

NII International Internship program

Segmented Fusion

Dataset

20170929

Sylvia

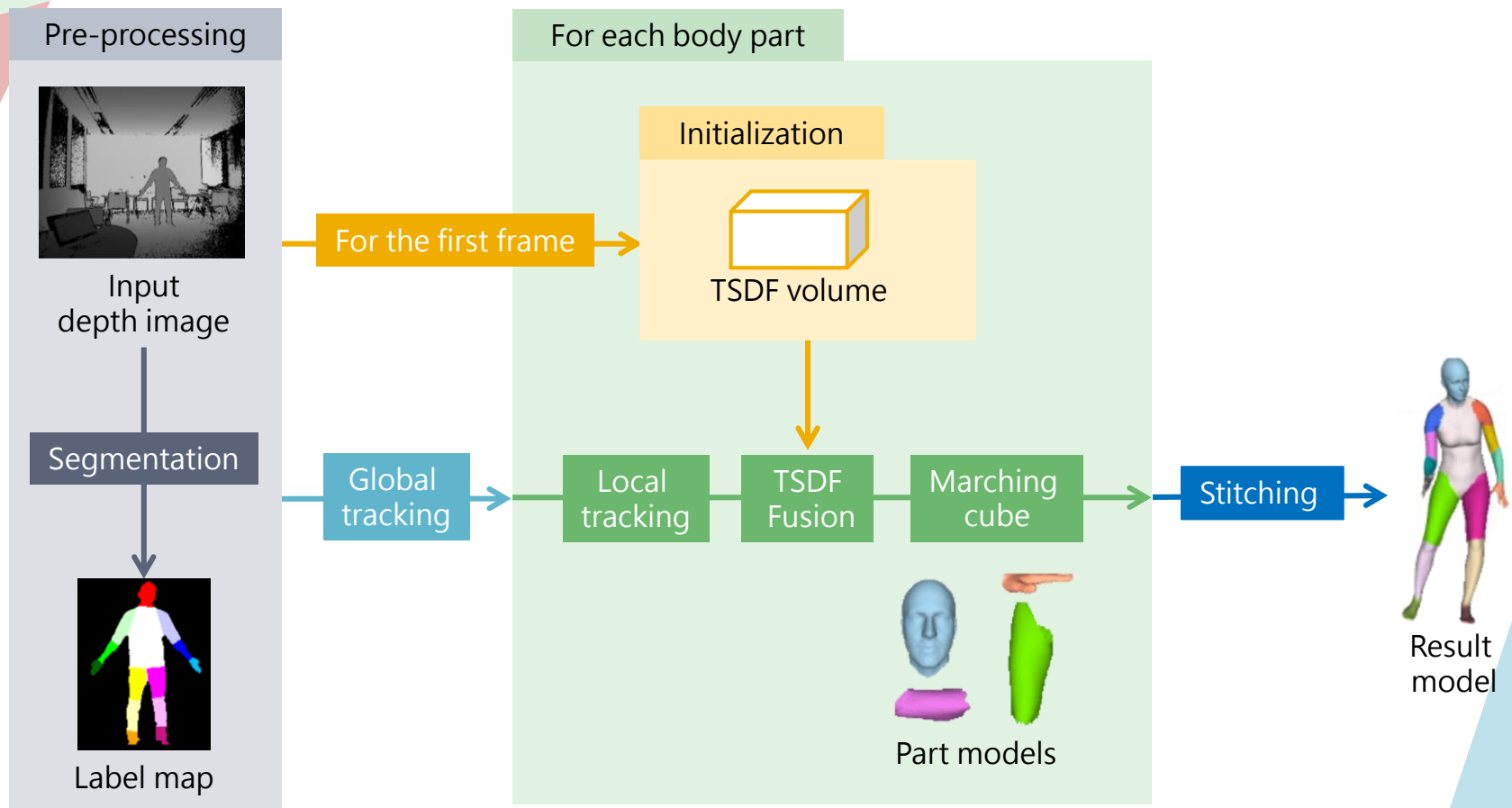
Advisors: Prof. A.Sugimoto

Ass.Prof. D.Thomas

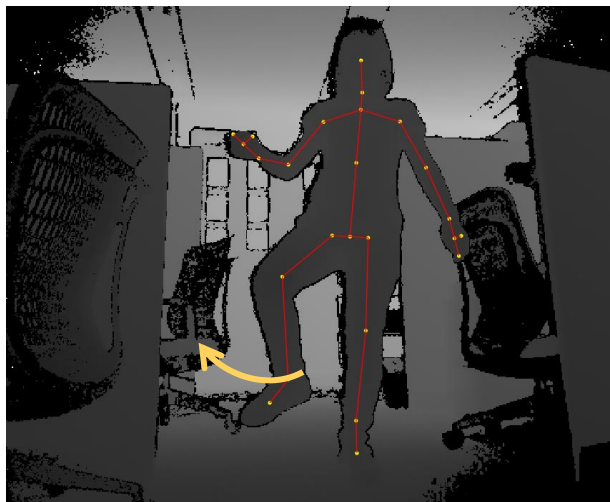
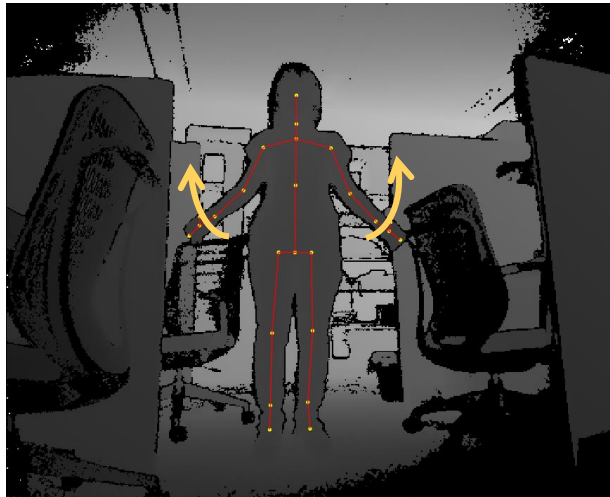
Last Meeting

- ♣ Previously
 - ♣ Discuss codes
- ♣ To-do
 - ♣ Pipeline
 - ♣ Create dataset
 - ♣ Modify codes
 - ♣ Run dataset and find problems or inspirations
 - ♣ Fusion4D

