

1 Sufficient conditions for the existence of an evolution- 2 ary tipping point

3 Here we sketch out in more detail what is required for an evolutionary tipping
4 point to exist for any continuous, real, thrice differentiable fitness function, $r(z)$,
5 which is monotonically declining from a sufficiently positive local maxima at
6 $z = \theta$ to a negative number as the lag between the local maxima and trait value
7 increases, $l = \theta - z \rightarrow \infty$.

8 Let the position of the local maxima, θ , at time t be kt . Expected popu-
9 lation mean fitness then monotonically declines from, $E[\bar{r}|\bar{l} = 0] = \bar{r}_m > 0$, as
10 the expected population mean lag, $E[\bar{l}] = E[\theta - \bar{z}] = kt - \bar{g}$, increases from 0.
11 Let \bar{l}_c be the mean lag that causes an expected population growth rate of zero,
12 $E[\bar{r}|\bar{l} = \bar{l}_c] = 0$. We then have $E[\bar{r}|\bar{l}] > 0 \forall \bar{l} \in [0, \bar{l}_c)$ and $E[\bar{r}|\bar{l}] < 0 \forall \bar{l} \in (\bar{l}_c, \infty)$.

13 As described in the main text, the expected rate of evolution given mean ad-
14 ditive genetic value \bar{g} is approximately $E\left[\frac{d\bar{g}}{dt}|\bar{g}\right] \approx \sigma_g^2 \frac{d\bar{r}}{d\bar{g}}$, where $\sigma_g^2 > 0$ is the
15 additive genetic variance (a constant that is independent of k) and \bar{r} is population
16 mean fitness. A quasi-steady-state is reached when the expected rate of evolution
17 equals the expected rate of change in the optimum, or equivalently, $\frac{d\bar{r}}{d\bar{l}} = -k/\sigma_g^2$.
18 One then wants to solve this equation for the steady-state lag, \hat{l} , which is the mean
19 lag at which mean fitness declines with mean lag at rate k/σ_g^2 .

20 Given that fitness, r , and thus mean growth rate, \bar{r} , has a local maxima at
21 θ , in a constant environment, $k = 0$, a quasi-steady-state is achieved when the
22 mean lag is zero, $\bar{l} = 0$. Since the expected growth rate at this lag is positive,

23 $E[\bar{r}|\bar{l}=0] = \bar{r}_m > 0$, the population can persist at this steady-state. We assume this
 24 is the starting point of the population. Because mean growth rate, \bar{r} , is continuous
 25 and monotonically declining as mean lag, \bar{l} , increases from zero, i.e., $\frac{d\bar{r}}{d\bar{l}} < 0$ for
 26 all $\bar{l} > 0$, we are guaranteed that near $\bar{l} = 0$ the steady-state lag increases with
 27 k . This is because near the local maxima, θ , the mean growth rate is necessarily
 28 concave down, $\frac{d^2\bar{r}}{d\bar{l}^2} < 0$, i.e., the strength of selection, and thus the rate of evolution
 29 with constant additive genetic variance, increases with increasing mean lag near
 30 $\bar{l} = 0$. However, as we depart from $\bar{l} = 0$ the monotonicity of \bar{r} is not enough to
 31 determine the sign of $\frac{d^2\bar{r}}{d\bar{l}^2}$. Thus, the expected rate of evolution, $\sigma_g^2 \frac{d\bar{r}}{d\bar{l}}$, can increase
 32 or decrease as mean lag increases. In particular, inflection points in the fitness
 33 function, which cause inflection points in mean growth rate, $\frac{d^2\bar{r}}{d\bar{l}^2} = 0$, create local
 34 minima and maxima in the expected rate of evolution as a function of mean lag.

