters in random data
- Histogram shows SSE of three clusters in 500 sets of random data points of size 100 distributed over the range 0.2 – 0.8 for x and y values



# Internal Measures: Cohesion and Separation

---

- **Cluster Cohesion:** Measures how closely related are objects in a cluster
  - Example: SSE
- **Cluster Separation:** Measure how distinct or well-separated a cluster is from other clusters
- Example: Squared Error
  - Cohesion is measured by the within cluster sum of squares (SSE)  
$$WSS = \sum_i \sum_{x \in C_i} (x - m_i)^2$$
  - Separation is measured by the between cluster sum of squares

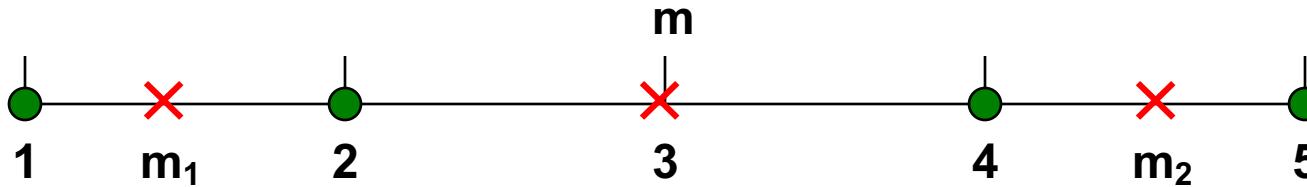
$$BSS = \sum |C_i| (m - m_i)^2$$

– Where  $|C_i|$  is the size of cluster i

# Internal Measures: Cohesion and Separation

- Example: SSE

- $BSS + WSS = \text{constant}$



K=1 cluster:

$$WSS = (1 - 3)^2 + (2 - 3)^2 + (4 - 3)^2 + (5 - 3)^2 = 10$$

$$BSS = 4 \times (3 - 3)^2 = 0$$

$$Total = 10 + 0 = 10$$

K=2 clusters:

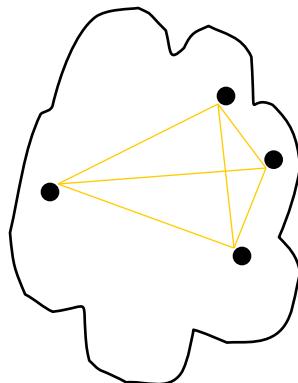
$$WSS = (1 - 1.5)^2 + (2 - 1.5)^2 + (4 - 4.5)^2 + (5 - 4.5)^2 = 1$$

$$BSS = 2 \times (3 - 1.5)^2 + 2 \times (4.5 - 3)^2 = 9$$

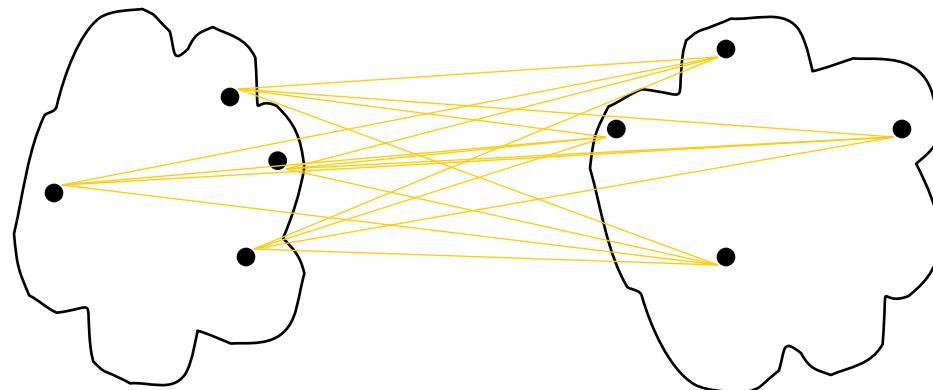
$$Total = 1 + 9 = 10$$

# Internal Measures: Cohesion and Separation

- A proximity graph based approach can also be used for cohesion and separation.
  - Cluster cohesion is the sum of the weight of all links within a cluster.
  - Cluster separation is the sum of the weights between nodes in the cluster and nodes outside the cluster.



cohesion



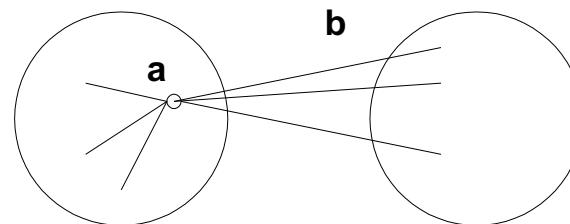
separation

# Internal Measures: Silhouette Coefficient

- Silhouette Coefficient combine ideas of both cohesion and separation, but for individual points, as well as clusters and clusterings
- For an individual point,  $i$ 
  - Calculate  $a$  = average distance of  $i$  to the points in its cluster
  - Calculate  $b$  = min (average distance of  $i$  to points in another cluster)
  - The silhouette coefficient for a point is then given by

$$s = 1 - a/b \quad \text{if } a < b, \quad (\text{or } s = b/a - 1 \quad \text{if } a \geq b, \text{ not the usual case})$$

- Typically between 0 and 1.
- The closer to 1 the better.



- Can calculate the Average Silhouette width for a cluster or a clustering

# External Measures of Cluster Validity: Entropy and Purity

**Table 5.9.** K-means Clustering Results for LA Document Data Set

Cluster	Entertainment	Financial	Foreign	Metro	National	Sports	Entropy	Purity
1	3	5	40	506	96	27	1.2270	0.7474
2	4	7	280	29	39	2	1.1472	0.7756
3	1	1	1	7	4	671	0.1813	0.9796
4	10	162	3	119	73	2	1.7487	0.4390
5	331	22	5	70	13	23	1.3976	0.7134
6	5	358	12	212	48	13	1.5523	0.5525
Total	354	555	341	943	273	738	1.1450	0.7203

**entropy** For each cluster, the class distribution of the data is calculated first, i.e., for cluster  $j$  we compute  $p_{ij}$ , the ‘probability’ that a member of cluster  $j$  belongs to class  $i$  as follows:  $p_{ij} = m_{ij}/m_j$ , where  $m_j$  is the number of values in cluster  $j$  and  $m_{ij}$  is the number of values of class  $i$  in cluster  $j$ . Then using this class distribution, the entropy of each cluster  $j$  is calculated using the standard formula  $e_j = \sum_{i=1}^L p_{ij} \log_2 p_{ij}$ , where the  $L$  is the number of classes. The total entropy for a set of clusters is calculated as the sum of the entropies of each cluster weighted by the size of each cluster, i.e.,  $e = \sum_{i=1}^K \frac{m_i}{m} e_j$ , where  $m_j$  is the size of cluster  $j$ ,  $K$  is the number of clusters, and  $m$  is the total number of data points.

