

# CFD Homework 2

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1. a) Classify the given PDE below.

$$2u_{xx} - 4u_{xy} + 2u_{yy} + 3u = 0$$

*Soln.* This is a PDE of the form

$$Au_{xx} + 2Bu_{xy} + Cu_{yy} + Du_x + Eu_y + Fu = 0$$

with  $A = 2 = C$ ,  $B = -2$ ,  $D = E = 0$ , and  $F = 3$ . To classify the PDE, we must inspect  $B^2 - AC$ . Well,  $B^2 - AC = (-2)^2 - (2)(2) = 4 - 4 = 0$ . Thus, by definition, the PDE is **parabolic**.

- b) Convert the PDE into a system of first order equations while keeping it the same. Write this system in matrix form.

*Soln.* Let  $v = u_x$  and  $w = u_y$ . Then the PDE in part a) becomes

$$2v_x - 4v_y + 2w_y + 3u = 0. \quad (1)$$

Assuming a sufficiently smooth solution  $u$ , we also have

$$v_y = w_x \quad (2)$$

and after dividing (1) by the scalar 2, we have the system

$$\begin{aligned} v_x - 2v_y + w_y + \frac{3}{2}u &= 0 \\ w_x - v_y &= 0. \end{aligned} \quad (3)$$

Writing (3) as a matrix system, we have

$$\frac{\partial}{\partial x} \begin{pmatrix} v \\ w \end{pmatrix} + \frac{\partial}{\partial y} \begin{pmatrix} -2 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} v \\ w \end{pmatrix} + \begin{pmatrix} \frac{3}{2}u \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

- c) Classify the system of equations found in part b.

*Soln.* To classify the system in part b), we must inspect the eigenvalues of  $A = \begin{pmatrix} -2 & 1 \\ -1 & 0 \end{pmatrix}$ . That is,

$$\begin{aligned} \det(A - \lambda I) &= \begin{vmatrix} -2 - \lambda & 1 \\ -1 & -\lambda \end{vmatrix} \\ &= \lambda(\lambda + 2) + 1 \\ &= \lambda^2 + 2\lambda + 1 \\ &= (\lambda + 1)^2 = 0 \\ \implies \lambda &= -1 \end{aligned}$$

with algebraic multiplicity 2. Thus, since we have a repeated eigenvalue, the system is **parabolic**.

2. Derive the fourth-order-accurate central finite-difference for  $\frac{\partial^2 u}{\partial x^2}$ :

$$\left(\frac{\partial^2 u}{\partial x^2}\right)_i = \frac{-u_{i-2} + 16u_{i-1} - 30u_i + 16u_{i+1} - u_{i+2}}{12(\Delta x)^2} + \mathcal{O}(\Delta x^4)$$

This is actually the same scheme in Anderson (4.18). In the derivation of the above equation, we have assumed the mesh is uniform, that is,  $\Delta x$  is constant.

*Soln.* We approach this by method of undetermined coefficients. Let  $x_i = x_0$  and  $x_{i\pm 1} = x_0 \pm \Delta x$ . We seek a scheme of the form

$$u_{xx}(x_0) \approx au(x_0 - 2\Delta x) + bu(x_0 - \Delta x) + cu(x_0) + du(x_0 + \Delta x) + eu(x_0 + 2\Delta x).$$

Taylor expanding each of the terms above, we find

$$\begin{aligned} u(x_0 + 2\Delta x) &= u(x_0) + 2\Delta x u_x(x_0) + 2(\Delta x)^2 u_{xx}(x_0) + \frac{8(\Delta x)^3}{3!} u_{xxx}(x_0) + \frac{16(\Delta x)^4}{4!} u_{xxxx}(x_0) + \mathcal{O}((\Delta x)^5) \\ u(x_0 + \Delta x) &= u(x_0) + \Delta x u_x(x_0) + \frac{(\Delta x)^2}{2} u_{xx}(x_0) + \frac{(\Delta x)^3}{3!} u_{xxx}(x_0) + \frac{(\Delta x)^4}{4!} u_{xxxx}(x_0) + \mathcal{O}((\Delta x)^5) \\ u(x_0 - \Delta x) &= u(x_0) - \Delta x u_x(x_0) + \frac{(\Delta x)^2}{2} u_{xx}(x_0) - \frac{(\Delta x)^3}{3!} u_{xxx}(x_0) + \frac{(\Delta x)^4}{4!} u_{xxxx}(x_0) + \mathcal{O}((\Delta x)^5) \\ u(x_0 - 2\Delta x) &= u(x_0) - 2\Delta x u_x(x_0) + 2(\Delta x)^2 u_{xx}(x_0) - \frac{8(\Delta x)^3}{3!} u_{xxx}(x_0) + \frac{16(\Delta x)^4}{4!} u_{xxxx}(x_0) + \mathcal{O}((\Delta x)^5) \end{aligned}$$

