1ohammadreza **Mousae**i

2715 Murray Ave Apt 911, Pittsburgh, PA, 15217

🛘 (+1) 312 478 6934 | 🗷 mmousaei@andrew.cmu.edu | 🌴 frc.ri.cmu.edu/ mmousaei/ | 🖫 mmousaei | 🖫 mmousaei | 😘 mmousaei

Research & Work Experience _____

Carnegie Mellon University

Pittsburgh, PA

RESEARCH ASSOCIATE AT AIR LAB

May. 2018 - present

- Developing Planning Software for DARPA Subterranean Challenge:
 - Developing custom DJI M-100 simulation with a rotary lidar in gazebo environment.
 - Developing Global Trajectory Planner using OMPL libraries in ROS.
 - Developing Local Trajectory Planner using custom trajectory libraries in ROS.

Carnegie Mellon University

Pittsburgh, PA

RESEARCH ASSOCIATE AT FIELD ROBOTICS CENTER

Nov. 2017 - present

- · Developing Software for Pipe Crawler robot:
 - Developing 3D Perception software for pipe crawler robot using ToF Lidar
 - Developing online robot localization software using EKF
 - Developing post processing robot localization software using Factograph optimization (with GTSAM package)
 - Constructing 3D map of the environment using ICP
 - Developing robot simulation environment using Gazebo
 - Developing and tuning steering software using PID controller
- Developing Software/Hardware for Moon Rover Robot:
 - Developing Hardware of a custom designed light weighted LiDar
 - Developing Software for our custom built Lidar to construct a 3D point cloud

University of Illinois at Chicago

Chicago, IL

RESEARCH ASSISTANT

Jun. 2016 - Nov 2017

- Designing a fully integrated radar and communication system named ComSens, Advisor: Dr. Smida
 - Proposing the novel idea of integrating radar and communication systems using pilot symbols
 - Formulating the optimization problem to design training signals
 - Solving the optimization problem using Convex Optimization methods
 - Published our results as a paper at Military Conference on Communication (IEEE MILCOM 2017)
- Optimizing Pilot Overhead for Ultra-Reliable Short-Packet Transmission, Advisor: Dr. Smida.
 - Channel estimation for short-packet communication
 - Formulating the optimization problem for finite-length packet transmission
 - Analytically solving the optimization problem and finding the optimal training signal
 - Published our results as a paper at International Conference on Communication (IEEE ICC 2017)

Sharif University Of Technology

Tehran, Iran

RESEARCH ASSISTANT AT COMPUTER VISION LAB

Nov. 2014 - Feb. 2015

- Designing and Implementing an @Home robot for participating in AUT-CUP competitions, Advisor: Dr. Jamzad. - Designing the platform (Differential Derive Robot with 4DOF Lynx Robotic Arm on top)
 - Controlling the robotic arm using inverse kinematic (analytical approach)
 - Motion planning of the robot (using Artificial Potential Field)
 - Our robot ranked 2nd in AUTCUP international Robotics competition (Artificial Intelligence League)

Tehran Polytechnic University

Tehran, Iran

RESEARCH ASSISTANT AT COMPUTER VISION LAB

Jan. 2015 - Jul. 2015

- · Completing and debugging an @Home Robot for ROBOCUP 2015 (Joao Pessoa, Brazil), Advisor: Dr. Shiri.
 - Designing a digital circuit for gathering sensors data (Ultrasound, IR, Gyroscope, ...) and IMUs over I2C BUS
 - Implementing Hough transform based algorithm for Robot Vision (using OpenCV)
 - Our robot participated in ROBOCUP 2015 in Joao Pessoa, Brazil

Shahid Beheshti University

Tehran, Iran

Sep. 2013 - Dec. 2013

RESEARCH ASSISTANT AT TELECOMMUNICATIONS LAB

- · Research on optimizing Power Line Communication Systems (PLC) with OFDM Modulation, Advisor: Prof. Afjei.
 - Simulating MMSE channel estimation method in PLC with OFDM Modulation(Using MATLAB)
 - Simulating the same channel over different modulations (QAM, FSK, PSK) and comparing with OFDM

Skills_

Programming C/C++, C#, Phyton, MATLAB, JAVA, VHDL, Verilog, LaTeX, ROS (Robot Operating System)

Smart Phone Programming iOS (Swift), Android (JAVA)

Web HTML, CSS, JS, php
Controllers AVR, ARM, FPGA, PLC
PCB Layout Altium Designer

Languages Persian (native), English (fluent), Arabic(Intermediate)

Education

University of Illinois at Chicago

Chicago, IL

M.Sc. in Electrical and Computer Engineering

Aug. 2015 - PRESENT

• **GPA:** 3.48/4

Shahid Beheshti University (former National University of Iran)

Tehran, Iran

B.S. IN ELECTRICAL AND COMPUTER ENGINEERING

Sep. 2010 - Jan 2015

• **GPA:** 17.09/20 (3.72/4)

Honors & Awards

2	014	2nd Place , AUT-CUP Robotic International Competition, Artificial Intelligence league	Amirkabir U. of Tech	
2	012	2nd Place, ACM ICPC Qualiffication Programing Contest	S. Beheshti Univ.	
2	012	19th Place, ACM ICPC West Asia Regional Programing Contest	Sharif U. of Tech	
2	011	5th Place , ACM ICPC Qualiffication Programing Contest	S. Beheshti Univ.	
2	2010	Ranked Top 1% , Mathematics and Physics among more than 178,000 students in Iranian nationwide	Tehran, Iran	
	2010	university entrance examination (Konkoor).	reman, nan	
2	800	Accepted, Iranian National Olympiad Competition in Mathematics	Tehran, Iran	
2	.007	Accepted, Iranian National Olympiad Competition in Computer Science	Tehran, Iran	

