

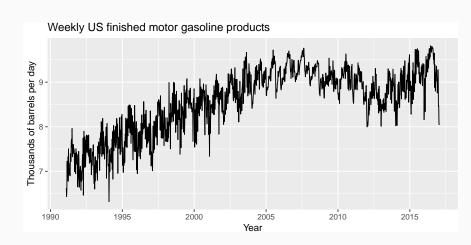
ETC3550: Applied forecasting for business and economics

Ch11. Advanced forecasting methods OTexts.org/fpp2/

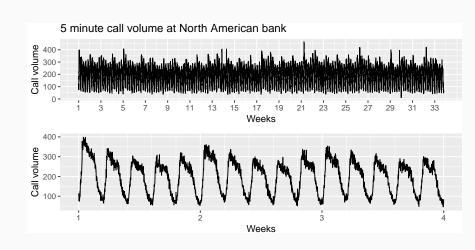
Outline

- 1 Complex seasonality
- **2** Vector autoregression
- 3 Neural network models
- 4 Bootstrapping and bagging

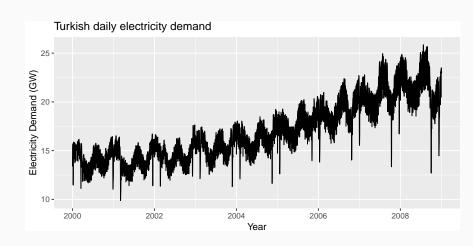
Examples



Examples



Examples



TBATS

Trigonometric terms for seasonality

Box-Cox transformations for heterogeneity

ARMA errors for short-term dynamics

Trend (possibly damped)

Seasonal (including multiple and

non-integer periods)

$$y_{t} = \text{observation at time } t$$

$$y_{t}^{(\omega)} = \begin{cases} (y_{t}^{\omega} - 1)/\omega & \text{if } \omega \neq 0; \\ \log y_{t} & \text{if } \omega = 0. \end{cases}$$

$$y_{t}^{(\omega)} = \ell_{t-1} + \phi b_{t-1} + \sum_{i=1}^{M} s_{t-m_{i}}^{(i)} + d_{t}$$

$$\ell_{t} = \ell_{t-1} + \phi b_{t-1} + \alpha d_{t}$$

$$b_{t} = (1 - \phi)b + \phi b_{t-1} + \beta d_{t}$$

$$d_{t} = \sum_{i=1}^{p} \phi_{i} d_{t-i} + \sum_{j=1}^{q} \theta_{j} \varepsilon_{t-j} + \varepsilon_{t}$$

$$s_{t}^{(i)} = \sum_{j=1}^{k_{i}} s_{j,t}^{(i)} \qquad s_{j,t}^{(i)} = s_{j,t-1}^{(i)} \cos \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \sin \lambda_{j}^{(i)} + \gamma_{1}^{(i)} d_{t}$$

$$s_{j,t}^{(i)} = -s_{j,t-1}^{(i)} \sin \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \cos \lambda_{j}^{(i)} + \gamma_{2}^{(i)} d_{t}$$

$$y_t$$
 = observation at time t

$$y_t^{(\omega)} = \begin{cases} (y_t^{\omega} - 1)/\omega & \text{if } \omega \neq 0; \\ \log y_t & \text{if } \omega = 0. \end{cases}$$

$$y_t^{(\omega)} = \ell_{t-1} + \phi b_{t-1} + \sum_{i=1}^{M} s_{t-m_i}^{(i)} + d_t$$

$$\ell_t = \ell_{t-1} + \phi b_{t-1} + \alpha d_t$$

$$b_t = (1 - \phi)b + \phi b_{t-1} + \beta d_t$$

$$d_t = \sum_{i=1}^p \phi_i d_{t-i} + \sum_{j=1}^q \theta_j \varepsilon_{t-j} + \varepsilon_t$$

$$s_{t}^{(i)} = \sum_{j=1}^{k_{i}} s_{j,t}^{(i)}$$

$$s_{j,t}^{(i)} = s_{j,t-1}^{(i)} \cos \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \sin \lambda_{j}^{(i)} + \gamma_{1}^{(i)} d_{t}$$

$$s_{j,t}^{(i)} = -s_{j,t-1}^{(i)} \sin \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \cos \lambda_{j}^{(i)} + \gamma_{2}^{(i)} d_{t}$$

Box-Cox transformation

$$y_t$$
 = observation at time t

$$y_t^{(\omega)} = \begin{cases} (y_t^{\omega} - 1)/\omega & \text{if } \omega \neq 0; \\ \log y_t & \text{if } \omega = 0. \end{cases}$$

