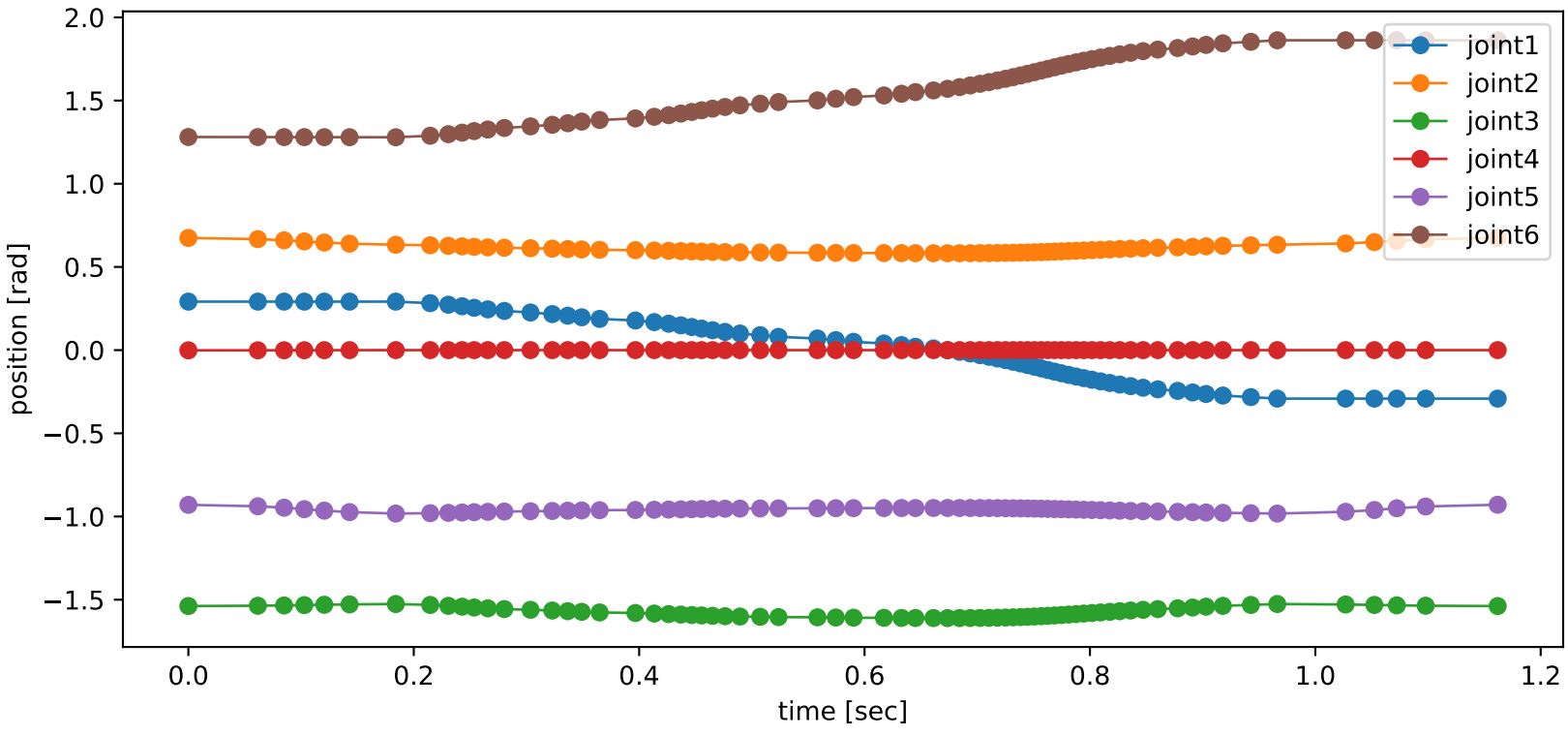
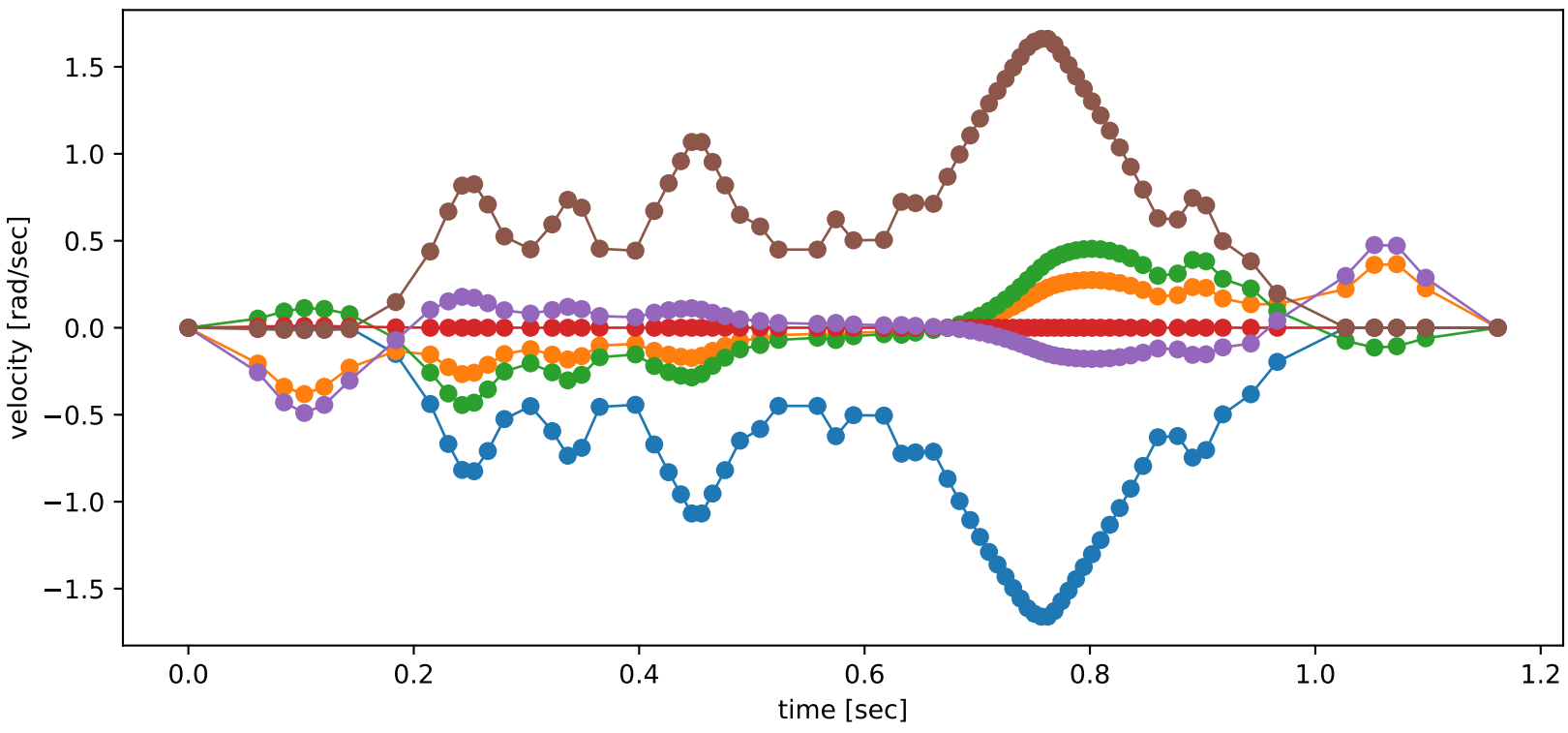