Progress Pipeline

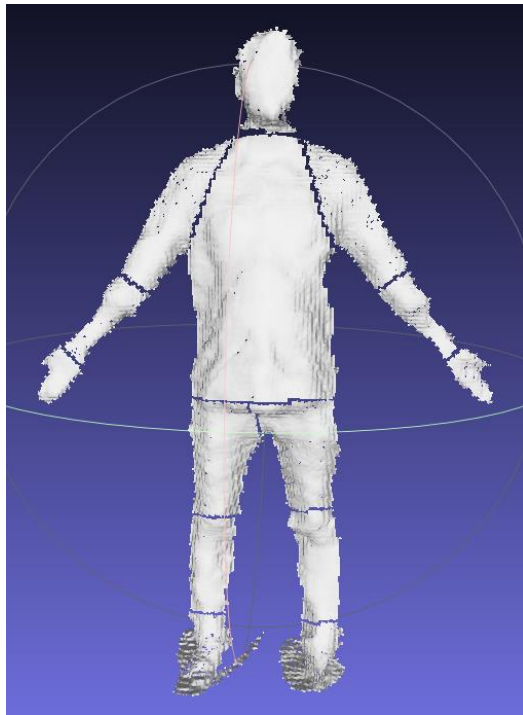


Progress Dataset



Progress Codes

- ♣ Before: 213.81s/10frames
- ♣ After: 167.39s/10frames



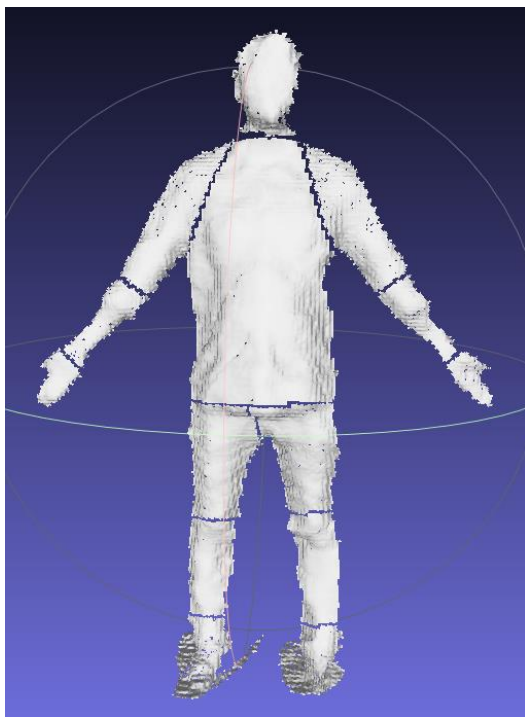
First frame mesh



Result mesh

Progress Tracking

- ♣ Improve the results by aborting the global tracking



First frame mesh

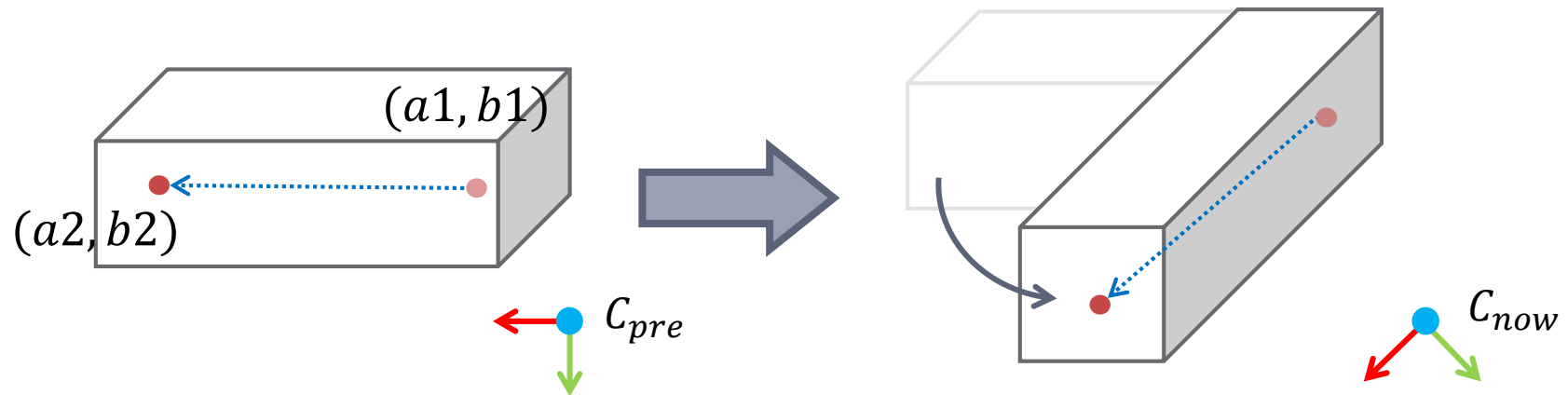


Before

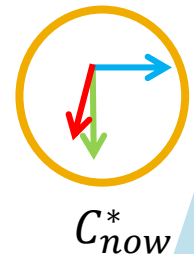


After

Progress Tracking

