



# Investigating the Relationship Between Plasticity and Evolvability in a Genetic Regulatory Network Model

Math/CS Day

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## Background

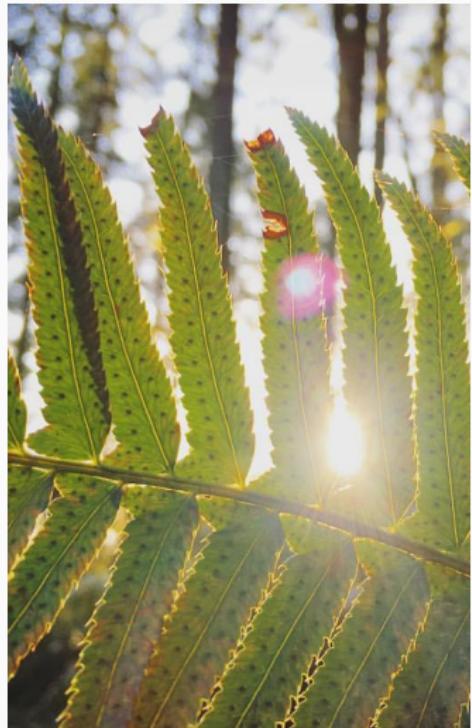
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## Evolutionary Algorithm: Example

**Figure 1:** Evolution in Action [Cheney et al., 2013]

# Evolutionary Algorithm: Problem Statement

What makes an evolutionary algorithm work?

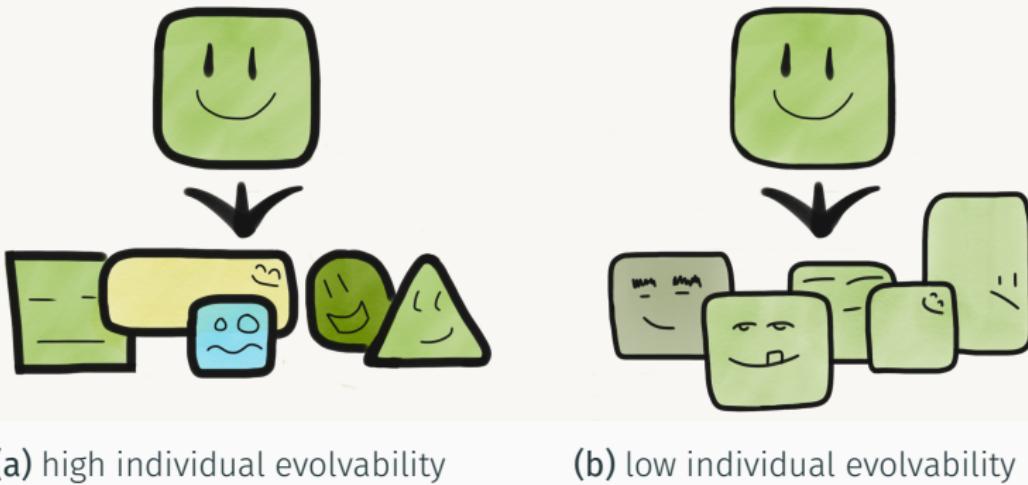


# Defining Evolvability

consensus: the amount of **viable variation** generated by the evolutionary process

- evolvability as the amount of **novel variation** generated
- evolvability the proportion of variation that is **viable**