Research Interest

• Robotics • Wireless Communication

Teaching Experience _____

2017	Wireless Communications, Teaching Assistant	UIC
2016	Digital Communications, Teaching Assistant	UIC
2016	Solid State Device Theory, Teaching Assistant	UIC
2016	Logic Design, Teaching Assistant	UIC
2015	Computer Communication Networks I, Teaching Assistant	UIC
2015	Probability and Random Processes, Teaching Assistant	UIC
2012-13	Digital Logic Design, Teaching Assistant	S. Beheshti Univ.
2012-13	Robotics Workshop, Instructor	Mofid I Highschool
2012-13	Robotics Workshop, Instructor	Mofid III Highschool
2012-13	Robotics Workshop, Instructor	Danesh Highschool
2012	Mathematics and Physics, Instructor	Allame Highschool
2012	Mathematics and Physics, Instructor	Salam Highschool
2012	Mathematics and Physics, Instructor	Talash Highschool

Work Experience _____

PLTW Illinois

IT EXPERT

Chicago, IL

Jun. 2016 - Sep. 2016

• Debug and Troubleshoot Network technical problems

- Analyzing performance using Linux
- Finding bottleneck of the network (NIC, Soft interrupt, Kernel buffer, Network layer, etc)
- Tuning the bottleneck (using tuned on Ubuntu)

DIGITAL DESIGNER Jan. 2012 - Jun. 2012

- · Designing and Implementing a mobile robot
 - Designing the platform (Differential Derive Robot)
 - Designing Control System (PID Hybrid Control system with Go-to-Goal and Obstacle-Avoidance states)
 - Implementing the Control system (with C++ on ROS Indigo installed on a Raspberry Pi 2 B+)

Rahjuyan Sanat Taban CO (RST)

Tehran, Iran

Jun. 2012 - Dec. 2012

• Design and Implementing digitally controlled current source

- Analog design of a buck current source (with a digital controller on MOSFET gate)
- Closing the feedback loop using Hall current sensor
- Designing the closed loop digital control system using PID controller
- Implementing the designed control system using C++ on ARM Cortex-M3 (LPC1768) Microcontroller

Projects

DIGITAL DESIGNER

2017	Computer Vision, Implementing different CV algorithms on OpenCV	Udacity
2017	Machine Learning, Implementing different ML algorithms on MATLAB	Coursera
2017	Image and Video Processing, Implementing Image and Video processing methods on OpenCV	Coursera
2016	Wireless Communication, Simulating LTE system on MATLAB	UIC
2016	Information Theory, Survey paper on Rate in Finite Blocklength	UIC
2015	Digital Control, Implementing a current source controlling with PID using ARM	S. Beheshti Univ.
2015	Image Processing, Implementing Different kinds of Visual Cryptography using both MATLAB and C#	S. Beheshti Univ.
2014	Communication Circuits, Simulating a Low Noise Amplifier (LNA) with ADS	S. Beheshti Univ.
2014	Digital Signal Processing (DSP) , Simulating Different kinds of filters (butterworth, chebishev etc) with MATLAB	S. Beheshti Univ.
2013	Industrial Electronics, Simulating different kinds of convertes(buck, boost, buck- boost) with MATLAB	S. Beheshti Univ.
2012	Electronics II , Designing, Simulating and Implementing a High gain Amplifier with low noise	S. Beheshti Univ.

Publications.

- **M. Mousaei**, S. Vahidian, B. Smida, "Training Signal Optimization for Communication in Finite-Blocklength: An Analytical Approach", **IEEE Communications Letters**, *Under Preparation*.
- **M. Mousaei**, M. Soltanalian, B. Smida, "ComSens: Exploiting Pilot Diversity for Pervasive Integration of Communication and Sensing", **IEEE Military Conference on Communication**, Oct 2017.
- **M. Mousaei**, B. Smida, "Optimizing Pilot Overhead for Ultra-Reliable Short-Packet Transmission", *IEEE International Confesence on Communication*, May 2017.
- A. Sheikhjafari, S. Gharghabi, K. Sartipi, **M. Mousaei**, A. Sheikhjafari, E. Babaians and S. Shiry Ghidary, "Amirkabir University of Technology (AUT) @Home 2014 Team Description Paper", **Robocup 2014, Joao Pessoa, Brazil**, Jul. 2014.
- **M. Mousaei**, A. Keipour, E. Babaians, "Automated High-Speed Traffic Monitoring and Violation Detection Using RFID Technology", **IEEE Iranian Conference on Electrical Engineerin**, May 2014.
- A. Keipour, K. Sartipi, M. Mousaei, S. Mohammadzadeh, M. Jamzad, "Team Description Paper for Sharif University of Technology (SUT) Team", AUTCUP Robotics competitions, Oct. 2013.

Test Scores

TOEFL ETS

Score: 105 Dec. 2014

Reading (29/30), Listening (29/30), Speaking (22/30), Writing (25/30)

GRE ETS

Score: 313 Nov. 2014

• Analytical (3.5/6.0), Quantitative (167/170), Verbal (146/170)

References ____

References available upon request