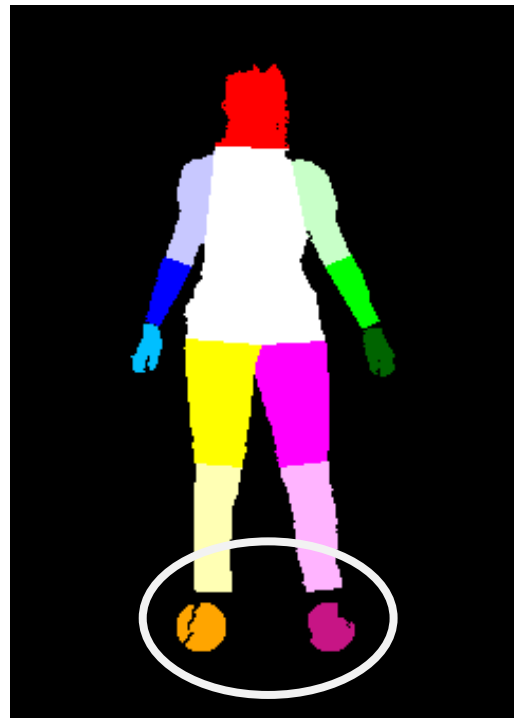


- ♣ $x_{axis} = \frac{(a2-a1, b2-b1, d)}{\|(a2-a1, b2-b1, d)\|}$
- ♣ $z_{axis} = (0, 0, 1)$
- ♣ $y_{axis} = x_{axis} \times z_{axis}$
- ♣ $T_{local} = C_{now} C_{pre}^{-1}$



New dataset

- ♣ The segmentation is not robust



- ♣ The real-time multi-view non-rigid reconstruction system for live performance capture
- ♣ The system is robust to large frame-to-frame motion and topology changes.