# Evolvability as Novel Variation

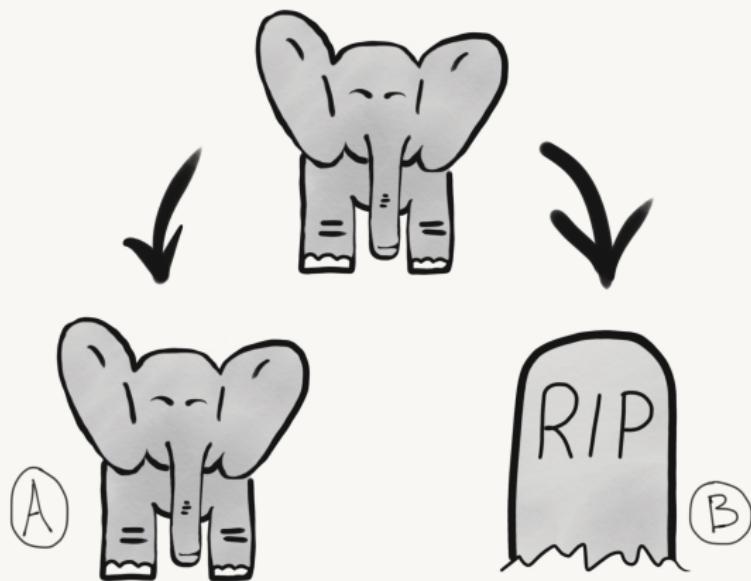


(a) high individual evolvability

(b) low individual evolvability

**Figure 2:** An illustration of individual evolvability, considering evolvability as heritable variation [Wilder and Stanley, 2015].

# Evolvability as Bias towards Viable Variation



**Figure 3:** Illustration of robustness; high evolvability left and low evolvability right [Downing, 2015].

## Objectives

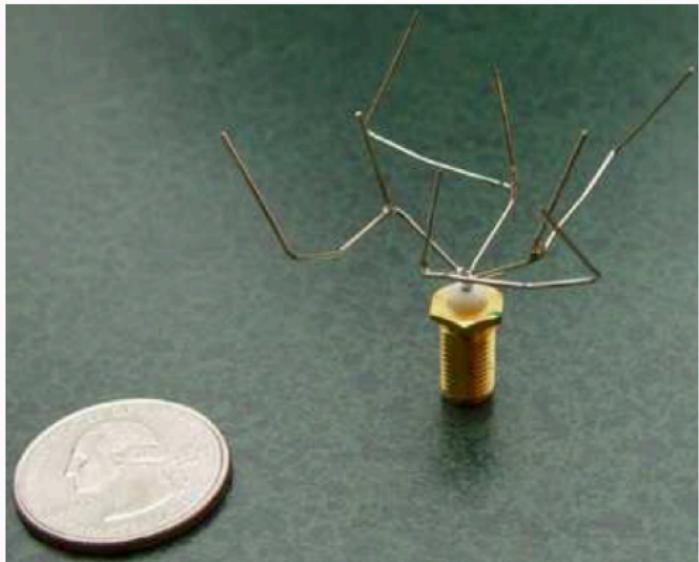
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# Environmental Influence on the Phenotype

- in biology, genotype not sole determinant of phenotype
- $P = G + E$
- plasticity: phenotypic response to the environment
- how does environmental influence on the phenotype affect evolvability?