By matching coefficients, we find the following linear system:

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ -2 & -1 & 0 & 1 & 2 \\ 2 & \frac{1}{2} & 0 & \frac{1}{2} & 2 \\ -\frac{4}{3} & -\frac{1}{6} & 0 & \frac{1}{6} & \frac{4}{3} \\ \frac{2}{3} & \frac{1}{24} & 0 & \frac{1}{24} & \frac{2}{3} \end{pmatrix} \begin{pmatrix} a \\ b \\ c \\ d \\ e \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \frac{1}{(\Delta x)^2} \\ 0 \\ 0 \end{pmatrix}$$

To solve the problem, we first perform the following row operations:  $R_2 + 2R_1 \rightarrow R_2$ ,  $R_2 - 2R_1 \rightarrow R_3$ ,

$R_4 + \frac{4}{3}R_1 \rightarrow R_4$ , and  $R_5 - \frac{2}{3}R_1 \rightarrow R_5$ . Then our system becomes (in augmented form)

$$\begin{aligned}
 & \left( \begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 2 & 3 & 4 & 0 \\ 0 & -\frac{3}{2} & -2 & -\frac{3}{2} & 0 & \frac{1}{(\Delta x)^2} \\ 0 & \frac{7}{6} & \frac{4}{3} & \frac{3}{2} & \frac{8}{3} & 0 \\ 0 & -\frac{5}{8} & -\frac{2}{3} & -\frac{5}{8} & 0 & 0 \end{array} \right) \begin{array}{l} R_3 - \frac{3}{2}R_2 \rightarrow R_3 \\ R_4 - \frac{7}{6}R_2 \rightarrow R_4 \\ R_5 + \frac{5}{8}R_2 \rightarrow R_5 \end{array} \\
 & \sim \left( \begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 2 & 3 & 4 & 0 \\ 0 & 0 & 1 & 3 & 6 & \frac{1}{(\Delta x)^2} \\ 0 & 0 & -1 & -2 & -2 & 0 \\ 0 & 0 & \frac{7}{12} & \frac{5}{4} & \frac{5}{2} & 0 \end{array} \right) \begin{array}{l} R_4 + R_3 \rightarrow R_4 \\ R_5 - \frac{7}{12}R_4 \rightarrow R_5 \end{array} \\
 & \sim \left( \begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 2 & 3 & 4 & 0 \\ 0 & 0 & 1 & 3 & 6 & \frac{1}{(\Delta x)^2} \\ 0 & 0 & 0 & 1 & 4 & \frac{1}{(\Delta x)^2} \\ 0 & 0 & 0 & -\frac{1}{2} & -1 & -\frac{7}{12(\Delta x)^2} \end{array} \right) \begin{array}{l} R_5 + \frac{1}{2}R_4 \rightarrow R_5 \end{array} \\
 & \sim \left( \begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 2 & 3 & 4 & 0 \\ 0 & 0 & 1 & 3 & 6 & \frac{1}{(\Delta x)^2} \\ 0 & 0 & 0 & 1 & 4 & \frac{1}{(\Delta x)^2} \\ 0 & 0 & 0 & 0 & 1 & -\frac{1}{12(\Delta x)^2} \end{array} \right).
 \end{aligned}$$

