

CSC 411
Design and Analysis of Algorithms

Chapter 5 Divide and Conquer
- Part 1

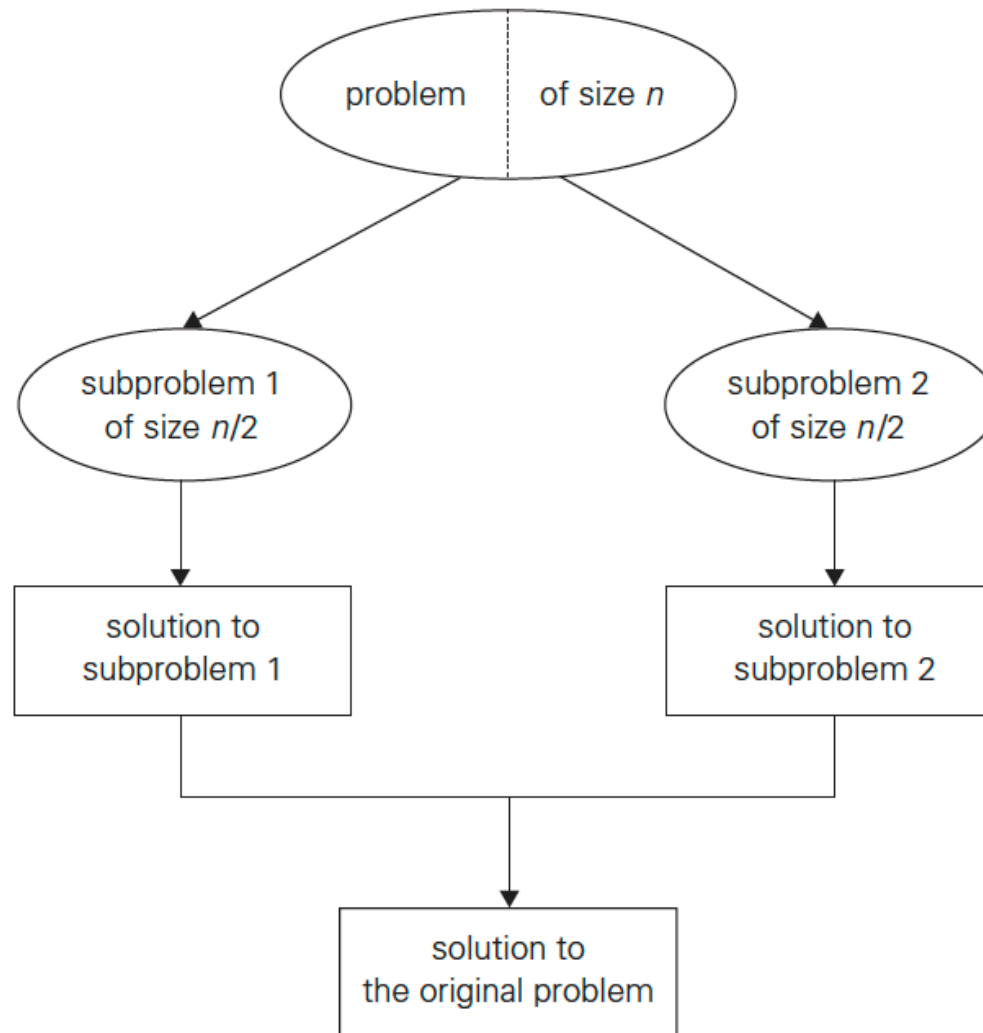
Instructor: Minhee Jun

Divide-and-Conquer

The most-well known algorithm design strategy:

1. A problem is divided into several subproblems of the same type
 - ideally of about equal size.
2. The subproblems are solved .
 - typically recursively, though sometimes a different algorithm is employed, especially when subproblems become small enough.
3. The solutions to the subproblems are combined to get a solution to the original problem

Divide-and-Conquer Technique



General Divide-and-Conquer Recurrence

$$T(n) = aT(n/b) + f(n) \quad \text{where } f(n) \in \Theta(n^d), \quad d \geq 0$$

- $aT(n/b)$: sample size n is divided into b instances of size n/b , with a of them needing to be solved.
- $f(n)$: a function that accounts for the time spent on dividing the problem into smaller ones and on combining their solutions.

General Divide-and-Conquer Recurrence

$$T(n) = aT(n/b) + f(n),$$

Master Theorem If $f(n) \in \Theta(n^d)$ where $d \geq 0$ in recurrence (5.1), then

$$T(n) \in \begin{cases} \Theta(n^d) & \text{if } a < b^d, \\ \Theta(n^d \log n) & \text{if } a = b^d, \\ \Theta(n^{\log_b a}) & \text{if } a > b^d. \end{cases}$$

Analogous results hold for the O and Ω notations, too.

- Example: $T(n) = 2T(n/2) + 1$?
 - $a = 2, b = 2, d = 0 \rightarrow T(n) \in \Theta(n)$

See Appendix B
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Exercise 3.1-5

5. Find the order of growth for solutions of the following recurrences.
- a. $T(n) = 4T(n/2) + n, T(1) = 1$
 - b. $T(n) = 4T(n/2) + n^2, T(1) = 1$
 - c. $T(n) = 4T(n/2) + n^3, T(1) = 1$

General Divide-and-Conquer Recurrence

$$T(n) = aT(n/b) + f(n),$$
$$f(n) \in \Theta(n^d)$$

- Master Theorem:

- If $a < b^d$, $T(n) \in \Theta(n^d)$
- If $a = b^d$, $T(n) \in \Theta(n^d \log_b n)$
- If $a > b^d$, $T(n) \in \Theta(n^{\log_b a})$

