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Proyecto final

Para correr el proyecto se debe hacer el cmake para después continuar con lo siguiente:

```
new terminal
source ./catkin_ws/devel/setup.bash
roslaunch bring_up robotino_simul.launch
```

```
new terminal
source ./catkin_ws/devel/setup.bash
roslaunch bring_up navigation_move_base.launch
```

```
new terminal
source ./catkin_ws/devel/setup.bash
roslaunch bring_up pocketsphinx_test.launch
```

```
new terminal
source ./catkin_ws/devel/setup.bash
roslaunch proyecto goal_reached.py
```

```
new terminal
source ./catkin_ws/devel/setup.bash
roslaunch proyecto new_goal.py
```

Los comandos son:

```
public <move> = [ROBOT] (<action> | GO TO <place>);
```

```
<place> = KITCHEN | ENTRANCE | ROOM | SPACE;
```

```
<action> = CONTINUE | STOP | RETURN;
```