Back substitution gives us  $e = -\frac{1}{12(\Delta x)^2}$ ,  $d = \frac{16}{12(\Delta x)^2}$ ,  $c = -\frac{30}{12(\Delta x)^2}$ ,  $b = \frac{16}{12(\Delta x)^2}$ ,  $a = -\frac{1}{12(\Delta x)^2}$ . Further, by symmetry of the coefficients and Taylor expansions, we find that the fifth order terms cancel (and the sixth order terms do not), so we are left with

$$\begin{aligned}
 \left( \frac{\partial u}{\partial x} \right)_i &= \frac{-u_{i+2} + 16u_{i+1} - 30u_i + 16u_{i-1} - u_{i-2}}{12(\Delta x)^2} + \frac{1}{12(\Delta x)^2} \mathcal{O}((\Delta x)^6) \\
 &= \frac{-u_{i+2} + 16u_{i+1} - 30u_i + 16u_{i-1} - u_{i-2}}{12(\Delta x)^2} + \mathcal{O}((\Delta x)^4)
 \end{aligned}$$

as desired.

3. Anderson Problems 4.6. Derive the third-order-accurate one-sided difference for  $\frac{\partial u}{\partial y}$

$$\left(\frac{\partial u}{\partial y}\right)_{i,j} = \frac{1}{6\Delta y}(-11u_{i,j} + 18u_{i,j+1} - 9u_{i,j+2} + 2u_{i,j+3})$$

*Soln.* We approach this by method of undetermined coefficients. Letting  $x_i = x_0$ ,  $y_i = y_0$ , and  $y_{i\pm 1} = y_0 \pm \Delta y$ , we seek a scheme of the form

$$\left(\frac{\partial u}{\partial y}\right)_i \approx au(x_0, y_0) + bu(x_0, y_0 + \Delta y) + cu(x_0, y_0 + 2\Delta y) + du(x_0, y_0 + 3\Delta y).$$

Taylor expanding the above terms, we find

$$\begin{aligned} u(x_0, y_0 + \Delta y) &= u(x_0, y_0) + \Delta y u_y(x_0, y_0) + \frac{(\Delta y)^2}{2} u_{yy}(x_0, y_0) + \frac{(\Delta y)^3}{3!} u_{yyy}(x_0, y_0) + \mathcal{O}((\Delta y)^4) \\ u(x_0, y_0 + 2\Delta y) &= u(x_0, y_0) + 2\Delta y u_y(x_0, y_0) + 2(\Delta y)^2 u_{yy}(x_0, y_0) + \frac{8(\Delta y)^3}{3!} u_{yyy}(x_0, y_0) + \mathcal{O}((\Delta y)^4) \\ u(x_0, y_0 + 3\Delta y) &= u(x_0, y_0) + 3\Delta y u_y(x_0, y_0) + \frac{9(\Delta y)^2}{2} u_{yy}(x_0, y_0) + \frac{27(\Delta y)^3}{3!} u_{yyy}(x_0, y_0) + \mathcal{O}((\Delta y)^4). \end{aligned}$$

Matching coefficients, we find the following linear system:

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & \frac{1}{2} & 2 & \frac{9}{2} \\ 0 & \frac{1}{6} & \frac{4}{3} & \frac{9}{2} \end{pmatrix} \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} 0 \\ \frac{1}{\Delta y} \\ 0 \\ 0 \end{pmatrix}$$

Performing the following row operations,  $R_3 - \frac{1}{2}R_2 \rightarrow R_3$  and  $R_4 - \frac{1}{6}R_2 \rightarrow R_4$ , the system becomes (in augmented form)

$$\begin{aligned} &\left( \begin{array}{cccc|c} 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 2 & 3 & \frac{1}{\Delta y} \\ 0 & \frac{1}{2} & 2 & \frac{9}{2} & 0 \\ 0 & \frac{1}{6} & \frac{4}{3} & \frac{9}{2} & 0 \end{array} \right) \begin{array}{l} R_3 - \frac{1}{2}R_2 \rightarrow R_3 \\ R_4 - \frac{1}{6}R_2 \rightarrow R_4 \end{array} \\ &\sim \left( \begin{array}{cccc|c} 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 2 & 3 & \frac{1}{\Delta y} \\ 0 & 0 & 1 & 3 & -\frac{1}{2\Delta y} \\ 0 & 0 & 0 & 1 & \frac{1}{3\Delta y} \end{array} \right). \end{aligned}$$