A. $T(n) = 4T(n/2) + n$?

• $a = 4, b = 2, d = 1 \rightarrow$ case 3 $\Rightarrow T(n) \in \Theta(n^2)$

B. $T(n) = 4T(n/2) + n^2$?

• $a = 4, b = 2, d = 2 \rightarrow$ case 2 $\Rightarrow T(n) \in \Theta(n^2 \log_2 n)$

C. $T(n) = 4T(n/2) + n^3$?

• $a = 4, b = 2, d = 3 \rightarrow$ case 1 $\Rightarrow T(n) \in \Theta(n^3)$

Divide-and-Conquer Examples

- Sorting: mergesort and quicksort (5.1 & 5.2)
- Binary tree traversals (5.3)
- Multiplication of large integers and Matrix multiplication: Strassen's algorithm (5.4)
- Closest-pair and convex-hull algorithms (5.5)

5.1 Mergesort

- Split array $A[0..n-1]$ in two about equal halves and make copies of each half in arrays B and C
- Sort arrays B and C recursively
- **Merge** sorted arrays B and C into array A as follows:
 - Repeat the following until no elements remain in one of the arrays:
 - compare the first elements in the remaining unprocessed portions of the arrays
 - copy the smaller of the two into A, while incrementing the index indicating the unprocessed portion of that array
 - Once all elements in one of the arrays are processed, copy the remaining unprocessed elements from the other array into A.

Pseudocode of Mergesort

ALGORITHM *Mergesort*($A[0..n - 1]$)

//Sorts array $A[0..n - 1]$ by recursive mergesort

//Input: An array $A[0..n - 1]$ of orderable elements

//Output: Array $A[0..n - 1]$ sorted in nondecreasing order

if $n > 1$

 copy $A[0..\lfloor n/2 \rfloor - 1]$ to $B[0..\lfloor n/2 \rfloor - 1]$

 copy $A[\lfloor n/2 \rfloor..n - 1]$ to $C[0..\lceil n/2 \rceil - 1]$

Mergesort($B[0..\lfloor n/2 \rfloor - 1]$)

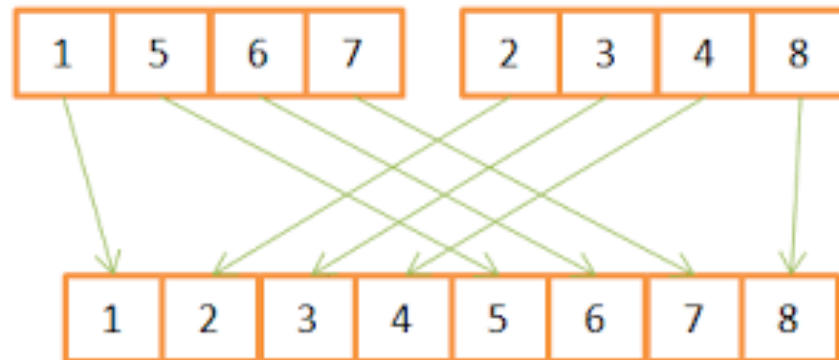
Mergesort($C[0..\lceil n/2 \rceil - 1]$)

Merge(B, C, A) //see below

$$T(n) = T(n/2) + T(n/2) + T(\text{merge})$$

Merging Two Sorted Arrays

- To merge two sorted arrays into a third (sorted) array, repeatedly **compare the two least elements** and copy the smaller of the two onto the third array.



of comparison:

7 in this example

(1, 2)

(5, 2)

(5, 3)

(5, 4)

(5, 8)

(6, 8)

(7, 8)

Pseudocode of Merge

ALGORITHM *Merge*($B[0..p-1]$, $C[0..q-1]$, $A[0..p+q-1]$)

