Mathematical Programming Homework 2

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Problem 1

Problem 1.a

Exercise 1. Find the equation of the plane passing through the points $A = (4,0,0)^{\top}$, $B = (0,6,0)^{\top}$, and $C = (0,0,12)^{\top}$. Write this equation in the form $a^{\top}x = k$.

Solution 1. Plugging in the points A, B, C into the equation $a^{\top}x = k$ gives us the three equations

$$4a_1 = k$$
$$6a_2 = k$$
$$12a_3 = k.$$

A solution to this system of equations is k = 12 and $a = (3,2,1)^{T}$. Thus the plane defined given by the equation

$$12 = 3x_1 + 2x_2 + x_3$$

= $a_1x_1 + a_2x_2 + a_3x_3$
= $a^{\top}x$

contains the points *A*, *B*, and *C*.

Problem 1.b

Exercise 2. Is the point $x^0 = (1,2,5)^{\top}$ located in this plane? Explain why.

Solution 2. Yes, because the point x^0 is a solution to the equation $a^{\top}x = 12$:

$$a^{\top} x^0 = 3 \cdot 1 + 2 \cdot 2 + 1 \cdot 5$$

= 3 + 4 + 5
= 12.

Problem 1.c

Exercise 3. Write the equation of this plane in the form $a^{\top}(x - x^0) = 0$ where $x^0 = (1, 2, 5)^{\top}$.

Solution 3. We again use $a = (3, 2, 1)^{\top}$. We have

$$0 = a^{T}(x - x^{0})$$

$$= 3(x_{1} - 1) + 2(x_{2} - 2) + (x_{3} - 5)$$

$$= 3x_{1} - 3 + 2x_{2} - 4 + x_{3} - 5$$

$$= 3x_{1} + 2x_{2} + x_{3} - 12.$$

Problem 2

Exercise 4. Let $f: [-2.5, 5.5] \rightarrow \mathbb{R}$ be defined by

$$f(x) = 3x^4 - 20x^3 - 24x^2 + 240x + 400.$$

Find all local/global minima/maxima and inflection points of this function on its domain.

Solution 4. First we calculate

$$f'(x) = 12(x^3 - 5x^2 - 4x + 20)$$

$$f''(x) = 12(3x^2 - 10x - 4).$$

Now we calculate the roots of f':

$$f'(x) = 0 \iff x^3 - 5x^2 - 4x + 20 = 0$$
$$\iff (x - 5)(x - 2)(x + 2) = 0$$
$$\iff x \in \{-2, 2, 5\}.$$

With this information so far, we can determine what the local minima/maxima are:

- 1. Since f''(-2) = 336 > 0, we see that f has a local minimum at x = -2.
- 2. Since f''(2) = -144 < 0, we see that f has a local maximum at x = 2.
- 3. Since f''(5) = 252 > 0, we see that f has a local minimum at x = 5.

Since $\lim_{x\to\infty} f(x) = \infty = \lim_{x\to-\infty} f(x)$, we see that f does not have a global maximum, but does have a global minimum. The only possible places where f can have a global minimum is at the local minima. Since

$$f(-2) = 32$$

$$< 375$$

$$= f(5)$$

we see that f has a global minimum at x = -2 (and only has a local minimum at x = 5). Finally, note that

$$f''(x) = 0 \iff 3x^2 - 10x - 4 = 0$$

$$\iff \left(x - \frac{5 - \sqrt{37}}{3}\right) \left(x - \frac{5 + \sqrt{37}}{3}\right) = 0$$

$$\iff x \in \left\{\frac{5 - \sqrt{37}}{3}, \frac{5 + \sqrt{37}}{3}\right\},$$

since $x = (5 \pm \sqrt{37})/3$ are simple roots of f'' (meaning multiplicity one), they must correspond to the inflection points of f.

Problem 3

Exercise 5. Consider a function $f: \mathbb{R}^n \to \mathbb{R}$ with level sets defined as

$$S_{\alpha} = \{x \in \mathbb{R}^n \mid f(x) \le \alpha\}$$

for $\alpha \in \mathbb{R}$.

- 1. Prove that if f is a convex function, then the level sets S_{α} are convex sets.
- 2. If the level set S_{α} is a convex set for all $\alpha \in \mathbb{R}$, is the function f necessarily convex? Explain.

Solution 5. 1. Assume f is a convex function. Let $\alpha \in \mathbb{R}$, let $x, y \in S_{\alpha}$, and let $t \in (0,1)$. Then observe that

$$f(tx + (1 - t)y) \le tf(x) + (1 - t)f(y)$$

$$\le t\alpha + (1 - t)\alpha$$

$$= (t + 1 - t)\alpha$$

$$= \alpha.$$

It follows that $tx + (1 - t)y \in S_{\alpha}$. Since $\alpha \in \mathbb{R}$ was arbitrary, we see that S_{α} is convex for all $\alpha \in \mathbb{R}$.

2. No, consider n = 1 and $f(x) = -e^x$. Observe that

$$S_{\alpha} = \begin{cases} \mathbb{R} & \text{if } \alpha \ge 0\\ (-\infty, \ln \alpha] & \text{if } \alpha < 0 \end{cases}$$

In each case, S_{α} is convex, even though $-e^{x}$ is not convex.