Box-Cox transformation

M seasonal periods

$$y_{t}^{(\omega)} = \ell_{t-1} + \phi b_{t-1} + \sum_{i=1}^{M} s_{t-m_{i}}^{(i)} + d_{t}$$
$$\ell_{t} = \ell_{t-1} + \phi b_{t-1} + \alpha d_{t}$$

 $b_{t} = (1 - \phi)b + \phi b_{t-1} + \beta d_{t}$

$$d_{t} = \sum_{i=1}^{p} \phi_{i} d_{t-i} + \sum_{i=1}^{q} \theta_{j} \varepsilon_{t-j} + \varepsilon_{t}$$

$$d_t = \sum_{i=1}^{n} \phi_i d_{t-i} + \sum_{j=1}^{n} \theta_j \varepsilon_{t-j} + \varepsilon_t$$

$$s_{t}^{(i)} = \sum_{j=1}^{k_{i}} s_{j,t}^{(i)} \qquad s_{j,t}^{(i)} = s_{j,t-1}^{(i)} \cos \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \sin \lambda_{j}^{(i)} + \gamma_{1}^{(i)} d_{t}$$

$$s_{t}^{(i)} = -s_{j,t-1}^{(i)} \sin \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \cos \lambda_{j}^{(i)} + \gamma_{2}^{(i)} d_{t}$$

$$y_t$$
 = observation at time t

$$y_t^{(\omega)} = \begin{cases} (y_t^{\omega} - 1)/\omega & \text{if } \omega \neq 0; \\ \log y_t & \text{if } \omega = 0. \end{cases}$$

Box-Cox transformation

$$y_t^{(\omega)} = \ell_{t-1} + \phi b_{t-1} + \sum_{i=1}^{M} s_{t-m_i}^{(i)} + d_t$$
$$\ell_t = \ell_{t-1} + \phi b_{t-1} + \alpha d_t$$

M seasonal periods

global and local trend

$$b_t = (1 - \phi)b + \phi b_{t-1} + \beta d_t$$

$$d_{t} = \sum_{i=1}^{p} \phi_{i} d_{t-i} + \sum_{j=1}^{q} \theta_{j} \varepsilon_{t-j} + \varepsilon_{t}$$

$$k_{i} \qquad \varepsilon^{(i)} = \varepsilon^{(i)}$$

 $s_{t}^{(i)} = \sum_{j,t}^{k_{i}} s_{j,t}^{(i)} \qquad s_{j,t-1}^{(i)} \cos \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \sin \lambda_{j}^{(i)} + \gamma_{1}^{(i)} d_{t}$ $s_{j,t}^{(i)} = -s_{j,t-1}^{(i)} \sin \lambda_j^{(i)} + s_{j,t-1}^{*(i)} \cos \lambda_j^{(i)} + \gamma_2^{(i)} d_t$

$$y_t$$
 = observation at time t

$$y_t^{(\omega)} = \begin{cases} (y_t^{\omega} - 1)/\omega & \text{if } \omega \neq 0; \\ \log y_t & \text{if } \omega = 0. \end{cases}$$

Box-Cox transformation

$$y_{t}^{(\omega)} = \ell_{t-1} + \phi b_{t-1} + \sum_{i=1}^{M} s_{t-m_{i}}^{(i)} + d_{t}$$
$$\ell_{t} = \ell_{t-1} + \phi b_{t-1} + \alpha d_{t}$$

M seasonal periods

$$b_t = (1 - \phi)b + \phi b_{t-1} + \beta d_t$$

global and local trend

$$d_{t} = \sum_{i=1}^{p} \phi_{i} d_{t-i} + \sum_{i=1}^{q} \theta_{j} \varepsilon_{t-j} + \varepsilon_{t}$$

ARMA error

$$s_{t}^{(i)} = \sum_{j=1}^{k_{i}} s_{j,t}^{(i)}$$

$$s_{j,t}^{(i)} = s_{j,t-1}^{(i)} \cos \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \sin \lambda_{j}^{(i)} + \gamma_{1}^{(i)} d_{t}$$

$$s_{j,t}^{(i)} = -s_{j,t-1}^{(i)} \sin \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \cos \lambda_{j}^{(i)} + \gamma_{2}^{(i)} d_{t}$$

 y_t = observation at time t

$$y_t^{(\omega)} = \begin{cases} (y_t^{\omega} - 1)/\omega & \text{if } \omega \neq 0; \\ \log y_t & \text{if } \omega = 0. \end{cases}$$

