		P_0	P_1	P_2	P_3	P_4	P_5	P_6	P_7		P_0	P_1	P_2	P_3	$\overline{P_4}$	P_5	P_6	P_7		P_0	P_1	P_2	P_3	P_4	P_5	P_6	P_7
Array (local l		18.4	2.37	1.63	1.59	1.24	1.22	2.15	2.14		15.8	2.37	1.63	1.59	1.24	1.22	2.15	2.14	>	3.92	2.37	1.63	1.59	1.24	1.22	2.15	2.14
Array (#tasks/		800	100	50	50	50	50	90	90		687	100	50	50	50	50	90	90		170	100	50	50	50	50	90	90
Array (sorted l	÷	P_0	P_1	P_6	P_7	P_2	P_3	P_4	P_5		P_0	P_1	P_6	P_7	P_2	P_3	P_4	P_5		P_0	P_1	P_6	P_7	P_2	P_3	P_4	P_5
		18.4	2.37	2.15	2.14	1.63	1.59	1.24	1.22		15.8	2.37	2.15	2.14	1.63	1.59	1.24	1.22		3.92	2.37	2.15	2.14	1.63	1.59	1.24	1.22
		P_0	P_1	P_2	P_3	P_4	P_5	P_6	P_7		P_0	P_1	P_2	P_3	P_4	P_5	P_6	P_7		P_0	P_1	P_2	P_3	P_4	P_5	P_6	P_7
Array (remote		0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0		0.0	0.0	0.0	0.0	0.0	2.61	0.0	0.0		0.0	1.48	2.21	2.24	2.61	2.61	1.68	1.70
	(1) Init steps								(2)	(2) The 1st outer loop: i=0 The 1st inner loop: j=0								End algorithm									
		P_0	P_1	P_2	P_3	P_4	P_5	P_6	P_7		P_0			P_3				P_7		P_0	P_1	P_2	P_3	P_4	P_5	P_6	P_7
able TB $(8 imes8)$	P_0	800									687					113				170	64	96	97	113	113	73	74
	P_1		100									100									100						
	P_2			50									50									50					
	P_3				50									50									50				
	P_4					50									50				>					50			
Tracking T	P_5						50									50									50		
Trac	P_6							90									90									90	
	P_7								90									90									90