

CSE 221: Algorithms

Dynamic Programming

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References

- 1 Jon Kleinberg and Éva Tardos, *Algorithm Design*. Pearson Education, 2006.
- 2 T. H. Cormen, C. E. Leiserson, R. L. Rivest, and C. Stein, *Introduction to Algorithms, Second Edition*. The MIT Press, September 2001.

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Contents

- Introduction
- Memoization
- Dynamic programming
- Weighted interval scheduling problem
- 0/1 Knapsack problem
- Coin changing problem
- What problems can be solved by DP?
- Conclusion

Dynamic Programming (DP)

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- Motivating the case for DP with Memoization – a top-down technique, and then moving on to Dynamic Programming – a bottom-up technique.

▷ *Greedy is evil, Dynamic Programming is good.* – Prof. Jeff Erickson, University of Illinois, Urbana-Champaign.

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Recursive solution to Fibonacci numbers

Definition (Fibonacci numbers)

The Fibonacci numbers are given by the following sequence:

$$\langle 0, 1, 1, 2, 3, 5, 8, 21, 34, 55, 89, \dots \rangle$$

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$$FIB(n) = \begin{cases} n & \text{if } n = 0 \text{ or } 1 \\ FIB(n-1) + FIB(n-2) & \text{if } n \geq 2 \end{cases}$$

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Straightforward recursive algorithm

$FIBONACCI(n) \quad \triangleright n \geq 0$

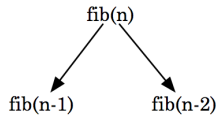
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1  if  $n = 0$  or  $n = 1$ 
2      then return  $n$ 
3      else return  $FIBONACCI(n-1) + FIBONACCI(n-2)$ 
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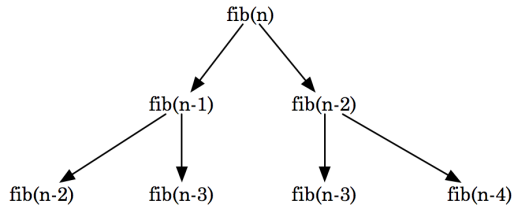
Recursion tree

$\text{fib}(n)$

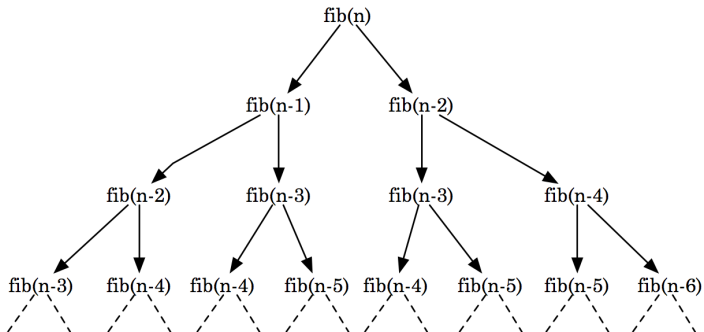
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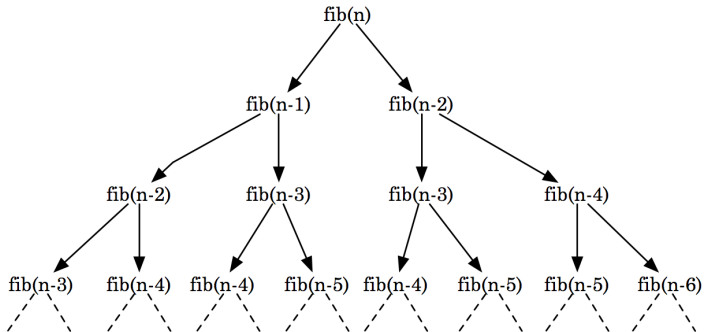
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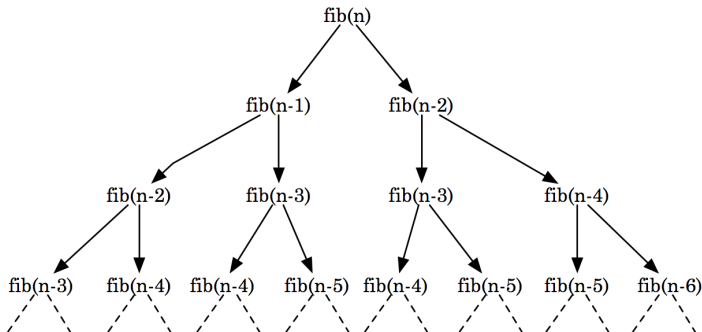
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Complexity

This recursive algorithm for Fibonacci numbers has **exponential** running time!