Problem 4

Exercise 6. Check that the function $f(x) = 2x_1^2x_2^{-1}$ is convex or strictly convex on the strictly positive orthant $\{x \in \mathbb{R}^2 \mid x > 0\}$.

Solution 6. Let $x \in \{x \in \mathbb{R}^2 \mid x > 0\}$, We calculate the Hessian matrix of f at x:

$$H_f(x) = \begin{pmatrix} \partial_{x_1} \partial_{x_1} f(x) & \partial_{x_1} \partial_{x_2} f(x) \\ \partial_{x_2} \partial_{x_1} f(x) & \partial_{x_2} \partial_{x_2} f(x) \end{pmatrix}$$
$$= \begin{pmatrix} \frac{4}{x_2} & -\frac{4x_1}{x_2^2} \\ -\frac{4x_1}{x_2^2} & \frac{4x_1^2}{x_2^3} \end{pmatrix}.$$

The leading principal minors of the Hessian are

$$\frac{16x_1^2}{x_2^4} - \frac{16x_1^2}{x_2^4} = 0 \quad \text{and} \quad \frac{4}{x_2} > 0.$$

In particular we see that the Hessian is positive semidefinite but not positive definite, so f is convex but not strictly convex.

Problem 5

Exercise 7. Consider the problem

minimize
$$f(x_1, x_2) = (x_2 - x_1)^2 (x_2 - 2x_1^2)$$

- 1. Check whether the first- and second-order necessary conditions and the second-order sufficient conditions for optimality are satisfied at $(0,0)^{\top}$.
- 2. Show that $(0,0)^{\top}$ is a local minimizer of f along any line passing through the origin (i.e., consider a line $x_2 = mx_1$).
- 3. Show that $(0,0)^{\top}$ is not a local minimizer of f along any curve passing through the origin (i.e., consider a curve $x_2 = mx_1^2$).

Solution 7. 1. First calculate the gradient of f at (0,0):

$$\nabla f(x)\Big|_{(0,0)} = \begin{pmatrix} -2(x_1 - x_2)(4x_1^2 - 2x_1x_2 - x_2) \\ (4x_1^2 + x_1 - 3x_2)(x_1 - x_2) \end{pmatrix} \Big|_{(0,0)}$$
$$= \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Next we calculate the Hessian of f at (0,0):

$$H_f(x_1, x_2)\Big|_{(0,0)} = \begin{pmatrix} -2(x_1 - x_2)(4x_1^2 - 2x_1x_2 - x_2) \\ (4x_1^2 + x_1 - 3x_2)(x_1 - x_2) \end{pmatrix}\Big|_{(0,0)}$$
$$= \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Problem 6

Exercise 8. Consider the problem

minimize
$$f(x_1, x_2) = x_1^2 + x_1x_2 + 2x_2^2 - 2x_1 + e^{x_1 + x_2}$$

- 1. Write down the first-order necessary conditions for optimality.
- 2. Check whether the point $(0,0)^{\top}$ is a local optimal solution. If not, find a direction $d \in \mathbb{R}^2$ along which the function decreases.
- 3. Minimize the function starting from $(0,0)^{\top}$ along the direction d you have found above.

Solution 8. 1. The first-order necessary condition states that $\overline{x} = (\overline{x}_1, \overline{x}_2)$ is a minimizer only if $\nabla f(\overline{x}) = 0$, that is, only if

$$\begin{pmatrix} 2\overline{x}_1 + \overline{x}_2 - 2 + e^{\overline{x}_1 + \overline{x}_2} \\ \overline{x}_1 + 4\overline{x}_2 + e^{\overline{x}_1 + \overline{x}_2} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

2. Since

$$\nabla f(0) = \begin{pmatrix} 2 \cdot 0 + 0 - 2 + e^{0+0} \\ 0 + 4 \cdot 0 + e^{0+0} \end{pmatrix}$$
$$= \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$
$$\neq \begin{pmatrix} 0 \\ 0 \end{pmatrix},$$

we see that $(0,0)^{\top}$ is not a local optimal solution. Since $\partial_{x_1} f(0,0) = -1$, we see that the function decreases along the direction d = (1,0).

3. Now we minimize the function starting from $(0,0)^{\top}$ along the direction d=(1,0). Let g(t)=f(t,0), so

$$g(t) = t^2 - 2t + e^t.$$

Observe that

$$g'(t) = 0 \iff 2t - 2 + e^t = 0$$
$$\iff t \approx 0.314923$$

 \overline{x} is a minimizer only if $\nabla f(\overline{x}) = 0 \iff \overline{x}$ is a minimizer only if $\begin{pmatrix} 2\overline{x}_1 + \overline{x}_2 - 2 + e^{\overline{x}_1 + \overline{x}_2} \\ \overline{x}_1 + 4\overline{x}_2 + e^{\overline{x}_1 + \overline{x}_2} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

Thus we need

$$2\overline{x}_1 + \overline{x}_2 - 2 + e^{\overline{x}_1 + \overline{x}_2} = 0$$
$$\overline{x}_1 + 4\overline{x}_2 + e^{\overline{x}_1 + \overline{x}_2} = 0$$

From these two equations we obtain $\overline{x}_1 - 3\overline{x}_2 - 2 = 0$, or in other words, $\overline{x}_1 = 3\overline{x}_2 + 2$.