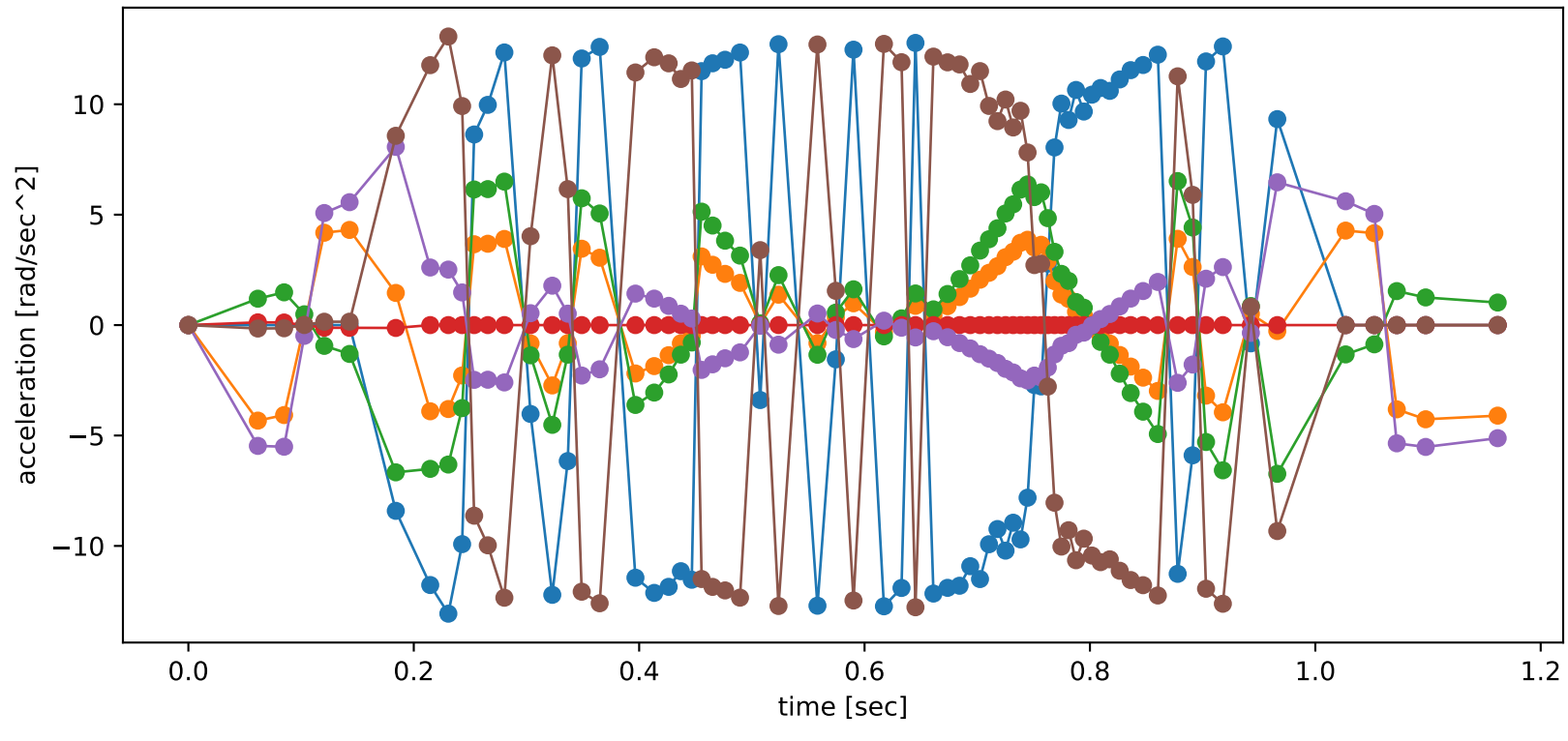
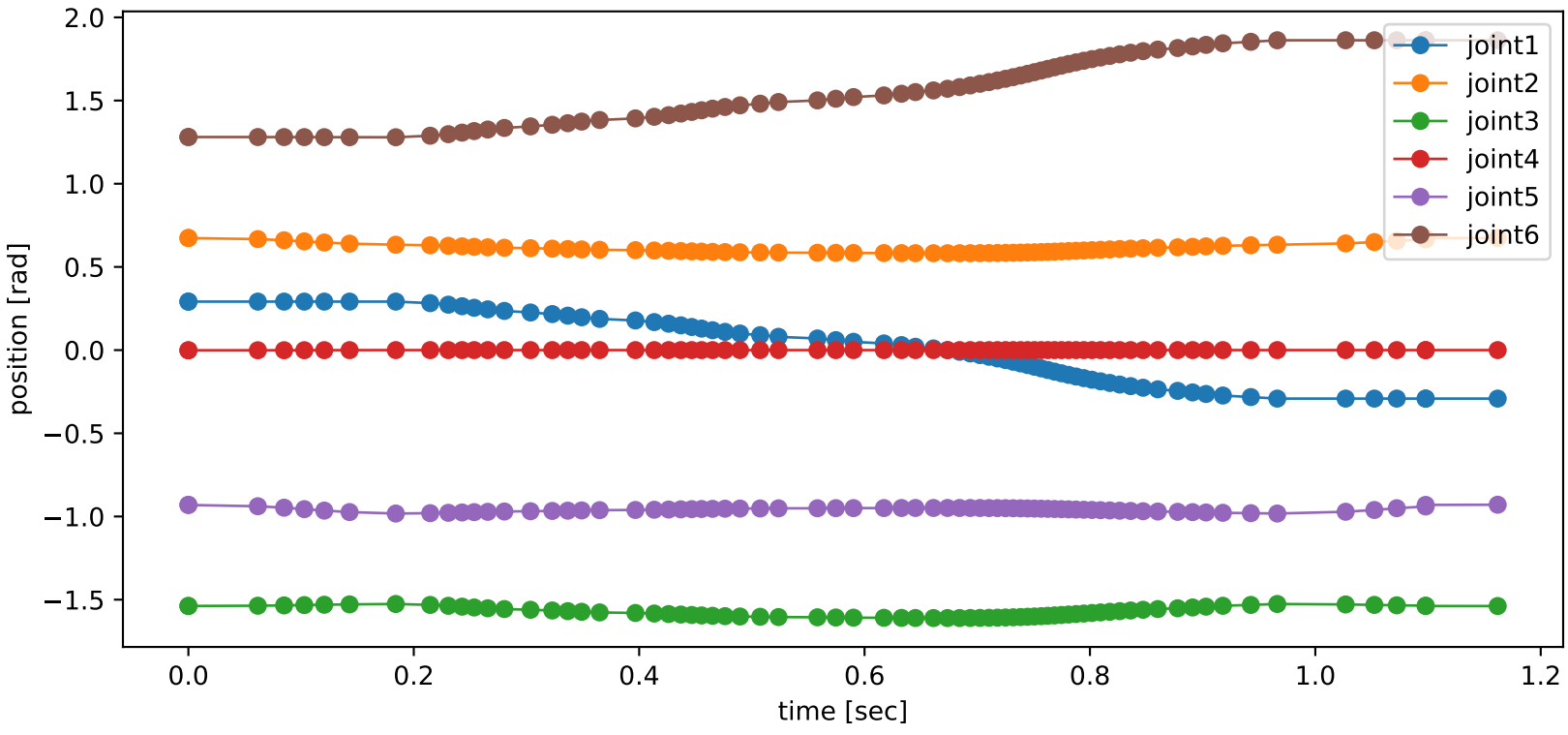