Back substitution gives  $d = \frac{1}{3\Delta y}$ ,  $c = -\frac{3}{2\Delta y}$ ,  $b = \frac{3}{\Delta y}$ ,  $a = -\frac{11}{6\Delta y}$  so that our scheme is

$$\begin{aligned} \left(\frac{\partial u}{\partial y}\right)_{i,j} &= \frac{1}{6\Delta y}(-11u_{i,j} + 18u_{i,j+1} - 9u_{i,j+2} + 24u_{i,j+3}) + \frac{1}{6\Delta y}\mathcal{O}((\Delta y)^4) \\ &= \frac{1}{6\Delta y}(-11u_{i,j} + 18u_{i,j+1} - 9u_{i,j+2} + 24u_{i,j+3}) + \mathcal{O}((\Delta y)^3) \end{aligned}$$

as desired.

4. Consider first order wave equation

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = 0$$

- (1) The finite difference equation with forward difference in time, central difference in space can be written as:

$$\frac{u_i^{t+\Delta t} - u_i^t}{\Delta t} = -c \frac{u_{i+1}^t - u_{i-1}^t}{2\Delta x}$$

Using von Neumann stability analysis, find out the amplification factor, and verify the above scheme is unconditional unstable.

*Soln.* Set  $\varepsilon_i^n = e^{at+ikx}$ . We have that  $\varepsilon_i^n$  satisfies the scheme above so that

$$\frac{e^{a(t+\Delta t)+ikx} - e^{at+ikx}}{\Delta t} = -c \frac{e^{at+ik(x+\Delta x)} - e^{at+ik(x-\Delta x)}}{2\Delta x}.$$

Dividing through by  $e^{at+ikx}$ , the above equation becomes

$$\begin{aligned} \frac{e^{a\Delta t} - 1}{\Delta t} &= -c \frac{e^{ik\Delta x} - e^{-ik\Delta x}}{2\Delta x} \\ \implies e^{a\Delta t} &= 1 - c \frac{\Delta t}{2\Delta x} i \sin(k\Delta x) \\ \implies |e^{a\Delta t}|^2 &= \left| 1 - c \frac{\Delta t}{2\Delta x} i \sin(k\Delta x) \right|^2 \\ &= 1 + \left( c \frac{\Delta t}{2\Delta x} \right)^2 \sin^2(k\Delta x). \end{aligned}$$

So we have the amplification factor  $1 + \left( c \frac{\Delta t}{2\Delta x} \right)^2 \sin^2(k\Delta x)$ , which we require to be greater than or equal to 1. That is, we require

$$1 + \left( c \frac{\Delta t}{2\Delta x} \right)^2 \sin^2(k\Delta x) \geq 1$$

and since  $\sin^2(k\Delta x) \geq 0$ , we have that the scheme is unconditionally unstable, as desired.

- (2) Using Lax method, the finite difference equation can be written as:

$$u_i^{n+1} = \frac{u_{i+1}^n + u_{i-1}^n}{2} - c \frac{\Delta t}{\Delta x} \frac{u_{i+1}^n - u_{i-1}^n}{2}$$

Using von Neumann stability analysis, find out the amplification factor, and find the requirement for the above scheme to be stable.

*Soln.* Following the process as in part (1), setting  $\varepsilon_i^n = e^{at+ikx}$ , we have

$$e^{a(t+\Delta t)+ikx} = \frac{e^{at+ik(x+\Delta x)} + e^{at+ik(x-\Delta x)}}{2} - c \frac{\Delta t}{\Delta x} \frac{e^{at+ik(x+\Delta x)} - e^{at+ik(x-\Delta x)}}{2}.$$

