

# Homework 1

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## Section 1.2 Problems

3. Classify the following differential equations. Is the equation linear, autonomous? What is its order?

- (i)  $y'(x) + y(x) = 0$ .
- (ii)  $\frac{d^2}{dt^2}u(t) = t \sin(u(t))$ .
- (iii)  $y(t)^2 + 2y(t) = 0$ .
- (iv)  $\frac{\partial^2}{\partial x^2}u(x, y) + \frac{\partial^2}{\partial y^2}u(x, y) = 0$ .
- (v)  $\dot{x} = -y, \dot{y} = x$ .

*Soln.*

- (i)  $y'(x) + y(x) = 0$  is a first order, linear, autonomous equation.
- (ii)  $\frac{d^2}{dt^2}u(t) = t \sin(u(t))$  is a second order, nonlinear, non-autonomous equation.
- (iii)  $y(t)^2 + 2y(t) = 0$  is a zeroth order, nonlinear, autonomous equation.
- (iv)  $\frac{\partial^2}{\partial x^2}u(x, y) + \frac{\partial^2}{\partial y^2}u(x, y) = 0$  is a second order, linear, autonomous equation.
- (v)  $\dot{x} = -y, \dot{y} = x$  is a first order, linear, autonomous system of equations.

4. Which of the following differential equations for  $y(x)$  are linear?

- (i)  $y' = \sin(x)y + \cos(y)$ .
- (ii)  $y' = \sin(y)x + \cos(x)$ .
- (iii)  $y' = \sin(x)y + \cos(x)$ .

*Soln.*

- (i)  $y' = \sin(x)y + \cos(y)$  is nonlinear because of the appearance of the  $\cos(y)$  term.
- (ii)  $y' = \sin(y)x + \cos(x)$  is nonlinear because of the appearance of the  $\sin(y)$  term.
- (iii)  $y' = \sin(x)y + \cos(x)$  is linear since the  $y$  terms and all its derivative terms appear linearly.

6. Transform the following differential equations into first-order systems.

- (i)  $\ddot{x} + t \sin(\dot{x}) = x$ .
- (ii)  $\ddot{x} = -y, \ddot{y} = x$ .

*Soln.*

- (i) Let  $y = \dot{x}$  so that the equation becomes the following system:

$$\begin{cases} \dot{x} = y \\ \dot{y} = x - t \sin(y) \end{cases}$$

- (ii) Let  $z = \dot{x}$  and  $w = \dot{y}$  so that the system becomes the new system

$$\begin{cases} \dot{x} = z \\ \dot{y} = w \\ \dot{z} = -y \\ \dot{w} = x \end{cases}$$

7. Transform the following differential equations into autonomous first-order systems.

(i)  $\ddot{x} + t \sin(\dot{x}) = x$ .

(ii)  $\ddot{x} = -\cos(t)x$ .

The last equation is linear. Is the corresponding autonomous system also linear?

*Soln.*

(i) Let  $z_1 = t$ ,  $z_2 = x$ , and  $z_3 = \dot{x}$  so that the equation becomes the new system

$$\begin{cases} \dot{z}_1 = 1 \\ \dot{z}_2 = z_3 \\ \dot{z}_3 = z_2 - z_1 \sin(z_3) \end{cases}$$

(ii) Let  $z_1 = t$ ,  $z_2 = x$ , and  $z_3 = \dot{x}$  so that the equation becomes the new system

$$\begin{cases} \dot{z}_1 = 1 \\ \dot{z}_2 = z_3 \\ \dot{z}_3 = -\cos(z_1)z_2 \end{cases}$$

Notice that, while the original equation was linear, our transformed equation is nonlinear because of the appearance of the  $\cos(z_1)$  term for the  $\dot{z}_3$  equation.

## Section 1.3 Problems

9. Solve the following differential equations:

(i)  $\dot{x} = x^3$ .