**purity** Using the terminology derived for entropy, the purity of cluster  $j$ , is given by  $purity_j = \max p_{ij}$  and the overall purity of a clustering by  $purity = \sum_{i=1}^K \frac{m_i}{m} purity_j$ .

# Final Comment on Cluster Validity

---

“The validation of clustering structures is the most difficult and frustrating part of cluster analysis.

Without a strong effort in this direction, cluster analysis will remain a black art accessible only to those true believers who have experience and great courage.”

*Algorithms for Clustering Data*, Jain and Dubes



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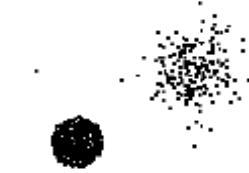
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# **Cluster Analysis: Anomaly/Outlier Detection**

# Anomaly/Outlier Detection

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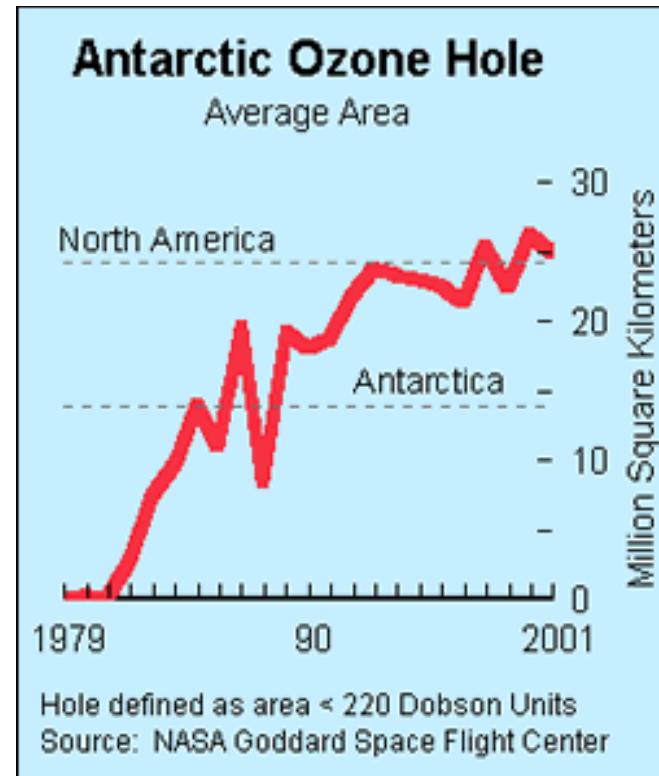
- What are anomalies/outliers?
  - The set of data points that are considerably different than the remainder of the data
- Natural implication is that anomalies are relatively rare
  - One in a thousand occurs often if you have lots of data
  - Context is important, e.g., freezing temps in July
- Can be important or a nuisance
  - 10 foot tall 2 year old
  - Unusually high blood pressure



# Importance of Anomaly Detection

## Ozone Depletion History

- In 1985 three researchers (Farman, Gardinar and Shanklin) were puzzled by data gathered by the British Antarctic Survey showing that ozone levels for Antarctica had dropped 10% below normal levels
- Why did the Nimbus 7 satellite, which had instruments aboard for recording ozone levels, not record similarly low ozone concentrations?
- The ozone concentrations recorded by the satellite were so low they were being treated as outliers by a computer program and discarded!



Sources:

<http://exploringdata.cqu.edu.au/ozone.html>  
<http://www.epa.gov/ozone/science/hole/size.html>

# Causes of Anomalies

---

- Data from different classes
  - Measuring the weights of oranges, but a few grapefruit are mixed in
- Natural variation
  - Unusually tall people
- Data errors
  - 200 pound 2 year old

# Distinction Between Noise and Anomalies

---

- Noise is erroneous, perhaps random, values or contaminating objects
  - Weight recorded incorrectly
  - Grapefruit mixed in with the oranges
- Noise doesn't necessarily produce unusual values or objects
- Noise is not interesting
- Anomalies may be interesting if they are not a result of noise
- Noise and anomalies are related but distinct concepts

# General Issues: Number of Attributes

---

- Many anomalies are defined in terms of a single attribute
  - Height
  - Shape
  - Color
- Can be hard to find an anomaly using all attributes
  - Noisy or irrelevant attributes
  - Object is only anomalous with respect to some attributes
- However, an object may not be anomalous in any one attribute

# General Issues: Anomaly Scoring

---

- Many anomaly detection techniques provide only a binary categorization
  - An object is an anomaly or it isn't
  - This is especially true of classification-based approaches
- Other approaches assign a score to all points
  - This score measures the degree to which an object is an anomaly
  - This allows objects to be ranked
- In the end, you often need a binary decision
  - Should this credit card transaction be flagged?
  - Still useful to have a score
- How many anomalies are there?

# Other Issues for Anomaly Detection

---

- Find all anomalies at once or one at a time
  - Swamping
  - Masking
- Evaluation
  - How do you measure performance?
  - Supervised vs. unsupervised situations
- Efficiency
- Context
  - Professional basketball team

# Variants of Anomaly Detection Problems

---

- Given a data set  $D$ , find all data points  $\mathbf{x} \in D$  with anomaly scores greater than some threshold  $t$
- Given a data set  $D$ , find all data points  $\mathbf{x} \in D$  having the top- $n$  largest anomaly scores
- Given a data set  $D$ , containing mostly normal (but unlabeled) data points, and a test point  $\mathbf{x}$ , compute the anomaly score of  $\mathbf{x}$  with respect to  $D$

# Model-Based Anomaly Detection

---

- Build a model for the data and see
  - Unsupervised
    - ◆ Anomalies are those points that don't fit well
    - ◆ Anomalies are those points that distort the model
    - ◆ Examples:
      - Statistical distribution
      - Clusters
      - Regression
      - Geometric
      - Graph
  - Supervised
    - ◆ Anomalies are regarded as a rare class
    - ◆ Need to have training data

