



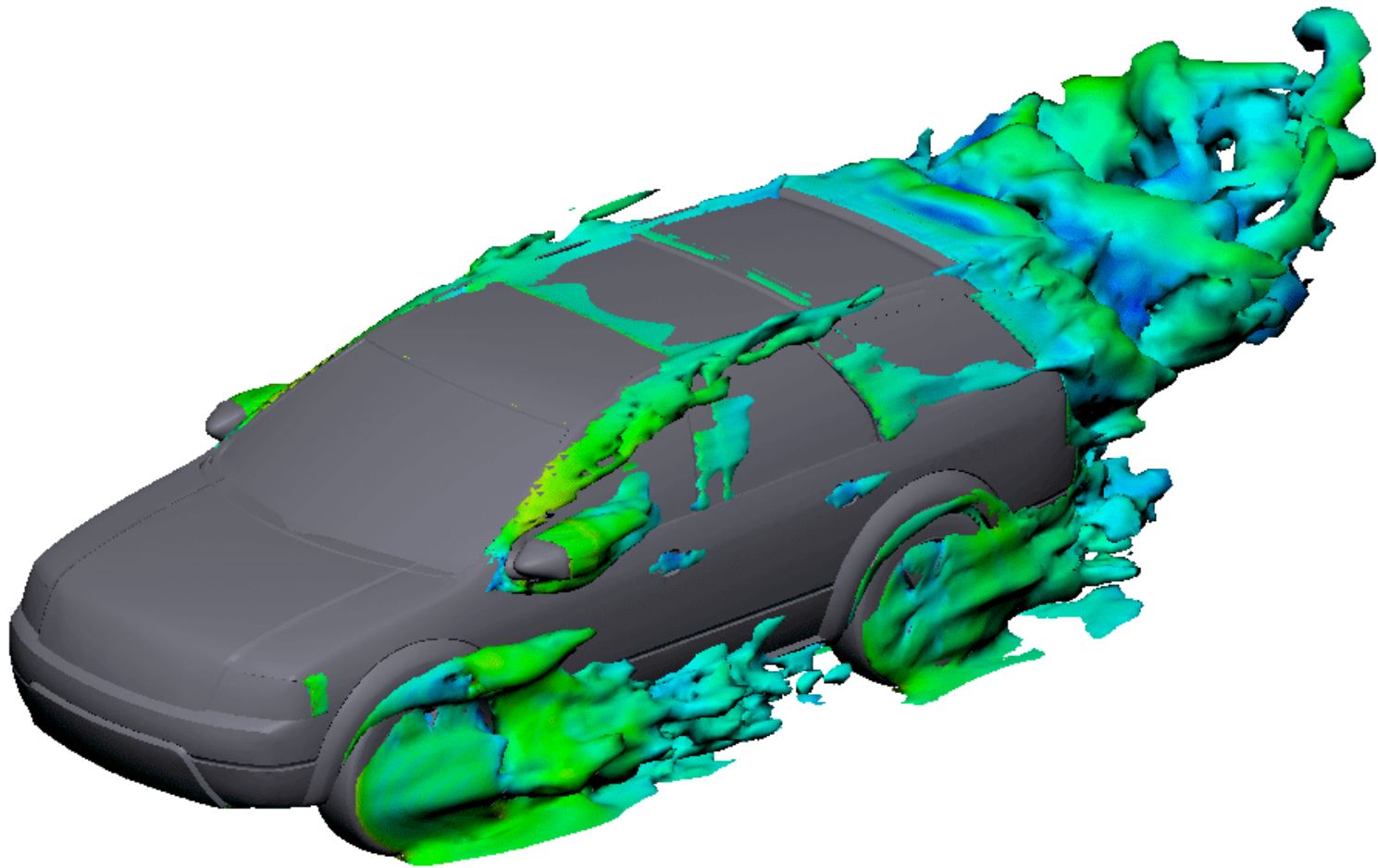
# **Lattice Boltzmann Methods for Fluid Dynamics**