# Motivation: Practical and Scientific



**Figure 4:** A spacecraft antenna design generated using evolutionary methods [Hornby et al., 2006, Figure 2(a)].

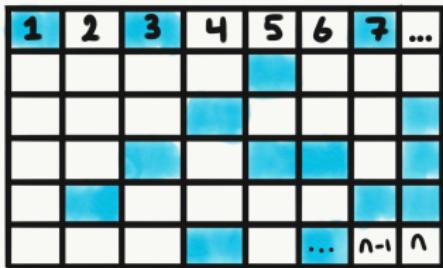


**Figure 5:** A biological frond design generated via evolution.

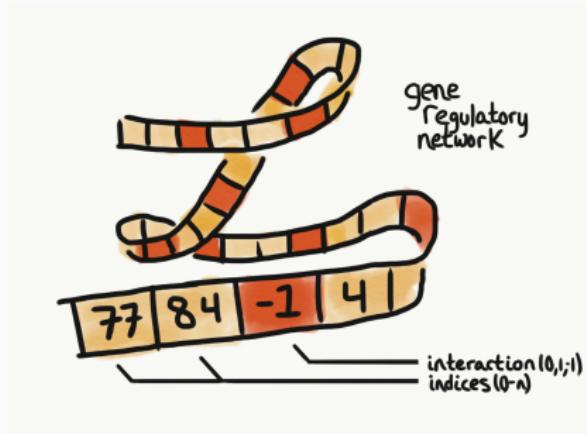
# Genetic Regulatory Network Model

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# Model Framework

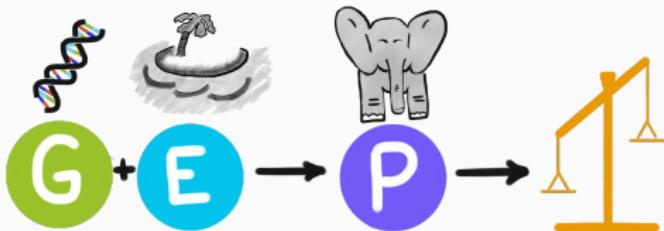


**Figure 6:** Chemical concentrations are represented as a list of boolean values.

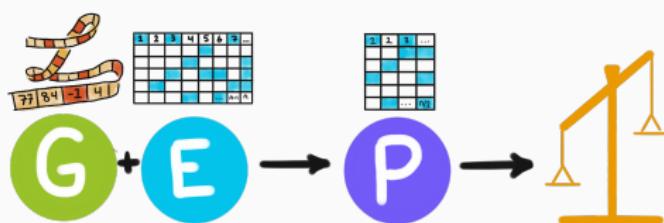


**Figure 7:** The GRN genotype is a set of if-then rules that acts on a set of chemical concentrations. The model employed was inspired by [Wilder and Stanley, 2015].

# Model Framework



(a) biological inspiration



(b) genetic regulatory network model

**Figure 8:** A comparison of the genetic regulatory network model and its biological inspiration.

# Model Implementation

- model implemented through DEAP  
(Distributed Evolutionary Algorithms  
in Python) framework  
[Fortin et al., 2012]
- experiments performed and  
analyzed on remote clusters using  
Jupyter notebook



## Experiment: Direct Plasticity

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## Direct Plasticity: Biological Intuition

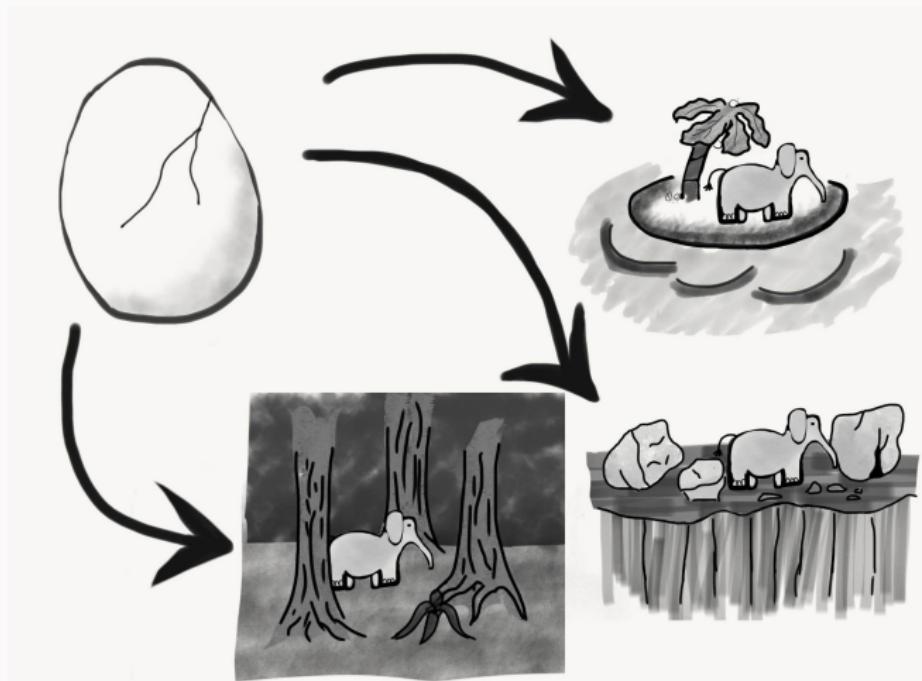
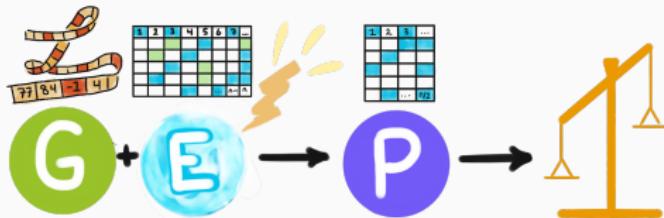
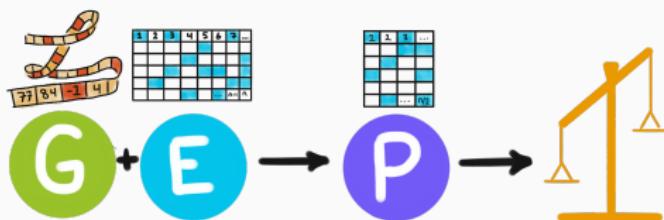