# Additional Anomaly Detection Techniques

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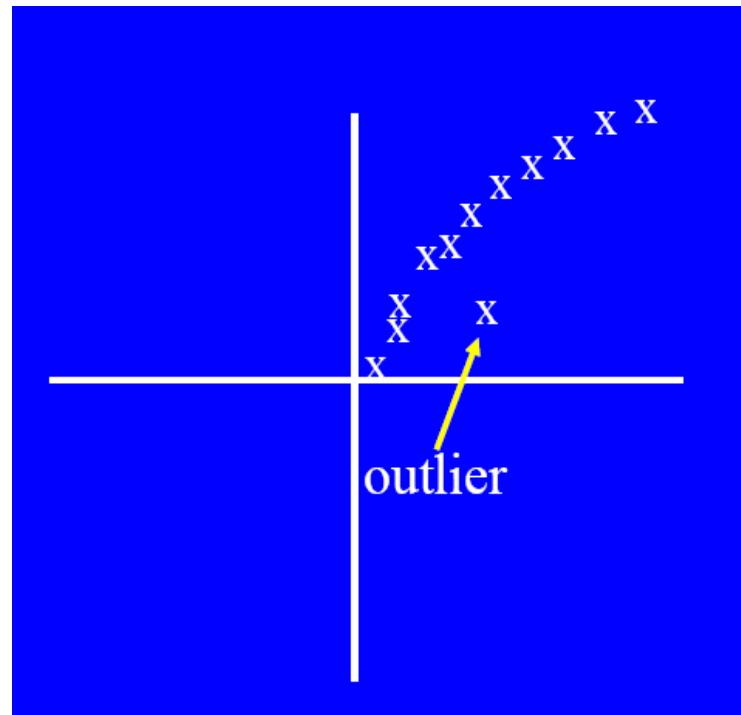
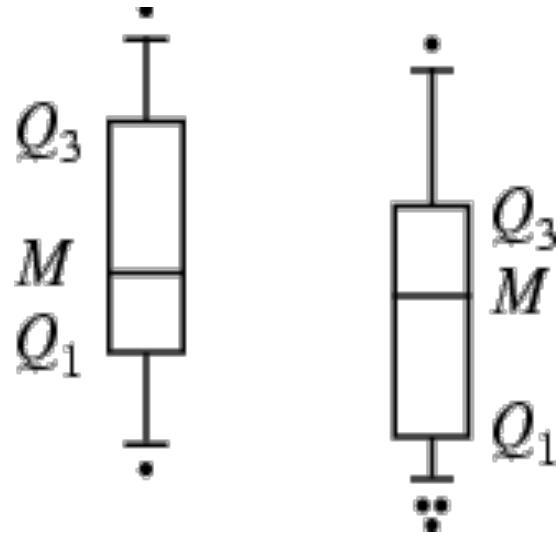
- Proximity-based
  - Anomalies are points far away from other points
  - Can detect this graphically in some cases
- Density-based
  - Low density points are outliers
- Pattern matching
  - Create profiles or templates of atypical but important events or objects
  - Algorithms to detect these patterns are usually simple and efficient

# Visual Approaches

- Boxplots or scatter plots

- Limitations

- Not automatic
  - Subjective



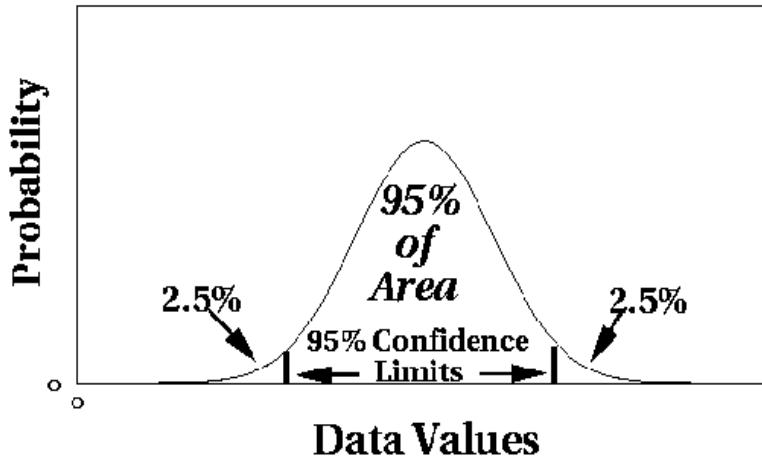
# Statistical Approaches

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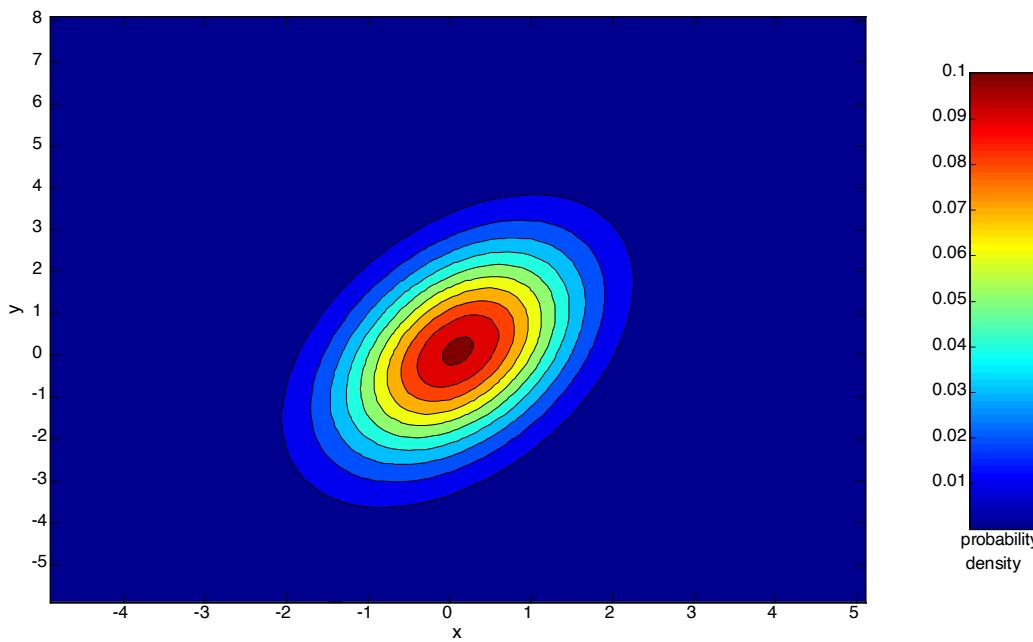
**Probabilistic definition of an outlier:** An outlier is an object that has a low probability with respect to a probability distribution model of the data.

- Usually assume a parametric model describing the distribution of the data (e.g., normal distribution)
- Apply a statistical test that depends on
  - Data distribution
  - Parameters of distribution (e.g., mean, variance)
  - Number of expected outliers (confidence limit)
- Issues
  - Identifying the distribution of a data set
    - ◆ Heavy tailed distribution
  - Number of attributes
  - Is the data a mixture of distributions?

# Normal Distributions



One-dimensional  
Gaussian



Two-dimensional  
Gaussian

# Grubbs' Test

---

- Detect outliers in univariate data
- Assume data comes from normal distribution
- Detects one outlier at a time, remove the outlier, and repeat
  - $H_0$ : There is no outlier in data
  - $H_A$ : There is at least one outlier
- Grubbs' test statistic:
- Reject  $H_0$  if:

$$G > \frac{(N-1)}{\sqrt{N}} \sqrt{\frac{t_{(\alpha/N, N-2)}^2}{N-2 + t_{(\alpha/N, N-2)}^2}}$$

# Statistical-based – Likelihood Approach

---

- Assume the data set D contains samples from a mixture of two probability distributions:
  - M (majority distribution)
  - A (anomalous distribution)
- General Approach:
  - Initially, assume all the data points belong to M
  - Let  $L_t(D)$  be the log likelihood of D at time t
  - For each point  $x_t$  that belongs to M, move it to A
    - ◆ Let  $L_{t+1}(D)$  be the new log likelihood.
    - ◆ Compute the difference,  $\Delta = L_t(D) - L_{t+1}(D)$
    - ◆ If  $\Delta > c$  (some threshold), then  $x_t$  is declared as an anomaly and moved permanently from M to A