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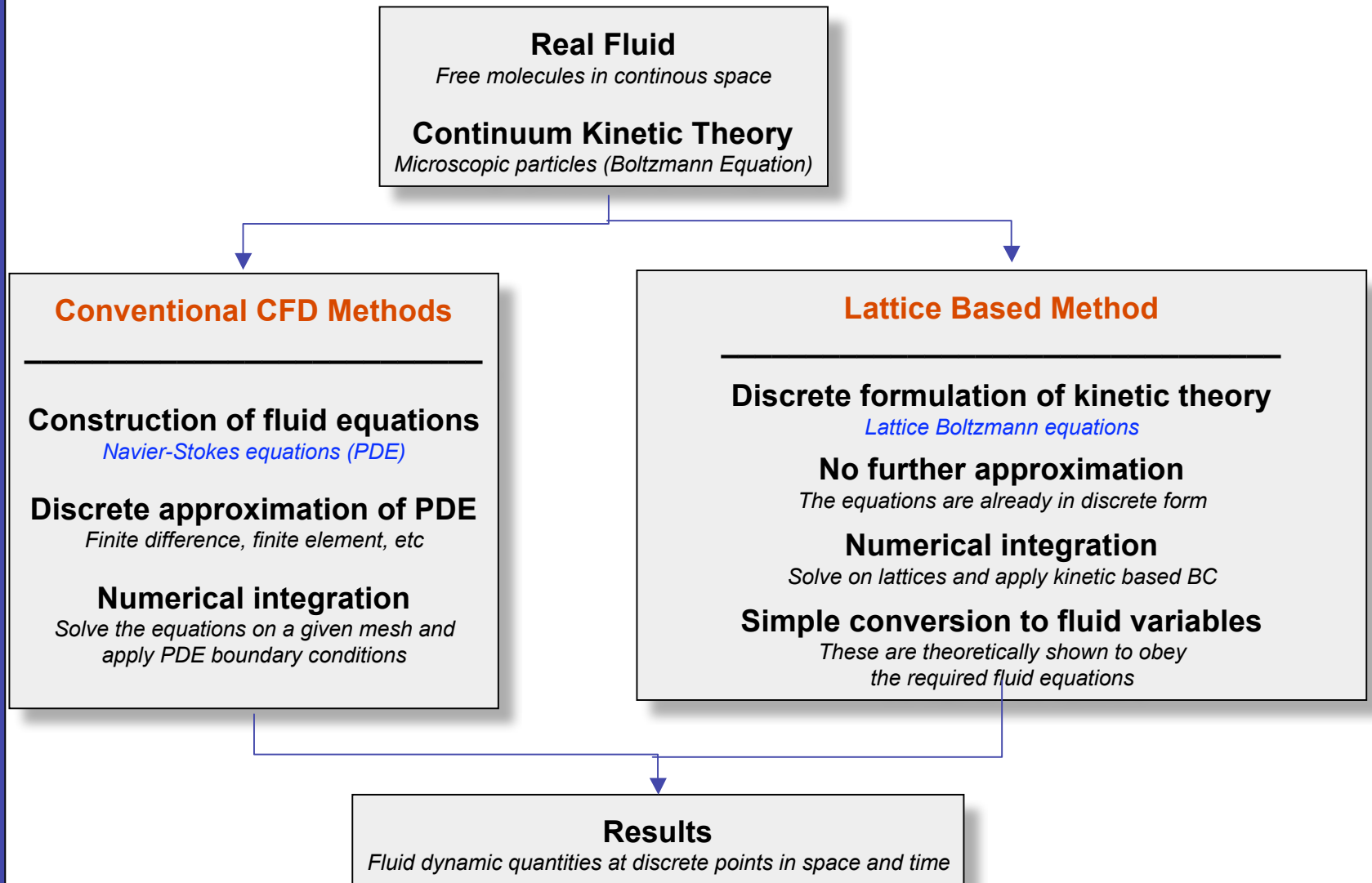
**In collaboration with Hudong Chen, Isaac  
Goldhirsch, and Rick Shock**

# **Transient flow around a car**

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# LBGK vs. CONVENTIONAL CFD



# Lattice Boltzmann (or BGK) Methods

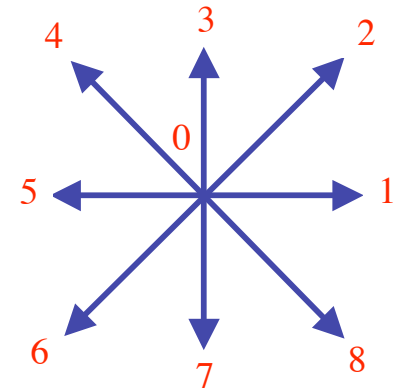
*Particles only have a finite number of discrete velocity values*

$$\vec{v} \rightarrow \{\vec{c}_i; i = 0, 1, \dots, b\}$$

$b$  in 3D  $\sim 20 - 30$

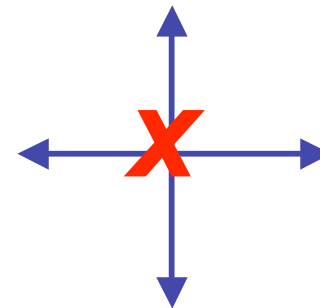
$$f(\vec{x}, \vec{v}, t) \rightarrow n_i(\vec{x}, t); i = 0, 1, \dots, b$$

Number density for particles with velocity  $\vec{c}_i$



*The choice is not arbitrary!*

- *Satisfy foundational symmetry requirements (up to required orders)*
- *Avoid spurious invariants*



# Lattice BGK method

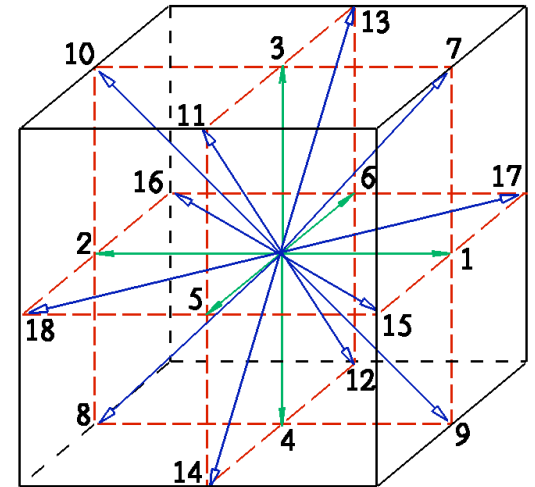
**LBGK:**

$$n_i(\vec{x} + \vec{c}_i \Delta t, t + \Delta t) = n_i(\vec{x}, t) + C_i(\vec{x}, t)$$

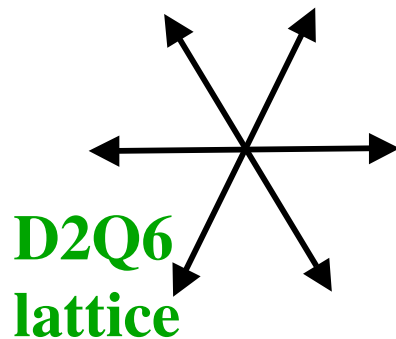
Coupled (via  $C_i$ ) algebraic difference equations

**BGK form:** 
$$C_i = -\frac{1}{\tau} (n_i - n_i^{eq})$$

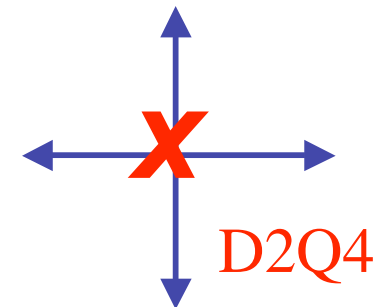
**D3Q19  
lattice**



Fluid quantities obtained via averaging over  $\vec{c}_i$  and space-time:



$$\begin{aligned}\rho &= \sum_i n_i \\ \rho \vec{u} &= \sum_i \vec{c}_i n_i \\ \rho T &= \frac{1}{D} \sum_i (\vec{c}_i - \vec{u})^2 n_i\end{aligned}$$