No Time Parametrization

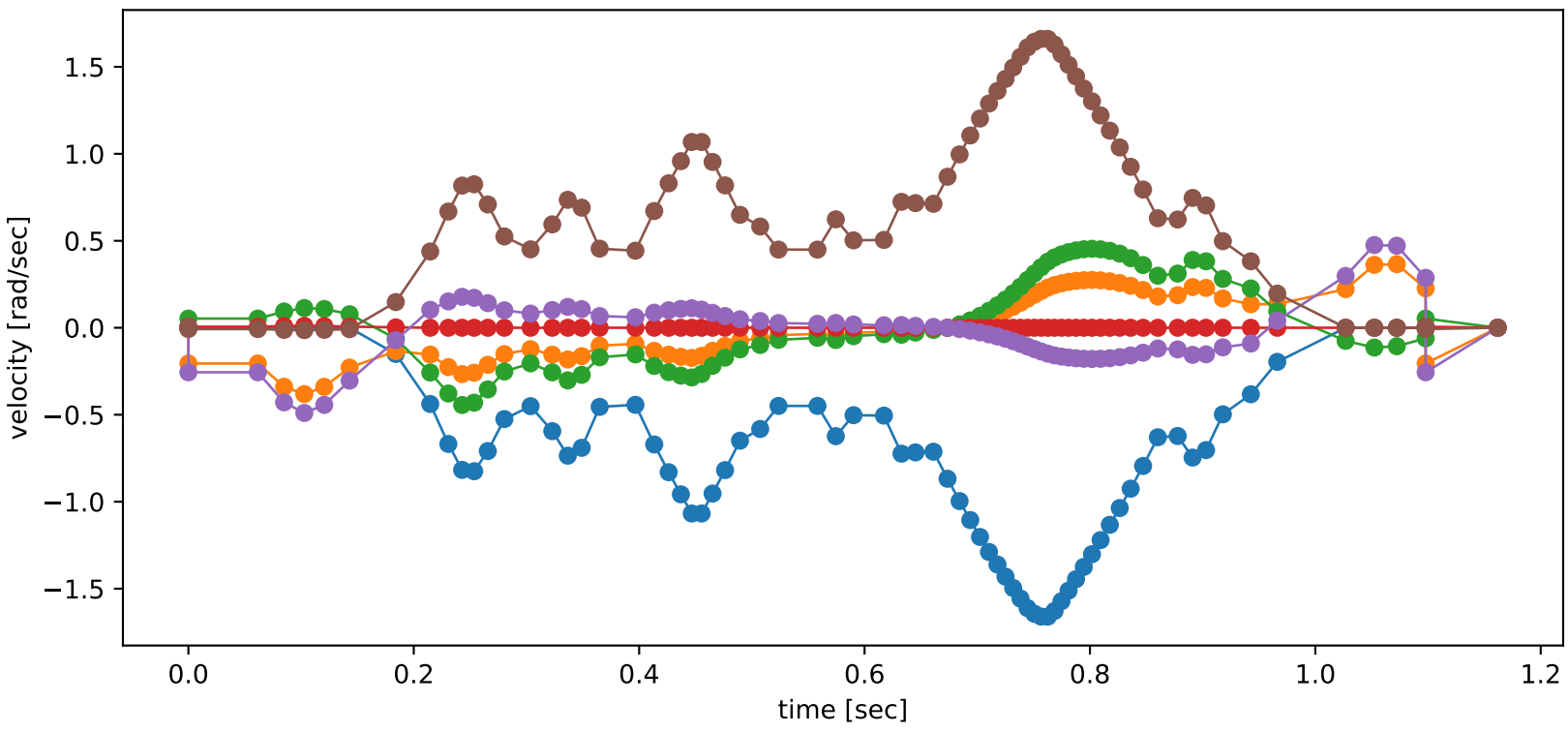