Dividing through by  $e^{at+ikx}$  gives

$$\begin{aligned}
 e^{a\Delta t} &= \frac{e^{ik\Delta x} + e^{-ik\Delta x}}{2} - c \frac{\Delta t}{\Delta x} \frac{e^{ik\Delta x} - e^{-ik\Delta x}}{2} \\
 &= \cos(k\Delta x) - ic \frac{\Delta t}{\Delta x} \sin(k\Delta x) \\
 \Rightarrow |e^{a\Delta t}|^2 &= \left| \cos(k\Delta x) - ic \frac{\Delta t}{\Delta x} \sin(k\Delta x) \right|^2 \\
 &= \cos^2(k\Delta x) + \left( c \frac{\Delta t}{\Delta x} \right)^2 \sin^2(k\Delta x) \\
 &= 1 - \sin^2(k\Delta x) + \left( c \frac{\Delta t}{\Delta x} \right)^2 \sin^2(k\Delta x) \\
 &= 1 + \left[ \left( \frac{\Delta t}{\Delta x} \right)^2 - 1 \right] \sin^2(k\Delta x).
 \end{aligned}$$

Since we require  $|e^{a\Delta t}|^2 \leq 1$ , we have

$$\begin{aligned}
 1 + \left[ \left( c \frac{\Delta t}{\Delta x} \right)^2 - 1 \right] \sin^2(k\Delta x) &\leq 1 \\
 \Rightarrow \left[ \left( c \frac{\Delta t}{\Delta x} \right)^2 - 1 \right] \sin^2(k\Delta x) &\leq 0
 \end{aligned}$$

and since  $\sin^2(k\Delta x) \geq 0$ , we require

$$\begin{aligned}
 \left( c \frac{\Delta t}{\Delta x} \right)^2 - 1 &\leq 0 \\
 \Rightarrow \left( c \frac{\Delta t}{\Delta x} \right)^2 &\leq 1 \\
 \Rightarrow \left| c \frac{\Delta t}{\Delta x} \right| &\leq 1.
 \end{aligned}$$

Thus, the scheme is stable whenever  $\left| c \frac{\Delta t}{\Delta x} \right| \leq 1$  and has amplification factor  $\cos(k\Delta x) - ic \frac{\Delta t}{\Delta x} \sin(k\Delta x)$ .

5. Consider first order wave equation

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = 0$$

The forward difference in time and central difference in space can be written as:

$$\frac{u_i^{t+\Delta t} - u_i^n}{\Delta t} = -c \frac{u_{i+1}^t - u_{i-1}^t}{2\Delta x}$$

Derive the modified equation for the scheme above:

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = -\frac{c\Delta x}{2} \nu \frac{\partial^2 u}{\partial x^2} - \frac{c(\Delta x)^2}{6} (1 + 2\nu^2) \frac{\partial^3 u}{\partial x^3} + \dots$$

and verify the scheme is unconditionally unstable.

*Soln.* Let  $u$  satisfy the finite difference equation. Taylor expanding, we have

$$\begin{aligned} u_i^{n+1} &= u_i^n + \Delta t \left( \frac{\partial u}{\partial t} \right)_i + \frac{(\Delta t)^2}{2} \left( \frac{\partial^2 u}{\partial t^2} \right)_i + \frac{(\Delta t)^3}{6} \left( \frac{\partial^3 u}{\partial t^3} \right)_i + \mathcal{O}((\Delta t)^4) \\ u_{i+1}^n &= u_i^n + \Delta x \left( \frac{\partial u}{\partial x} \right)_i + \frac{(\Delta x)^2}{2} \left( \frac{\partial^2 u}{\partial x^2} \right)_i + \frac{(\Delta x)^3}{6} \left( \frac{\partial^3 u}{\partial x^3} \right)_i + \mathcal{O}((\Delta x)^4) \\ u_{i-1}^n &= u_i^n - \Delta x \left( \frac{\partial u}{\partial x} \right)_i + \frac{(\Delta x)^2}{2} \left( \frac{\partial^2 u}{\partial x^2} \right)_i - \frac{(\Delta x)^3}{6} \left( \frac{\partial^3 u}{\partial x^3} \right)_i + \mathcal{O}((\Delta x)^4) \\ \Rightarrow \frac{u_i^{n+1} - u_i^n}{\Delta t} &= \frac{\partial u}{\partial t} + \frac{\Delta t}{2} \frac{\partial^2 u}{\partial t^2} + \frac{(\Delta t)^2}{6} \frac{\partial^3 u}{\partial t^3} + \mathcal{O}((\Delta t)^3) \\ \frac{u_{i+1}^n - u_{i-1}^n}{2\Delta x} &= \frac{\partial u}{\partial x} + \frac{(\Delta x)^2}{6} \frac{\partial^3 u}{\partial x^3} + \mathcal{O}((\Delta x)^4) \end{aligned}$$