 //Merges two sorted arrays into one sorted array

 //Input: Arrays $B[0..p-1]$ and $C[0..q-1]$ both sorted

 //Output: Sorted array $A[0..p+q-1]$ of the elements of B and C

$i \leftarrow 0$; $j \leftarrow 0$; $k \leftarrow 0$

while $i < p$ **and** $j < q$ **do**

if $B[i] \leq C[j]$

$A[k] \leftarrow B[i]$; $i \leftarrow i + 1$

else $A[k] \leftarrow C[j]$; $j \leftarrow j + 1$

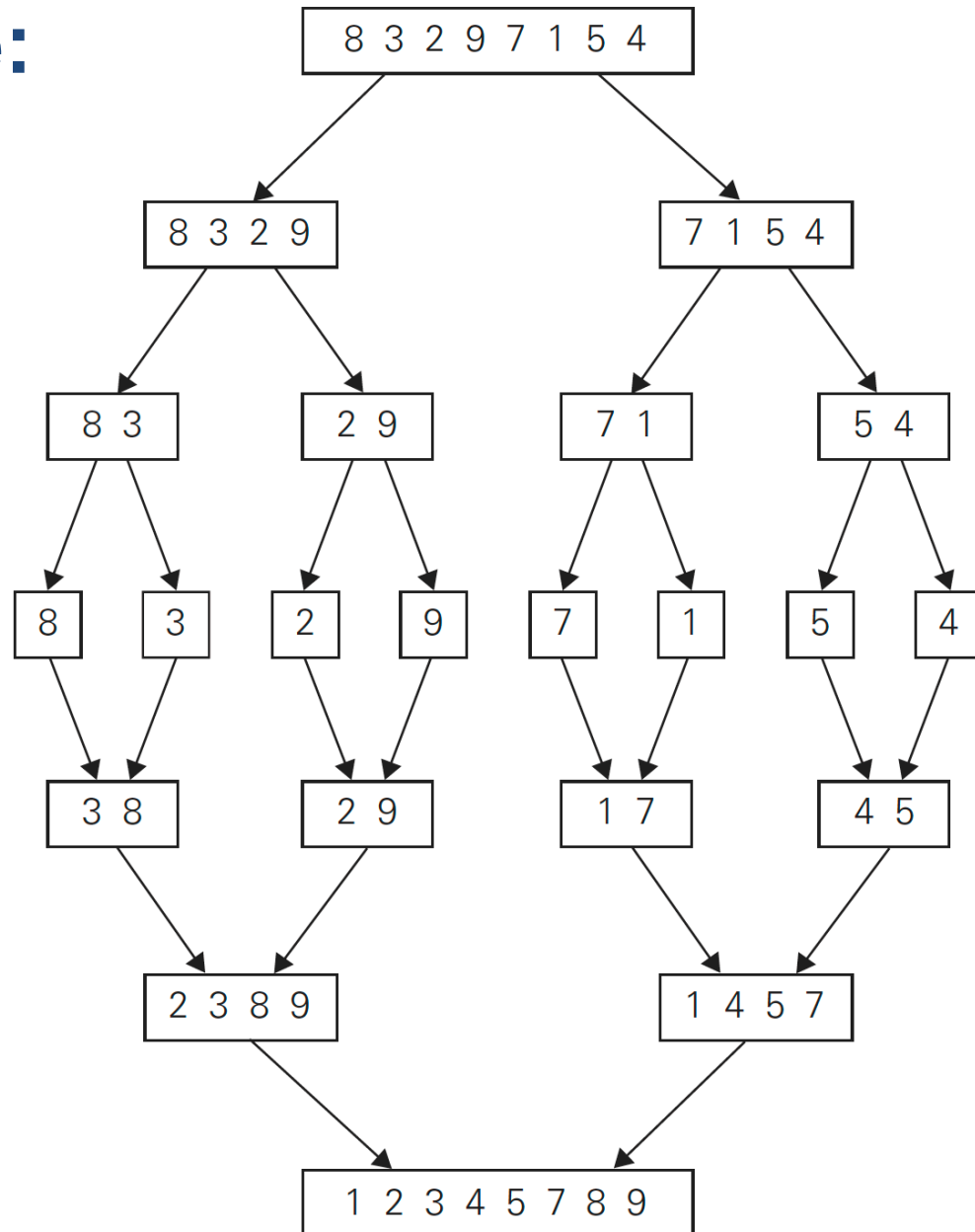
$k \leftarrow k + 1$

if $i = p$

 copy $C[j..q-1]$ to $A[k..p+q-1]$

else copy $B[i..p-1]$ to $A[k..p+q-1]$

Example:



Analysis of Mergesort

- How efficient is mergesort?

$$C(n) = 2C(n/2) + C_{merge}(n) \quad \text{for } n > 1, \quad C(1) = 0.$$

- Worst case:
 - neither of the two arrays becomes empty before the other one contains just one element (e.g., smaller elements may come from the alternating arrays).

$$C_{worst}(n) = 2C_{worst}(n/2) + n - 1 \quad \text{for } n > 1, \quad C_{worst}(1) = 0.$$

- Master's Theorem

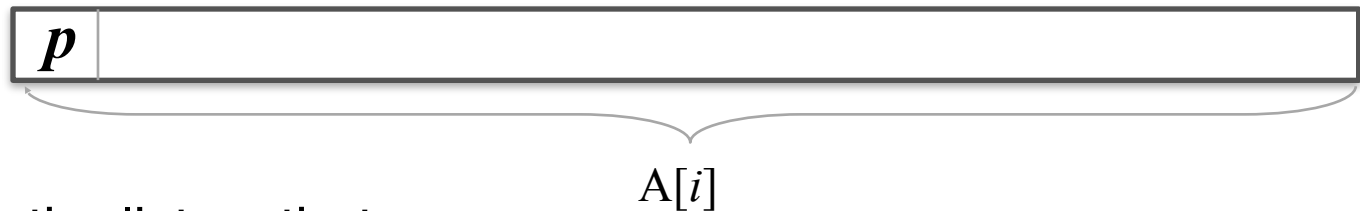
$$C_{worst}(n) \in \Theta(n \log n)$$

Exercise 5.1-6

6. Apply mergesort to sort the list *E, X, A, M, P, L, E* in alphabetical order.

5.2 Quicksort

- Select a **pivot** (partitioning element) – here, the first element



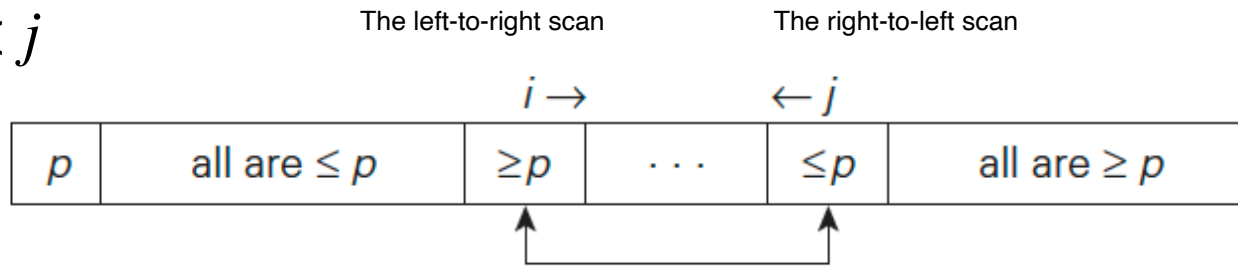
- Rearrange the list so that

$$\underbrace{A[0] \dots A[s-1]}_{\text{all are } \leq A[s]} \quad A[s] \quad \underbrace{A[s+1] \dots A[n-1]}_{\text{all are } \geq A[s]}$$