Box-Cox transformation

$$y_{t}^{(\omega)} = \ell_{t-1} + \phi b_{t-1} + \sum_{i=1}^{M} s_{t-m_{i}}^{(i)} + d_{t}$$
$$\ell_{t} = \ell_{t-1} + \phi b_{t-1} + \alpha d_{t}$$

M seasonal periods

$$b_t = (1 - \phi)b + \phi b_{t-1} + \beta d_t$$

global and local trend

ARMA error

$$d_{t} = \sum_{i=1}^{p} \phi_{i} d_{t-i} + \sum_{i=1}^{q} \theta_{j} \varepsilon_{t-j} + \varepsilon_{t}$$

$$s_{t}^{(i)} = \sum_{j=1}^{k_{i}} s_{j,t}^{(i)}$$

$$s_{j,t}^{(i)} = s_{j,t-1}^{(i)} \text{ convier-like seasonal terms}$$

$$s_{j,t}^{(i)} = -s_{j,t-1}^{(i)} \sin \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \cos \lambda_{j}^{(i)} + \gamma_{2}^{(i)} d_{t}$$

$$y_{t} = \text{observation at time } t$$

$$y_{t}^{(\omega)} = \begin{cases} (y_{t}^{\omega} - 1)/\omega & \text{if } \omega \neq 0; \\ \text{TBATS} \end{cases}$$
Box-Cox transformation
$$y_{t}^{(\omega)} = \ell_{t} \text{Box-Cox}$$

$$\ell_{t} = \ell_{t} \text{Box-Cox}$$

$$\ell_{t} = \ell_{t} \text{ARMA}$$

$$b_{t} = (1)$$

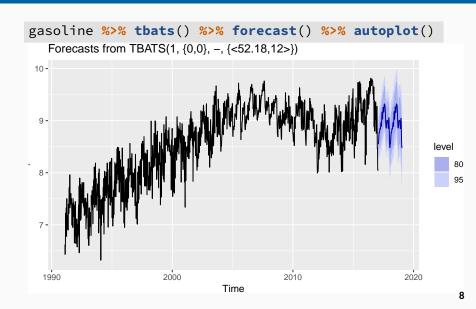
$$d_{t} = \sum_{i=1}^{k} \text{Seasonal}$$

$$s_{t}^{(i)} = \sum_{j=1}^{k_{i}} s_{j,t}^{(i)}$$

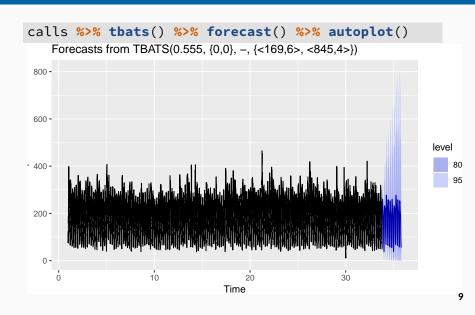
$$s_{j,t}^{(i)} = s_{j,t-1}^{(i)} \text{cc Fourier-like seasonal terms}$$

$$s_{j,t}^{(i)} = -s_{j,t-1}^{(i)} \sin \lambda_{j}^{(i)} + s_{j,t-1}^{*(i)} \cos \lambda_{j}^{(i)} + \gamma_{2}^{(i)} d_{t}$$

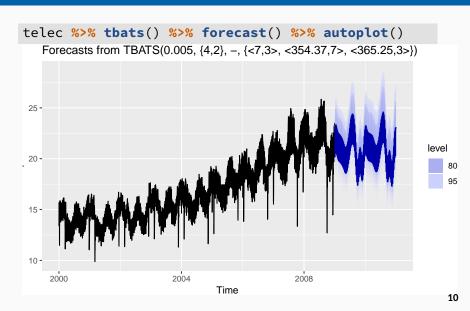
Complex seasonality



Complex seasonality



Complex seasonality



TBATS

Trigonometric terms for seasonality

Box-Cox transformations for heterogeneity

ARMA errors for short-term dynamics

Trend (possibly damped)

Seasonal (including multiple and non-integer periods)

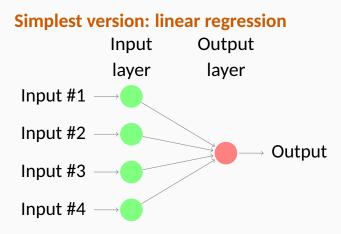
- Handles non-integer seasonality, multiple seasonal periods.
- Entirely automated
- Prediction intervals often too wide
- Very slow on long series

