GP - Rasmussen & Williams - Ch. 2: Regression

Outline

- Regression
 - Sampling from prior
 - Posterior
 - Python toolboxes

GP prior

$$k(x,y) = \exp(-\frac{1}{2}|x-y|^2)$$
 (1)

$$\mathbf{f} \sim \mathcal{N}(\mathbf{0}, K(\mathbf{x}, \mathbf{x}))$$
 (2)

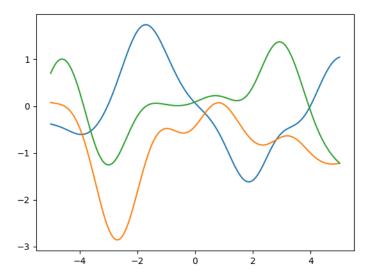
Sampling from prior: Python code

```
from numpy import sum, eye, exp #, zeros
from numpy.linalg import cholesky
from numpy.random import normal #, multivariate_normal
def rbf(length_scale):
   def k(x,y):
        if len(x.shape) == 1:
            d = 1
        else:
            d = x.shape[1]
       lx = x.shape[0]
       ly = y.shape[0]
       dists = sum(((x.T.reshape([d,lx,1]) - y.T.reshape([d,1,ly]))/length_scale)**2,0)
       return exp(-.5 * dists)
   return k
def genSamplesSimple(x, k):
   n = x.shape[0]
   L = cholesky(k(x,x)+eye(n)*1e-8)
   return L.dot(normal(size=n))
# Same as:
     return multivariate\_normal(zeros(n), k(x,x) + eye(n)*1e-8)
```

```
from matplotlib.pyplot import figure, plot, savefig, close, legend
from numpy import linspace

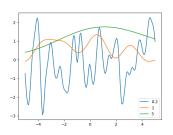
figure()
x = linspace(-5,5,150)
k = rbf(1)
for i in range(3): plot(x, genSamplesSimple(x,k));
```

Random functions in 1D



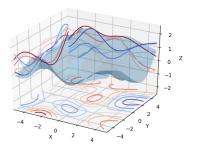
Different length scales

```
scales = [0.2, 1, 5]
for i in scales:
  plot(x, genSamplesSimple(x,rbf(i)))
legend(scales)
```



Two dimensions

```
from numpy import meshgrid, concatenate
x = linspace(5, -5, 50)
xx, yy = meshgrid(x, x)
xy = concatenate([xx.reshape([1, -1]),
                  vy.reshape([1, -1])]).T
z = genSamplesSimple(xy, rbf(2)).reshape([50, 50]
fig = figure()
ax = fig.gca(projection='3d')
ax.plot_surface(xx, yy, z, rstride=8,
                cstride=8, alpha=0.3)
cset = ax.contour(xx, yy, z, zdir='z',
                  offset=-2.5, cmap=cm.coolwarm)
cset = ax.contour(xx, yy, z, zdir='x',
                  offset=-5, cmap=cm.coolwarm)
cset = ax.contour(xx, yy, z, zdir='y',
                  offset=5, cmap=cm.coolwarm)
ax.set xlabel('X')
ax.set xlim(-5, 5)
ax.set_ylabel('Y')
ax.set_vlim(-5, 5)
ax.set_zlabel('Z')
ax.set zlim(-2.5, 2.5)
```



Computing posterior

$$\begin{bmatrix} \mathbf{y} \\ \mathbf{f}_* \end{bmatrix} \sim \mathcal{N} \left(\mathbf{0}, \begin{bmatrix} K(X,X) + \sigma^2 I & K(X,X_*) \\ K(X_*,X) & K(X_*,X_*) \end{bmatrix} \right)$$

$$\mathbf{f}_* | X, \mathbf{y}, X_* \sim \mathcal{N}(\overline{\mathbf{f}}_*, \text{cov}(\mathbf{f}_*))$$