So the finite difference scheme becomes

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = -\frac{\Delta t}{2} \frac{\partial^2 u}{\partial t^2} - \frac{(\Delta t)^2}{6} \frac{\partial^3 u}{\partial t^3} - c \frac{(\Delta x)^2}{6} \frac{\partial^3 u}{\partial x^3} + \mathcal{O}((\Delta x)^4 + (\Delta t)^2). \quad (4)$$

To derive the modified equation, we wish to express  $\frac{\partial^2 u}{\partial t^2}, \frac{\partial^3 u}{\partial t^3}$  in terms of  $\frac{\partial^n u}{\partial x^n}$ . First differentiate (4) with respect to  $t$ :

$$\frac{\partial^2 u}{\partial t^2} + \frac{\partial^2 u}{\partial t \partial x} = -\frac{\Delta t}{2} \frac{\partial^3 u}{\partial t^3} - \frac{(\Delta t)^2}{6} \frac{\partial^4 u}{\partial t^4} - c \frac{(\Delta x)^2}{6} \frac{\partial^4 u}{\partial t \partial x^3} + \dots$$

We wish to keep up to second order terms in (4), so we truncate after the linear terms, giving

$$\frac{\partial^2 u}{\partial t^2} + c \frac{\partial^2 u}{\partial t \partial x} = -\frac{\Delta t}{2} \frac{\partial^3 u}{\partial t^3} + \dots \quad (5)$$

Differentiating (4) with respect to  $t$ , we find (to leading order)

$$\frac{\partial^3 u}{\partial t^3} = -c \frac{\partial^3 u}{\partial t^2 \partial x} + \dots \quad (6)$$

Now, we need to express  $\frac{\partial^3 u}{\partial t \partial x^2}, \frac{\partial^3 u}{\partial t^2 \partial x}$  in terms of  $\frac{\partial^n u}{\partial x^n}$ . Assuming a sufficiently smooth solution  $u$ , we have

$$\begin{aligned} \frac{\partial^3 u}{\partial x^2 \partial t} &= \frac{\partial^2}{\partial x^2} \left( \frac{\partial u}{\partial t} \right) \\ \frac{\partial^3 u}{\partial x \partial t^2} &= \frac{\partial}{\partial x} \left( \frac{\partial^2 u}{\partial t^2} \right) \end{aligned}$$

Notice that we have (to leading order)

$$\begin{aligned}\frac{\partial^2}{\partial x^2} \left( \frac{\partial u}{\partial t} \right) &= \frac{\partial^2}{\partial x^2} \left( -c \frac{\partial u}{\partial x} + \dots \right) \\ &= -c \frac{\partial^3 u}{\partial x^3} + \dots\end{aligned}$$

and

$$\begin{aligned}\frac{\partial}{\partial x} \left( \frac{\partial^2 u}{\partial t^2} \right) &= \frac{\partial}{\partial x} \left( -c \frac{\partial^2 u}{\partial x \partial t} + \dots \right) \\ &= -c \frac{\partial^2}{\partial x^2} \left( \frac{\partial u}{\partial t} + \dots \right) \\ &= -c \frac{\partial^2}{\partial x^2} \left( -c \frac{\partial u}{\partial x} + \dots \right) \\ &= c^2 \frac{\partial^3 u}{\partial x^3} + \dots\end{aligned}$$

which gives us

$$\frac{\partial^3 u}{\partial t^3} = -c^3 \frac{\partial^3 u}{\partial x^3} + \dots$$

and

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} + c^3 \Delta t \frac{\partial^3 u}{\partial x^3} + \dots$$