Recursion tree

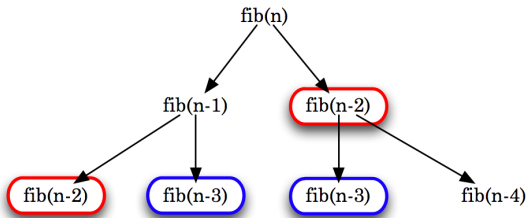


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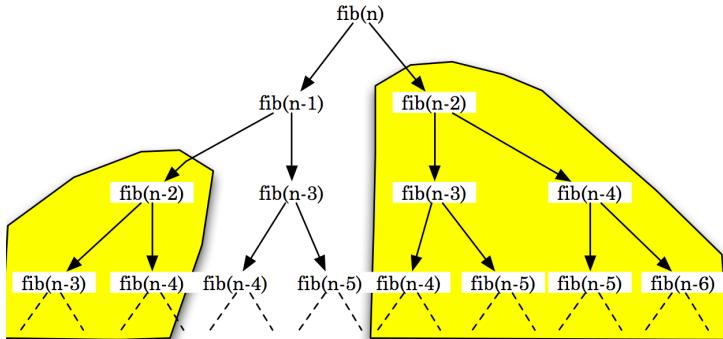
To be precise, $T(n) = O(\varphi^n)$, where $\varphi = \frac{1+\sqrt{5}}{2}$ is the **golden ratio**.

Redundant computations



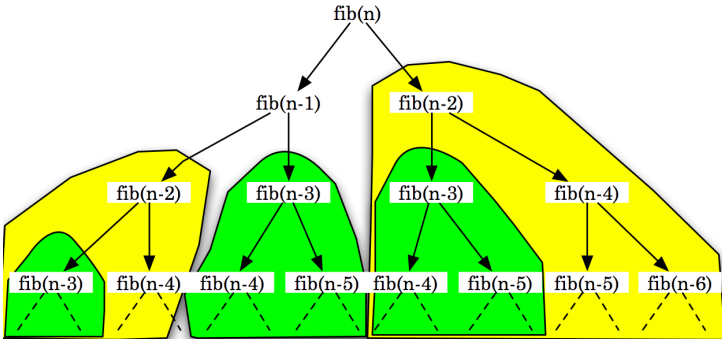
▷ Note how $\text{FIB}(n-2)$ and $\text{FIB}(n-3)$ are each being computed twice.

Redundant computations



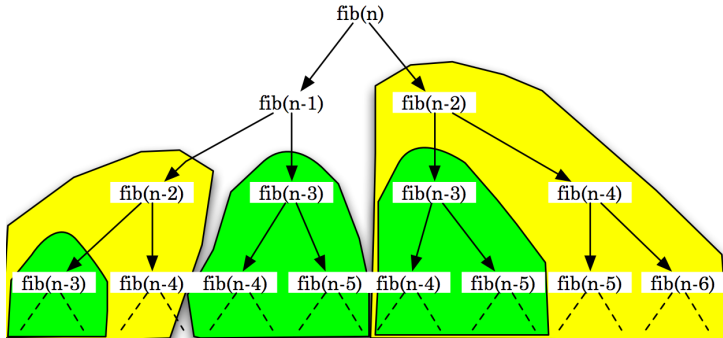
▷ In fact, computing $\text{FIB}(n - 2)$ involves computing a whole subtree.

Redundant computations



▷ Likewise for computing $\text{FIB}(n - 3)$.

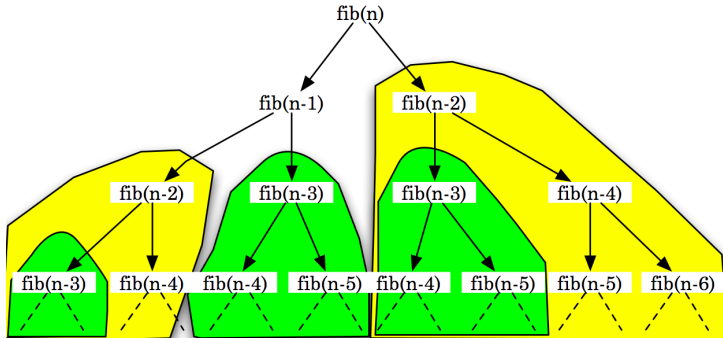
Redundant computations



Observations

- Spectacular redundancy in computation

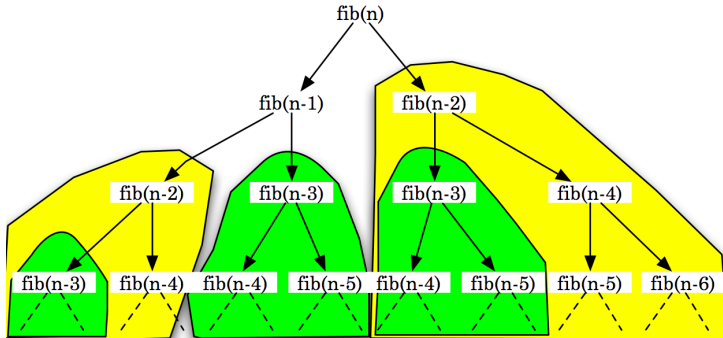
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- Spectacular redundancy in computation – how many times are we computing $\text{FIB}(n - 2)$?

