

Brushless DC-Servomotors

66 mNm

2 Pole Technology

126 W

Values at 22°C and nominal voltage 356				012 B	024 B	036 B	048 B	
	Nominal voltage	U _N		12	24	36	48	V
	Terminal resistance, phase-phase	R		0,56	1,1	2,61	4,1	Ω
3	Efficiency, max.	$\eta_{\scriptscriptstyle max.}$		82	83	83	83	%
	No-load speed	no		8 300	11 500	11 600	12 800	min ⁻¹
5	No-load current, typ. (with shaft ø 4 mm)	l o		0,198	0,166	0,112	0,099	Α
6	Stall torque	Мн		293	432	408	418	mNm
7	Friction torque, static	Co		1,2	1,2	1,2	1,2	mNm
8	Friction torque, dynamic	Cv		1,8.10-4	1,8-10-4	1,8-10-4	1,8.10-4	mNm/min
9	Speed constant	k n		696	481	323	266	min ⁻¹ /V
10	Back-EMF constant	Kε		1,44	2,08	3,1	3,75	mV/min ⁻¹
11	Torque constant	k м		13,7	19,9	29,6	35,8	mNm/A
12	Current constant	k ı		0,073	0,05	0,034	0,028	A/mNm
13	Slope of n-M curve	$\Delta n I \Delta M$		28	27	28	31	min-1/mNn
14	Terminal inductance, phase-phase	L		90	190	410	640	μH
15	Mechanical time constant	τ_m		10,4	9,7	10,4	11,1	ms .
16	Rotor inertia	J		34,9	34,9	34,9	34,9	gcm ²
17	Angular acceleration	Clmax.		84	124	117	120	·10³rad/s²
	3							
18	Thermal resistance	Rth1 / Rth2	1,6 / 6,2					K/W
19	Thermal time constant	$ au_{w1}$ / $ au_{w2}$	15,4 / 820			s		
20	Operating temperature range:							
	– motor		-30 +125					°C
	 winding, max. permissible 	+125				°C		
21	Shaft bearings	ball bearings, preloaded						
22	Shaft load max.:	J .						
	- with shaft diameter	4					mm	
	- radial at 3 000 min ⁻¹ (5 mm from mounting flange)		112				N	
	- axial at 3 000 min ⁻¹ (push only)		50				N	
	 axial at standstill (push only) 		131					N
23	Shaft play:							
	– radial	≤	0,015					mm
	– axial	=	0					mm
24	Housing material		aluminium, black anodized					
	Mass	311	11				g	
26	Direction of rotation	electronically reversible						
27	Speed up to	n _{max.} 29 000			min ⁻¹			
28	Number of pole pairs		1					
29	Hall sensors		digital					
30	Magnet material		SmCo					
	<u> </u>							
Rat	ed values for continuous operation		·					·
	Rated torque	MΝ		56,2	55,3	53,5	50,4	mNm
	Rated current (thermal limit)	IN		4,43	3,04	1,98	1,55	Α
	Rated speed	nn		6 160	9 620	9 640	10 800	min ⁻¹

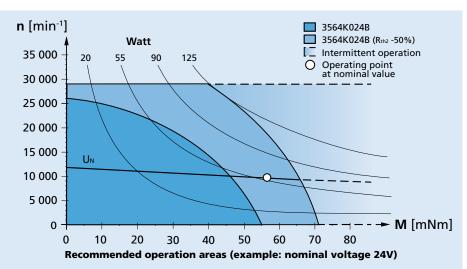
Note: Rated values are calculated with nominal voltage and at a 22°C ambient temperature. The Rth2 value has been reduced by 25%.

Note:

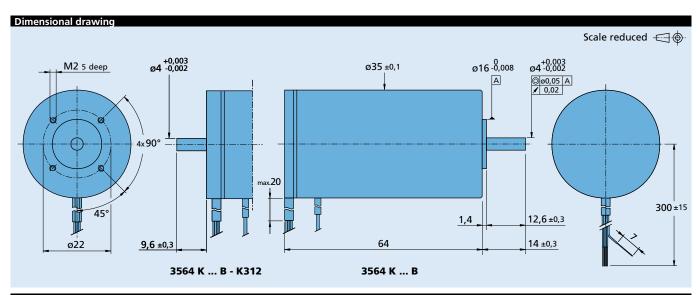
The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

The diagram shows the motor in a completely insulated as well as thermally coupled condition (Rth2 50% reduced).

The nominal voltage (U_N) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.







Option, cable and connection information								
Example product designation: 3564K012B-K1155								
Option	Туре	Description	Connection					
K1155	Controller combination	Analog Hall sensors for combination with Motion Controller MCBL	Function	Colour				
K1026	Sensorless	Motor without Hall sensors	Phase C	yellow				
K1838	Encoder combination	Motor with rear end shaft for combination with Encoder IE3	Phase B	orange				
K312	Encoder combination	Motor with rear end shaft for combination with Encoder HEDS/HEDL/HEDM	Phase A	brown				
K179	Bearing lubrication	For vacuum of 10 ^{-s} Pa @ 22°C	GND	black				
			U _{DD} (+5V)	red				
			Hall sensor C	grey				
			Hall sensor B	blue				
			Hall sensor A	green				
			Standard cabl	a				
			Single wires, mate	erial PTFE				
			AWG 20: Phase A/					
			AWG 26: Hall A/B/	C, Udd, GND				

Product combination							
Precision Gearheads / Lead Screws	Encoders	Drive Electronics	Cables / Accessories				
30/1 30/1 S 32/3 32/3 S 38A 38/1 38/1 S 38/2 38/2 S	HEDS 5500 IE3-1024 IE3-1024 L HEDL 5540	SC 2804 SC 5004 SC 5008 MC 5005 MC 5010 MCBL 3003 MCBL 3006	MBZ To view our large range of accessory parts, please refer to the "Accessories" chapter.				