Figure 9: A cartoon illustration of resistance to environmental perturbation.

# Direct Plasticity: Initial State Perturbation



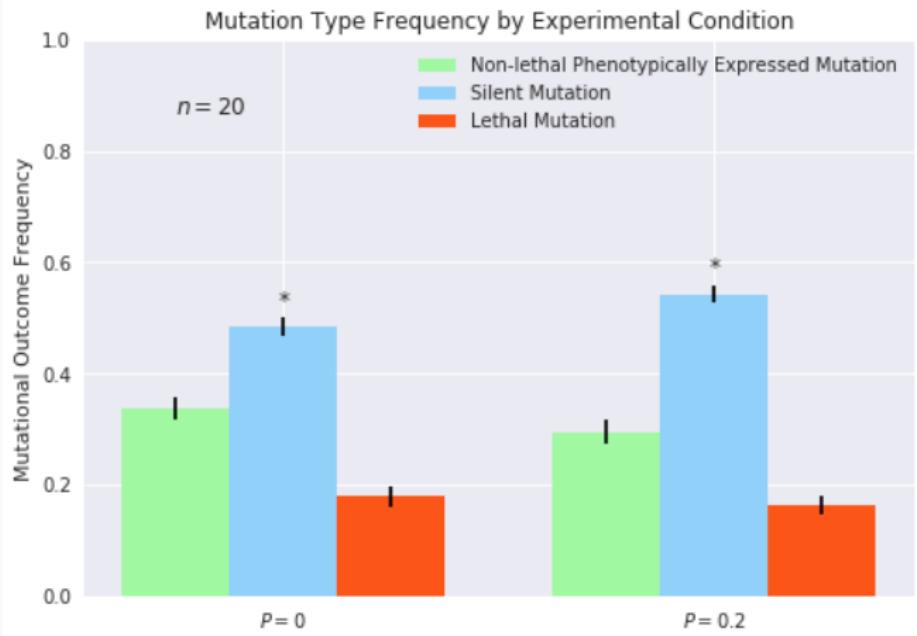
(a) experimental scheme



(b) control scheme

**Figure 10:** A comparison of the control and experimental schemes employed to investigate the relationship between direct plasticity and evolvability.