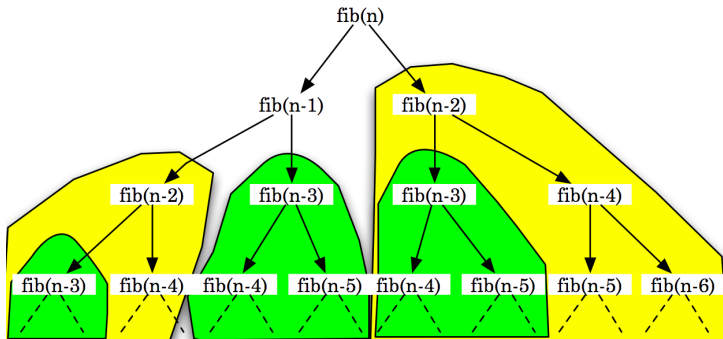
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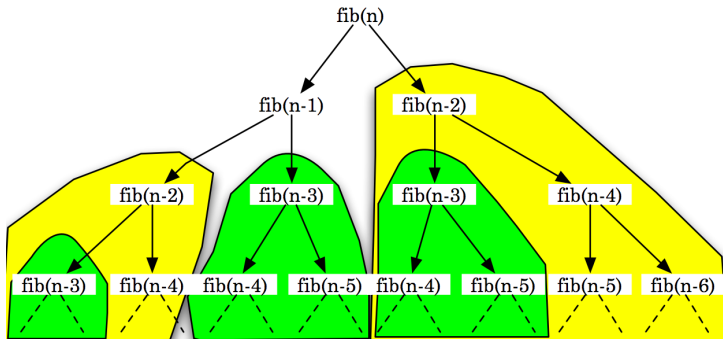
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- Spectacular redundancy in computation – how many times are we computing $\text{FIB}(n-2)$? $\text{FIB}(n-3)$?
- What if we compute and save the result of $\text{FIB}(i)$ for $i = \{2, 3, \dots, n\}$ the first time, and then re-use it each time afterward?

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- What if we compute and save the result of $\text{FIB}(i)$ for $i = \{2, 3, \dots, n\}$ the first time, and then re-use it each time afterward?
- Ah, we've just (re)discovered [Memo\(r\)ization](#)!

Memoization

Definition (Memoization)

The process of saving solutions to subproblems that can be re-used later without redundant computations.

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Typically, the solutions to subproblems (i.e., the intermediate solutions) are saved in a global array, which are later looked up and re-used as needed.

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- 1 At each step of computation, first see if the solution to the subproblem has already been found and saved.
- 2 If so, simply return the solution.
- 3 If not, compute the solution, and save it before returning the solution.

Memoized recursive algorithm for Fibonacci numbers

$M\text{-FIBONACCI}(n) \quad \triangleright n \geq 0, \text{ global } F = [0 \dots n]$
 1 **if** $n = 0$ or $n = 1$
 2 **then return** n \triangleright Our base conditions.
 3 **if** $F[n]$ is empty \triangleright No saved solution found for n .
 4 **then** $F[n] \leftarrow M\text{-FIBONACCI}(n - 1) + M\text{-FIBONACCI}(n - 2)$
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Questions

- What is this **global array** F ?

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- What is an appropriate **sentinel** to indicate that $F[i], 0 \leq i \leq n$ has not been solved yet (i.e., empty)?

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Memoized ... Fibonacci numbers (continued)

FIBONACCI(n) $\triangleright n \geq 0$

\triangleright Allocate an array $F[0..n]$ to save results ($\text{LENGTH}[F] = n + 1$).

1 **for** $i \leftarrow 0$ **to** n

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3 **return** M-FIBONACCI(F, n)

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M-FIBONACCI(F, n) $\triangleright n \geq 0, F = [0..n]$

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```

Running time

Each element $F[2] \dots F[n]$ is filled in just once in $\Theta(1)$ time, so

$$T(n) = \Theta(n).$$

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- What are the drawbacks, if any, of memoization?
- Would all recursive algorithms benefit from memoization?
For example, would the recursive algorithm to compute the factorial of a number benefit from memoization?

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Dynamic programming (continued)

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- 1 Must ensure that the recurrence is correct of course!
- 2 Need a “place” to store the solutions to subproblems, and need to look these solutions up when needed. Typically, but not always, a multi-dimensional table is used as storage.

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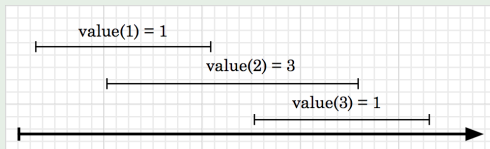
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Weighted interval scheduling problem

Definition (Weighted interval scheduling problem)

Given a set of schedules $I = \{I_i\}$, with associated weights $W = \{w_i\}$, find $A \subseteq I$ such that the members of A are **non-conflicting** and the total weight $\sum_{i \in A} w_i$ is **maximized**.

Example (an instance of weighted interval problem)



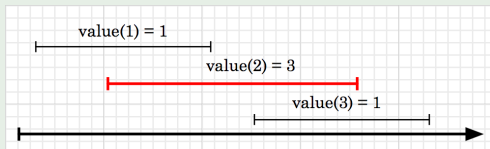
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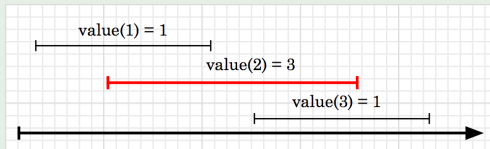
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Example (using an optimal strategy)



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What now?

First step is to formulate a recursive solution, but first we need to figure out what the subproblems are.

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- All we can say about ϑ is the following: **interval n (the last interval) either belongs to ϑ , or it doesn't.**

Developing a recursive solution

- Let W be an instance of a weighted interval problem.
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If $n \in \vartheta$ Then clearly all intervals that conflict with n are not members of ϑ . ϑ then contains n , plus an optimal solution to all intervals that do not conflict with n . We now need to have a quick way of computing list of conflicting intervals for n .