## Remarks on LBGK

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- Lattice BGK yields the Navier-Stokes equations
  - Chapman-Enskog asymptotic expansion in powers of Knudsen number  $\lambda/L$  or  $\tau/T \ll 1$
- Easy to compute time dependent flows
- Relaxation time  $\tau$  defines viscosity
- No need to compute pressure explicitly
- Boundary conditions are fully realizable
- Stability is ensured
- Parallel performance with arbitrary geometry

# Brief Comparison of LBGK and Conventional CFD

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## Conventional CFD

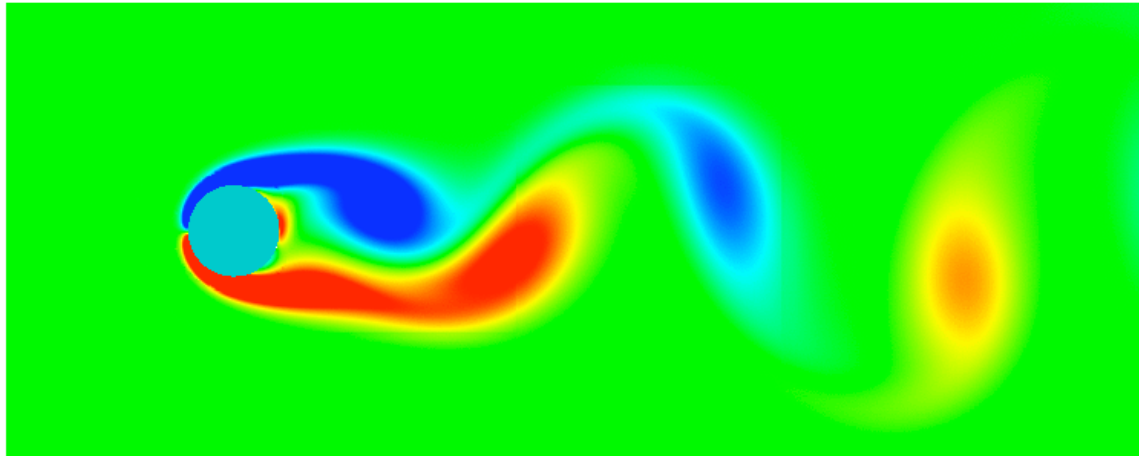
1. Nonlinear dynamic advection
2. Non-local – limited parallel performance
3. Issues with boundary conditions (BC)
4. Geometry setup slow
5. 3D time dependent flows costly to simulate
6. Complex physics (like multi-phase flows) require complex physical models

## LBGK

1. Linear advection
2. Local and fully parallel
3. BC are fully realizable for arbitrary geometry
4. Geometry setup fast
5. Time dependent flows straightforward – especially important in 3D
6. Complex physics (like multi-phase flows) involve simple physical models

# 2D Cylinder

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# 2D Cylinder

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$Re = 100$

	$Re = 100$	
	Cd	St
Exp.	...	0.164 (Williamson)
Braza et al.	1.364	0.16
Liu et al.	1.350	0.164
Calhoun	1.330	0.175
Henderson	1.35	0.167
PowerFLOW 4.0beta3	1.336	0.164

Braza et al. 1986, Finite volume with ADI (p-v NS), 2<sup>nd</sup> order accurate

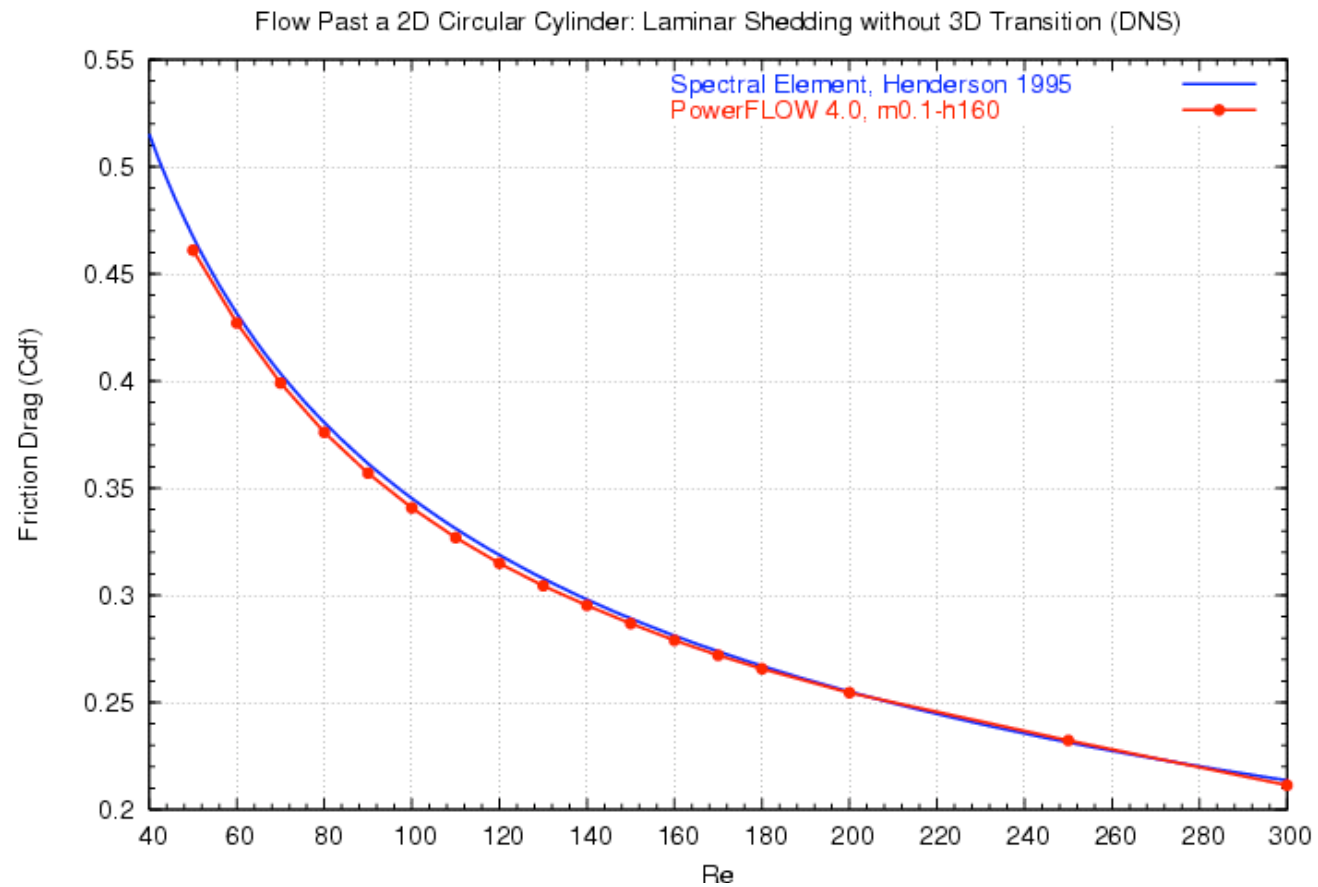
Liu et al. 1997, Finite volume with AC (p-v NS), preconditioned multigrid 2<sup>nd</sup> order central difference