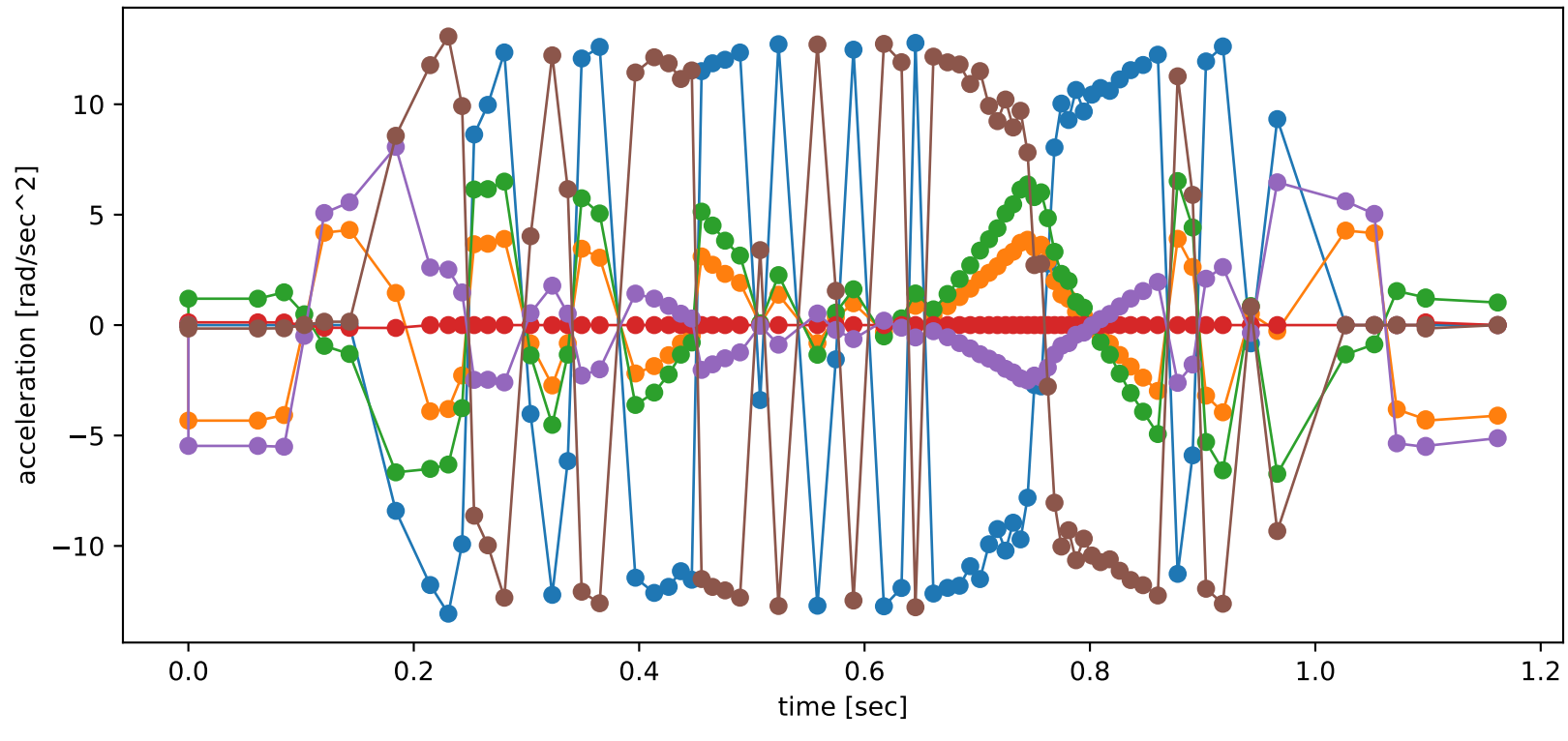




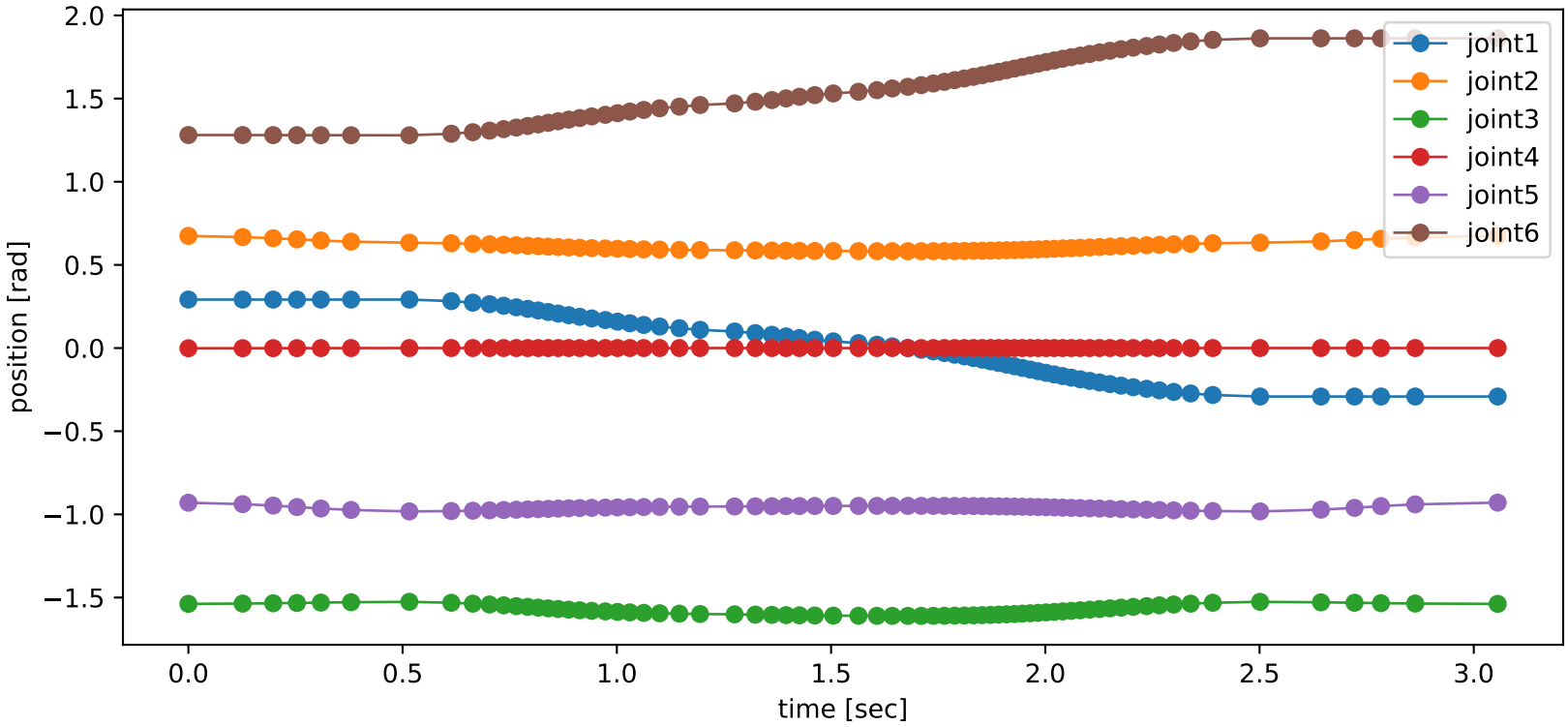