Developing a recursive solution

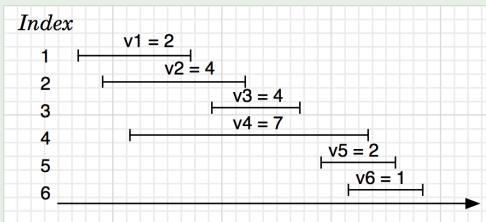
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If $n \notin \vartheta$ Then ϑ contains an optimal solution for the intervals $\{i_1, i_2, \dots, i_{n-1}\}$.

Developing a recursive solution (continued)

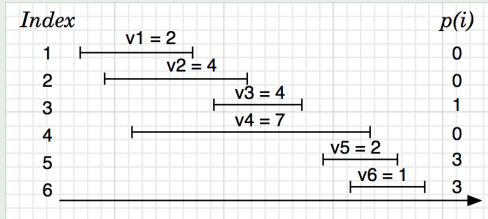
Example (an instance of a weighted interval problem)



► For each interval i , compute $p(i)$, the leftmost interval that does not conflict with i . Define $p(j) = 0$ if not request $i < j$ is disjoint from j .

Developing a recursive solution (continued)

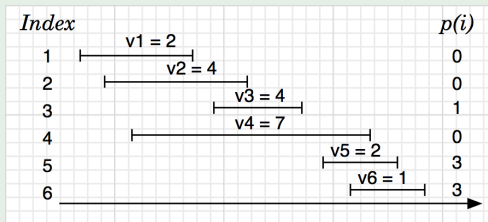
Example (an instance of a weighted interval problem)



► For a given interval i , $p(i)$ means that intervals $\{p(i) + 1, p(i) + 2, \dots, i - 1\}$ overlap with it. For example, $p(6) = 3$, which means that intervals $\{4, 5\}$ overlap interval 6.

Developing a recursive solution (continued)

Example (an instance of a weighted interval problem)



► Alternatively, intervals $\{1, 2, \dots, p(i)\}$ *do not* overlap interval i . For example, $p(6) = 3$ means that intervals $\{1, 2, 3\}$ do not overlap interval 6.

Developing a recursive solution (continued)

- If $n \in \vartheta$, then ϑ must include, in addition to interval n , an optimal solution to the subproblem consisting of intervals $\{1, 2, \dots, p(n)\}$.

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▷ $\vartheta(n) = \vartheta(n-1)$
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▷ $\vartheta(n) = \text{MAX}(w_n + \vartheta(p(n)), \vartheta(n-1))$

Developing a recursive solution (continued)

Recursive algorithm for an optimal value

If $OPT(j)$ is an optimal solution to the subproblem for intervals $\{1, 2, \dots, j\}$, for any $j \in \{1, 2, \dots, n\}$, then:

$$OPT(j) = \text{MAX}(w_j + OPT(p(j)), OPT(j - 1))$$

Developing a recursive solution (continued)

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Extracting the intervals in an optimal solution

The interval j is in an optimal solution $OPT(j)$ **if and only if** the first of the two options is larger than the second.

Developing a recursive solution (continued)

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Extracting the intervals in an optimal solution

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*Interval j belongs to an optimal solution on the set $\{1, 2, \dots, j\}$ **if and only if***

$$w_j + OPT(p(j)) \geq OPT(j - 1)$$

A recursive algorithm

$\text{WIS}(j)$

```
1  if  $j = 0$ 
2    then return 0
3    else return  $\text{MAX}(w_j + \text{WIS}(p(j)),$   
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```

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- The tree grows very rapidly, leading to **exponential** running time. The tree when $p(j) = j - 2$ for all j shows how quickly it grows.
- There are many **overlapping subproblems**, so the obvious choice is to **memoize** the recursion.

Memoizing the recursion

M-WIS(j)

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1  if  $j = 0$ 
2      then return 0
3  elseif  $M[j]$  is empty
4      then  $M[j] \leftarrow \text{MAX}(w_j + \text{M-WIS}(p(j)),$   

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- Each entry in $M[j]$ gets filled in only once at $\Theta(1)$ time, and there are $n + 1$ entries, so M-WIS(n) takes $\Theta(n)$ time.

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- Of course, sorting the intervals by the finish times takes $\Theta(n \lg n)$ time.

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- Of course, sorting the intervals by the finish times takes $\Theta(n \lg n)$ time.
- This memoized algorithm *plus* sorting the intervals takes $\Theta(n \lg n) + \Theta(n) = \Theta(n \lg n)$ time.

Computing a solution in addition to its values

- The memoized algorithm only computes the optimal value, but does not extract the intervals that make up the solution.
- The key to extracting the solution is to note that item j is in ϑ if and only if $w_j + M[p(j)] \geq M[j - 1]$. This provides two ways of extracting the intervals in the optimal solution:
 - 1 Trace back from $M[n]$ and extract the solution by checking which choice was made – $j - 1$ or $p(j)$ – when $M[j]$ was included in the optimal set of intervals.
 - 2 Whenever a choice is made between two options, save in $pred[j]$, the predecessor pointer, the choice that was made between $j - 1$ and $p(j)$.

Computing a solution in addition to its values (continued)

- The first way recursively extracts an optimal set of intervals for a problem size of $1 \leq j \leq n$.
- Calling WIS-FIND-SOLUTION(n) extracts all the intervals in the optimal solution.

Computing a solution in addition to its values (continued)

- The first way recursively extracts an optimal set of intervals for a problem size of $1 \leq j \leq n$.
- Calling WIS-FIND-SOLUTION(n) extracts all the intervals in the optimal solution.

WIS-FIND-SOLUTION(j)