Calhoun 2002, Cell centered Cartesian grid (s-v NS)

Henderson 1995, Spectral Element (NS)

# 2D Cylinder

## Friction Drag



# How do you derive N-S from LBGK?

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- Chapman-Enskog (moment expansion) procedure in powers of Knudsen number  $\lambda/L$
- Navier-Stokes equations are independent of orientation of coordinate system
- BUT – lattice BGK is highly anisotropic
- REMARKABLE FACT – isotropy of velocity moments only up to a fixed finite order are required

# Isothermal Navier-Stokes equations at low Mach numbers

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- Density/momentum

$$\rho(\mathbf{x}, t) \equiv \sum_{\alpha=1}^b f_{\alpha}(\mathbf{x}, t), \quad \rho \mathbf{u}(\mathbf{x}, t) \equiv \sum_{\alpha=1}^b \mathbf{c}_{\alpha} f_{\alpha}(\mathbf{x}, t)$$

- Momentum flux tensor

$$P_{ij}(\mathbf{x}, t) \equiv \sum_{\alpha=1}^b c_{\alpha,i} c_{\alpha,j} f_{\alpha}(\mathbf{x}, t)$$

- Energy flux tensor

$$Q_{ijk}(\mathbf{x}, t) \equiv \sum_{\alpha=1}^b c_{\alpha,i} c_{\alpha,j} c_{\alpha,k} f_{\alpha}(\mathbf{x}, t)$$

- **Navier-Stokes requires isotropy of velocity moments only up to 4<sup>th</sup> order**




# High-order models

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- Non-isothermal low Mach number Navier-Stokes equations requires velocity moment isotropy up to 6<sup>th</sup> order
- Other physically relevant models require even higher-order velocity moment isotropy, further restricting the discrete velocity set used in lattice BGK
- For example, non-isothermal flow with Burnett corrections requires 8<sup>th</sup> order isotropy

# Relation between rotational symmetry and order of moment isotropy in 2D

- $b$  velocities  $C = \{\mathbf{c}_\alpha = (\cos(\frac{2\pi\alpha}{b}), \sin(\frac{2\pi\alpha}{b})); \alpha = 0, \dots, b-1\}$   
is invariant under rotations by multiples of  $2\pi/b$
- Isotropy of the  $n^{th}$  order basis moment tensor  

$$\mathbf{M}^{(n)} \equiv \sum_{\alpha}^b \mathbf{c}_\alpha \mathbf{c}_\alpha \mathbf{c}_\alpha \mathbf{c}_\alpha$$
  
 requires that  $\sum_{\alpha}^b (\mathbf{c}_\alpha \cdot \hat{\mathbf{v}})^n = A$  where  $A$  is a constant and  $\hat{\mathbf{v}} = (\cos \theta, \sin \theta)$  is any unit vector
- This requires that  $h_b^{(n)}(\theta) \equiv \sum_{\alpha=0}^{b-1} \cos^n(\frac{2\pi\alpha}{b} - \theta)$  be independent of  $\theta$ , which holds if  $\sum_{\alpha=0}^{b-1} e^{i\frac{2\pi\alpha}{b}(2j-n)} = 0$   
ie  $(2j-n)/b$  is not a nonzero integer for  $j=0, \dots, n$
- CONCLUSION: Isotropy for so  $n \leq b-2$   
hexagonal lattice gives 4<sup>th</sup> order isotropy, etc.

- $n^{th}$  order basis moment tensor

$$\mathbf{M}^{(n)} = \sum_{\alpha=1}^b w_\alpha \text{ } \begin{array}{c} \bullet \\ \swarrow \searrow \\ \bullet \end{array} \otimes \begin{array}{c} \bullet \\ \swarrow \searrow \\ \bullet \end{array} \otimes \dots \otimes \begin{array}{c} \bullet \\ \swarrow \searrow \\ \bullet \end{array}$$