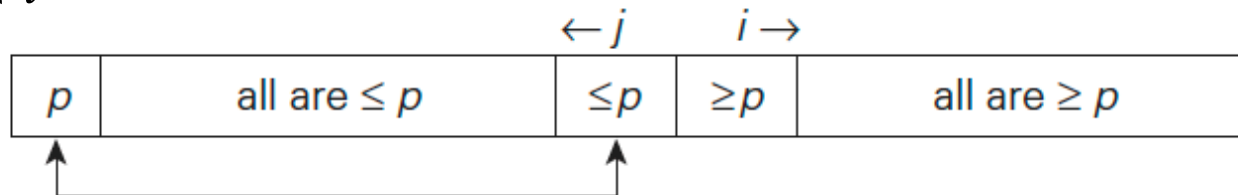
- all the elements in the first s positions are smaller than or equal to the pivot
- all the elements in the remaining $n - s$ positions are larger than or equal to the pivot
- Sort the two subarrays recursively

5.2 Quicksort

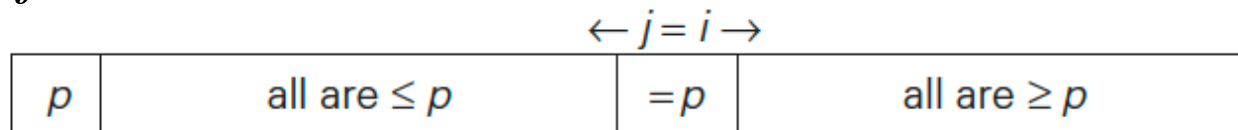
- $i < j$



- $j < i$



- $i = j$



Pseudocode of Partitioning Algorithm

ALGORITHM *HoarePartition*($A[l..r]$)

//Partitions a subarray by Hoare's algorithm, using the first element

// as a pivot

//Input: Subarray of array $A[0..n - 1]$, defined by its left and right

// indices l and r ($l < r$)

//Output: Partition of $A[l..r]$, with the split position returned as

// this function's value

$p \leftarrow A[l]$

$i \leftarrow l; j \leftarrow r + 1$

repeat

repeat $i \leftarrow i + 1$ **until** $A[i] \geq p$

repeat $j \leftarrow j - 1$ **until** $A[j] \leq p$

 swap($A[i]$, $A[j]$)

until $i \geq j$

swap($A[i]$, $A[j]$) //undo last swap when $i \geq j$

swap($A[l]$, $A[j]$)

return j

Pseudocode of Quicksort

ALGORITHM *Quicksort*($A[l..r]$)

//Sorts a subarray by quicksort

//Input: Subarray of array $A[0..n - 1]$, defined by its left and right

// indices l and r

//Output: Subarray $A[l..r]$ sorted in nondecreasing order

if $l < r$

$s \leftarrow \text{Partition}(A[l..r])$ // s is a split position

Quicksort($A[l..s - 1]$)

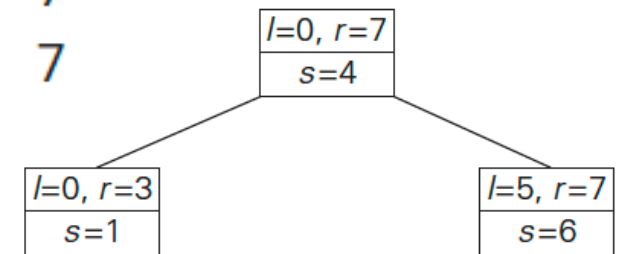
Quicksort($A[s + 1..r]$)

What is the best case?

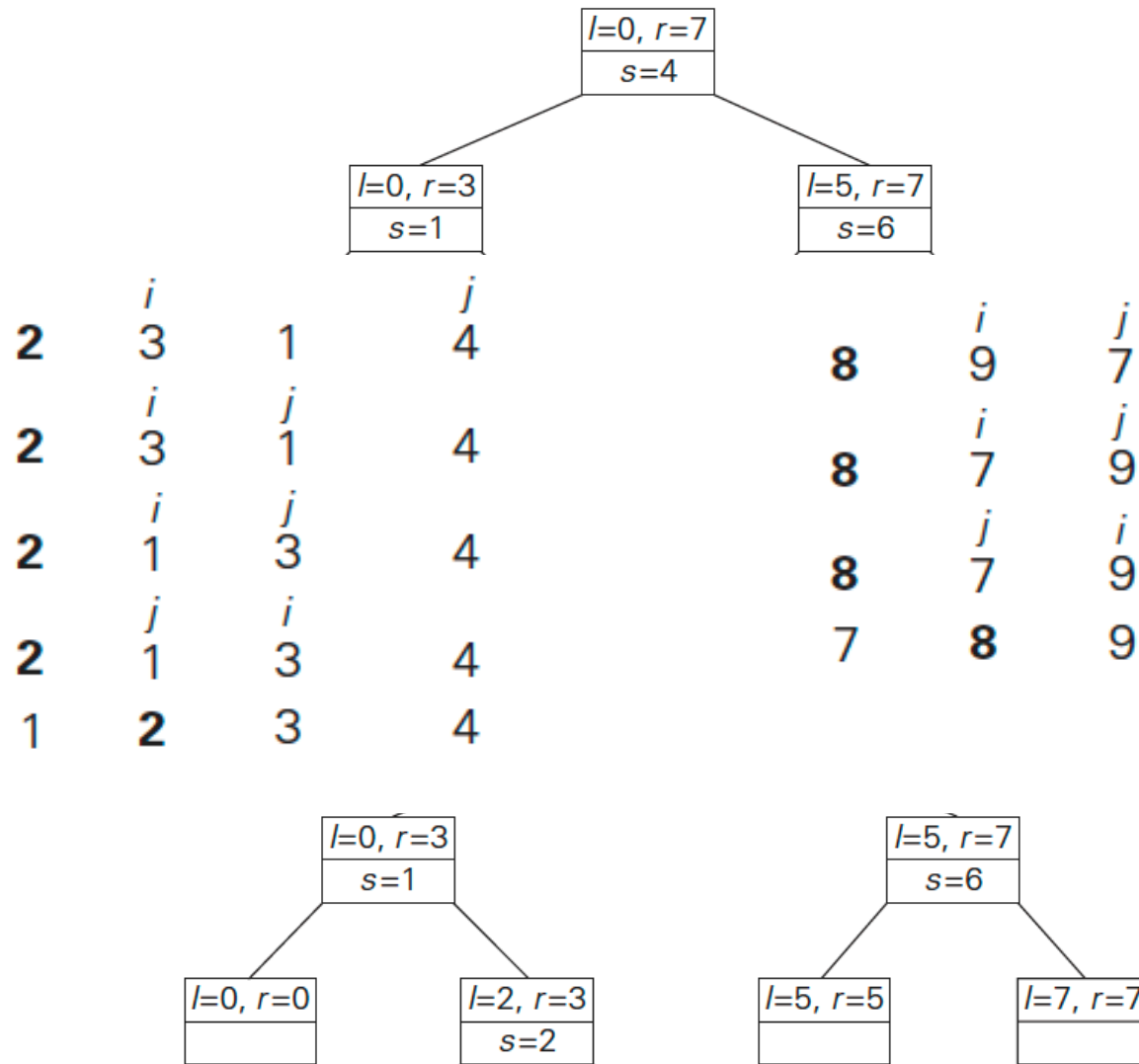
What is the worst case?