Outline

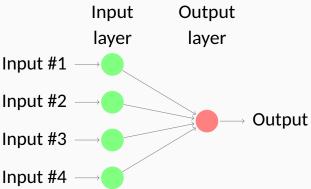
- 1 Complex seasonality
- 2 Vector autoregression
- 3 Neural network models
- 4 Bootstrapping and bagging

Outline

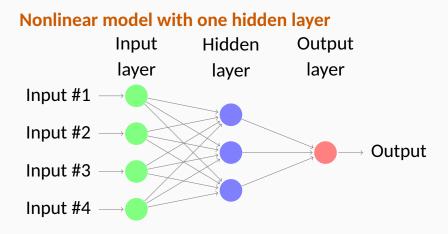
- 1 Complex seasonality
- **2** Vector autoregression
- 3 Neural network models
- 4 Bootstrapping and bagging



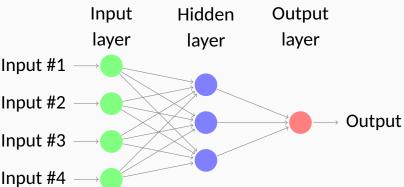




- Coefficients attached to predictors are called "weights".
- Forecasts are obtained by a linear combination of inputs.
- Weights selected using a "learning algorithm" that minimises a "cost function".



Nonlinear model with one hidden layer



- A multilayer feed-forward network where each layer of nodes receives inputs from the previous layers.
- Inputs to each node combined using linear

Inputs to hidden neuron *j* linearly combined:

$$z_j = b_j + \sum_{i=1}^4 w_{i,j} x_i.$$

Modified using nonlinear function such as a sigmoid:

$$s(z)=\frac{1}{1+e^{-z}},$$

This tends to reduce the effect of extreme input values, thus making the network somewhat robust to outliers.

- Weights take random values to begin with, which are then updated using the observed data.
- There is an element of randomness in the predictions. So the network is usually trained several times using different random starting points, and the results are averaged.
- Number of hidden layers, and the number of nodes in each hidden layer, must be specified in advance.

NNAR models

- Lagged values of the time series can be used as inputs to a neural network.
- NNAR(p, k): p lagged inputs and k nodes in the single hidden layer.
- NNAR(p, 0) model is equivalent to an ARIMA(p, 0, 0) model but without stationarity restrictions.
- Seasonal NNAR(p, P, k): inputs $(y_{t-1}, y_{t-2}, \dots, y_{t-p}, y_{t-m}, y_{t-2m}, y_{t-Pm})$ and k neurons in the hidden layer.
- NNAR(p, P, 0) $_m$ model is equivalent to an ARIMA(p, 0, 0)(P,0,0) $_m$ model but without stationarity restrictions.

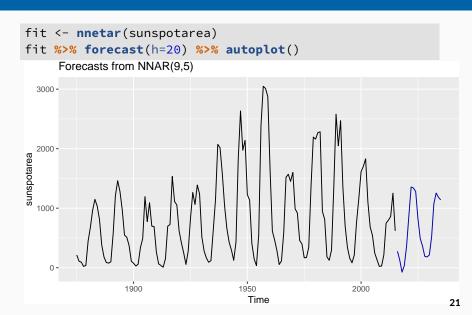
NNAR models in R

- The nnetar() function fits an NNAR(p, P, k)_m model.
- If *p* and *P* are not specified, they are automatically selected.
- For non-seasonal time series, default p = optimal number of lags (according to the AIC) for a linear AR(p) model.
- For seasonal time series, defaults are *P* = 1 and *p* is chosen from the optimal linear model fitted to the seasonally adjusted data.
- Default k = (p + P + 1)/2 (rounded to the nearest integer).

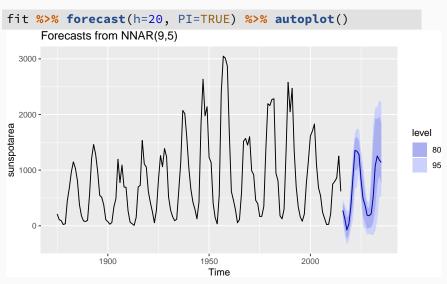
Sunspots

- Surface of the sun contains magnetic regions that appear as dark spots.
- These affect the propagation of radio waves and so telecommunication companies like to predict sunspot activity in order to plan for any future difficulties.
- Sunspots follow a cycle of length between 9 and 14 years.

NNAR(9,5) model for sunspots



Prediction intervals by simulation



Outline

- 1 Complex seasonality
- **2** Vector autoregression
- 3 Neural network models
- 4 Bootstrapping and bagging