- Isotropy requires

$$M_{\substack{\begin{array}{c} \text{\textcolor{blue}{i}} \\ \text{\textcolor{blue}{k}} \end{array}}^{\text{\textcolor{blue}{n}}} = \frac{(n-1)c^2}{D+n-2} M_{\substack{\begin{array}{c} \text{\textcolor{blue}{i}} \\ \text{\textcolor{blue}{k}} \end{array}}^{\text{\textcolor{blue}{n-2}}}$$

$$M_{\begin{array}{c} \text{\tiny $\nwarrow$} \\ i \\ \text{\tiny $\nearrow$} \\ n-2 \end{array}}^{(n)} = \frac{(n-3)c^2}{D+n-2} M_{\begin{array}{c} \text{\tiny $\nwarrow$} \\ i \\ \text{\tiny $\nearrow$} \\ n-4 \end{array}}^{(n-2)}$$

$$M_{\substack{\begin{array}{c} \text{---} \text{---} \text{---} \\ \text{---} \text{---} \text{---} \\ \text{---} \text{---} \text{---} \end{array}}_{n-4}}^{(n)} = \frac{(n-5)c^2}{D+n-2} M_{\substack{\begin{array}{c} \text{---} \text{---} \text{---} \\ \text{---} \text{---} \text{---} \\ \text{---} \text{---} \text{---} \end{array}}_{n-6}}^{(n-2)}$$

and so on

# Generation of $N^{\text{th}}$ order isotropic lattices

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- Using these relations an  $N^{\text{th}}$  order isotropic lattice can be constructed by a union of  $(N-2)^{\text{nd}}$  order isotropic lattices and its rotated realizations
- Example: 6<sup>th</sup> order set with 59 velocities

1	(0,0,0)	12	$\{(\pm 1, \pm 1, 0), (\pm 1, 0, \pm 1), (0, \pm 1, \pm 1)\}$
6	$\{(\pm 1, 0, 0), (0, \pm 1, 0), (0, 0, \pm 1)\}$	8	$\{(\pm 1, \pm 1, \pm 1)\}$
6	$\{(\pm 2, 0, 0)\}$	12	$\{(\pm 2, \pm 2, 0), (\pm 2, 0, \pm 2), (0, \pm 2, \pm 2)\}$
8	$\{(\pm 2, \pm 2, \pm 2)\}$	6	$\{(\pm 4, 0, 0), (0, \pm 4, 0), (0, 0, \pm 4)\}$



# Boltzmann- $\tau$ Turbulence Modeling

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- Turbulence modeled *via* a modified relaxation time  $\tau$

$$\frac{\partial f}{\partial t} = -\frac{1}{\tau} (f - f^{eq})$$

$$\frac{1}{\tau} = \frac{1}{\tau_{turb}} + \frac{1}{\tau_{shear}} + \frac{1}{\tau_{buoyancy}} + \frac{1}{\tau_{swirl}} + \dots$$

## Advantages of Boltzmann- $\tau$ Method - I

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- Realizability of the turbulence model
- Boltzmann- $\tau$  has guaranteed realizability
  - *Requires only  $\tau_{\text{turb}} > 0$*
  - *Stable numerical results*
  - *Positive eddy viscosity*
- Navier-Stokes-based turbulence models can have significant difficulties with realizability
  - *Divergent turbulence quantities*
  - *Negative eddy viscosities, ...*

## Advantages of Boltzmann- $\tau$ Method - II

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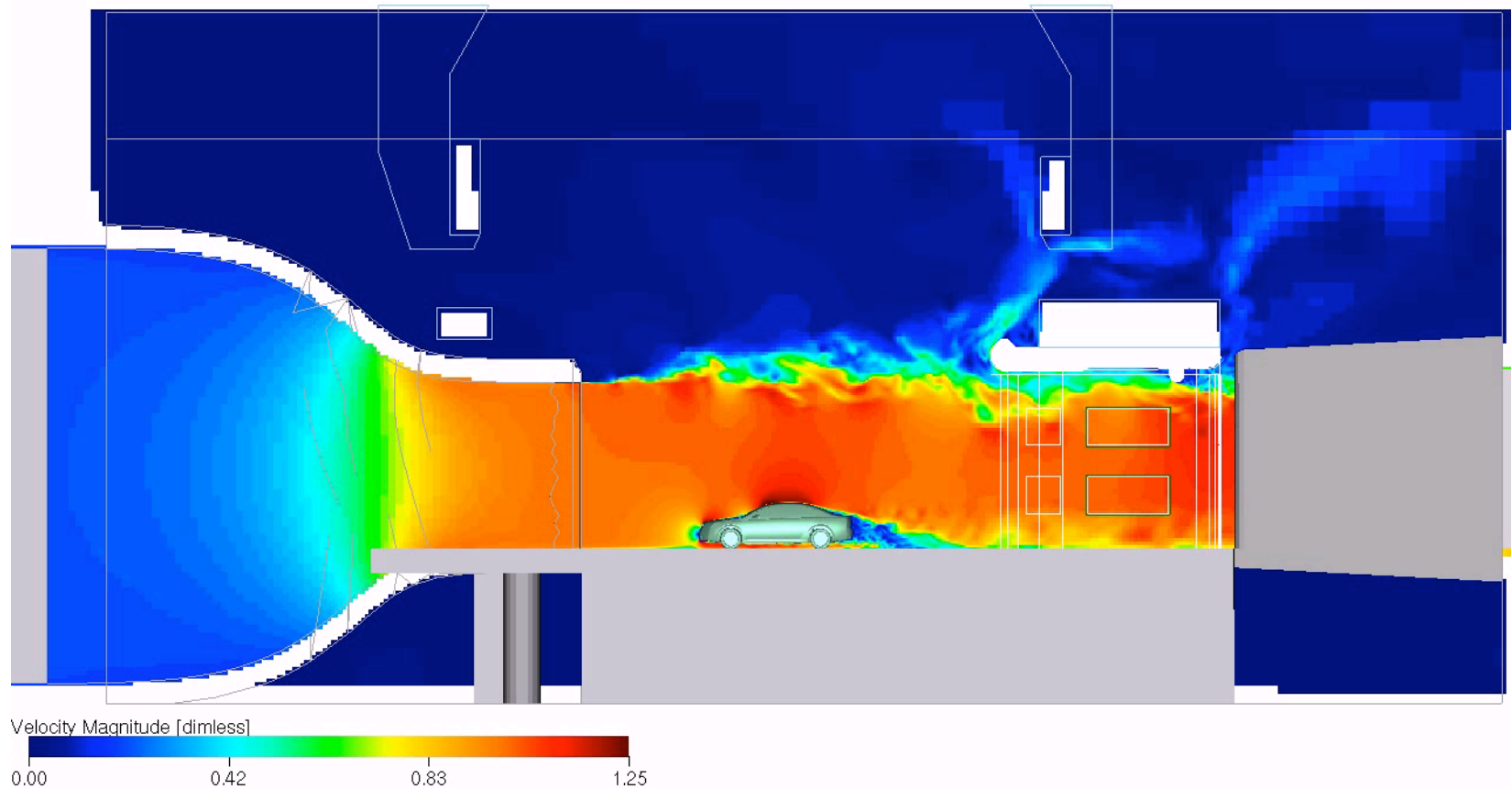
- With the BGK model in terms of space, time, and velocity as independent coordinates, simple approximations (like  $\tau$  models) may be extraordinarily complex in fluid (velocity/pressure) variables
- Fluid velocity/pressure are projections of the BGK variables onto a lower-dimensional space
- In contrast to higher-order Chapman-Enskog projections, the BCs on BGK are well defined and easy to implement