Quicksort Example

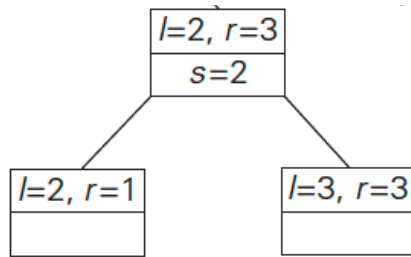
0	1	2	3	4	5	6	7
	<i>i</i>						<i>j</i>
5	3	1	9	8	2	4	7
5	3	1	<i>i</i>	8	2	<i>j</i>	7
5	3	1	4	8	2	9	7
5	3	1	4	<i>i</i>	<i>j</i>	9	7
5	3	1	4	2	8	9	7
5	3	1	4	<i>j</i>	<i>i</i>	9	7
2	3	1	4	5	8	9	7



Quicksort Example

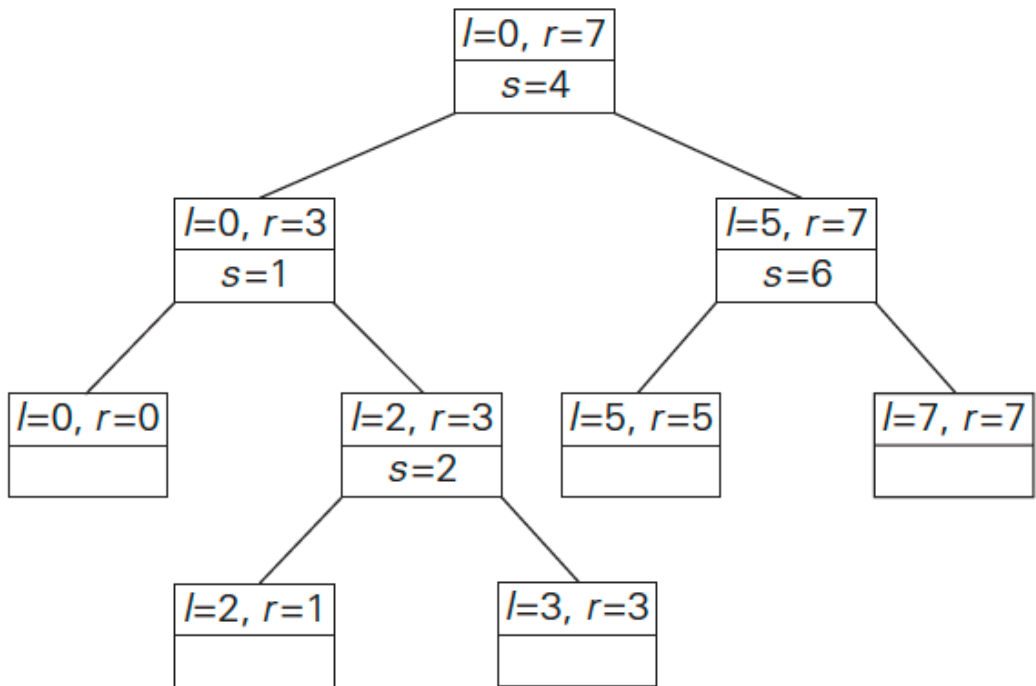


Quicksort Example



3
j
3

ij
 4
i
 4
 4



Quicksort Example

5 3 1 9 8 2 4 7
↓
pivot

2 3 1 4 5 8 9 7

the best case

1 3 5 9 8 2 4 7
↓
pivot

1 3 5 9 8 2 4 7

the worse case

Analysis of Quicksort

- Best case: split in the middle - $\Theta(n \log n)$

$$C_{best}(n) = 2C_{best}(n/2) + n \quad \text{for } n > 1, \quad C_{best}(1) = 0.$$

$$C_{best}(n) \in \Theta(n \log_2 n);$$

- Worst case: sorted array! - $\Theta(n^2)$

$$C_{worst}(n) = (n+1) + n + \cdots + 3 = \frac{(n+1)(n+2)}{2} - 3 \in \Theta(n^2).$$