Putting these equations into (4), we find

$$\begin{aligned}\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} &= -\frac{\Delta t}{2} \left( c^2 \frac{\partial^2 u}{\partial x^2} + c^3 \Delta t \frac{\partial^3 u}{\partial x^3} + \dots \right) - \frac{(\Delta t)^2}{6} \left( -c^3 \frac{\partial^3 u}{\partial x^3} + \dots \right) - c \frac{(\Delta x)^2}{6} \frac{\partial^3 u}{\partial x^3} + \dots \\ &= -c^2 \frac{\Delta t}{2} \frac{\partial^2 u}{\partial x^2} - c^3 \frac{(\Delta t)^2}{2} \frac{\partial^3 u}{\partial x^3} + c^3 \frac{(\Delta t)^2}{6} \frac{\partial^3 u}{\partial x^3} - c \frac{(\Delta x)^2}{6} \frac{\partial^3 u}{\partial x^3} + \dots \\ &= -c\nu \frac{\Delta x}{2} \frac{\partial^2 u}{\partial x^2} - c \frac{(\Delta x)^2}{6} (1 + 2\nu^2) \frac{\partial^3 u}{\partial x^3} + \dots\end{aligned}$$

where we used  $\nu = c \frac{\Delta t}{\Delta x}$ , as desired.

Now, to verify that the scheme is unconditionally unstable, we apply von Neumann stability analysis: let  $u_i^n = e^{at+ikx}$ . Then the scheme becomes

$$\begin{aligned}\frac{e^{a(t+\Delta t)+ikx} - e^{at+ikx}}{\Delta t} &= -c \frac{e^{at+ik(x+\Delta x)} - e^{at+ik(x-\Delta x)}}{2\Delta x} \\ \implies \frac{e^{a\Delta t} - 1}{\Delta t} &= -c \frac{e^{ik\Delta x} - e^{-ik\Delta x}}{2\Delta x} \\ \implies e^{a\Delta t} &= 1 - \frac{c\Delta t}{\Delta x} \left( \frac{e^{ik\Delta x} - e^{-ik\Delta x}}{2} \right) \\ \implies e^{a\Delta t} &= 1 - i \frac{c\Delta t}{\Delta x} \sin(k\Delta x).\end{aligned}$$

For stability, we require  $|e^{a\Delta t}|^2 \leq 1$ . From above, we have

$$|e^{a\Delta t}|^2 = 1 + \left( \frac{c\Delta t}{\Delta x} \right)^2 \sin^2(k\Delta x)$$

and since  $\left( \frac{c\Delta t}{\Delta x} \right)^2 \sin^2(k\Delta x) \geq 0$ , we have  $|e^{a\Delta t}|^2 \geq 1$ , hence the scheme is unconditionally unstable, as desired.



6. Consider first order wave equation

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = 0$$

The Lax-Wendroff scheme for this wave equation is given as:

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} + c \frac{u_{i+1}^n - u_{i-1}^n}{2\Delta x} = \frac{c^2 \Delta t}{2} \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{(\Delta x)^2}$$

Derive the associated modified equation:

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = -\frac{c(\Delta x)^2}{6}(1 - \nu^2) \frac{\partial^3 u}{\partial x^3} - \frac{c(\Delta x)^3}{8} \nu(1 - \nu^2) \frac{\partial^4 u}{\partial x^4} + \dots$$

and verify that the scheme is conditionally stable for  $\nu \leq 1$ .

*Soln.* We begin by showing the method is conditionally stable for  $\nu \leq 1$ . Replace  $u_i^n = e^{at+ikx}$  so that the scheme becomes