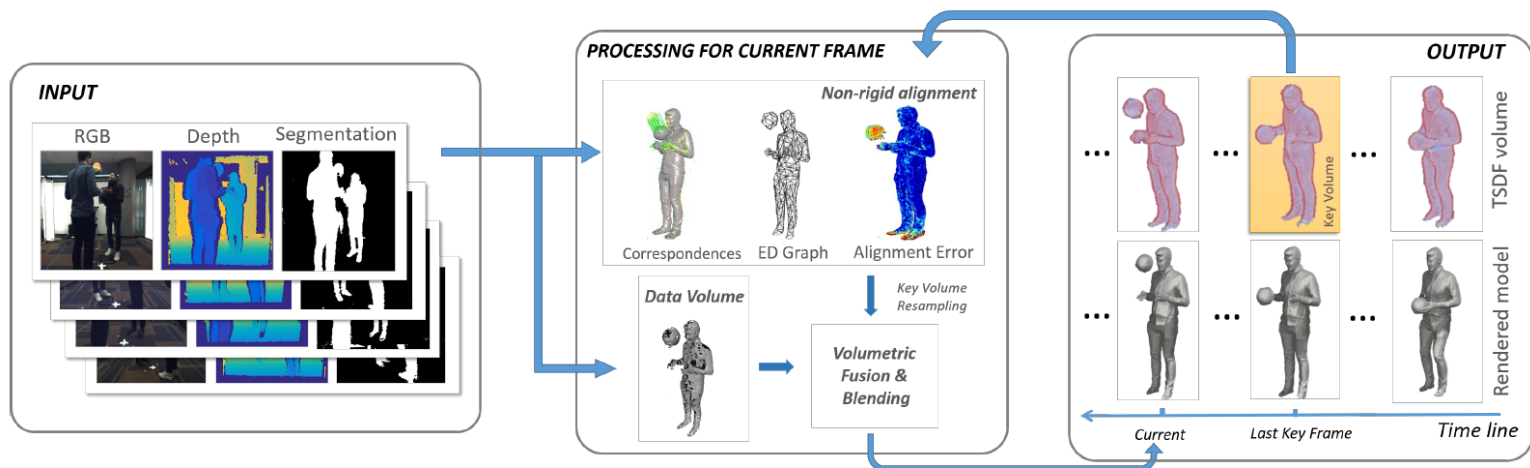


Figure 2: *The Fusion4D pipeline. Please see text in Sec. 3 for details.*

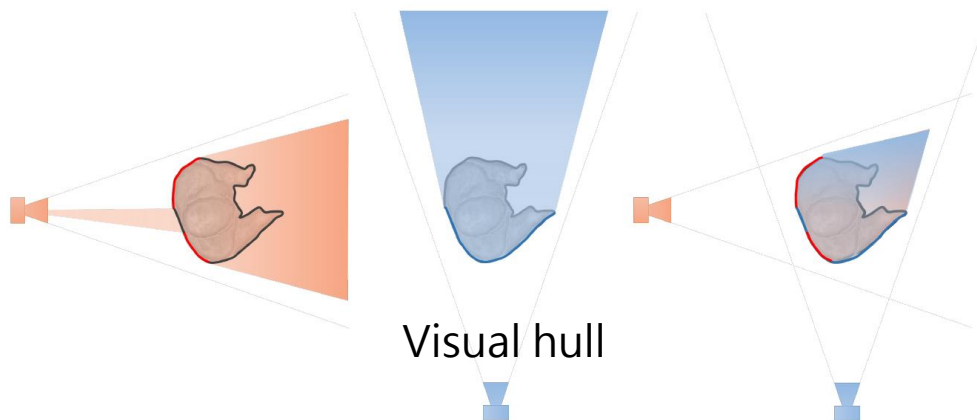
Dou, Mingsong, et al. "Fusion4d: Real-time performance capture of challenging scenes." *ACM Transactions on Graphics* *TT* (TOG) 35.4 (2016): 114.

Presenter: Sylvia

Advisors: Prof. A.Sugimoto, Ass.Prof. D.Thomas

4DFusion

- ♣ This paper uses ‘ED nodes’ with local deformation and global transformation to warp the reference volume.
- ♣
$$E(G) = \lambda_{data}E_{data}(G) + \lambda_{hull}E_{hull}(G) + \lambda_{corr}E_{corr}(G) + \lambda_{rot}E_{rot}(G) + \lambda_{smooth}E_{smooth}(G)$$



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4DFusion

- ♣ This paper uses two volumes, data volume and reference volume, to handle tracking failure and topology changes.
- ♣ After fusing the data volume from the current frame into the reference volume, the system fuses the reference volume back into the data volume.

Dou, Mingsong, et al. "Fusion4d: Real-time performance capture of challenging scenes." *ACM Transactions on Graphics* *TT* (TOG) 35.4 (2016): 114.

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Next step

- ♣ Modify the tracking part
- ♣ Improve the segmentation