(ii)  $\dot{x} = x(1 - x)$ .

*Soln.*

(i) Rewriting the differential equation, we have

$$\frac{dx}{dt} = x^3$$

via separation of variables, we find

$$\begin{aligned} \frac{dx}{x^3} &= dt \\ \int \frac{dx}{x^3} &= \int dt \\ -\frac{1}{2x^2} &= t + C \\ x^2 &= -\frac{1}{2(t + C)} \\ x(t) &= \pm \sqrt{-\frac{1}{2(t + C)}} \end{aligned}$$

where  $C$  is a constant of integration and  $t + C < 0$ .

(ii) Rewriting the differential equation, we have

$$\frac{dx}{dt} = x(1 - x)$$

via separation of variables, we find

$$\begin{aligned}
 \frac{dx}{x(1-x)} &= dt \\
 \int \frac{dx}{x(1-x)} &= \int dt \\
 \int \frac{dx}{x} + \int \frac{dx}{1-x} &= t + C \\
 \ln|x| - \ln|1-x| &= t + C \\
 \ln\left|\frac{x}{1-x}\right| &= t + C \\
 \frac{x}{1-x} &= C_1 e^t \\
 x &= C_1 e^t - x C_1 e^t \\
 x(1 + C_1 e^t) &= C_1 e^t \\
 x(t) &= \frac{C_1 e^t}{1 + C_1 e^t}
 \end{aligned}$$

where  $C_1 = e^C$  with  $C$  a constant of integration.

10. Show that the solution of (1.20) is unique if  $f \in C^1(\mathbb{R})$ .

*Proof:* Suppose by way of contradiction that there exist two distinct functions  $\phi(t)$  and  $\varphi(t)$  that satisfy (1.20) and further suppose that that  $I_t$  is an open interval containing  $t_0$  such that the differential equation (1.20) is satisfied, and let  $I_x$  be the associated open interval that contains  $x_0$ . Since  $f \in C^1(\mathbb{R})$ , by the mean value theorem, for  $(x_0, x) \subseteq I_x$  (likewise  $(t_0, t) \in I_t$ ), there exists a  $c(x) \in (x_0, x)$  such that

$$f'(c(x)) = \frac{f(x) - f(x_0)}{x - x_0}$$

but from (1.20), we have  $\dot{\phi}(t) = f(x)$  and  $\dot{\varphi}(t) = f(x)$ , hence from the above equation, we find

$$\frac{\dot{\phi}(t) - f(x_0)}{x - x_0} = \frac{\dot{\varphi}(t) - f(x_0)}{x - x_0}$$

Hence,

$$\begin{aligned}
 \dot{\phi}(t) - f(x_0) &= \dot{\varphi}(t) - f(x_0) \\
 \dot{\phi}(t) &= \dot{\varphi}(t) \\
 \phi(t) &= \varphi(t) + C
 \end{aligned}$$

Plugging in  $t = t_0$ , we find

$$\begin{aligned}
 \phi(t_0) &= \varphi(t_0) + C \\
 x_0 &= x_0 + C \\
 C &= 0
 \end{aligned}$$

Hence,  $\phi(t) = \varphi(t)$ . And since  $t \in I_t$  was chosen arbitrarily, we have that  $\phi(t) = \varphi(t)$  for all  $t$  satisfying the differential equation, a contradiction.

12. Solve the following differential equations:

(i)  $\dot{x} = \sin(t)x$ .

(iii)  $\dot{x} = \sin(t)e^x$ .

Sketch the solutions. For which initial conditions (if any) are the solutions bounded?