# Mutational Outcome Frequencies

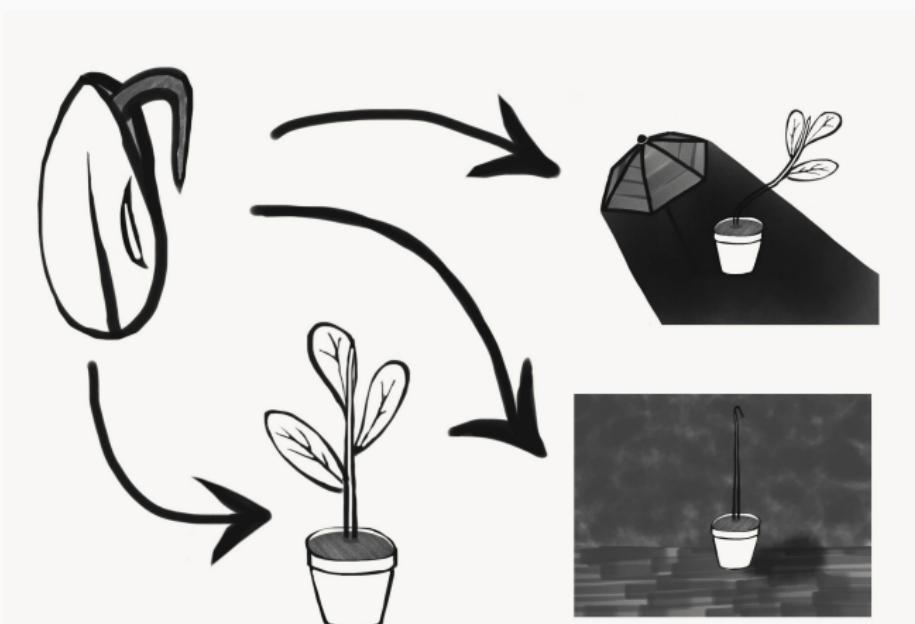


**Figure 11:** Comparison of mutational outcome frequencies for champions evolved with and without initial state perturbation.

## Experiment: Indirect Plasticity

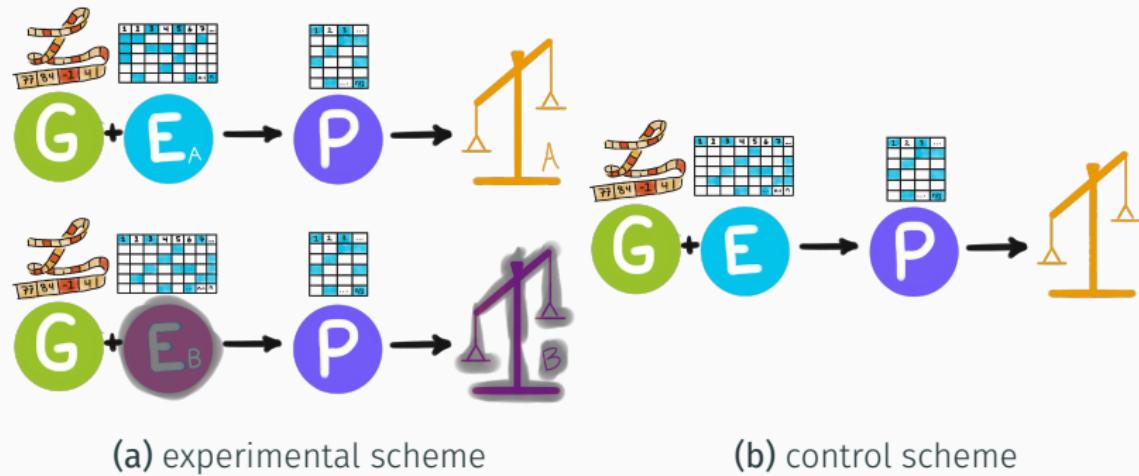
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# Indirect Plasticity: Biological Intuition