# An Opel in a Wind Tunnel

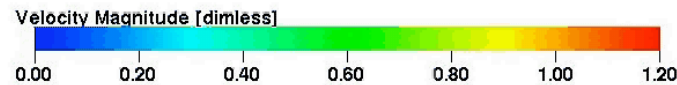
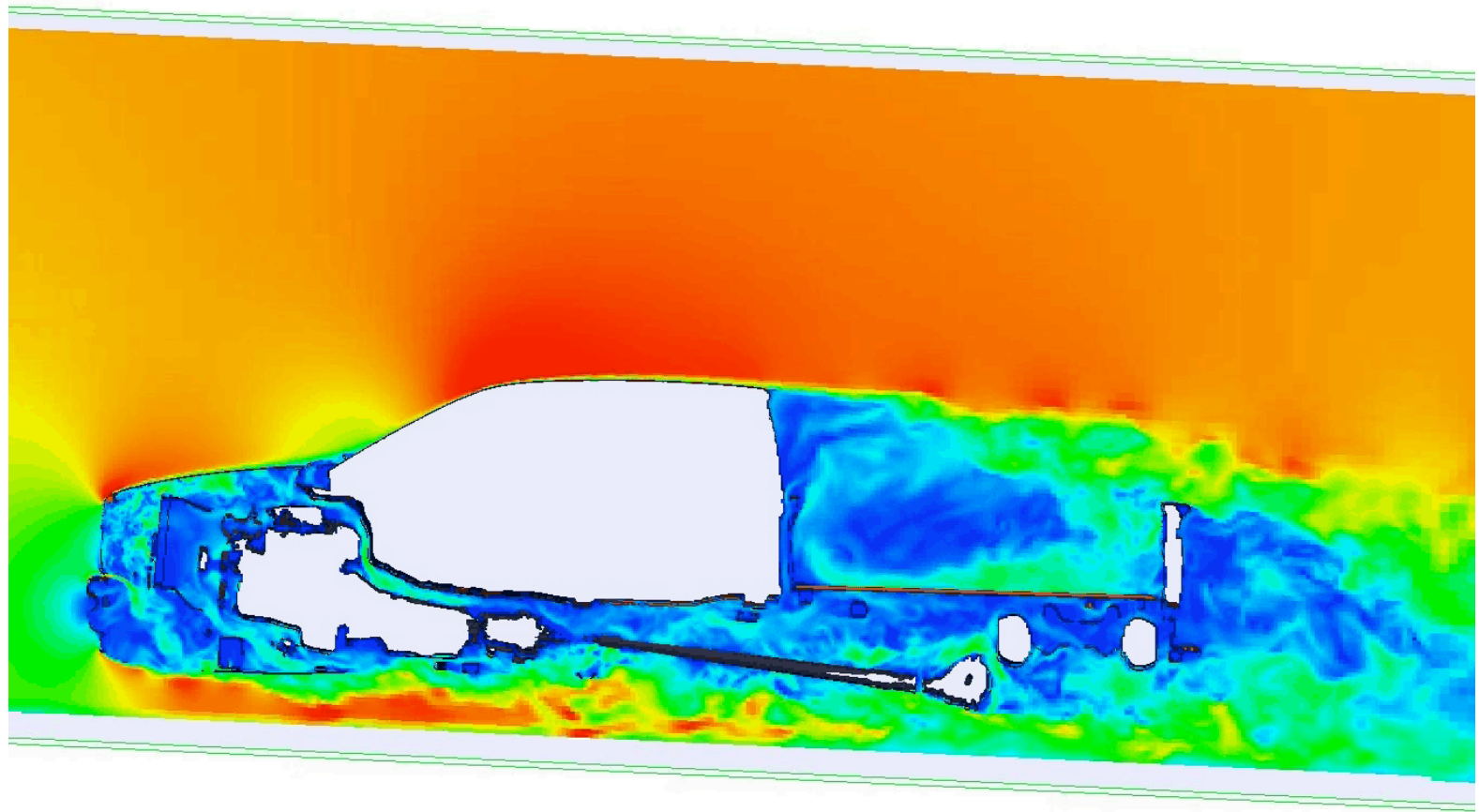
## Centerline Velocity at 140 km/h