```

1  if  $j = 0$ 
2      then Output nothing
3      else
4          if  $w_j + M[p(j)] \geq M[j - 1]$ 
5              then Output  $j$ 
6                  WIS-FIND-SOLUTION( $p(j)$ )
7              else WIS-FIND-SOLUTION( $j - 1$ )

```

Computing a solution in addition to its values (continued)

- The second way requires that M-WIS use an auxiliary array $pred[0..n]$ to save the predecessor of each interval in the solution.
- Initialize $pred[j] = 0$ for all $0 \leq j \leq n$.

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M-WIS(j)

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1  if  $j = 0$ 
2      then return 0
3  elseif  $M[j]$  is empty
4      then if  $w_j + \text{M-WIS}(p(j)) > M[j - 1]$ 
5          then  $M[j] \leftarrow w_j + \text{M-WIS}(p(j))$ 
6               $pred[j] \leftarrow p(j)$ 
7          else  $M[j] \leftarrow M[j - 1]$ 
8               $pred[j] \leftarrow j - 1$ 
9  return  $M[j]$ 
  
```

Computing a solution in addition to its values (continued)

Now that we have $pred[j]$ filled in, we start from $M[n]$ and work backwards.

- 1 If $pred[j] = p(j)$, then we did add the j^{th} interval in the final solution, and we continue with $pred[j] \leftarrow p(j)$.
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Can you come up with an iterative version?

Developing a Dynamic Programming algorithm

- The value of an optimal solution $OPT(j)$ for any $j \in \{1, 2, 3, \dots, n\}$ depends on the values of $OPT(p(j))$ and $OPT(j - 1)$.

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Dynamic programming algorithm

WIS(n)

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$$T(n) = \Theta(n)$$

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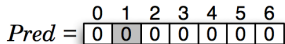
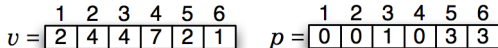
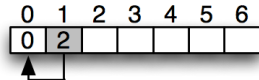
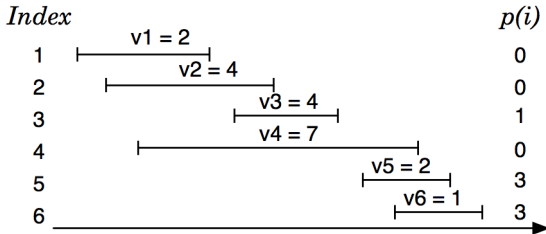
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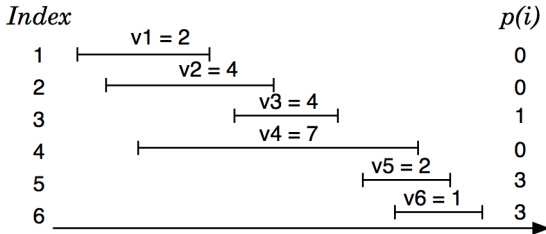
WIS-FIND-SOLUTION(j)

```
1   $j \leftarrow n$ 
2  while  $j > 0$ 
3      do if  $pred[j] = p(j)$ 
4          then Output  $j$ 
5           $j \leftarrow pred[j]$ 
```


Weighted Interval Scheduling DP algorithm in action



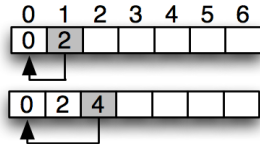
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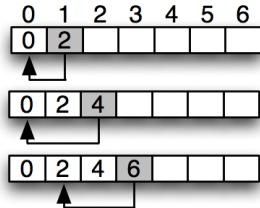
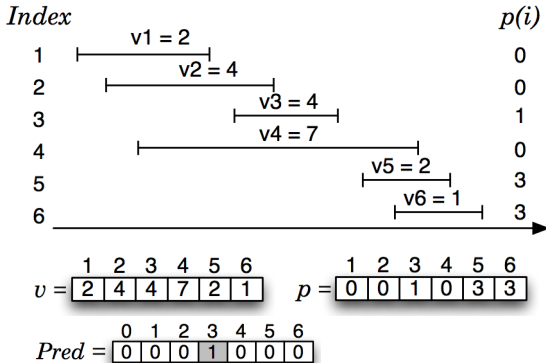
$v =$	1	2	3	4	5	6
	2	4	4	7	2	1