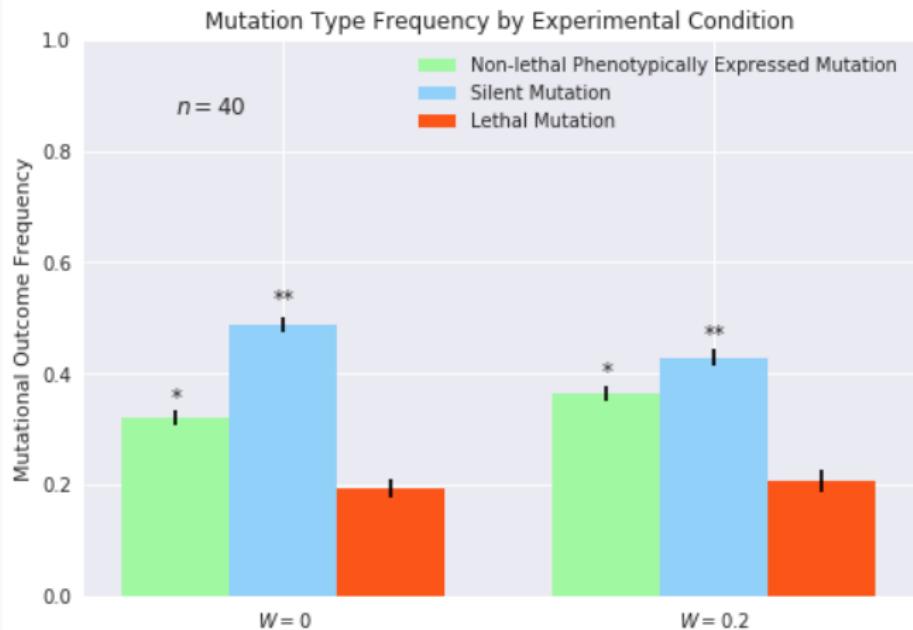
**Figure 12:** A cartoon illustration of alternate phenotypes expressed based on environmental signals.

# Indirect Plasticity: Conditional Initial State



**Figure 13:** A comparison of the control and experimental schemes employed to investigate the relationship between indirect plasticity and evolvability.

# Mutational Outcome Frequencies

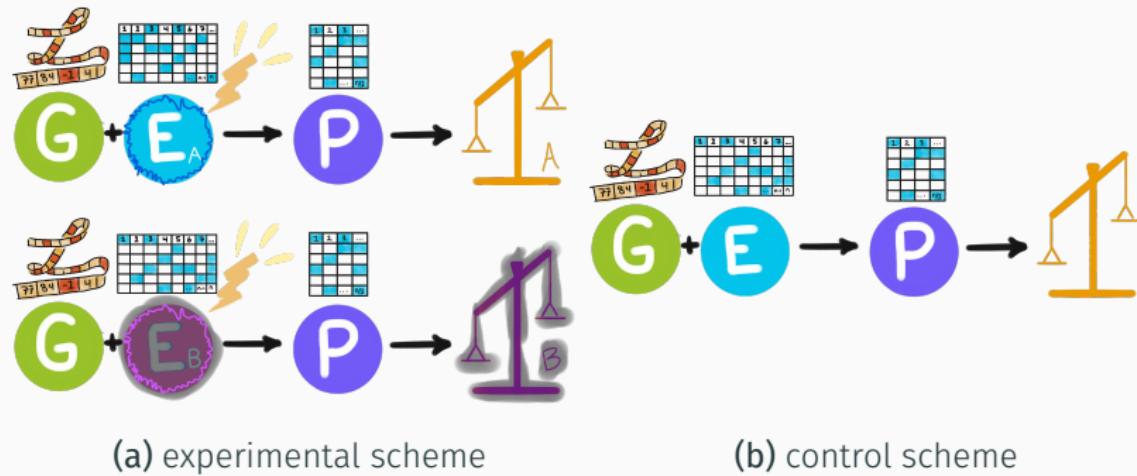


**Figure 14:** Comparison of mutational outcome frequencies for champions evolved with only primary condition/objective pair versus with both primary and secondary condition/objective pairs.