*Soln.*

(i) Rewriting our differential equation, we have

$$\frac{dx}{dt} = \sin(t)x$$

via separation of variables, we find

$$\begin{aligned}\frac{dx}{x} &= \sin(t)dt \\ \int \frac{dx}{x} &= \int \sin(t)dt \\ \ln|x| &= -\cos(t) + C \\ x(t) &= C_1 e^{-\cos(t)}\end{aligned}$$

where  $C_1 = e^C$  with  $C$  a constant of integration. Notice that since  $|\cos(t)| \leq 1$  for all  $t$ ,

$$C_1 e^{-1} \leq x(t) \leq C_1 e$$

so  $x(t)$  is bounded for all  $t$ . Hence, for any initial condition, the solution remains bounded.

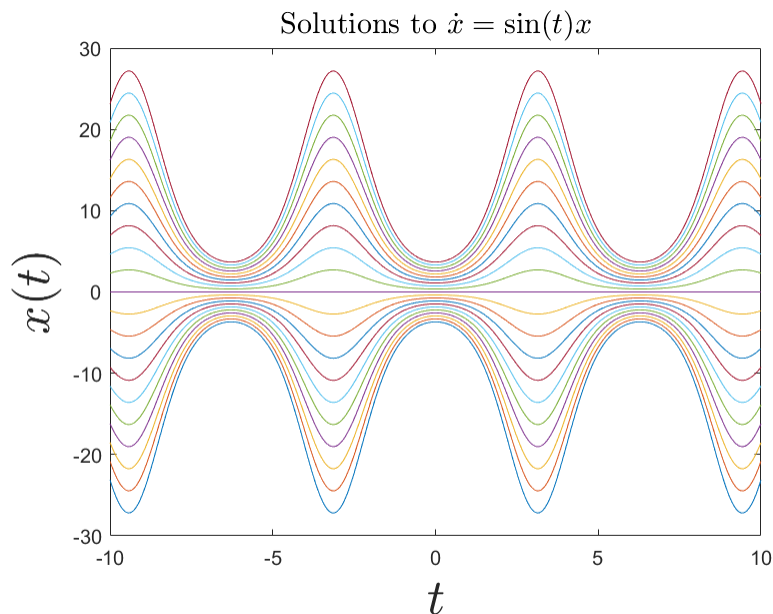


Figure 1: Various solutions to  $\dot{x} = \sin(t)x$  for values of  $C_1$  between  $-10$  and  $10$ .

(iii) Rewriting the differential equation, we have

$$\frac{dx}{dt} = \sin(t)e^x$$

via separation of variables, we find

$$\begin{aligned}\frac{dx}{e^x} &= \sin(t)dt \\ \int e^{-x} dx &= \int \sin(t)dt \\ -e^{-x} &= -\cos(t) + C \\ e^{-x} &= \cos(t) - C \\ -x &= \ln(\cos(t) - C) \\ x(t) &= -\ln(\cos(t) - C)\end{aligned}$$

Where  $C$  is a constant of integration. For some initial condition  $x(0) = x_0$ , from our above equation, we find

$$\begin{aligned}x_0 &= -\ln(1 - C) \\ e^{-x_0} &= 1 - C \\ C &= 1 - e^{-x_0}\end{aligned}$$

so that we may rewrite our solution as

$$x(t) = -\ln(\cos(t) - 1 + e^{-x_0})$$

Note that since  $|\cos(t)| \leq 1$  for all  $t$ , the argument of the natural log will never go to infinity, and thus is bounded so long as

$$\cos(t) - 1 + e^{-x_0} \neq 0$$

or equivalently,

$$\cos(t) \neq 1 - e^{-x_0}$$

and since  $|\cos(t)| \leq 1$  is continuous,  $\cos(t)$  will attain every real value between  $-1$  and  $1$ . Hence, our above condition is equivalent to

$$|1 - e^{-x_0}| > 1$$

which means that either

$$1 - e^{-x_0} > 1$$

or

$$-1 + e^{-x_0} > 1.$$

Notice that the first condition is never satisfied, so turning our attention to the second condition, we have (using the fact that  $\ln(\cdot)$  is monotone),

$$\begin{aligned}e^{-x_0} &> 2 \\ -x_0 &> \ln(2) \\ x_0 &< -\ln(2)\end{aligned}$$

Thus, our solution is bounded for all initial conditions  $x_0 < -\ln(2)$ .