DIVK-Opel-Fine

Frame = 000, Time = 0.00048 sec



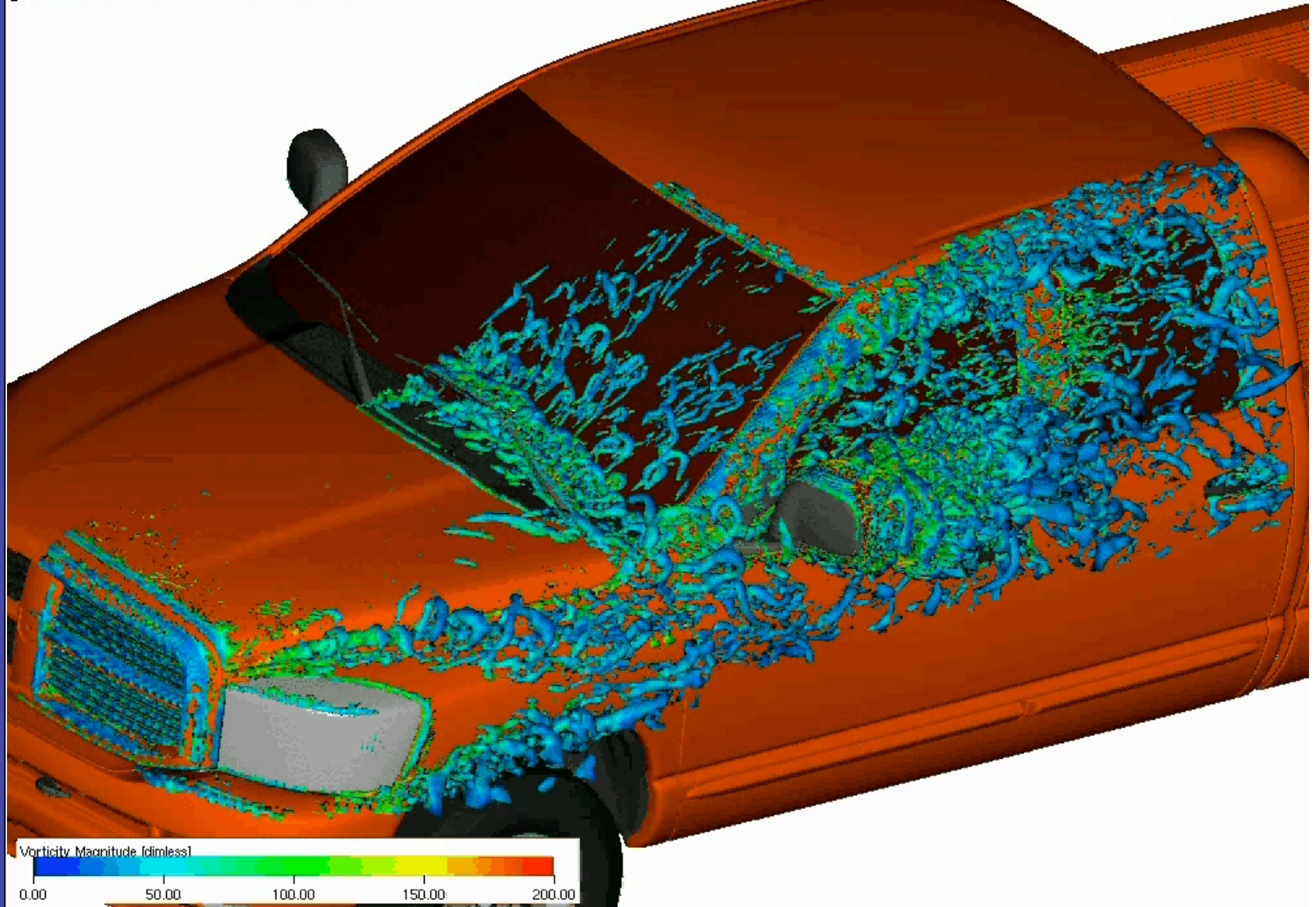
# Dodge RAM – Exterior/underhood/ under-carriage flow – centerline velocity



# Dodge RAM – Acoustic Impact of Headlight/Hood Design on A-Pillar and Door Seals:

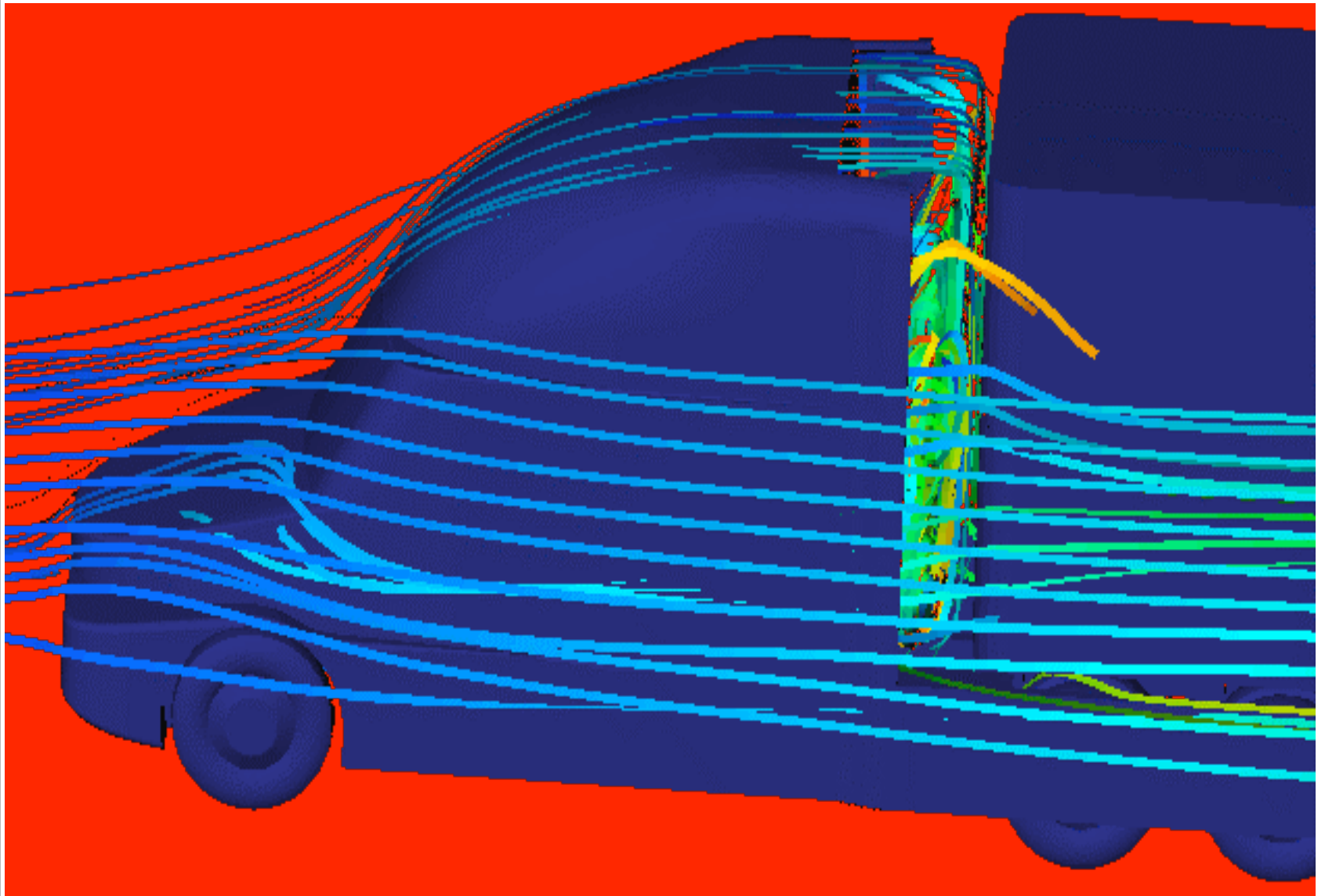
Design on A-Pillar and Door Seals:  $\lambda_2 = |\omega^2| - |S^2|$