## Experiment: Combined Plasticity

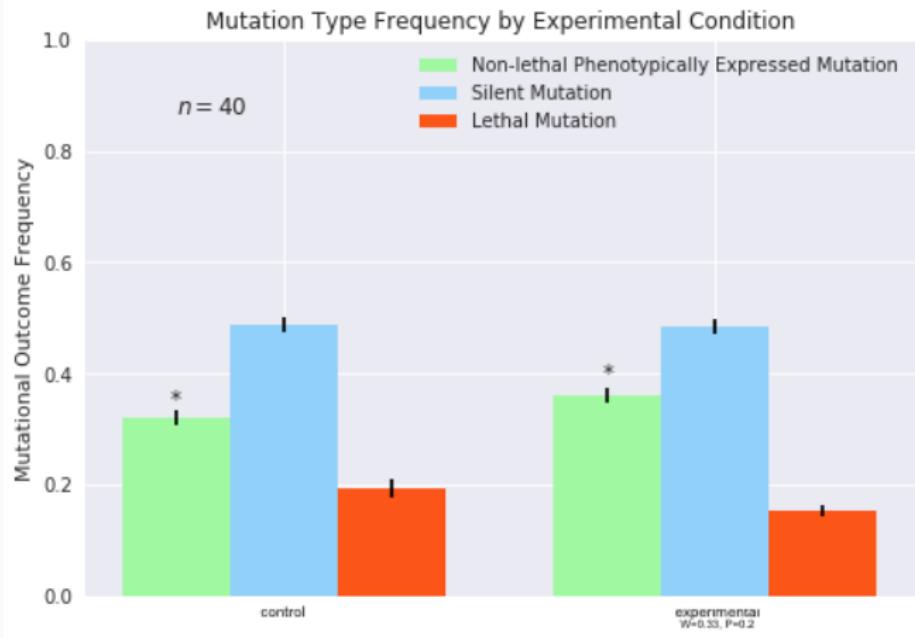
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# Combined Plasticity: Conditional Initial State with Perturbation



**Figure 15:** A comparison of the control and experimental schemes employed to investigate the relationship between combined plasticity and evolvability.

# Mutational Outcome Frequencies



**Figure 16:** Comparison of mutational outcome frequencies for champions evolved with only primary condition/objective pair and no initial state perturbation versus with both primary and secondary condition/objective pairs and initial state perturbation.

## Analysis

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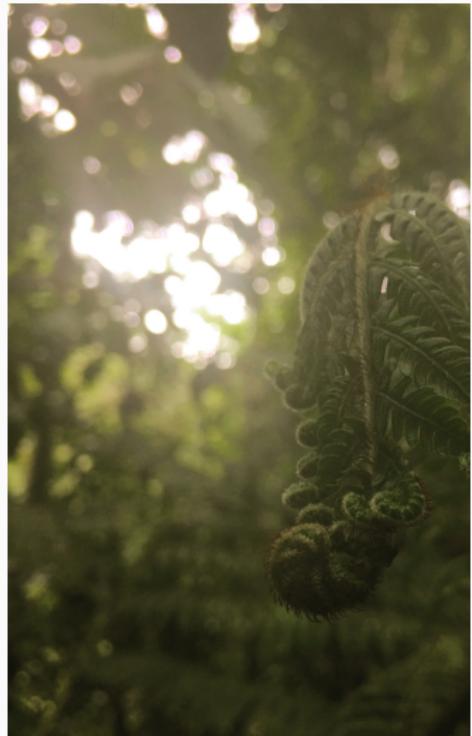
# Analysis

**big idea:** internal system configuration determines the outcomes of change to the system



# Analysis

- environmental noise → noise mitigation structures → more silent mutations
- alternate phenotypic targets → developmental path switching structures → fewer silent mutations
- environmental noise and alternate phenotypic targets → ... → more nonlethal, expressed mutations



## Closing Thoughts

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# Closing Thoughts: Challenges and Reflection

- data management
  - save data trial-wise instead of batch-wise
  - export to standard format
- Jupyter notebooks
  - write frequently used analysis functions into package
- compute time
  - seek grant funding for more stable compute environment



# Closing Thoughts: Next Steps

- more directly biologically-inspired model
- attempt to demonstrate situation where search with plasticity outperforms search without



# Acknowledgements

- DEAP [Fortin et al., 2012]
- Professor Richards for leading CS capstone
- Professor Chiu and Chili Johnson for lending me compute time
- Professors Smith and Chambers for serving as my thesis committee



Questions?

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