# Statistical-based – Likelihood Approach

---

- Data distribution,  $D = (1 - \lambda) M + \lambda A$
- M is a probability distribution estimated from data
  - Can be based on any modeling method (naïve Bayes, maximum entropy, etc)
- A is initially assumed to be uniform distribution
- Likelihood at time t:

$$L_t(D) = \prod_{i=1}^N P_D(x_i) = \left( (1 - \lambda)^{|M_t|} \prod_{x_i \in M_t} P_{M_t}(x_i) \right) \left( \lambda^{|A_t|} \prod_{x_i \in A_t} P_{A_t}(x_i) \right)$$

$$LL_t(D) = |M_t| \log(1 - \lambda) + \sum_{x_i \in M_t} \log P_{M_t}(x_i) + |A_t| \log \lambda + \sum_{x_i \in A_t} \log P_{A_t}(x_i)$$

# Strengths/Weaknesses of Statistical Approaches

---

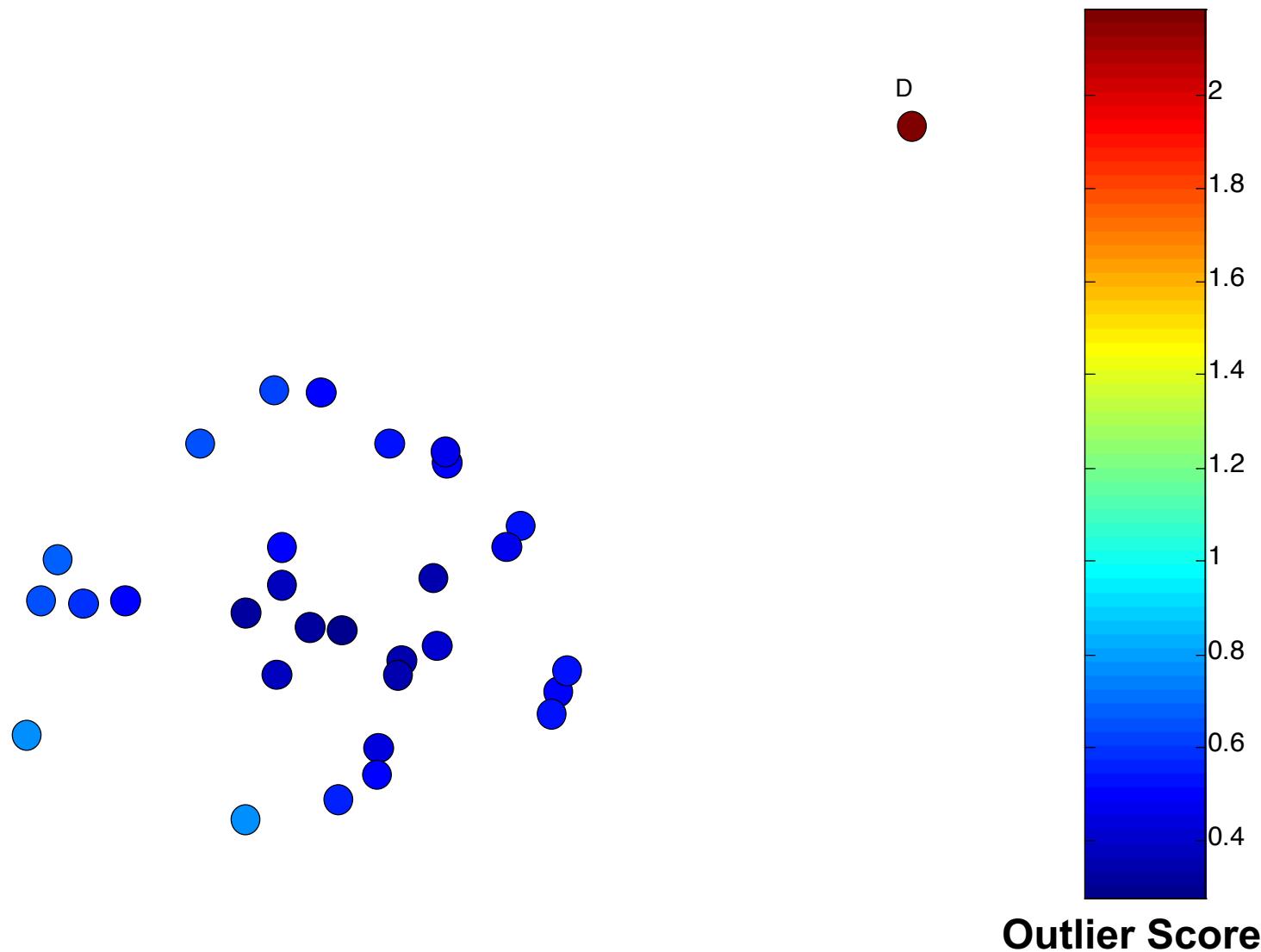
- Firm mathematical foundation
- Can be very efficient
- Good results if distribution is known
- In many cases, data distribution may not be known
- For high dimensional data, it may be difficult to estimate the true distribution
- Anomalies can distort the parameters of the distribution