$p =$	1	2	3	4	5	6
	0	0	1	0	3	3

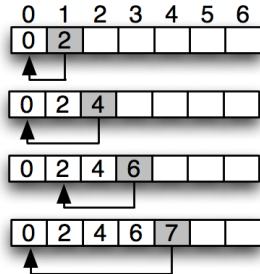
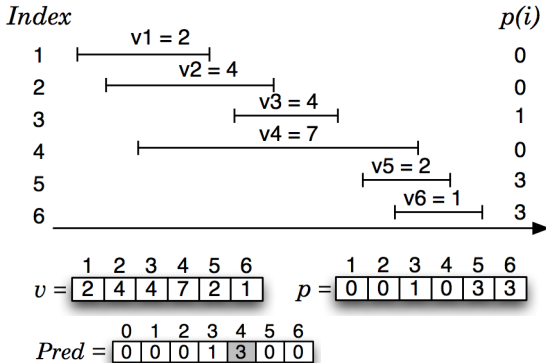
$Pred =$	0	1	2	3	4	5	6
	0	0	1	0	0	0	0



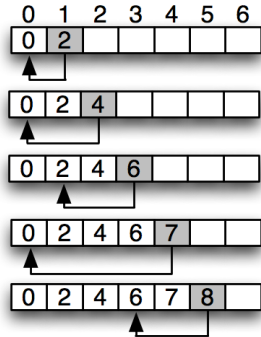
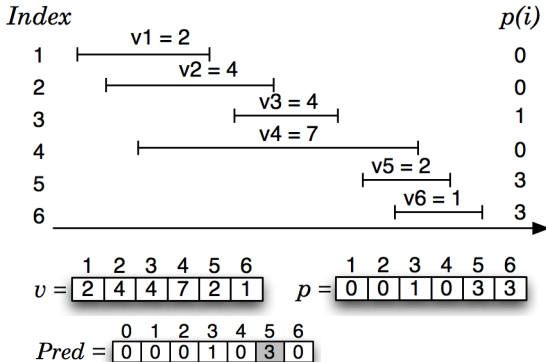
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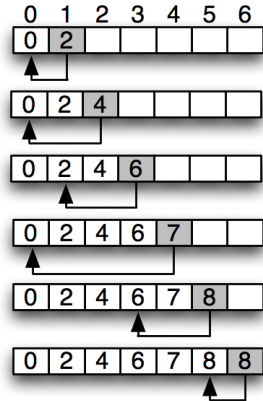
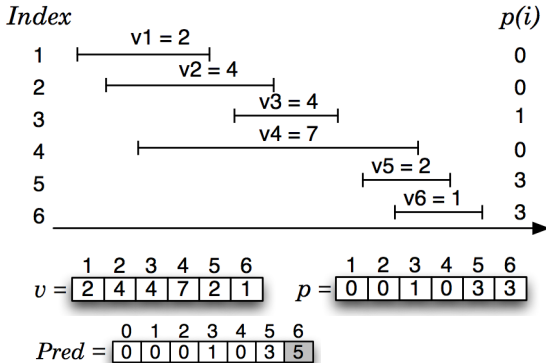
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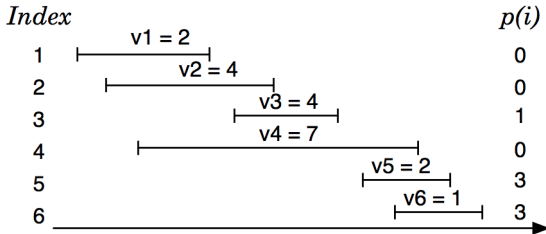
Weighted Interval Scheduling DP algorithm in action



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$v =$

1	2	3	4	5	6
2	4	4	7	2	1

 $p =$

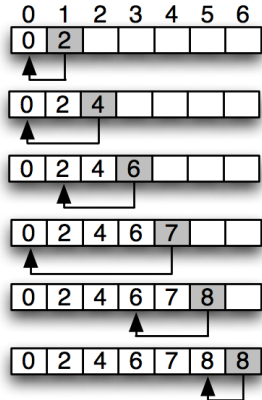
1	2	3	4	5	6
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$Pred =$

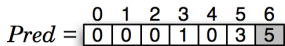
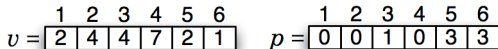
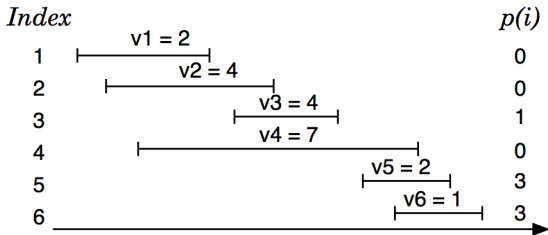
0	1	2	3	4	5	6
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Optimal value: 8

Optimal solution: {5, 3, 1}

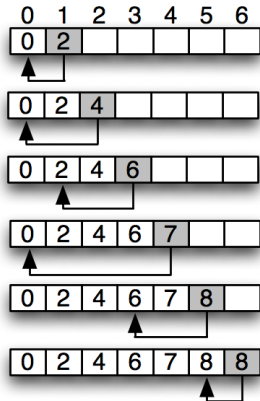


Weighted Interval Scheduling DP algorithm in action



Optimal value: 8

Optimal solution: {1, 3, 5}



So, you think you understand Dynamic Programming now?

Answer the following questions

- 1 Instead of sorting the intervals by **finish time**, what if we sorted the requests by **start time**?

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- 3 If all the *weights* are the same, what does this problem become?

So, you think you understand Dynamic Programming now?

Answer the following questions

- 1 Instead of sorting the intervals by **finish time**, what if we sorted the requests by **start time**?
- 2 What if we didn't sort the requests at all? Would it still work?
- 3 If all the *weights* are the same, what does this problem become? Can you solve it using DP?