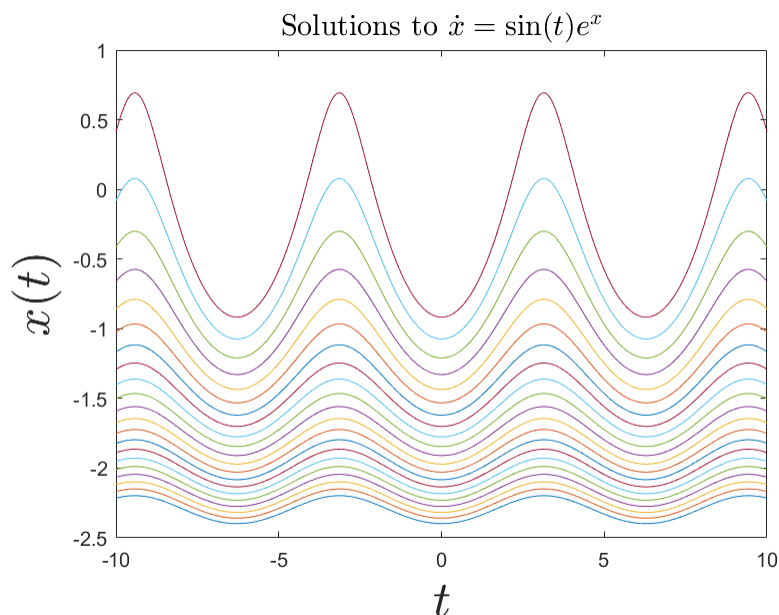


Figure 2: Various solutions to  $\dot{x} = \sin(t)e^x$  for values of  $C$  between  $-10$  and  $-1.5$ .

## Section 1.4 Problems

18. Try to find solutions of the following differential equations:

- (i)  $\dot{x} = \frac{3x-2t}{t}$ .
- (ii)  $\dot{x} = \frac{x-t+2}{2x+t+1} + 5$ .
- (iii)  $y' = y^2 - \frac{y}{x} - \frac{1}{x^2}$ .
- (iv)  $y' = \frac{y}{x} - \tan\left(\frac{y}{x}\right)$ .

*Soln.*

- (i) To begin, notice we may rewrite the differential equation as

$$\dot{x} = f\left(\frac{x}{t}\right)$$

for  $f\left(\frac{x}{t}\right) = 3\frac{x}{t} - 2$ . Let  $y = \frac{x}{t}$ . Then

$$\dot{y} = \frac{1}{t}f(y) - \frac{y}{t}$$

so that

$$\begin{aligned} \int \frac{dy}{f(y) - y} &= \int \frac{dt}{t} \\ \int \frac{dy}{3y - 2 - y} &= \ln|t| + C_0 \\ \frac{1}{2} \int \frac{dy}{y - 1} &= \ln|t| + C_0 \\ \ln|y - 1| &= \ln(t^2) + C_1 \\ y - 1 &= C_2 t^2 \\ y &= C_2 t^2 + 1 \end{aligned}$$

Substituting back  $y = \frac{x}{t}$ , we find the solution to our differential equation is

$$x(t) = C_2 t^3 + t$$

(ii) Rewriting, we have

$$\begin{aligned}\dot{x} &= f(x, t) \\ &= \frac{11x + 4t + 7}{2x + t + 1} \\ &= \frac{ax + bt + c}{\alpha x + \beta t + \gamma}\end{aligned}$$

for  $a = 11, b = 4, c = 7$  and  $\alpha = 2, \beta = 1, \gamma = 1$ . Note that  $a\beta - \alpha b = 3 \neq 0$ , so we will make the substitution  $y = x - x_0, s = t - t_0$  where  $x_0, t_0$  solve the following linear system:

$$\begin{pmatrix} 11 & 4 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x_0 \\ t_0 \end{pmatrix} = \begin{pmatrix} -7 \\ -1 \end{pmatrix}$$

which has the unique solution  $(x_0, t_0)^T = (-1, 1)$ . Hence, let  $y = x + 1$  and  $s = t - 1$  so that  $f(y, s)$  becomes

$$\begin{aligned}f(y, s) &= \frac{11y + 4s}{2y + s} \\ &= \frac{11\frac{y}{s} + 4}{2\frac{y}{s} + 1} \\ &= f\left(\frac{y}{s}\right)\end{aligned}$$

Let  $z = \frac{y}{s}$  so that  $f\left(\frac{y}{s}\right) = f(z)$  and  $\dot{z} = \frac{f(z)-z}{s} = \frac{1}{s} \left( \frac{-2z^2 + 10z + 4}{2z + 1} \right)$  and our equation is now separable. Then

$$\begin{aligned}\dot{z} &= \frac{1}{s} \left( \frac{-2z^2 + 10z + 4}{2z + 1} \right) \\ \int \frac{2z + 1}{-2z^2 + 10z + 4} dz &= \int \frac{1}{s} ds.\end{aligned}$$

Let us evaluate the integral on the left hand side of the above equation:

$$\begin{aligned}\int \frac{2z + 1}{-2z^2 + 10z + 4} dz &= -\frac{1}{2} \int \frac{2z + 1}{z^2 - 5z - 2} dz \\ &= -\frac{1}{2} \int \frac{2z - 5 + 6}{z^2 - 5z - 2} dz \\ &= -\frac{1}{2} \int \frac{2z - 5}{z^2 - 5z - 2} dz - 3 \int \frac{1}{z^2 - 5z - 2} dz \\ &= -\frac{1}{2} \ln |z^2 - 5z - 2| - 3 \int \frac{1}{\left(z - \frac{5}{2}\right)^2 - \frac{29}{4}} dz\end{aligned} \tag{1}$$

Now, inspecting the second integral, let  $z - \frac{5}{2} = \frac{\sqrt{29}}{2} \tanh(\varphi)$  so that  $dz = \frac{\sqrt{29}}{2} \operatorname{sech}^2(\varphi) d\varphi$  and the integral becomes

$$\begin{aligned}\int \frac{1}{\left(z - \frac{5}{2}\right)^2 - \frac{29}{4}} dz &= \int \frac{\frac{\sqrt{29}}{4} \operatorname{sech}^2(\varphi)}{\frac{29}{4} \operatorname{sech}^2(\varphi)} d\varphi \\ &= \frac{1}{\sqrt{29}} \varphi + C \\ &= \frac{1}{\sqrt{29}} \tanh^{-1} \left( \frac{2}{\sqrt{29}} \left( z - \frac{5}{2} \right) \right) + C.\end{aligned}$$

Then (1) becomes

$$-\frac{1}{2} \ln |z^2 - 5z - 2| - \frac{3}{\sqrt{29}} \tanh^{-1} \left( \frac{2}{\sqrt{29}} \left( z - \frac{5}{2} \right) \right) + C.$$

Hence, our differential equation becomes

$$-\frac{1}{2} \ln |z^2 - 5z - 2| - \frac{3}{\sqrt{29}} \tanh^{-1} \left( \frac{2}{\sqrt{29}} \left( z - \frac{5}{2} \right) \right) = \ln |s| + C$$

Substituting back in  $z = \frac{y}{s}$ , we have

$$-\frac{1}{2} \ln \left| \left( \frac{y}{s} \right)^2 - 5 \frac{y}{s} + 2 \right| - \frac{3}{\sqrt{29}} \tanh^{-1} \left( \frac{2}{\sqrt{29}} \left( z - \frac{5}{2} \right) \right) = \ln |s| + C.$$

Now, substituting back in  $y = x + 1$  and  $s = t - 1$ , we have

$$-\frac{1}{2} \ln \left| \left( \frac{x+1}{t-1} \right)^2 - 5 \left( \frac{x+1}{t-1} \right) + 2 \right| - \frac{3}{\sqrt{29}} \tanh^{-1} \left( \frac{2}{\sqrt{29}} \left( \frac{x+1}{t-1} - \frac{5}{2} \right) \right) = \ln |t-1| + C.$$

So the solution to our differential equation satisfies the above implicit equation.

