

Social Intelligence in Computer Vision: A Review of Cues, Models, and Applications

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Outline

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- Complexity of Group Activities
- Social and Cognitive Cues
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- SoGAR: Self-supervised Spatiotemporal Attention-based Social Group Activity Recognition
- LaIAR: Language-Model-Guided Interpretable Video Action Reasoning

Introduction

- ▶ **Activity Recognition (Individual)** Identifying what a person is doing. Datasets: UCF101, Kinetics
- ▶ **Group Activity Recognition (Social)** Understanding coordinated or interacting actions within groups. Datasets: Collective Activity, Volleyball Dataset
- ▶ **Why It Matters**
 - ▶ Moves beyond visual labels → requires reasoning about *roles*, *relationships*, *intentions*.
 - ▶ Foundation for social intelligence in computer vision.
 - ▶ Applications: autonomous driving, social robotics, surveillance, human–AI collaboration.

Complexity Beyond Actions

- ▶ Group activities involve **multiple people** and their interactions.
- ▶ Requires modeling of:
 - ▶ *Roles* (leader, follower, bystander)
 - ▶ *Relationships* (friend, rival, teammate)
 - ▶ *Intentions* (cooperation, competition, avoidance)
 - ▶ *Context* (sports field, meeting room, street)
- ▶ Moves beyond simple action recognition → toward **social reasoning**.

Social and Cognitive Cues

- ▶ Key cues from **social psychology** and **cognitive science**:
 - ▶ Facial expressions → emotions
 - ▶ Body language → posture, gestures
 - ▶ Gaze direction → attention, focus
 - ▶ Proxemics → distance and spatial relationships
 - ▶ Turn-taking → conversational dynamics
- ▶ These cues provide the foundation for **interpreting group interactions**.

Technical Challenges

- ▶ Multi-person detection and tracking across frames.
- ▶ Temporal reasoning: modeling interactions over time.
- ▶ Multimodal integration: vision + audio + language.
- ▶ Ambiguity and context dependence of group behaviors.
- ▶ Generalization: handling unseen group dynamics.

From Recognition to Understanding

- ▶ Traditional goal: **recognize what is happening.**
- ▶ Emerging goal: **understand why it is happening.**
 - ▶ Infer group goals, intentions, and social context.
 - ▶ Connect low-level cues with high-level reasoning.
- ▶ This leap is the essence of **social intelligence in video.**

Literature Review

- ▶ Overview of key works in social intelligence and computer vision.
- ▶ Discussion of methodologies, datasets, and findings.
- ▶ Identification of gaps and future directions.

SoGAR: Self-supervised Spatiotemporal Attention-based Social Group Activity Recognition

- ▶ **Datasets:** Volleyball Dataset, JRDB-PAR, NBA Dataset
- ▶ **Key Contributions:**
 - ▶ Introduced a self-supervised learning framework.
 - ▶ Leveraged spatiotemporal attention for improved interaction modeling.
 - ▶ Demonstrated effectiveness on multiple group activity datasets.
- ▶ **Model Architecture:**
 - ▶ Base: Vision Transformer (ViT) and TimeSformer
 - ▶ Learning: Self-supervised pretraining on large video datasets

SoGAR

- ▶ **Methodology:**
- ▶ Uses a self-supervised transformer framework (Vision Transformer backbone) for social group activity recognition.
- ▶ Key idea: generate **local** and **global** spatio-temporal views from the same video, with variation in frame rate and spatial crop size.
- ▶ A teacher-student architecture: teacher processes global view, student processes local views. The student is trained to align its features to those of the teacher.
- ▶ Two contrastive / correspondence objectives:
 - ▶ Temporal Collaborative Learning (TCL): relate views differing in temporal resolution.
 - ▶ Spatio-temporal Cooperative Learning (SCL): relate views that differ in spatial crop + temporal sampling.
- ▶ Does **not** require actor bounding boxes or individual action labels during pre-training, reducing annotation burden.
- ▶ Uses motion as supervisory signal from RGB alone; the model becomes invariant to scale, viewpoint, and motion speed.

LalAR: Language-Model-Guided Interpretable Video Action Reasoning

- ▶ **Datasets:** Charades, CAD-120
- ▶ **Key Contributions:**
 - ▶ Proposed a framework that integrates large language models (LLMs) for interpretable action reasoning. Utilizing knowledge transfer between LLMs and video model.
 - ▶ Utilized LLMs to generate explanations and rationales for recognized actions. Inferring high-level actions from low-level changes in relationships between actors and objects.
- ▶ **Model Architecture:**
 - ▶ R-CNN and ResNet-101 as backbones for object, category, and relation detection.
 - ▶ Relations and visual features are mapped to a joint embedding space.
 - ▶ Embeddings are fed into a dynamic token transformer (DT-Former).

LaIAR

- ▶ **Methodology:**
- ▶ Introduces a dual-branch framework: a video model and a language model, trained together so the video model learns reasoning from the language model.
- ▶ Uses relationship transitions between humans/objects as cues: visual relations (appearance, bounding boxes, spatial configuration) and semantic relations (human/object categories + relationships) are encoded.
- ▶ Both visual and semantic relations are encoded via Faster R-CNN + ResNet-101 for detecting entities, extracting features, forming human-object pairs.
- ▶ Core architecture: DT-Former (Dynamic Token Transformer) which applies adaptive token selection (spatio-temporal tokens) and then transformer layers to model relation transitions. Tokens with low importance are discarded via a Gumbel-Softmax mechanism.
- ▶ Learning scheme includes:
 - ▶ Joint visual-semantic embedding: aligning visual relation features and semantic relation features into a common space