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MNS

- Matrix:
- Rectangular array of real numbers
 - m Rows by n columns
 - Named using capital letters
 - First subscript is row, second subscript is column.

$$A_{mn} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \cdots & a_{mn} \end{bmatrix}$$

Terminology:

- A matrix with m rows and n columns is called a matrix of order $m \times n$
- A square matrix is a matrix with an equal number of rows and columns. Since the number of rows & columns are the same, it is said to have order n .
- The main diagonal of a square matrix are the elements from the upper left to the lower right of the matrix.
- A row matrix is a matrix that has only one ~~one~~ row
- A column matrix is a matrix that has only one column.
- ④ A matrix with only one row or column is called a vector.

* Converting System of Linear Equations to Matrices

Definition 1: A linear equation in the variable x_1, \dots, x_n is an equation that can be written in the form

$$a_1x_1 + \dots + a_nx_n = b;$$

where a_1, \dots, a_n and b are constants, x_1, \dots, x_n are variables.

Example: The equation

$$2x_1 + x_2 - 7x_3 = \sqrt{5} \text{ is linear}$$

The equation

$$3x_1x_2 + 2x_3^2 = 1 \text{ is NOT linear.}$$

Definition 2: A system of linear equations (or a linear system) is a collection of one or more linear equations.

Example: $3x_1 + 2x_2 + 7x_3 - x_4 = 6$

$$x_1 + x_2 - x_3 + x_4 = 1$$

$$4x_1 + 3x_2 + 6x_3 = 8$$

Conversion: Each equation in the system becomes a row. Each variable in the system becomes a column. The variables are dropped and the coefficients are placed into a matrix.

~~Q~~ If the right hand side is included it's called an augmented matrix. If the right hand side isn't included it is called a coefficient matrix. page: 2

Example:

Given a system

$$\begin{aligned}x_2 - 4x_3 &= 8 \\2x_1 - 3x_2 + 2x_3 &= 1 \\5x_1 - 8x_2 + 7x_3 &= 1\end{aligned}\quad \left.\right\}$$

The matrix $\begin{bmatrix} 0 & 1 & -4 \\ 2 & -3 & 2 \\ 5 & -8 & 7 \end{bmatrix}$ is called the coefficient matrix of the system,

and $\begin{bmatrix} 0 & 1 & -4 & 8 \\ 2 & -3 & 2 & 1 \\ 5 & -8 & 7 & 1 \end{bmatrix}$ is called the augmented matrix of the system.

Elementary Row Operations: When ~~working with~~^a systems of linear equations is converted to an augmented matrix, each equation become a row. So, there are three elementary row operations which will produce a row-equivalent matrix.

1. Interchange two rows
2. Multiply a row by a non-zero constant
3. Multiply a row by a non-zero constant & add it to another row, replacing that row.

Types of Solutions:

There are three types of solutions which are possible when solving a system of linear equations.

Independent:

- Consistent
- Unique Solution
 - A row-reduced matrix has the same number of non-zero rows as variable
 - The left hand side is usually the identity matrix, but not necessarily
- There must be at least as many equations as variable to get an independent solution.

Example:

$$\left[\begin{array}{ccc|c} x & y & z & \text{rhs} \\ 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2 \end{array} \right]$$

When you convert the augmented matrix back into equation form, you get

$$x=3, y=1, \text{ and } z=2$$

Dependent:

- Consistent
- Many solutions
- Write answer in parametric form
- A row-reduced matrix has more variable than non-zero rows
- There doesn't have to be a row of zeros, but there usually is
- This could also happen when there are less equations than variables.

Example:

$$\left[\begin{array}{ccc|c} x & y & z & \text{rhs} \\ 1 & 0 & 3 & 4 \\ 0 & 1 & -2 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

The first equation will be $x + 3z = 4$

$$\Rightarrow x = 4 - 3z$$

The second equation will be $y - 2z = 3$

$$\Rightarrow y = 3 + 2z$$

Here the variables x & y depends on z .

Therefore; z will be the parameter & the solution is $x = 4 - 3t, y = 3 + 2t, z = t$

Inconsistent: No solution

A row-reduced matrix has a row on the left side, but the right hand side isn't zero.

Example:

$$\left[\begin{array}{ccc|c} x & y & z & \text{rhs} \\ 1 & 0 & 3 & 4 \\ 0 & 1 & -2 & 3 \\ 0 & 0 & 0 & 2 \end{array} \right]$$

There is no solution here. You can write that as the null set \emptyset , the empty set $\{\}$, or no solutions.

Row-Echelon Form:

A matrix is in rowechelon form when the following conditions are met.

1. If there is a row of all zeros, then it is at the bottom of the matrix.
2. The first non-zero element of any row is a one. That element is called the leading one.
3. The leading one of any row is to the right of the leading one of the previous row.

Note: The row-echelon form of a matrix is not necessarily unique.

* Gaussian Elimination places a matrix into row echelon form, and then back substitution is required to finish finding the solutions to the system.

Example:

$$\left[\begin{array}{ccc|c} 1 & -3 & 1 & 4 \\ 0 & 1 & -3 & 5 \\ 0 & 0 & 1 & -2 \end{array} \right]$$

which is in row-echelon form.

Reduce Row - Echelon Form:

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A matrix is in reduce row-echelon form when all of the conditions of row-echelon form are met and all elements above, as well as below, the leading ones are zero.

1. If there is a row of all zeros, then it is at the bottom of the matrix.
2. The first non-zero element of any row is a one. That element is called the leading one.
3. The leading one of any row is ~~equal~~ to the right of the leading one of the previous row.
4. All elements above and below a leading one are zero.

Note: The reduce row-echelon form of a matrix is unique.

- Gauss-Jordan Elimination places a matrix into reduced row-echelon form.

Example:

$$\left[\begin{array}{cccc|c} 1 & 0 & 0 & -1 & -6 \\ 0 & 1 & 0 & 1 & 5 \\ 0 & 0 & 1 & 0 & 9 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

which is in ^{reduce-row} echelon form.