- Average case: random arrays - $\Theta(n \log n)$

$$C_{avg}(n) = \frac{1}{n} \sum_{s=0}^{n-1} [(n+1) + C_{avg}(s) + C_{avg}(n-1-s)] \quad \text{for } n > 1,$$

$$C_{avg}(0) = 0, \quad C_{avg}(1) = 0.$$

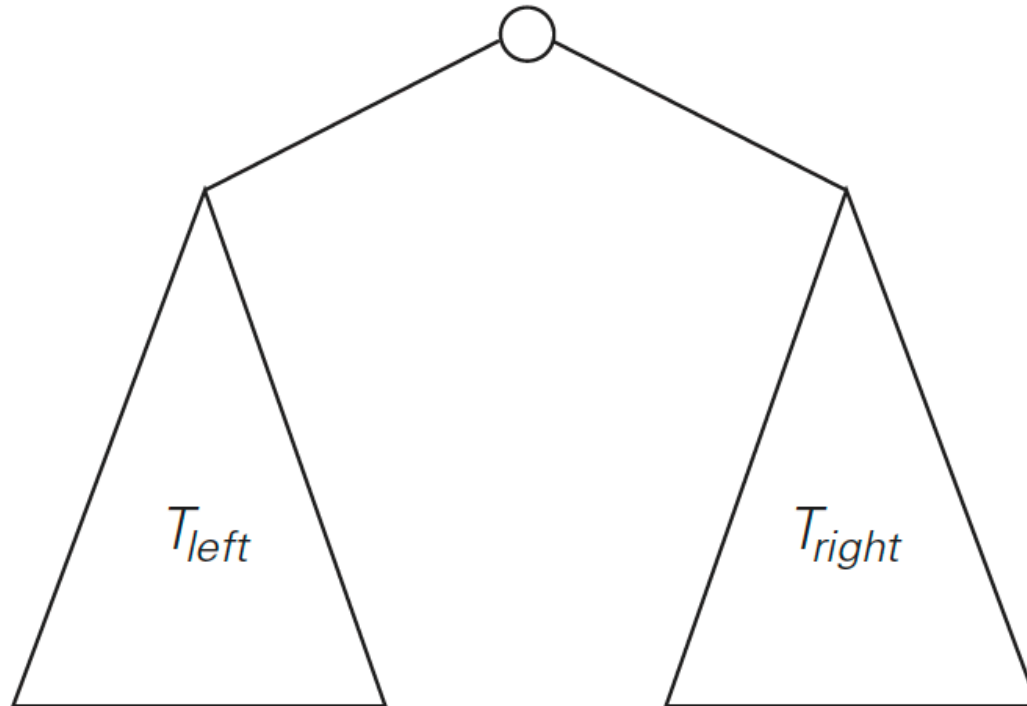
$$C_{avg}(n) \approx 2n \ln n \approx 1.39n \log_2 n.$$

Exercise 5.2-1

1. Apply quicksort to sort the list *E, X, A, M, P, L, E* in alphabetical order. Draw the tree of the recursive calls made.

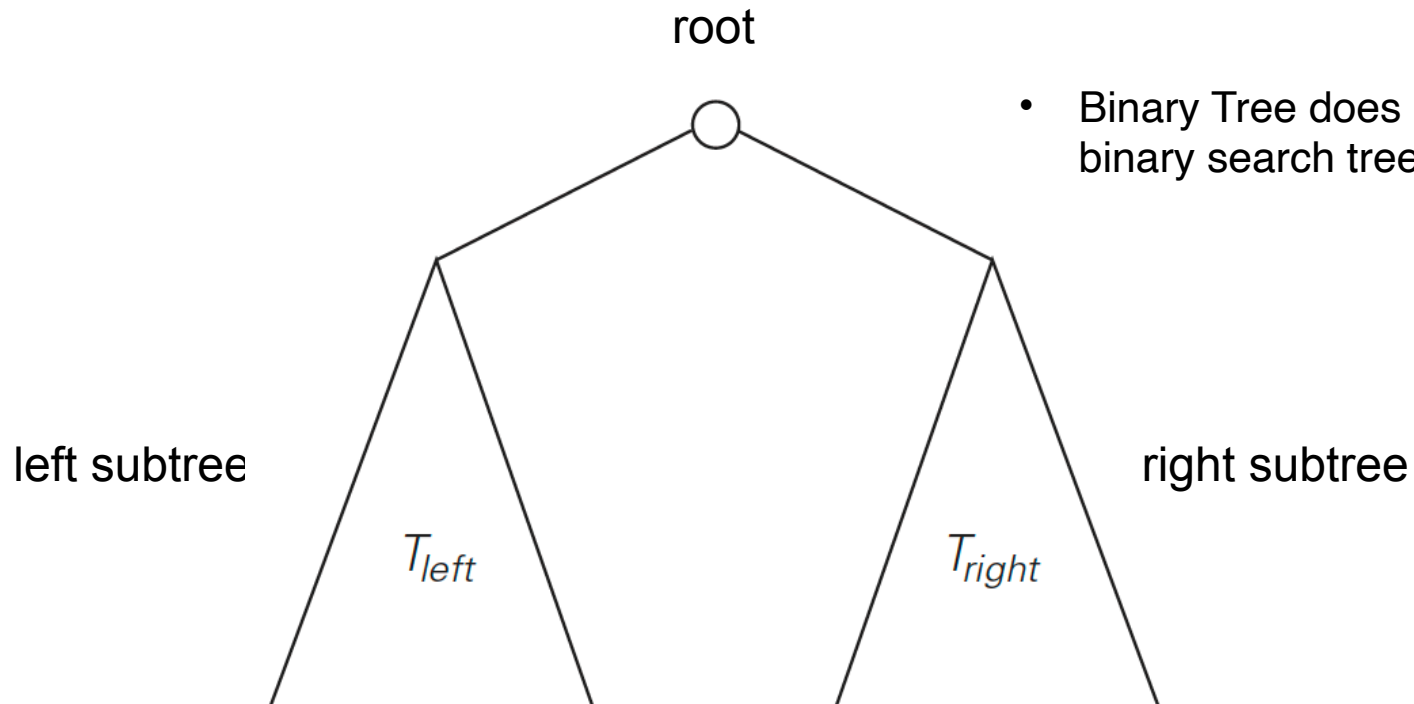
5.3 Binary Search

- A binary tree T
 - a finite set of nodes that is either empty or consists of a root and two disjoint binary trees T_L and T_R called, respectively, the left and right subtree of the root.