$$\begin{aligned} \frac{e^{a(t+\Delta t)+ikx} - e^{at+ikx}}{\Delta t} + c \frac{e^{at+ik(x+\Delta x)} - e^{at+ik(x-\Delta x)}}{2\Delta x} &= \frac{c^2 \Delta t}{2} \frac{e^{at+ik(x+\Delta x)} - 2e^{at+ikx} + e^{at+ik(x-\Delta x)}}{(\Delta x)^2} \\ \Rightarrow \frac{e^{a\Delta t} - 1}{\Delta t} + c \frac{e^{ik\Delta x} - e^{-ik\Delta x}}{2\Delta x} &= \frac{c^2 \Delta t}{2} \frac{e^{ik\Delta x} + e^{-ik\Delta x} - 2}{(\Delta x)^2} \\ \Rightarrow e^{a\Delta t} &= 1 - \frac{c\Delta t}{2\Delta x} (e^{ik\Delta x} - e^{-ik\Delta x}) + \left(\frac{c\Delta t}{\Delta x}\right)^2 (e^{ik\Delta x} + e^{-ik\Delta x} - 2) \\ \Rightarrow e^{a\Delta t} &= 1 - i \frac{c\Delta t}{\Delta x} \sin(k\Delta x) + \left(\frac{c\Delta t}{\Delta x}\right)^2 (\cos(k\Delta x) - 1) \\ \Rightarrow |e^{a\Delta t}|^2 &= \left(1 + \left(\frac{c\Delta t}{\Delta x}(\cos(k\Delta x) - 1)\right)\right)^2 + \left(\frac{c\Delta t}{\Delta x}\right)^2 \sin^2(k\Delta x) \\ \Rightarrow |e^{a\Delta t}|^2 &= 1 + 2 \left(\frac{c\Delta t}{\Delta x}\right) (\cos(k\Delta x) - 1) + \left(\frac{c\Delta t}{\Delta x}\right)^2 (\cos(k\Delta x) - 1)^2 + \left(\frac{c\Delta t}{\Delta x}\right)^2 \sin^2(k\Delta x) \\ &= 1 + 2 \left(\frac{c\Delta t}{\Delta x}\right) (\cos(k\Delta x) - 1) + \left(\frac{c\Delta t}{\Delta x}\right)^2 (\cos^2(k\Delta x) - 2\cos(k\Delta x) + 1) + \left(\frac{c\Delta t}{\Delta x}\right)^2 \sin^2(k\Delta x) \\ &= 1 + 2 \left(\frac{c\Delta t}{\Delta x}\right) \cos(k\Delta x) - 2 \left(\frac{c\Delta t}{\Delta x}\right) + \left(\frac{c\Delta t}{\Delta x}\right)^2 (\cos^2(k\Delta x) + \sin^2(k\Delta x)) + \\ &\quad - 2 \left(\frac{c\Delta t}{\Delta x}\right)^2 \cos(k\Delta x) + \left(\frac{c\Delta t}{\Delta x}\right)^2 \\ &= 1 + 2 \left(\frac{c\Delta t}{\Delta x}\right) \cos(k\Delta x) - 2 \left(\frac{c\Delta t}{\Delta x}\right) + \left(\frac{c\Delta t}{\Delta x}\right)^2 - 2 \left(\frac{c\Delta t}{\Delta x}\right)^2 \cos(k\Delta x) + \left(\frac{c\Delta t}{\Delta x}\right)^2 \\ &= 1 + 2 \left(\frac{c\Delta t}{\Delta x}\right) \cos(k\Delta x) - 2 \frac{c\Delta t}{\Delta x} + 2 \left(\frac{c\Delta t}{\Delta x}\right)^2 - 2 \left(\frac{c\Delta t}{\Delta x}\right)^2 \cos(k\Delta x) \\ &= 1 + 2 \left(\frac{c\Delta t}{\Delta x}\right) \left[ \frac{c\Delta t}{\Delta x} - 1 - \frac{c\Delta t}{\Delta x} \cos(k\Delta x) + \cos(k\Delta x) \right] \\ &= 1 + 2 \left(\frac{c\Delta t}{\Delta x}\right) \left[ \left(\frac{c\Delta t}{\Delta x} - 1\right) - \cos(k\Delta x) \left(\frac{c\Delta t}{\Delta x} - 1\right) \right] \\ &= 1 + 2 \left(\frac{c\Delta t}{\Delta x}\right) \left(\frac{c\Delta t}{\Delta x} - 1\right) [1 - \cos(k\Delta x)] \leq 1 \\ \Rightarrow 2 \left(\frac{c\Delta t}{\Delta x}\right) \left(\frac{c\Delta t}{\Delta x} - 1\right) [1 - \cos(k\Delta x)] &\leq 0 \end{aligned}$$

which is satisfied whenever  $0 \leq \frac{c\Delta t}{\Delta x} \leq 1$ . Thus the scheme is conditionally stable whenever

$$\nu := \frac{c\Delta t}{\Delta x} \leq 1$$

as desired.