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- Introduction
- Memoization
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0/1 knapsack problem

Definition (0/1 knapsack problem)

Given a set S of n items, such that each item i has a positive benefit v_i and a positive weight w_i , the goal is to find the maximum-benefit subset that does not exceed a given weight W .

0/1 knapsack problem

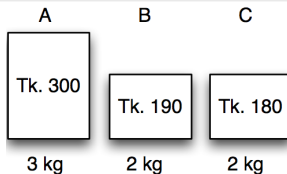
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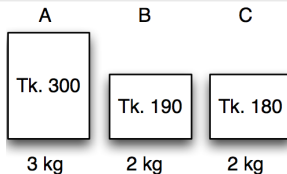


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Maximum weight: $W = 4 \text{ kg}$

Optimal solution: items B and C

Benefit: **370**

Developing a recursive solution

- Let S be an instance of a 0/1 Knapsack problem, and v^* be an optimal solution (even if we have no idea what it is yet).

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- We have two parameters for each subproblem – the items S , and the maximum allowed weight W .

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Developing a recursive solution (continued)

Recursive algorithm for an optimal value

If $OPT(j, w)$ is an optimal solution to the subproblem for items $\{1, 2, \dots, j\}$, for any $j \in \{1, 2, \dots, n\}$, and with a maximum allowed weight of w , then:

$$OPT(j, w) = \begin{cases} OPT(j-1, w) & \text{if } w_j > w, \\ \text{MAX}(v_j + OPT(j-1, w - w_j), \\ \quad OPT(j-1, w)) & \text{otherwise.} \end{cases}$$

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Extracting the items in an optimal solution

The item j is in an optimal solution $OPT(j, w)$ **if and only if** the first of the two options is larger than the second.

$$v_j + OPT(j-1, w - w_j) \geq OPT(j-1, w)$$

A recursive algorithm

KNAPSACK(j, w)

```
1  if  $j = 0$  or  $w = 0$ 
2    then return 0
3  elseif  $w_j > w$ 
4    then return KNAPSACK( $j - 1, w$ )
5  else return MAX( $v_j + \text{KNAPSACK}(j - 1, w - w_j)$ ,
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- The initial call is KNAPSACK(n, W).
- The tree grows very rapidly, leading to **exponential** running time.
- There are many **overlapping subproblems**, so the obvious choice is to **memoize** the recursion.

Memoizing the recursion

$$\text{M-KNAPSACK}(j, w)$$
1 **if** $j = 0$ or $w = 0$

```
2    then return 0
```

```

3 elseif  $M[j, w]$  is empty

```

```

4   then  $M[j, w] \leftarrow \text{MAX}(v_j + \text{M-KNAPSACK}(j - 1, w - w_j),$   

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5  return  $M[j, w]$ 

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- Each entry in $M[j, w]$ gets filled in only once at $\Theta(1)$ time, and there are $n + 1 \times W + 1$ entries, so M-KNAPSACK(n, W) takes $\Theta(nW)$ time.

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- Is this a linear-time algorithm?
- This is an example of a pseudo-polynomial problem, since it depends on another parameter W that is independent of the problem size.

Developing a Dynamic Programming algorithm

KNAPSACK(n, W)

```

1  for  $i \leftarrow 0$  to  $n$       ▷ no remaining capacity
2      do  $M[i, 0] \leftarrow 0$ 
3  for  $w \leftarrow 0$  to  $W$     ▷ no item to choose from
4      do  $M[0, w] \leftarrow 0$ 
5  for  $j \leftarrow 1$  to  $n$ 
6      do for  $w \leftarrow 1$  to  $W$ 
7          do if  $w_j > w$ 
8              then  $M[j] = M[j - 1, w]$ 
9              else  $M[j, w] \leftarrow \text{MAX}(v_j + M[j - 1, w - w_j],$ 
                                      $M[j - 1, w])$ 
10 return  $M[n, W]$ 

```


0/1 Knapsack recursive algorithm in action

Given the following (from M. H. Alsuwaiyel, ex. 7.6):

$$W = 9$$

$$w_i = \{2, 3, 4, 5\}$$

$$v_i = \{3, 4, 5, 7\}$$

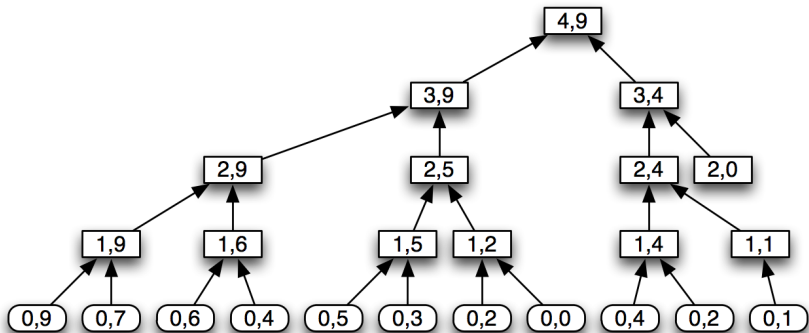
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4	-	-	-	-	-	-	-	-	-	-
3	-	-	-	-	-	-	-	-	-	-
2	-	-	-	-	-	-	-	-	-	-
1	-	-	-	-	-	-	-	-	-	-
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3	0	0	3	4	4	7	8	9	9	12
2	0	0	3	4	4	7	7	7	7	7
1	0	0	3	3	3	3	3	3	3	3
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Related problem: Subset Sums problem

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Given a set S of n items, such that each item i has a positive weight w_i , the goal is to find the maximum-weight subset that does not exceed a given weight W .