Iterative Spline Parametrization

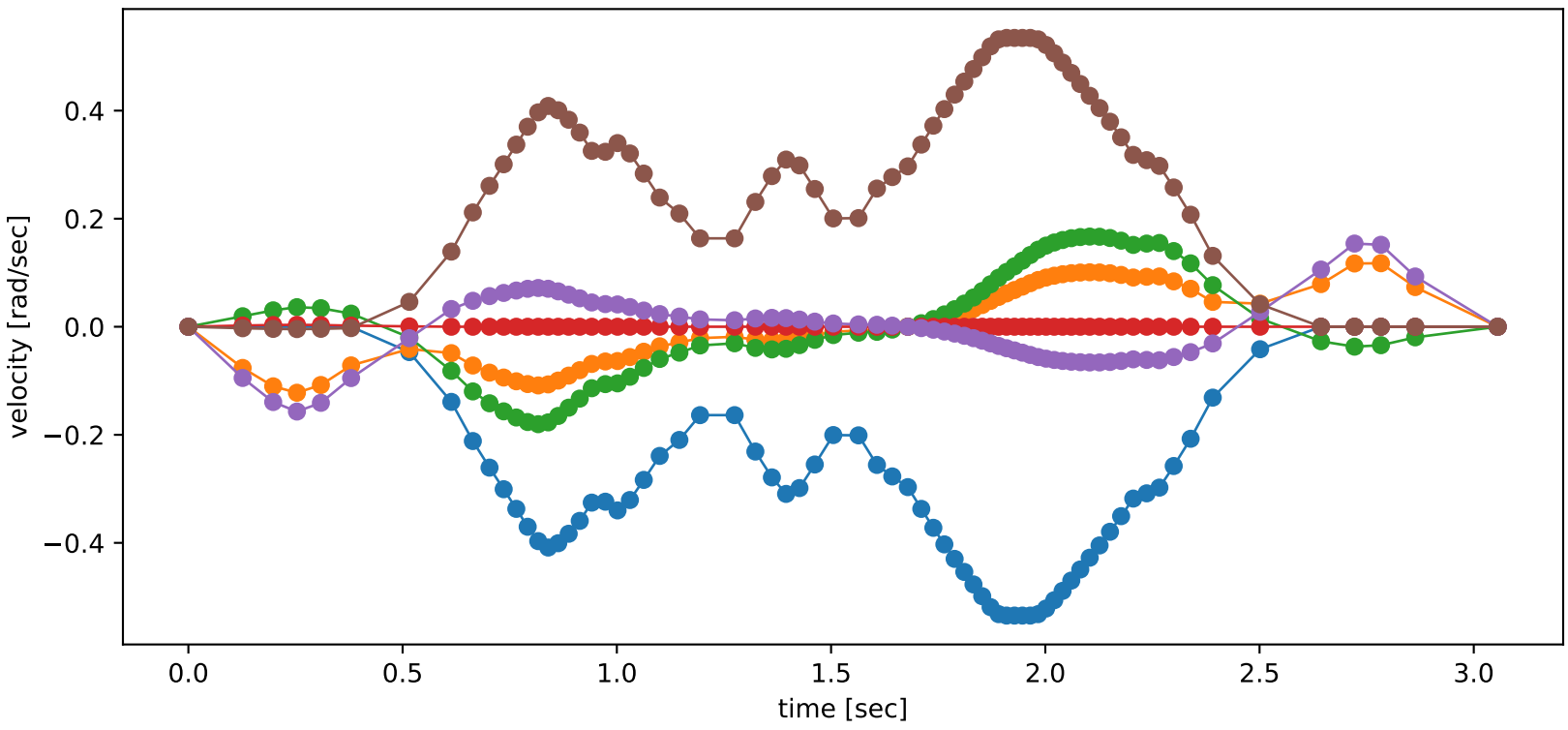


