ECE 201 Spring 2022 - Homework 2

Assigned by Prof. Wujie Wen

Due Apr. 14th, 2022 23:59pm

Please type/write your answers on a single document and submit through coursesite

1. (10 pts) Control Signal Question: Explain each of the "don't cares" of control signals in Figure 4.18.

2. (30 pts) Hazard Questions 4.27 on textbook, note there are six sub questions.

4.27 Problems in this exercise refer to the following sequence of instructions, and assume that it is executed on a five-stage pipelined datapath:

```
ADD   X5, X2, X1
LDUR  X3, [X5, #4]
LDUR  X2, [X2, #0]
ORR   X3, X5, X3
STUR  X3, [X5, #0]
```

4.27.1 [5] <§4.7> If there is no forwarding or hazard detection, insert NOPs to ensure correct execution.

4.27.2 [10] <§4.7> Now, change and/or rearrange the code to minimize the number of NOPs needed. You can assume register X7 can be used to hold temporary values in your modified code.

4.27.3 [10] <§4.7> If the processor has forwarding, but we forgot to implement the hazard detection unit, what happens when the original code executes?

4.27.4 [20] <§4.7> If there is forwarding, for the first seven cycles during the execution of this code, specify which signals are asserted in each cycle by hazard detection and forwarding units in Figure 4.59.

4.27.5 [10] <§4.7> If there is no forwarding, what new input and output signals do we need for the hazard detection unit in Figure 4.59? Using this instruction sequence as an example, explain why each signal is needed.

4.27.6 [20] <§4.7> For the new hazard detection unit from 4.26.5, specify which output signals it asserts in each of the first five cycles during the execution of this code.

3. (30 pts) Branch Prediction (Question 4.28 on textbook)

4.28 The importance of having a good branch predictor depends on how often conditional branches are executed. Together with branch predictor accuracy, this will determine how much time is spent stalling due to mispredicted branches. In this exercise, assume that the breakdown of dynamic instructions into various instruction categories is as follows:

R-Type	CBZ/CBNZ	B	LDUR	STUR
40%	25%	5%	25%	5%

Also, assume the following branch predictor accuracies:

Always-Taken	Always-Not-Taken	2-Bit
45%	55%	85%

4.28.1 [10] <§4.8> Stall cycles due to mispredicted branches increase the CPI. What is the extra CPI due to mispredicted branches with the always-taken predictor? Assume that branch outcomes are determined in the ID stage and applied in the EX stage that there are no data hazards, and that no delay slots are used.

4.28.2 [10] <§4.8> Repeat 4.28.1 for the "always-not-taken" predictor.

4.28.3 [10] <§4.8> Repeat 4.28.1 for the 2-bit predictor.

4.28.4 [10] <§4.8> With the 2-bit predictor, what speedup would be achieved if we could convert half of the branch instructions to some ALU instruction? Assume that correctly and incorrectly predicted instructions have the same chance of being replaced.

4.28.5 [10] <§4.8> With the 2-bit predictor, what speedup would be achieved if we could convert half of the branch instructions in a way that replaced each branch instruction with two ALU instructions? Assume that correctly and incorrectly predicted instructions have the same chance of being replaced.

4.28.6 [10] <§4.8> Some branch instructions are much more predictable than others. If we know that 80% of all executed branch instructions are easy-to-predict loop-back branches that are always predicted correctly, what is the accuracy of the 2-bit predictor on the remaining 20% of the branch instructions?