# Distance-Based Approaches

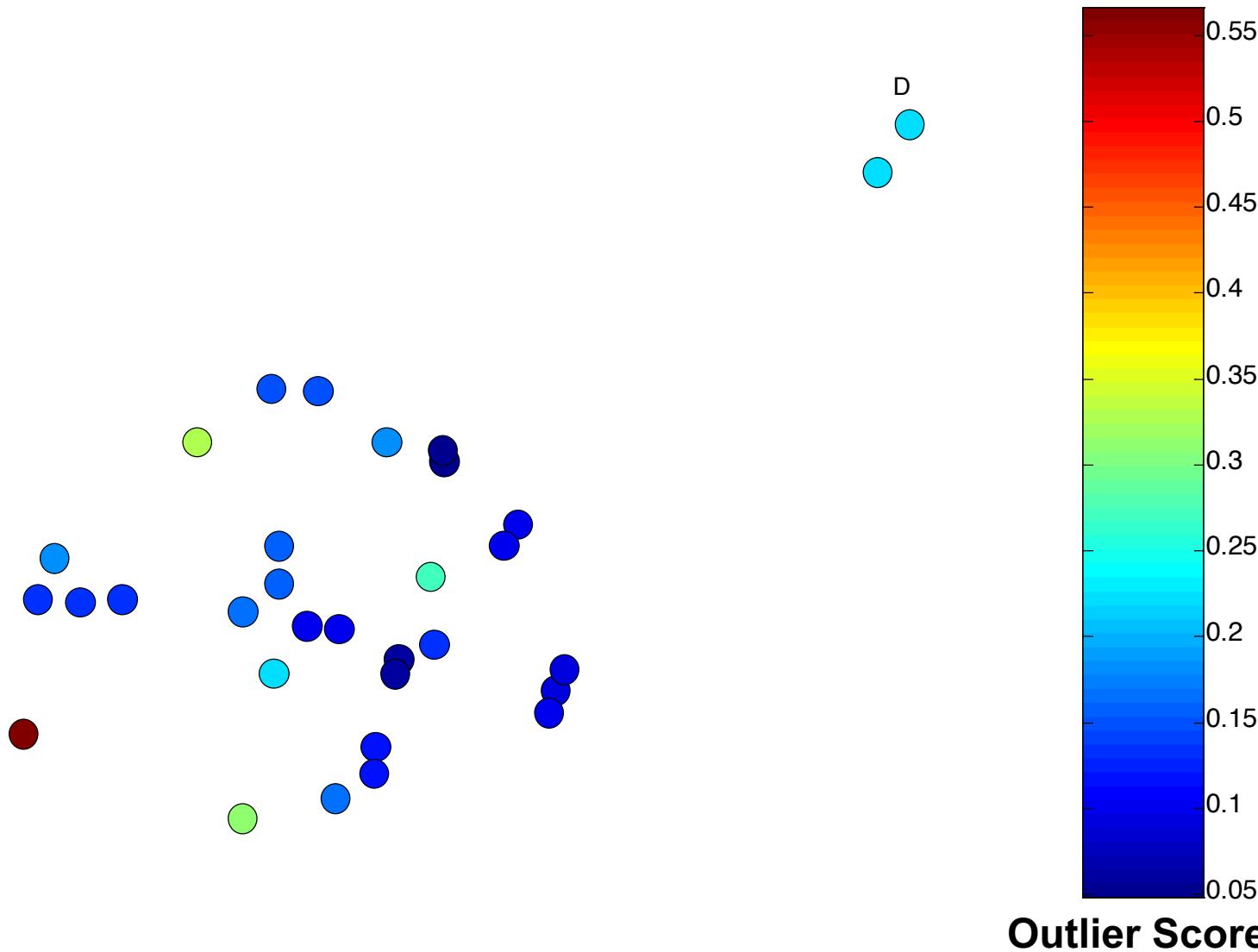
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- Several different techniques
- An object is an outlier if a specified fraction of the objects is more than a specified distance away (Knorr, Ng 1998)
  - Some statistical definitions are special cases of this
- The outlier score of an object is the distance to its kth nearest neighbor