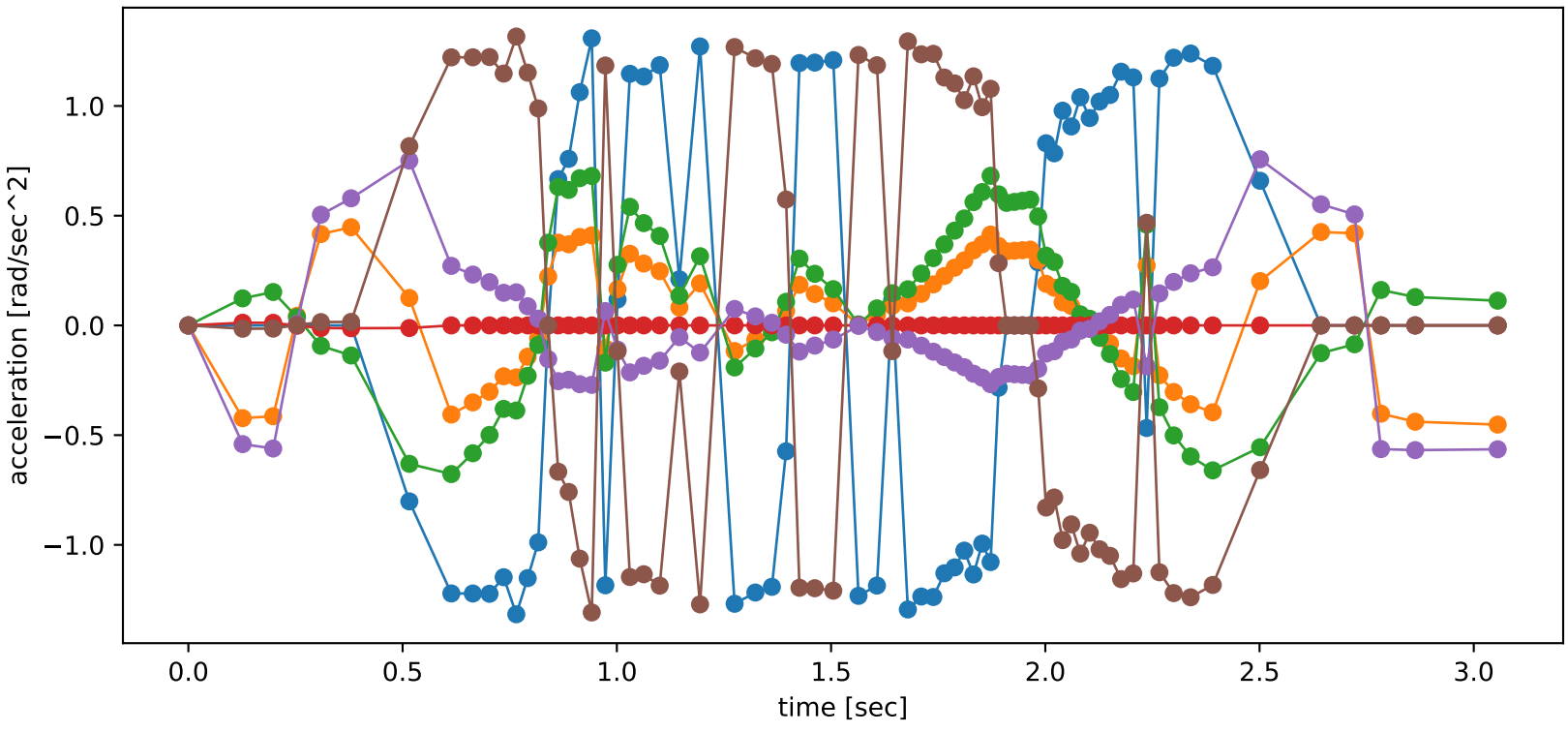
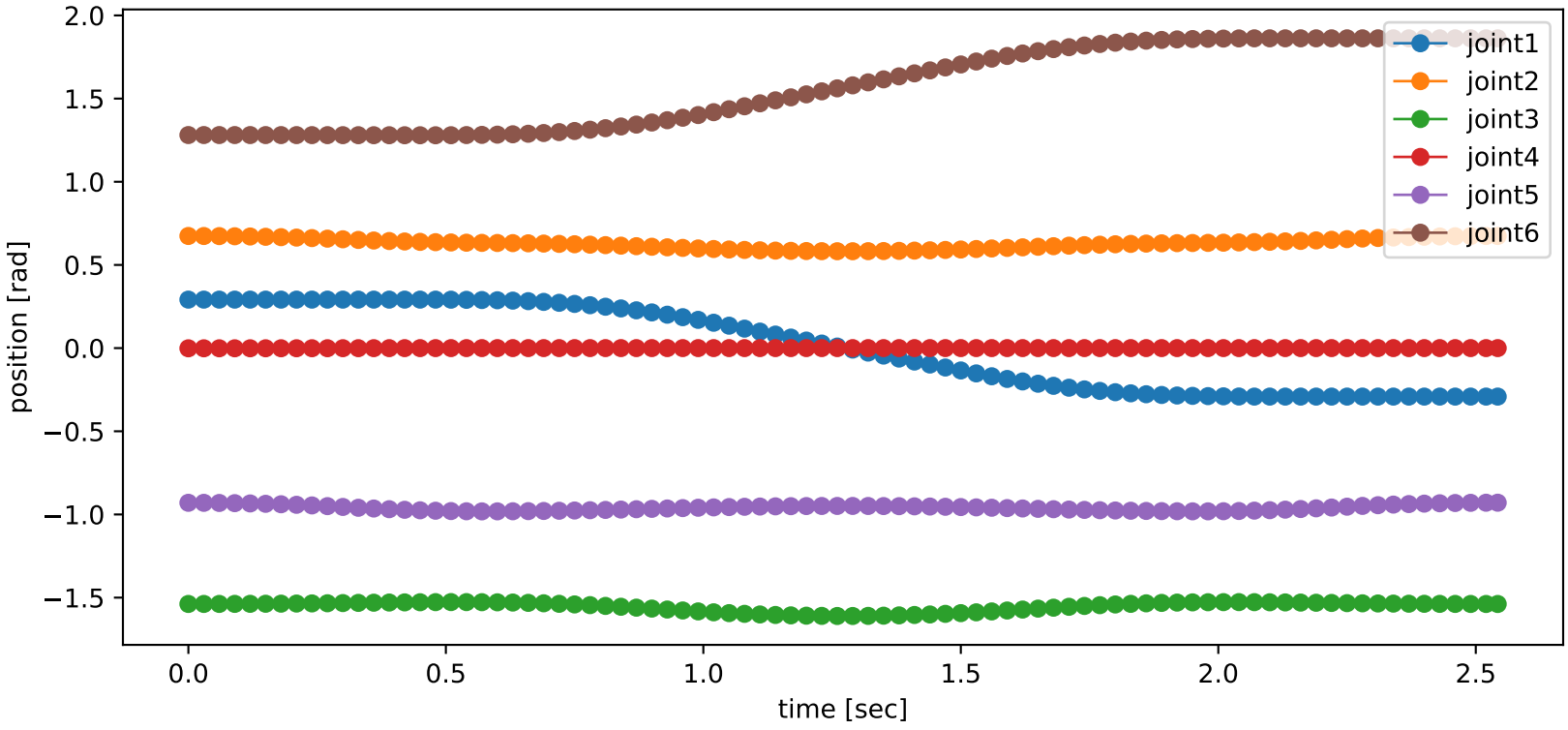