35 Let $L = \{\bar{l}_1, \bar{l}_2, \dots, \bar{l}_n\}$ be the ordered set of mean lags at which there are lo-
 36 cal minima and maxima in the expected rate of evolution (i.e., at which there are
 37 inflection points in the fitness function, $\frac{d^2\bar{r}}{d\bar{l}^2}$) and let $M = \{m_1, m_2, \dots, m_n\}$ be the
 38 corresponding expected rates of evolution, i.e., $E[\frac{d\bar{r}}{d\bar{l}}|\bar{l}_i] = m_i$. Due to the mono-
 39 tonicity of mean growth rate, \bar{r} , the first extrema, at $\bar{l} = \bar{l}_1$, must be a maximum. If
 40 the lag that causes this first maxima in the rate of evolution is greater than the lag
 41 that causes a mean growth rate of zero, $\bar{l}_1 > \bar{l}_c$, then the expected rate of evolution
 42 is monotonically increasing as the mean lag increases from 0 to \bar{l}_c , and therefore
 43 the expected rate of evolution at $\bar{l} = \bar{l}_c$ is the critical rate of environmental change
 44 (i.e., the k that causes $\bar{r} = 0$). If, however, $\bar{l}_1 < \bar{l}_c$, then the steady-state lag contin-
 45 uously increases as the rate of environmental change, k , increases from 0 to m_1 ,

46 where the population can persist (given $\bar{l}_1 < \bar{l}_c$), after which the steady-state lag
 47 makes a discontinuous increase. Technically, there is a saddle-node bifurcation at
 48 $k = m_1$. The size of the discontinuous increase in the steady-state lag as the rate
 49 of environmental change, k , increases through the first maxima in the rate of evo-
 50 lution, m_1 , and the consequences for population persistence, depends on the other
 51 lags that cause extrema, L , and their respective rates of evolution, M . In particular,
 52 if the first local maxima is the global maxima, $m_1 > m_i \forall i > 1$, then there is no
 53 quasi-steady-state solution when the rate of environmental change is greater than
 54 it, $k > m_1$, and the mean lag will increase towards infinity. Thus the population
 55 will go extinct for any $k > m_1$ and m_1 is an evolutionary tipping point. This is the
 56 situation discussed in the main text, as our alternative fitness function only creates
 57 one extrema in the rate of evolution as a function of mean lag. However, if there
 58 is a maxima that is greater than the first, $m_1 < m_i$ for some $i > 1$, then as the rate
 59 of environmental change, k , increases through m_1 the steady-state lag increases
 60 to the next largest mean lag that produces an expected rate of evolution slightly
 61 larger than m_1 . If this next largest mean lag is greater than the lag that causes a
 62 mean growth rate of zero, \bar{l}_c , the population is still expected to go extinct for any
 63 $k > m_1$, and m_1 is still an evolutionary tipping point. But if the next largest mean
 64 lag that produces an expected rate of evolution slightly larger than m_1 is less than
 65 \bar{l}_c , then m_1 is not an evolutionary tipping point and the arguments above for \bar{l}_1 can
 66 be repeated for \bar{l}_3 (the next maxima). I.e., if $\bar{l}_3 > \bar{l}_c$ then the critical rate of change
 67 determines persistence, while if $\bar{l}_3 < \bar{l}_c$ the other lags and respective evolutionary
 68 extrema determine whether \bar{l}_3 is an evolutionary tipping point or not.

69 This argument can be generalized by letting \bar{l}_j be the mean lag in $[0, \bar{l}_c]$ that
 70 produces the maximum expected rate of evolution. If $\bar{l}_j < \bar{l}_c$ it must cause a local
 71 maximum in the rate of evolution and thus be in L (with j odd). Extinction then
 72 occurs whenever $k > m_j$. We then call the height of the largest local maxima in
 73 the expected rate of evolution within the persistence zone, m_j , an evolutionary
 74 tipping point, as a saddle-node bifurcation occurs as k increases through m_j . This
 75 bifurcation causes long-run population growth rates to go from $E[\bar{r}|\bar{l} = \bar{l}_j] > 0$ to
 76 a negative value without ever crossing zero.