Binary Tree Algorithms

- The definition itself divides a binary tree into two smaller structures of the same type
- Binary tree is a divide-and-conquer ready structure!
- Three parts: root, left subtree, and right subtree



Example: Binary Tree Algorithm

- Height of Binary Tree

ALGORITHM *Height(T)*

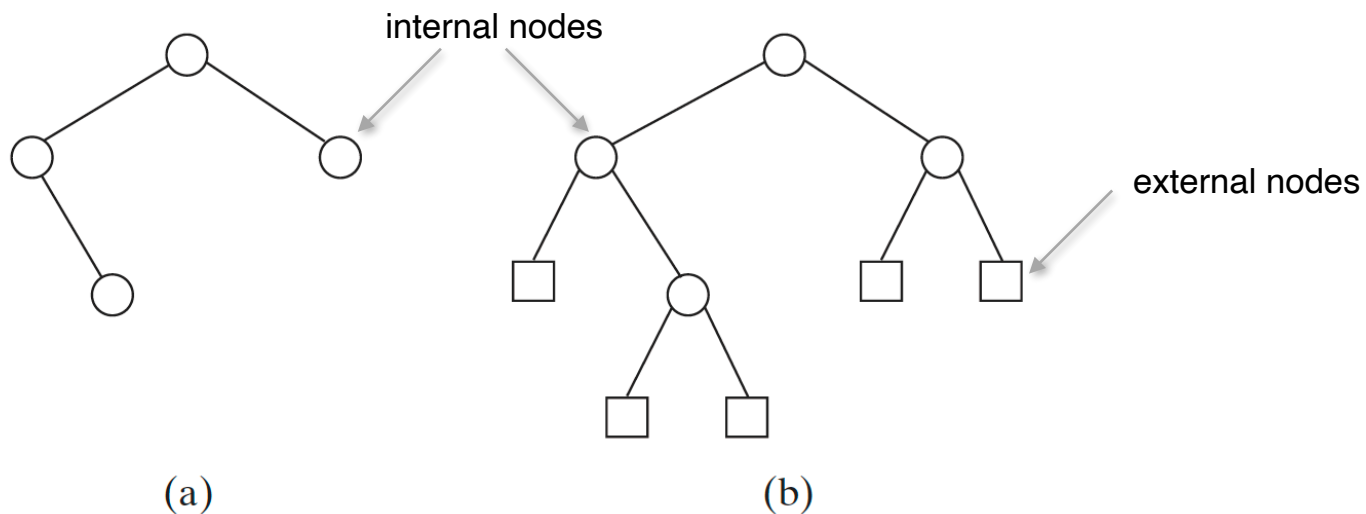
//Computes recursively the height of a binary tree

//Input: A binary tree T

//Output: The height of T

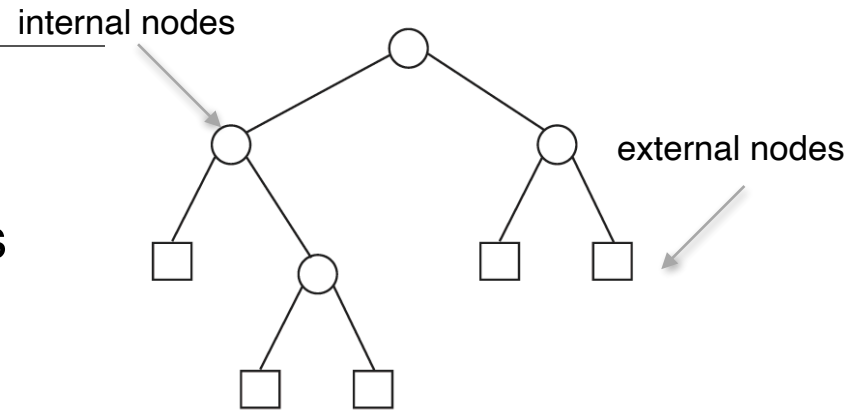
if $T = \emptyset$ **return** -1

else return $\max\{\text{Height}(T_{\text{left}}), \text{Height}(T_{\text{right}})\} + 1$



Example: Binary Tree Algorithm

- $x = n + 1$
 - x : the number of external nodes
 - n : the number of internal nodes



- Proof: the total number of nodes is $2n + 1 = n + x$
- Efficiency? $\Theta(\text{height})$

$$A(n(T)) = A(n(T_{\text{left}})) + A(n(T_{\text{right}})) + 1 \quad \text{for } n(T) > 0,$$

$$A(0) = 0.$$

$$A(n) = n.$$

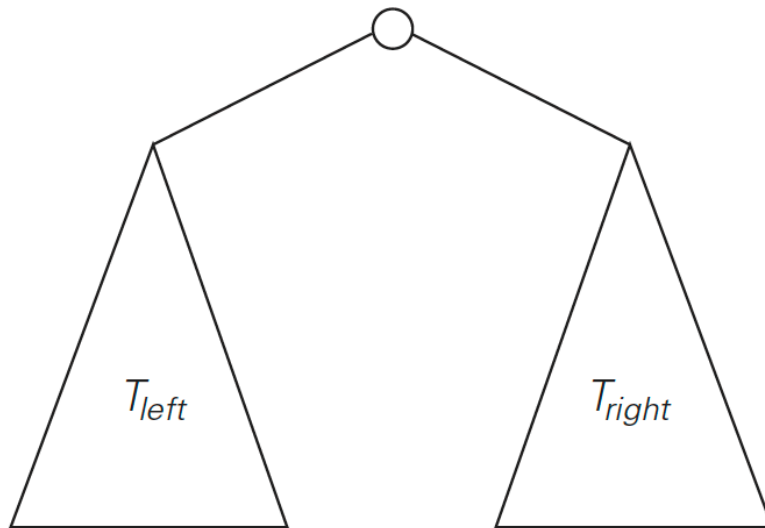
$$C(n) = n + x = 2n + 1,$$

Binary Search

- Very efficient algorithm for searching in [sorted array](#):