(iii) Notice we may rewrite the differential equation as

$$y' = \frac{(xy)^2 - xy - 1}{x^2}$$

Let  $z = xy$ . Then

$$y' = \frac{z^2 - z - 1}{x^2}$$

and  $z' = y'x + y$  so that

$$z' = \frac{z^2 - 1}{x}$$

Solving via separation of variables, we find

$$\begin{aligned} \int \frac{dz}{z^2 - 1} &= \int \frac{dx}{x} \\ \frac{1}{2} \int \frac{dz}{z-1} - \frac{1}{2} \int \frac{dz}{z+1} &= \ln |x| + C_0 \\ \ln |z-1| - \ln |z+1| &= \ln(x^2) + C_1 \\ \ln \left| \frac{z-1}{z+1} \right| &= \ln(x^2) + C_1 \\ \frac{z-1}{z+1} &= C_2 x^2 \\ z &= C_2 x^2 z + C_2 x^2 + 1 \\ z(1 - C_2 x^2) &= C_2 x^2 + 1 \\ z &= \frac{C_2 x^2 + 1}{1 - C_2 x^2} \end{aligned}$$

Substituting  $xy$  back in for  $z$ , we find the solution to our differential equation as

$$y(x) = \frac{C_2 x^2 + 1}{x - C_2 x^3}$$



(iv) Let  $z = \frac{y}{x}$  so that

$$y' = f(z)$$

with  $f(z) = \frac{x}{y} - \tan\left(\frac{y}{x}\right)$  and  $z' = \frac{f(z)-z}{x}$ . Using separation of variables,

$$\begin{aligned}\int \frac{dz}{f(z)-z} &= \int \frac{dx}{x} \\ \int \frac{dz}{-\tan(z)} &= \ln|x| + C_0 \\ -\ln|\sin(z)| &= \ln|x| + C_0 \\ \ln|\sin(z)| &= \ln\left|\frac{1}{x}\right| + C_1 \\ \sin(z) &= \frac{C_2}{x} \\ z &= \arcsin\left(\frac{C_2}{x}\right)\end{aligned}$$

substituting back  $\frac{y}{x} = z$ , we have the solution to our differential equation as

$$y(x) = x \arcsin\left(\frac{C_2}{x}\right)$$

19. (Euler equation). *Transform the differential equation*

$$t^2\ddot{x} + 3t\dot{x} + x = \frac{2}{t}$$

to the new coordinates  $y = x$ ,  $s = \log(t)$ . (Hint: You are not asked to solve it.)

*Soln.* Notice that since  $y = x$ , we have that

$$\frac{dy}{dt} = \frac{dx}{dt}$$

and

$$\frac{d^2y}{dt^2} = \frac{d^2x}{dt^2}$$

By the chain rule, we have

$$\frac{dy}{dt} = \frac{dy}{ds} \frac{ds}{dt}$$

and since  $s = \log(t)$ ,

$$\frac{ds}{dt} = \frac{1}{t} = e^{-s}$$

so that

$$\dot{x} = \dot{y}e^{-s}.$$

Additionally by the chain rule,

$$\frac{d^2y}{dt^2} = \frac{d^2y}{dx^2} \left(\frac{ds}{dt}\right)^2 + \frac{dy}{ds} \frac{d^2s}{dt^2}$$