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- How is this similar to the 0/1 Knapsack problem?
- Can you solve this using the same algorithm?

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Questions

What is the natural search space? Does this problem have a Dynamic Programming solution? If so, how do we develop it?

Developing a recursive solution

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- What are the subproblems?

Developing a recursive solution (continued)

If $OPT(p)$ is the minimum number of coins needed to make change for amount p with denominations $C = \{c_1, c_2, \dots, c_k\}$, then:

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If $OPT(p)$ is the minimum number of coins needed to make change for amount p with denominations $C = \{c_1, c_2, \dots, c_k\}$, then:

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- The number of coins for 0 amount is 0.

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If $OPT(p)$ is the minimum number of coins needed to make change for amount p with denominations $C = \{c_1, c_2, \dots, c_k\}$, then:

- The coin c_i chosen at any step must be smaller than p , the amount left at that point.
- Once we choose $c_i \leq p$, $OPT(p) = 1 + OPT(p - c_i)$, since we have to find the best combination for the remaining amount (picking a coin smaller than the amount at each step).
- Since we don't know which coin would be chosen, we have to search all $|C|$ denominations and find the minimum.
- The number of coins for 0 amount is 0.

Recurrence

$$OPT(p) = \begin{cases} 0 & \text{if } p = 0 \\ \min_{i: c_i \leq p} \{1 + OPT(p - c_i)\} & \text{if } p > 0 \end{cases}$$

A recursive algorithm

CHANGE(n, C)

```
1  if  $n = 0$ 
2    then return 0
3    else  $min \leftarrow \infty$ 
4        for  $i \leftarrow 1$  to  $|C|$ 
5            do if  $c_i \leq n$  and  $1 + \text{CHANGE}(n - c_i, C) < min$ 
6                then  $min \leftarrow 1 + \text{CHANGE}(n - c_i, C)$ 
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- The tree grows very rapidly, leading to **exponential** running time.

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- The initial call is CHANGE(A, C).
- The tree grows very rapidly, leading to **exponential** running time.
- There are many **overlapping subproblems**, so the obvious choice is to **memoize** the recursion.

Memoizing the recursion

M-CHANGE(n, C)

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1  if  $n = 0$ 
2      then return 0
3      else if  $M[n]$  is empty
4          then  $min \leftarrow \infty$ 
5              for  $i \leftarrow 1$  to  $|C|$ 
6                  do if  $c_i \leq n$  and
9                       $1 + \text{M-CHANGE}(n - c_i, C) < min$ 
7                          then  $min \leftarrow 1 + \text{M-CHANGE}(n - c_i, C)$ 
8                       $M[n] \leftarrow min$ 
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- Each entry in $M[n]$ gets filled in only once at $\Theta(|C|)$ time, and there are $n + 1$ entries, so M-CHANGE(n) takes

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- Another **pseudo-polynomial** problem!

Developing a Dynamic Programming algorithm

CHANGE(n, C)

▷ $M = [0 \dots n], S = [0 \dots n]$

```

1   $M[0] \leftarrow 0$       no amount to change
2  for  $p \leftarrow 1$  to  $n$ 
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6                  then  $min \leftarrow 1 + M[p - c_i]$ 
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9           $S[p] \leftarrow coin$ 
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```

- $M[p]$ for all $0 \leq p \leq n$ – minimum number of coins needed to change for p paisa.
- $S[p]$ for all $0 \leq p \leq n$ – the first coin chosen in computing an optimal solution for making change for p paisa.

Computing a solution in addition to its values

- The S array in the algorithm “remembers” the first coin we use when computing an optimal value for a given amount.
- We go backwards using $S[n]$ until $n = 0$ and find the coin that was added at each step.

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COINS(S, C, n)

```
1  while  $n > 0$ 
2      do Output  $S[n]$ 
3       $n \leftarrow n - C_{S[n]}$ 
```


Contents

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- Memoization
- Dynamic programming
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- 0/1 Knapsack problem
- Coin changing problem
- What problems can be solved by DP?
- Conclusion

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Polynomially many subproblems The total number of subproblems should be a polynomial, or else DP may not provide an efficient solution.

Subproblem optimality If the optimal solution to the entire problem contain optimal solution to the subproblems, then it has the subproblem optimality property. Also called the *principle of optimality*.

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- Unlike Memoization, which solves only the needed subproblems, DP solves all the subproblems, because it does it bottom-up.
- Dynamic Programming on the other hand may be much more efficient because its iterative, whereas Memoization must pay for the (often significant) overhead due to recursion.

Conclusion

- Memoization is the top-down technique, and dynamic programming is a bottom-up technique.
- The key to Dynamic programming is in “intelligent” recursion (the hard part), not in filling up the table (the easy part).
- Dynamic Programming has the potential to transform exponential-time brute-force solutions into polynomial-time algorithms.
- Greed does not pay, Dynamic Programming does!