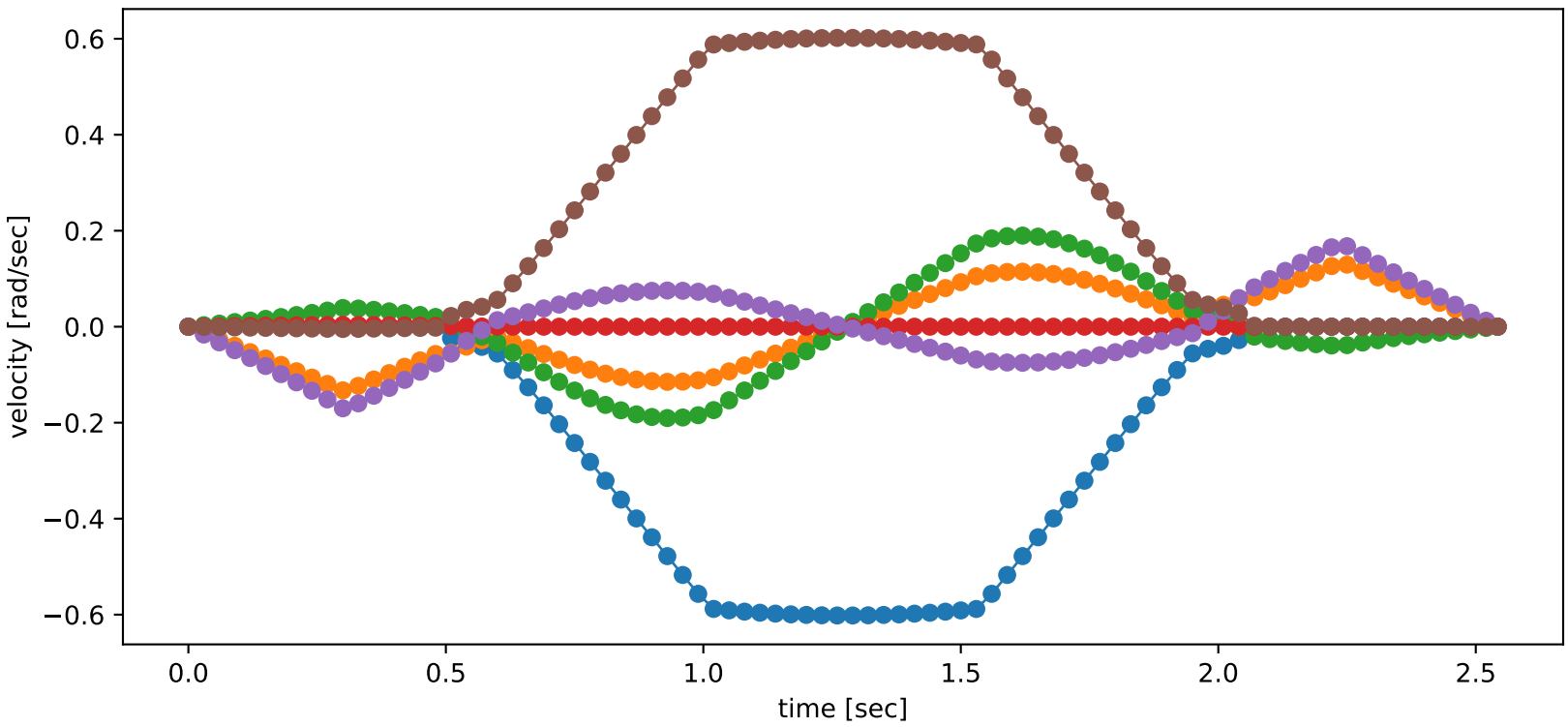
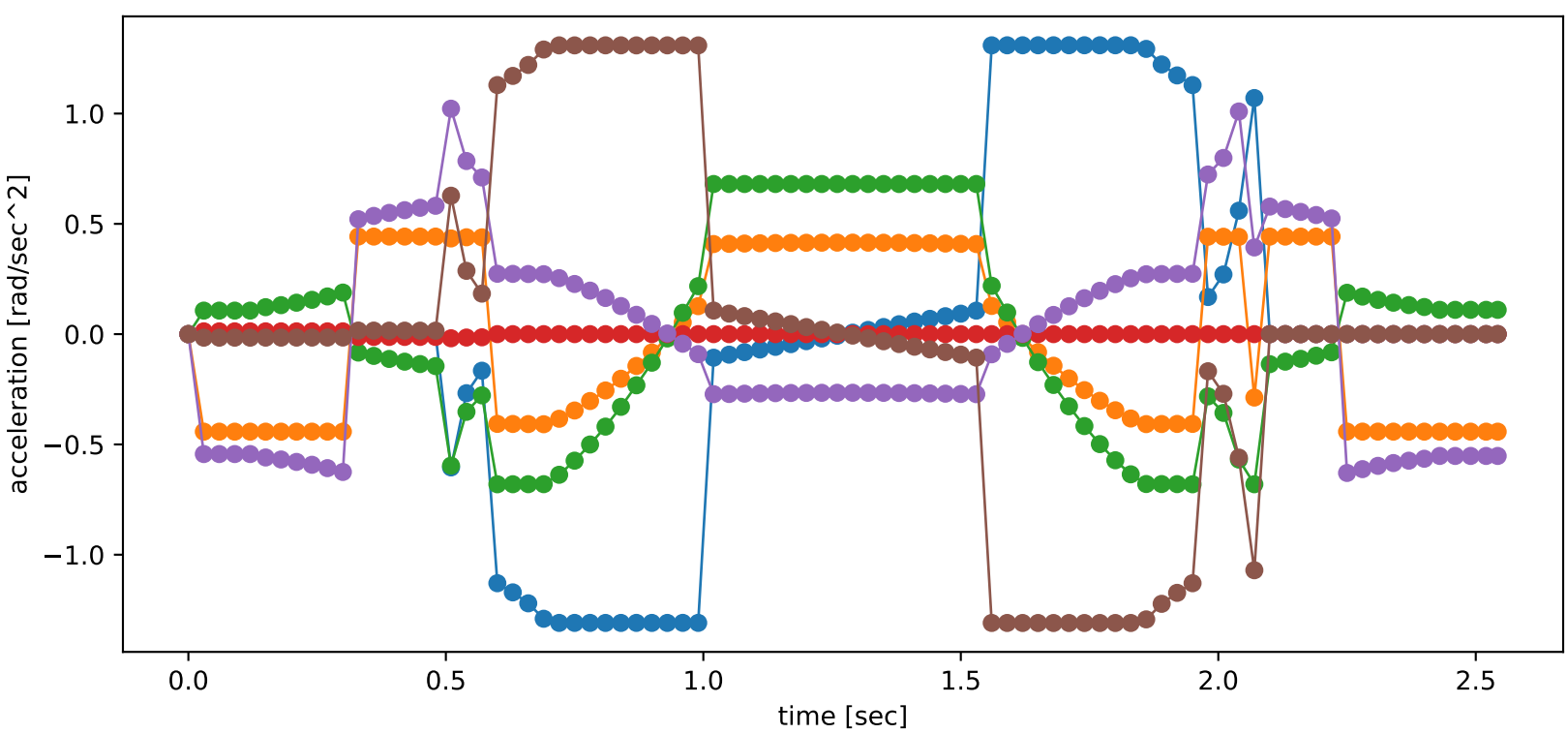




Iterative Time Parametrization







Time Optimal Trajectory Generation (New)