and

$$\frac{d^2s}{dt^2} = -\frac{1}{t^2} = -e^{-2s}$$

so

$$\ddot{x} = \ddot{y}e^{-2s} - \dot{y}e^{-2s}$$

so that our differential equation becomes

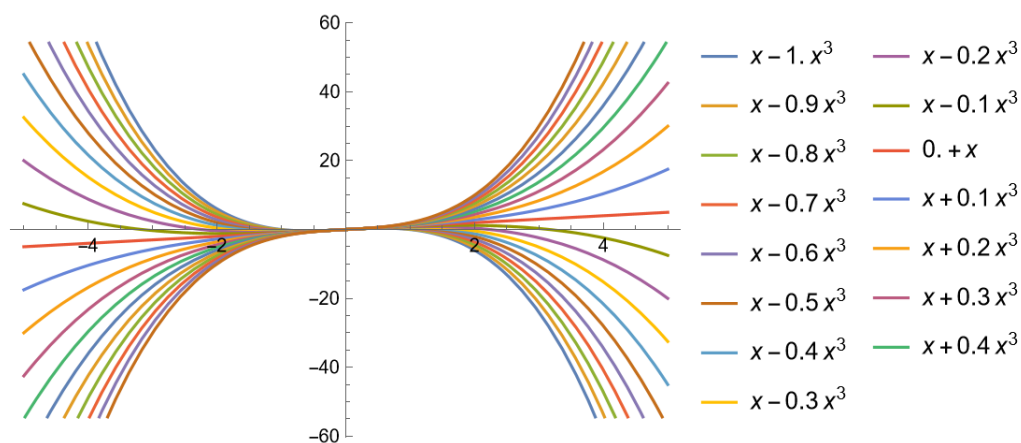
$$\begin{aligned} e^{2s}(e^{-2s}\ddot{y} - e^{-2s}\dot{y}) + 3e^s(e^{-s}\dot{y}) + y &= 2e^{-s} \\ \ddot{y} - \dot{y} + 3\dot{y} + y &= 2e^{-s} \\ \ddot{y} + 2\dot{y} + y &= 2e^{-s} \end{aligned}$$

Thus, our differential equation under the given transformation is

$$\ddot{y} + 2\dot{y} + y = 2e^{-s}$$

20. Pick some differential equations from the previous problems and solve them using your favorite computer algebra system. Plot the solutions.

Using Mathematica to solve the differential equation in problem 18 (a), and plotting for multiple values of  $C$  between  $-1$  and  $1$ , we find the following:



25. (Catenary). Solve the differential equation describing the shape  $y(x)$  of a hanging chain suspended at two points:

$$y'' = a\sqrt{1 + (y')^2}, \quad a > 0.$$

To begin, let  $v = y'$  so that  $v' = y''$  and the differential equation becomes

$$v' = a\sqrt{1 + v^2}$$

which is separable. Separating, we find

$$\begin{aligned} \int \frac{dv}{\sqrt{1 + v^2}} &= \int a dx \\ &= ax + C_0. \end{aligned}$$

To evaluate the integral on the left hand side, make the substitution  $v = \sinh(u)$  so that  $dv = \cosh(u)du$  and the integral becomes

$$\begin{aligned} \int \frac{dv}{\sqrt{1 + v^2}} &= \int \frac{\sinh(u)}{\sqrt{1 + \cosh^2(u)}} du \\ &= \int \frac{\sinh(u)}{\sinh(u)} du \\ &= \int du \\ &= u \\ &= \sinh^{-1}(v). \end{aligned}$$

We now have

$$\begin{aligned}\sinh^{-1}(v) &= ax + C_0 \\ v &= \sinh(ax + C_0) \\ \frac{dy}{dx} &= \sinh(ax + C_0) \\ \int dy &= \int \sinh(ax + C_0) dx \\ y &= \frac{1}{a} \cosh(ax + C_0) + C_1.\end{aligned}$$