

NUMBER REPRESENTATION

Mahdi Nazm Bojnordi

Assistant Professor

School of Computing

University of Utah

Overview

- Homework 4 is due on Feb. 7th
 - Verify your uploaded file before the deadline

Important Notes:

- Solutions turned in must be your own. Please, mention references (if any) at the end of each question. Please refrain from cheating.
- All units must be mentioned wherever required.
- Late submissions (after 11:59 pm) will not be accepted
- All submissions must be in **PDF only**. Scanned copies of handwritten solutions will not be accepted as a valid submission.
- **Show your solution steps** so you receive partial credit for incorrect answers and we know you have understood the material. Don't just show us the final answer.

- This lecture
 - Data/number representation

Recall: Saving Convention

- Caller saved
 - ▣ \$t0-\$t9: the callee won't bother saving these, so save them if you care
 - ▣ \$ra: it's about to get over-written
 - ▣ \$a0-\$a3: so you can put in new arguments
- Callee saved
 - ▣ \$s0-\$s7: these typically contain “valuable” data

Dealing with Characters

- Instructions are also provided to deal with byte-sized and half-word quantities: `lb` (load-byte), `sb`, `lh`, `sh`
- These data types are most useful when dealing with characters, pixel values, etc.
 - ▣ e.g., `printf("Hello World!");`
- C employs ASCII formats to represent characters – each character is represented with 8 bits and a string ends in the null character
 - ▣ e.g., `null is 0, A is 65, a is 97`

Dealing with Characters

ASCII value	Character	ASCII value	Character	ASCII value	Character	ASCII value	Character	ASCII value	Character	ASCII value	Character
32	space	48	0	64	@	80	P	96	`	112	p
33	!	49	1	65	A	81	Q	97	a	113	q
34	"	50	2	66	B	82	R	98	b	114	r
35	#	51	3	67	C	83	S	99	c	115	s
36	\$	52	4	68	D	84	T	100	d	116	t
37	%	53	5	69	E	85	U	101	e	117	u
38	&	54	6	70	F	86	V	102	f	118	v
39	'	55	7	71	G	87	W	103	g	119	w
40	(56	8	72	H	88	X	104	h	120	x
41)	57	9	73	I	89	Y	105	i	121	y
42	*	58	:	74	J	90	Z	106	j	122	z
43	+	59	;	75	K	91	[107	k	123	{
44	,	60	<	76	L	92	\	108	l	124	
45	-	61	=	77	M	93]	109	m	125	}
46	.	62	>	78	N	94	^	110	n	126	~
47	/	63	?	79	O	95	_	111	o	127	DEL

Example

□ Convert to Assembly

```
void strcpy (char x[], char y[])  
{  
    int i=0;  
    while ((x[i] = y[i]) != '\0')  
        i += 1;  
}
```

Example

□ Convert to Assembly

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void strcpy (char x[], char y[])  
{  
    int i=0;  
    while ((x[i] = y[i]) != '\0')  
        i += 1;  
}
```

Callee saves \$s0-\$s7

Example

□ Convert to Assembly

```
void strcpy (char x[], char y[])  
{  
    int i=0;  
    while ((x[i] = y[i]) != '\0')  
        i += 1;  
}
```

strcpy:

```
addi $sp, $sp, -4  
sw    $s0, 0($sp)  
add   $s0, $zero, $zero
```


Example

□ Convert to Assembly

```
void strcpy (char x[], char y[])
{
    int i=0;
    while ((x[i] = y[i]) != '\0')
        i += 1;
}
```

strcpy:

```
addi $sp, $sp, -4
sw   $s0, 0($sp)
add  $s0, $zero, $zero
while: add $t1, $s0, $a1
      lb  $t2, 0($t1)
      add $t3, $s0, $a0
      sb  $t2, 0($t3)
```

Example

□ Convert to Assembly

```
void strcpy (char x[], char y[])  
{  
    int i=0;  
    while ((x[i] = y[i]) != '\0')  
        i += 1;  
}
```

strcpy:

```
    addi $sp, $sp, -4  
    sw   $s0, 0($sp)  
    add  $s0, $zero, $zero  
while: add  $t1, $s0, $a1  
    lb   $t2, 0($t1)  
    add  $t3, $s0, $a0  
    sb   $t2, 0($t3)  
    beq  $t2, $zero, exit  
    addi $s0, $s0, 1  
    j    while  
exit:
```

Example

□ Convert to Assembly

```
void strcpy (char x[], char y[])  
{  
    int i=0;  
    while ((x[i] = y[i]) != '\0')  
        i += 1;  
}
```

strcpy:

```
    addi $sp, $sp, -4  
    sw   $s0, 0($sp)  
    add  $s0, $zero, $zero  
while: add  $t1, $s0, $a1  
    lb   $t2, 0($t1)  
    add  $t3, $s0, $a0  
    sb   $t2, 0($t3)  
    beq  $t2, $zero, exit  
    addi $s0, $s0, 1  
    j    while  
exit:  lw   $s0, 0($sp)  
    addi $sp, $sp, 4  
    jr   $ra
```

Large Constants

- Immediate instructions can only specify 16-bit constants

- ▣ Recall: I-Type



- The `lui` instruction is used to store a 16-bit constant into the upper 16 bits of a register... combine this with an OR instruction to specify a 32-bit constant
 - ▣ `lui $t0, 9`
 - ▣ `ori $a0, $t0, 64497`
- The destination PC-address in a conditional branch is specified as a 16-bit constant, relative to the current PC
- A jump (`j`) instruction can specify a 26-bit constant; if more bits are required, the jump-register (`jr`) instruction is used

Example: Sort Algorithm

□ Convert to assembly

```
void sort (int v[ ], int n)
{
    int i, j;
    for (i=0; i<n; i+=1) {
        for (j=i-1; j>=0 && v[j] > v[j+1]; j-=1) {
            swap (v,j);
        }
    }
}
```

```
void swap (int v[ ], int k)
{
    int temp;
    temp = v[k];
    v[k] = v[k+1];
    v[k+1] = temp;
}
```

- (1) Allocate registers to program variables
- (2) Produce code for the program body
- (3) Preserve registers across procedure invocations

Example: Sort Algorithm

- Convert to assembly

```
                                $a0    $a1
void swap (int v[ ], int k)
{
    $t0
    int temp;
    temp = v[k];
    v[k] = v[k+1];
    v[k+1] = temp;
}
```

Callee saves \$s0-\$s7

Example: Sort Algorithm

□ Convert to assembly

```
swap: sll    $t1, $a1, 2
      add    $t1, $a0, $t1
      lw     $t0, 0($t1)
      lw     $t2, 4($t1)
      sw     $t2, 0($t1)
      sw     $t0, 4($t1)
      jr     $ra
```



```
                                $a0    $a1
void swap (int v[ ], int k)
{
    $t0
    int temp;
    temp = v[k];
    v[k] = v[k+1];
    v[k+1] = temp;
}
```

No need for saves and restores as we're not using \$s0-\$s7
No need to re-use \$a0 and \$a1)

Example: Sort Algorithm

□ Convert to assembly

```
void sort (int v[ ], int n)
{
    int i, j;
    for (i=0; i<n; i+=1) {
        for (j=i-1; j>=0 && v[j] > v[j+1]; j-=1) {
            swap (v,j);
        }
    }
}
```


Example: Sort Algorithm

□ Convert to assembly

```
void sort (int v[ ], int n)
{
    int i, j;
    for (i=0; i<n; i+=1) {
        for (j=i-1; j>=0 && v[j] > v[j+1]; j-=1) {
            swap (v,j);
        }
    }
}
```

```
        move $s0, $zero
loopbody1: bge $s0, $a1, exit1
        ... body of inner loop ...
        addi $s0, $s0, 1
        j    loopbody1
exit1:
```

Need to store \$a0 and \$a1
Note the use of pseudo-instructions

Example: Sort Algorithm

- ❑ Convert to assembly

```
for (j=i-1; j>=0 && v[j] > v[j+1]; j--){
    swap (v,j);
}
```

```

    addi $s1, $s0, -1
loopbody2: blt  $s1, $zero, exit2
            sll  $t1, $s1, 2
            add  $t2, $a0, $t1
            lw   $t3, 0($t2)
            lw   $t4, 4($t2)
            bgt  $t3, $t4, exit2
    ... body of inner loop ...
    addi $s1, $s1, -1
    j     loopbody2
exit2:

```

Example: Sort Algorithm

□ Convert to assembly

```
void sort (int v[ ], int n)
{
    int i, j;
    for (i=0; i<n; i+=1) {
        for (j=i-1; j>=0 && v[j] > v[j+1]; j-=1) {
            swap (v,j);
        }
    }
}
```

```
void swap (int v[ ], int k)
{
    int temp;
    temp = v[k];
    v[k] = v[k+1];
    v[k+1] = temp;
}
```

Use \$s2 and \$s3 instead of \$a0 and \$a1 in the rest of “sort”

Save \$ra at the start of “sort”

Save \$s0-\$s3 so “sort” does not overwrite something that belongs to its caller

Example: Sort Algorithm

□ Saves and restores

```
sort:    addi    $sp, $sp, -20
         sw      $ra, 16($sp)
         sw      $s3, 12($sp)
         sw      $s2, 8($sp)
         sw      $s1, 4($sp)
         sw      $s0, 0($sp)
         move    $s2, $a0
         move    $s3, $a1

         ...

         move    $a0, $s2           # the inner loop body starts here
         move    $a1, $s1
         jal     swap

         ...

exit1:   lw      $s0, 0($sp)

         ...

         addi    $sp, $sp, 20
         jr      $ra
```