PR: Iso-surfaces of lambda2 = -200

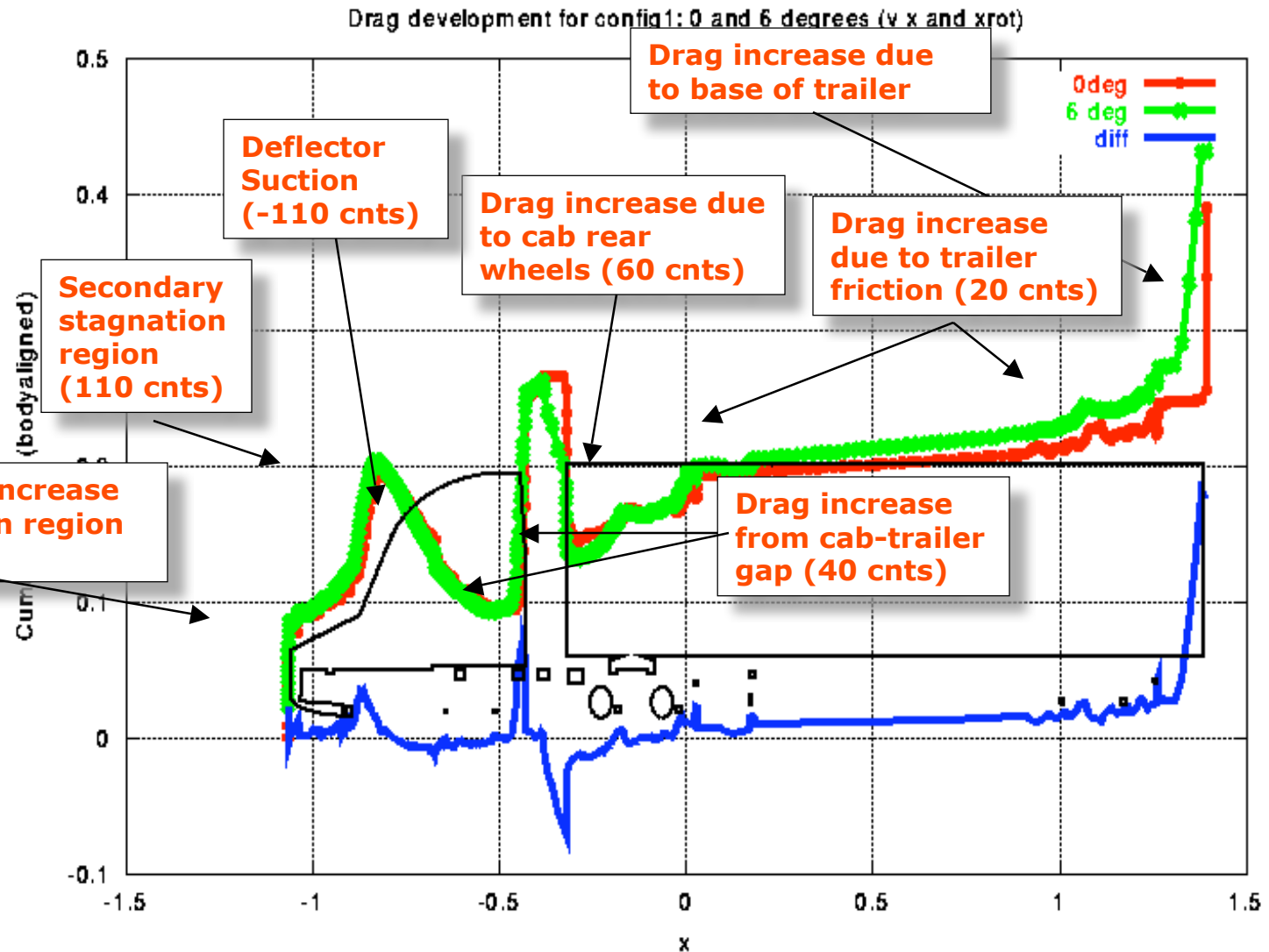




# 3D Streamlines of Flow Past a Large Truck



# Drag Development





# Conclusions

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- **Lattice BGK allows straightforward mix of complex fluids, complex physics, and complex geometries**
- **Appropriate lattice structures can be derived to assure accurate and efficient flow computations, even with turbulence and other complex physics included**