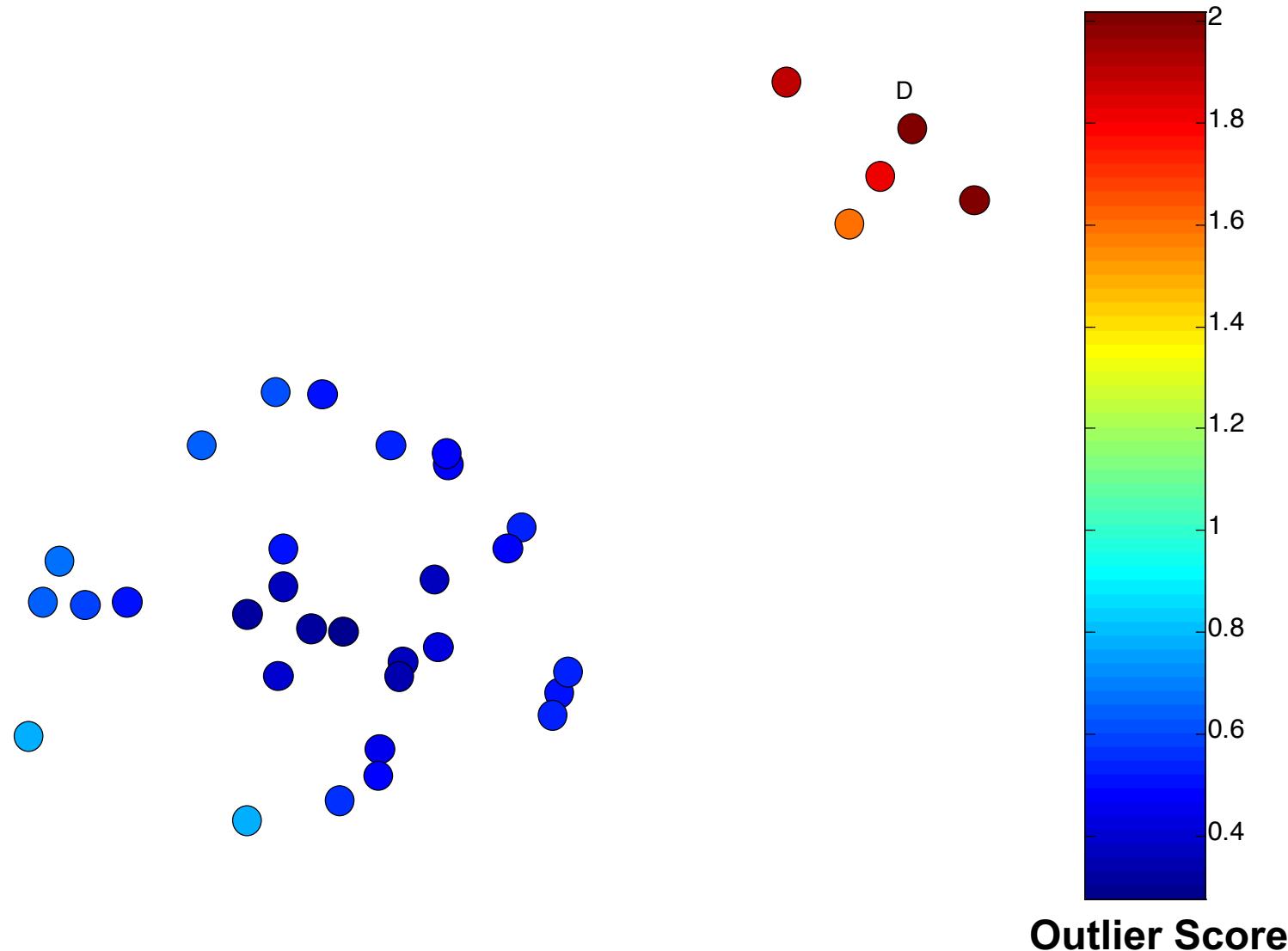
# One Nearest Neighbor - One Outlier



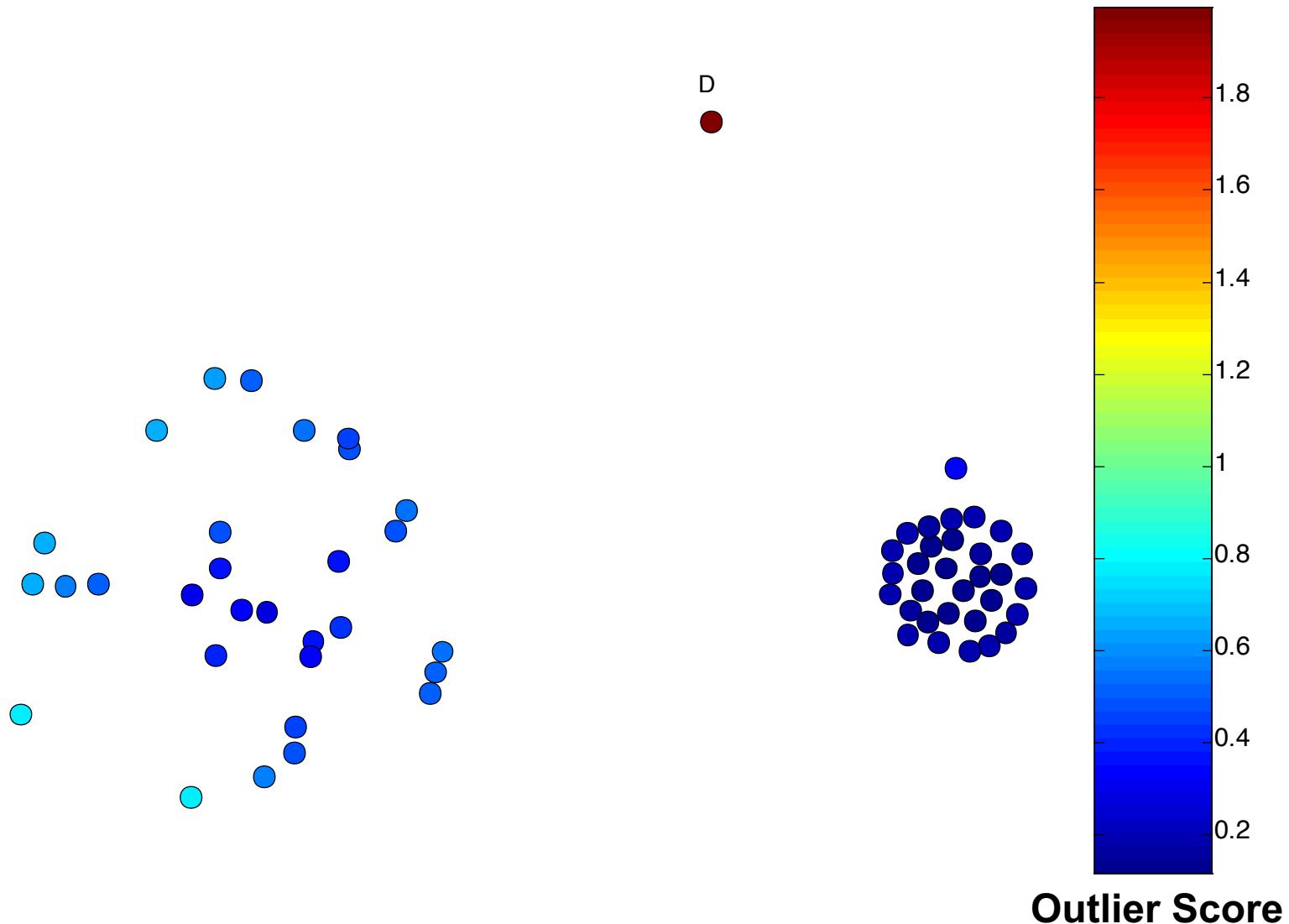
# One Nearest Neighbor - Two Outliers



# Five Nearest Neighbors - Small Cluster



# Five Nearest Neighbors - Differing Density



# Strengths/Weaknesses of Distance-Based Approaches

---

- Simple
- Expensive –  $O(n^2)$
- Sensitive to parameters
- Sensitive to variations in density
- Distance becomes less meaningful in high-dimensional space

# Density-Based Approaches

---

- **Density-based Outlier:** The outlier score of an object is the inverse of the density around the object.
  - Can be defined in terms of the  $k$  nearest neighbors
  - One definition: Inverse of distance to  $k^{\text{th}}$  neighbor
  - Another definition: Inverse of the average distance to  $k$  neighbors
  - DBSCAN definition
- If there are regions of different density, this approach can have problems

# Relative Density

---

- Consider the density of a point relative to that of its  $k$  nearest neighbors

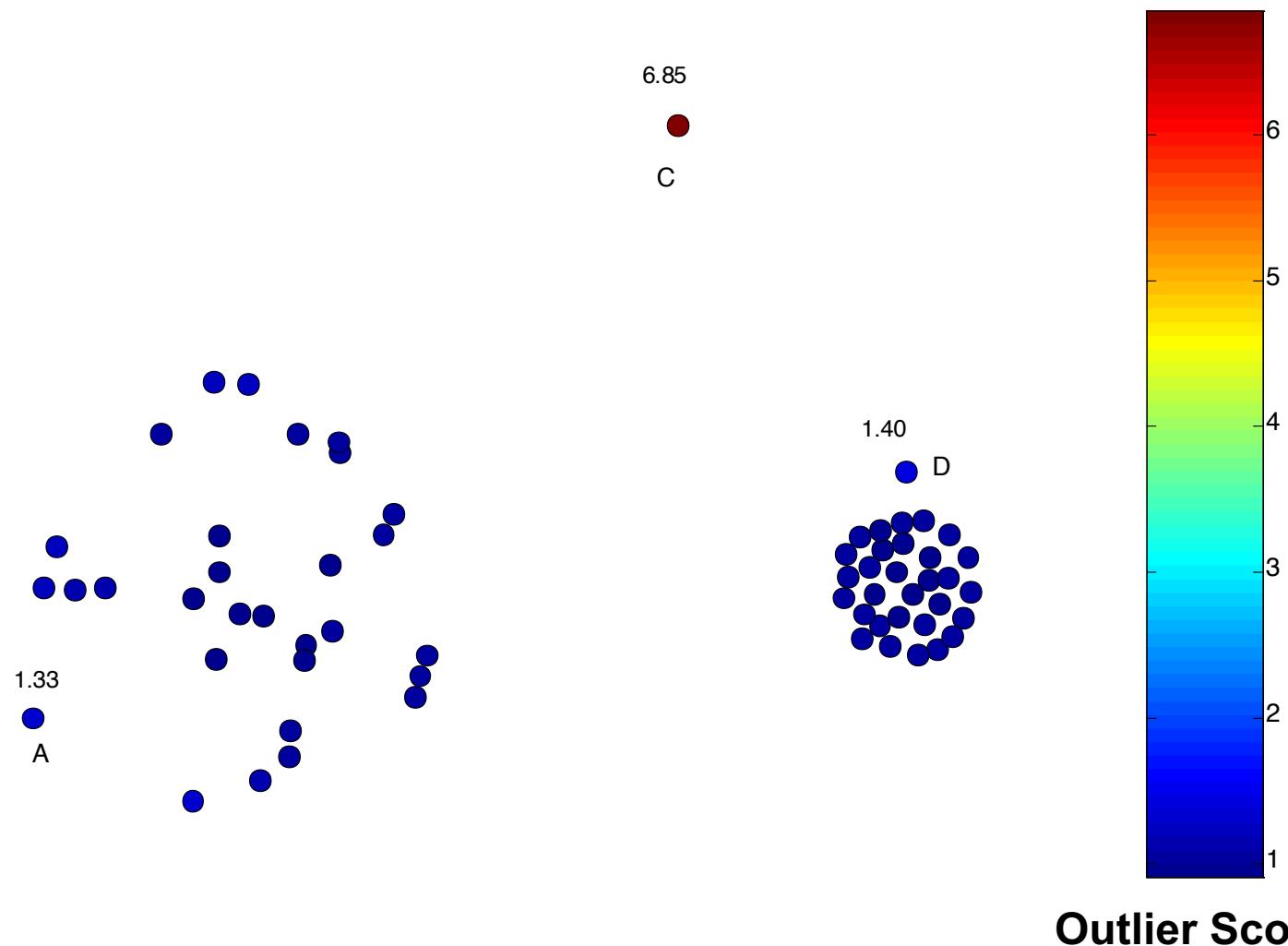
$$\text{average relative density}(\mathbf{x}, k) = \frac{\text{density}(\mathbf{x}, k)}{\sum_{\mathbf{y} \in N(\mathbf{x}, k)} \text{density}(\mathbf{y}, k) / |N(\mathbf{x}, k)|}. \quad (10.7)$$