K vs $A[0] \dots A[m] \dots A[n-1]$

- If $K = A[m]$, stop (successful search);
- otherwise,
 - If $K < A[m]$, continue searching by the same method in $A[0..m-1]$
 - If $K > A[m]$, in $A[m+1..n-1]$



```
 $l \leftarrow 0; \quad r \leftarrow n-1$   
while  $l \leq r$  do  
     $m \leftarrow \lfloor (l + r)/2 \rfloor$   
    if  $K = A[m]$  return  $m$   
    else if  $K < A[m]$   $r \leftarrow m - 1$   
    else  $l \leftarrow m + 1$   
return -1
```

Exercise 5.3-2

2. The following algorithm seeks to compute the number of leaves in a binary tree.

ALGORITHM *LeafCounter*(T)

//Computes recursively the number of leaves in a binary tree

//Input: A binary tree T

//Output: The number of leaves in T

if $T = \emptyset$ **return** 0

else return *LeafCounter*(T_{left}) + *LeafCounter*(T_{right})

Is this algorithm correct? If it is, prove it; if it is not, make an appropriate correction.

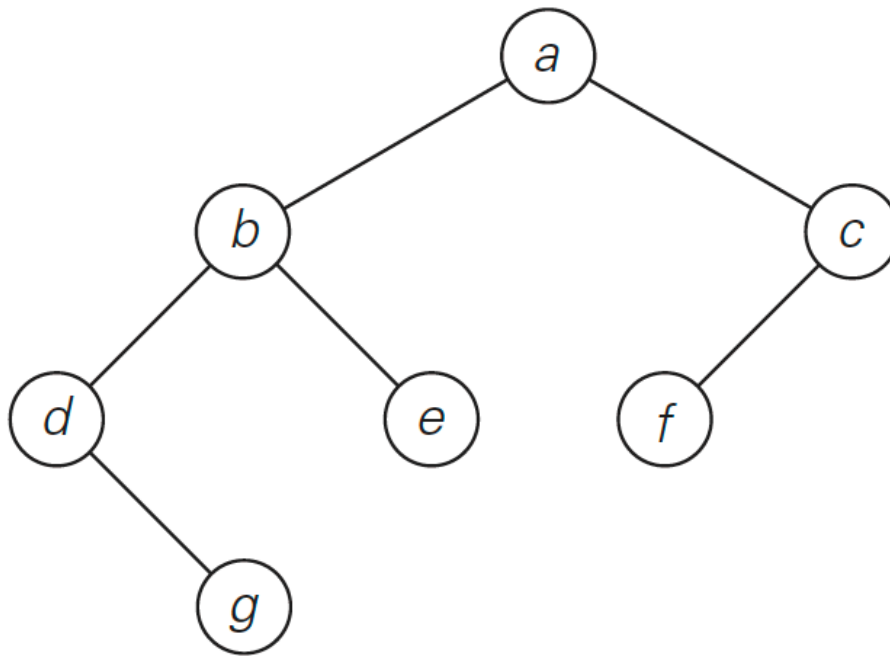
Binary Tree Traversals

The most important divide-and-conquer algorithms for binary trees are the three classic traversals: preorder, inorder, and postorder.

- **Preorder:** root, T_L , and T_R
 - the root is visited before the left and right subtrees are visited
- **Inorder:** T_L , root and T_R
 - the root is visited after visiting its left subtree but before visiting its right subtree
- **Postorder:** T_L , T_R and root
 - the root is visited after the left and right subtrees are visited

Classic traversals

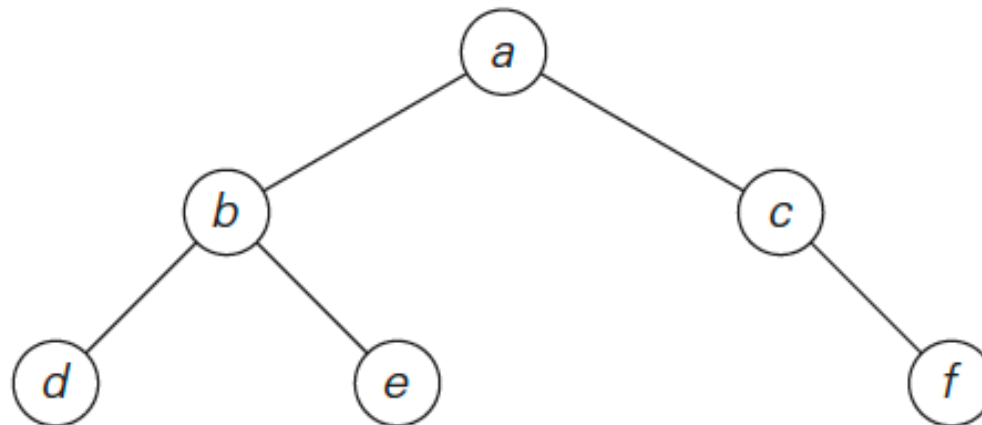
- Preorder: root, TL, and TR
- Inorder: TL, root and TR
- Postorder: TL, TR and root



preorder: *a, b, d, g, e, c, f*
inorder: *d, g, b, e, a, f, c*
postorder: *g, d, e, b, f, c, a*

Exercise 5.3-5

5. Traverse the following binary tree
- a. in preorder.
 - b. in inorder.
 - c. in postorder.



Exercise 5.3-6

6. Write pseudocode for one of the classic traversal algorithms (preorder, inorder, and postorder) for binary trees. Assuming that your algorithm is recursive, find the number of recursive calls made.