$$\overline{\mathbf{f}}_* = K(X_*, X)[K(X,X) + \sigma^2 I]^{-1}\mathbf{y}$$

$$= K(X_*, X)\alpha$$

$$\text{cov}(\mathbf{f}_*) = K(X_*, X_*) - K(X_*, X)[K(X,X) + \sigma^2 I]^{-1}K(X, X_*)$$

$$= K(X_*, K_*) - V^T V$$

Where

$$\begin{array}{rcl} L & = & \operatorname{chol}(K(X,X) + \sigma^2 I) \rightarrow LL^T = K(X,X) + \sigma^2 I \\ \alpha & = & [K(X,X) + \sigma^2 I]^{-1} \mathbf{y} = L^{-T} L^{-1} \mathbf{y} \\ V & = & L^{-1} K(X,X_*) \end{array}$$

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Python code

```
from numpy import pi, eye, log, diag
from numpy.random import normal
from numpy.linalg import cholesky, solve #, inv
# solve(A.b) equals inv(A)*v. but it is more robust
def compPosterior(y, x, k, X, snoise):
    n = x.shape[0]
    K = k(x,X)
    L = cholesky(k(x, x) + eye(n)*(snoise + 1e-8))
    alpha = solve(L.T,solve(L,v))
    f mean = K.T.dot(alpha)
    v = solve(L,K)
    V = k(X,X) - v.T.dot(v)
    log_p = -.5*y.T.dot(alpha) - sum(log(diag(L))) - .5*n*log(2*pi)
    return f_mean, V, log_p
def genSamples(x, m, K):
    n = x.shape[0]
    L = cholesky(K+eye(n)*1e-8)
    return m + L.dot(normal(size=n))
```

Fitting some data

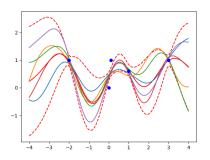
```
from numpy import array, sqrt

x = array([-2, 0, 0.1, 1, 3])
y = array([ 1, 0, 1, 0.6, 1])
X = linspace(-4, 4, 150)

k = rbf(1)
f_m, V, _ = compPosterior(y, x, k, X, 0.01)

s = sqrt(diag(V))

plot(X, f_m, 'r')
plot(X, f_m + 2*s, 'r--')
plot(X, f_m - 2*s, 'r--')
for i in range(5):
    plot(X, genSamples(X, f_m, V))
plot(x, y, 'ob')
```



scikit-learn

```
from sklearn.gaussian_process import GaussianProcessRegressor as GPR
from sklearn.gaussian_process.kernels import RBF
      # other kernels: Matern, WhiteKernel, ConstantKernel
k = RBF(1) # exactly the same behaviour as before
# but many kernels can be combined more easily:
# ConstantKernel() + Matern(length scale=2, nu=3/2)
      + WhiteKernel(noise level=1)
x = x.reshape([-1,1]) # but now x must be a 2D array
X = X.reshape([-1,1])
gp = GPR(alpha = 0.01, kernel=k, optimizer = None)
# it has many more options, in particular, optimizer
# must be set to None to prevent ML kernel estimation
gp.fit(x, y)
                                                          -1
y_pred, sigma = gp.predict(X, return_std=True)
plot(x,y,'ob')
plot(X, y_pred, 'r')
plot(X, y_pred + 2*sigma, 'r--'); plot(X, y_pred - 2*sigma, 'r--')
# same results as raw python code
plot(X, f_m, 'g:')
plot(X, f m + 2*s, 'g:'); plot(X, f m - 2*s, 'g:')
```

GPFlow

```
import gpflow
Y = y.reshape(-1,1)
k = gpflow.kernels.RBF(1)
m = gpflow.models.gpr(x, Y, kern=k)
m.likelihood.variance = 0.01
f, sgpf = m.predict_y(X)
plot(x,y,'ob')
plot(X, f, 'r')
plot(X, f + 2*sqrt(sgpf), 'r--'); plot(X, f - 2*sqrt(s
# similar (not identical) to previous results
plot(X, f_m, 'g:')
plot(X, f_m + 2*s, 'g:'); plot(X, f_m - 2*s, 'g:')
```