---

**Algorithm 10.2** Relative density outlier score algorithm.

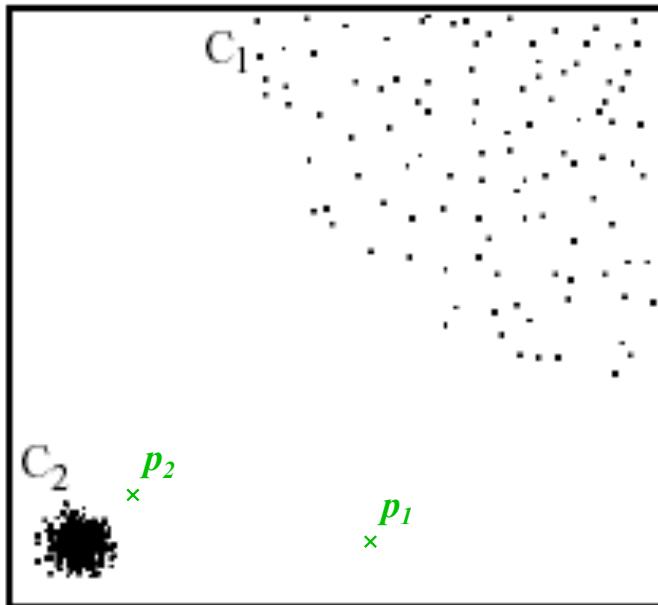
- 1:  $\{k\}$  is the number of nearest neighbors}
  - 2: **for all** objects  $\mathbf{x}$  **do**
  - 3:   Determine  $N(\mathbf{x}, k)$ , the  $k$ -nearest neighbors of  $\mathbf{x}$ .
  - 4:   Determine  $\text{density}(\mathbf{x}, k)$ , the density of  $\mathbf{x}$ , using its nearest neighbors, i.e., the objects in  $N(\mathbf{x}, k)$ .
  - 5: **end for**
  - 6: **for all** objects  $\mathbf{x}$  **do**
  - 7:   Set the  $\text{outlier score}(\mathbf{x}, k) = \text{average relative density}(\mathbf{x}, k)$  from Equation 10.7.
  - 8: **end for**
-

# Relative Density Outlier Scores



# Density-based: LOF approach

- For each point, compute the density of its local neighborhood
- Compute local outlier factor (LOF) of a sample  $p$  as the average of the ratios of the density of sample  $p$  and the density of its nearest neighbors
- Outliers are points with largest LOF value



In the NN approach,  $p_2$  is not considered as outlier, while LOF approach find both  $p_1$  and  $p_2$  as outliers

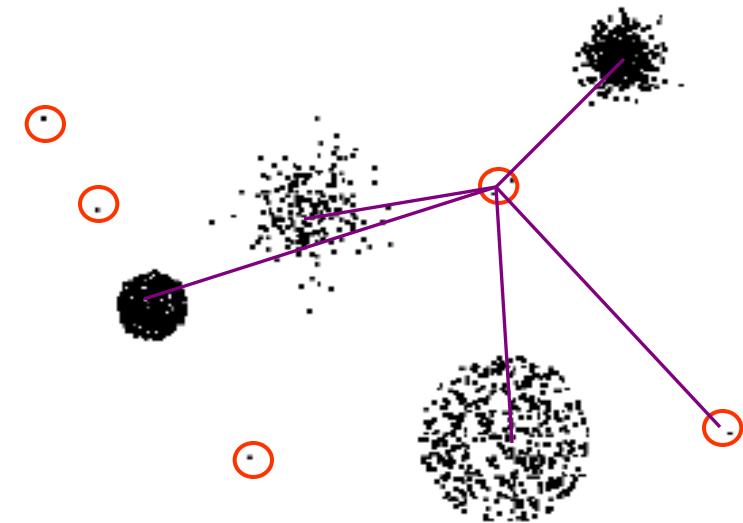
# Strengths/Weaknesses of Density-Based Approaches

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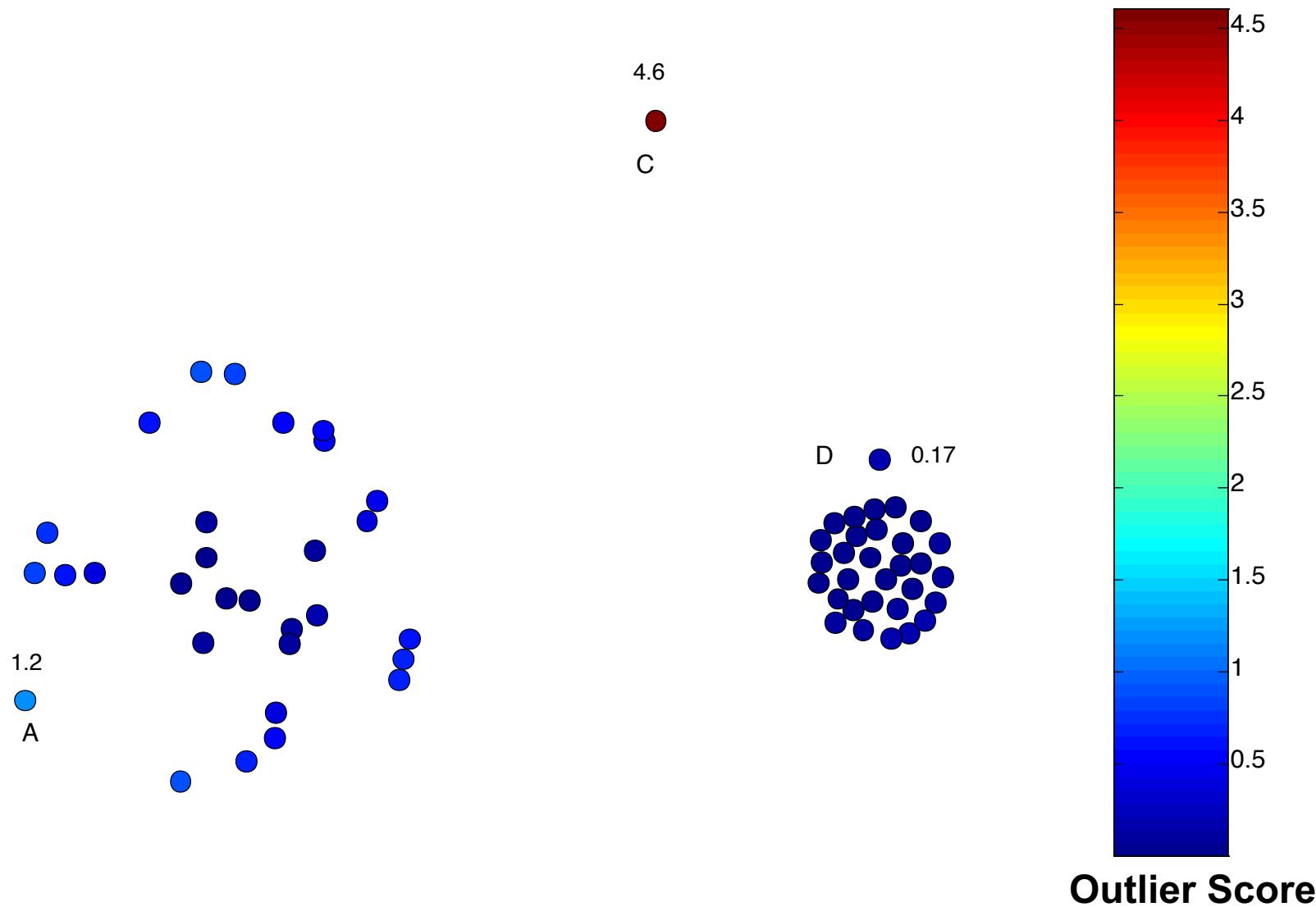
- Simple
- Expensive –  $O(n^2)$
- Sensitive to parameters
- Density becomes less meaningful in high-dimensional space

# Clustering-Based Approaches

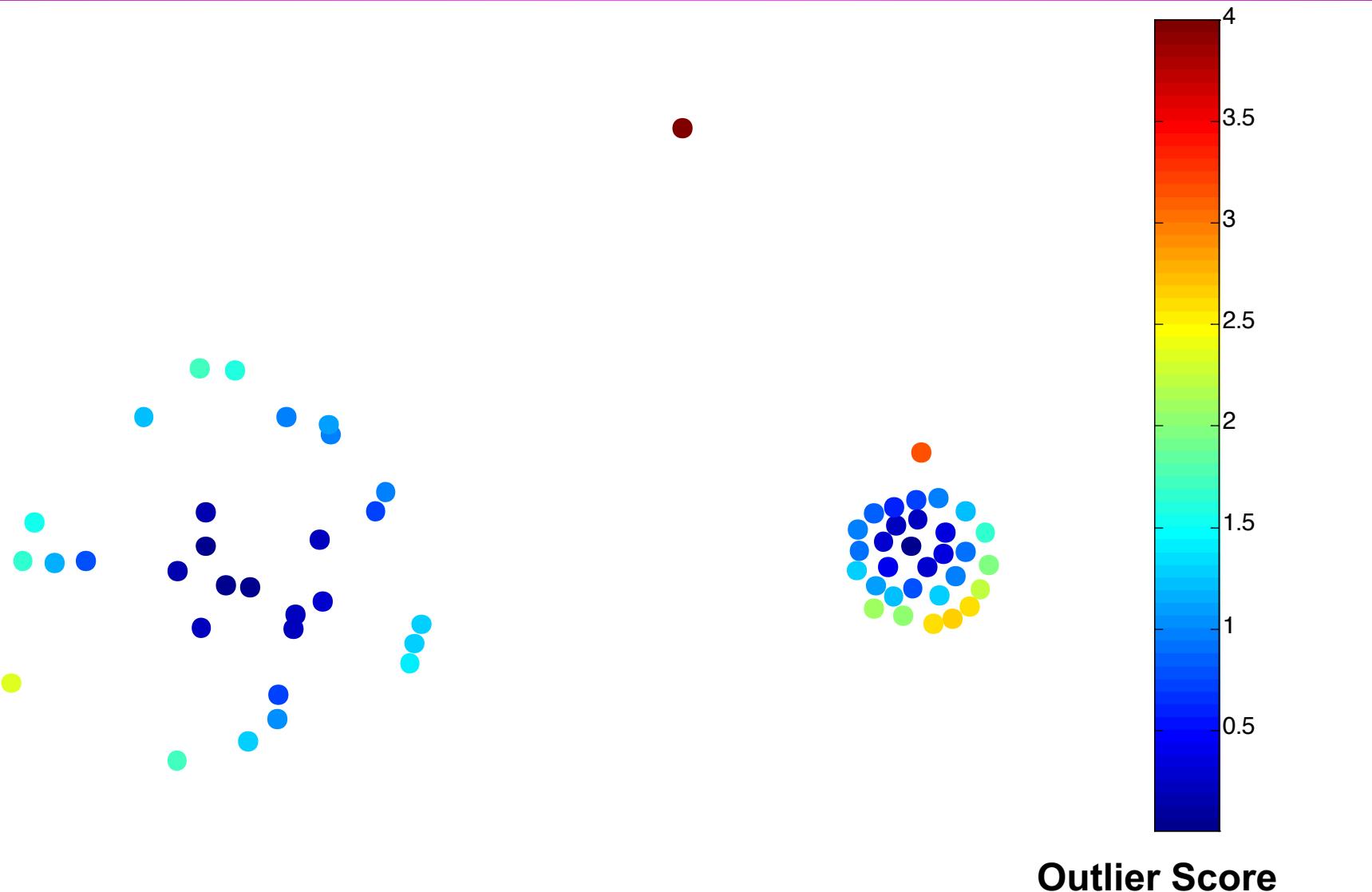
- **Clustering-based Outlier:** An object is a cluster-based outlier if it does not strongly belong to any cluster
  - For prototype-based clusters, an object is an outlier if it is not close enough to a cluster center
  - For density-based clusters, an object is an outlier if its density is too low
  - For graph-based clusters, an object is an outlier if it is not well connected
- Other issues include the impact of outliers on the clusters and the number of clusters



# Distance of Points from Closest Centroids



# Relative Distance of Points from Closest Centroid



# Strengths/Weaknesses of Distance-Based Approaches

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- Simple
- Many clustering techniques can be used
- Can be difficult to decide on a clustering technique
- Can be difficult to decide on number of clusters
- Outliers can distort the clusters