



## Deconstructing the matrix exponential

- Have seen the key role of  $e^{At}$  in the solution for  $x(t)$ .
- Impacts the system response, but need more insight.
- Consider what happens if the matrix  $A$  is *diagonalizable*, that is, there exists a matrix  $T$  such that  $T^{-1}AT = \Lambda = \text{diagonal}$ . Then,

$$\begin{aligned} e^{At} &= I + At + \frac{A^2 t^2}{2!} + \frac{A^3 t^3}{3!} + \dots \\ &= I + T\Lambda T^{-1}t + \frac{T\Lambda T^{-1}T\Lambda T^{-1}t^2}{2!} + \frac{T\Lambda T^{-1}T\Lambda T^{-1}T\Lambda T^{-1}t^3}{3!} + \dots \\ &= T \left[ I + \Lambda t + \frac{\Lambda^2 t^2}{2!} + \frac{\Lambda^3 t^3}{3!} + \dots \right] T^{-1} = T e^{\Lambda t} T^{-1}, \end{aligned}$$

and

$$e^{\Lambda t} = \text{diag} \left( e^{\lambda_1 t}, e^{\lambda_2 t}, \dots, e^{\lambda_n t} \right).$$



## How to find the transformation matrix

- Much simpler form for the exponential, but how to find  $T, \Lambda$ ?
- Write  $T^{-1}AT = \Lambda$  as  $T^{-1}A = \Lambda T^{-1}$  with

$$T^{-1} = \begin{bmatrix} w_1^T \\ w_2^T \\ \vdots \\ w_n^T \end{bmatrix}, \quad \text{i.e., } w_j^T \text{ are the rows of } T^{-1}.$$

- We have:  $w_i^T A = \lambda_i w_i^T$ , so  $w_i$  is a *left eigenvector* of  $A$ .
- Can also write  $T^{-1}AT = \Lambda$  as  $AT = \Lambda T$  with
 
$$T = \begin{bmatrix} v_1 & v_2 & \dots & v_n \end{bmatrix}, \quad \text{i.e., } v_j \text{ are the columns of } T.$$
  - We have  $Av_i = \lambda_i v_i$ , so  $v_i$  is a *right eigenvector* of  $A$ .
- Also, since  $T^{-1}T = I$ , we have that  $w_i^T v_j = \delta_{i,j}$ .



## How the deconstruction simplifies things

- So,  $T$  comprises the eigenvectors of  $A$ . How does this help?

$$e^{At} = T e^{\Lambda t} T^{-1}$$

$$= \begin{bmatrix} v_1 & v_2 & \dots & v_n \end{bmatrix} \begin{bmatrix} e^{\lambda_1 t} & & & 0 \\ & e^{\lambda_2 t} & & \\ & & \ddots & \\ 0 & & & e^{\lambda_n t} \end{bmatrix} \begin{bmatrix} w_1^T \\ w_2^T \\ \vdots \\ w_n^T \end{bmatrix} = \sum_{i=1}^n e^{\lambda_i t} v_i w_i^T.$$

- Very simple form, which can be used to develop intuition about dynamic response:

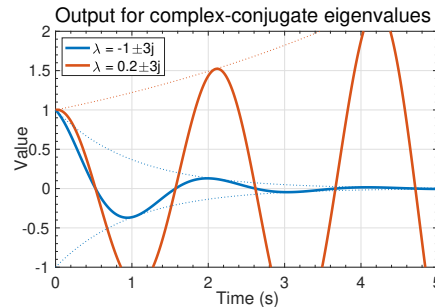
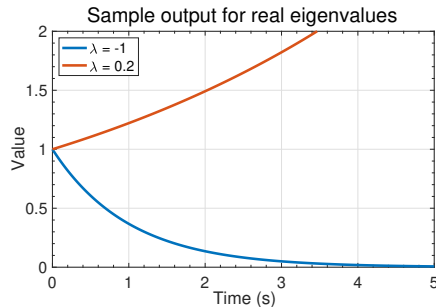
$$x(t) = e^{At} x(0) = T e^{\Lambda t} T^{-1} x(0) = \sum_{i=1}^n e^{\lambda_i t} v_i (w_i^T x(0)).$$

- Notice that the only time-varying components are  $e^{\lambda_i t}$ , which are then multiplied by constant matrices so that the states are linear combinations of  $e^{\lambda_i t}$ .



## Visualizing $e^{\lambda_i t}$

- The signal  $e^{\lambda_i t}$  can take on several different characteristics, as shown in the figures below.
  - If  $\lambda_i$  is real, we observe a smooth monotonically growing or decaying signal.
  - If  $\lambda_i$  occur in complex-conjugate pairs, the output is of the pair is of the form  $e^{\Re(\lambda_i)t} \cos(\Im(\lambda_i)t)$ : a cosine with an exponential “envelope.”



## An example to illustrate the complexity

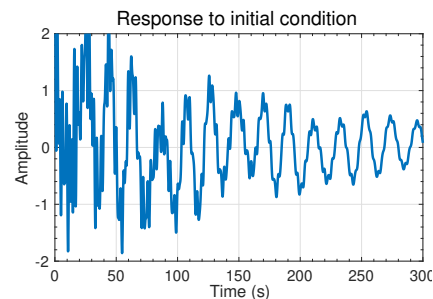
- Consider again:  $x(t) = \sum_{i=1}^n e^{\lambda_i t} v_i(w_i^T x(0))$ .
- Can be expressed as a linear combination of modes:  $v_i e^{\lambda_i t}$ .
- Left eigenvectors decompose  $x(0)$  into modal coordinates  $w_i^T x(0)$ .
- $e^{\lambda_i t}$  propagates mode forward in time.

- **EXAMPLE:** Consider a specific system with  $x(t) \in \mathbb{R}^{16 \times 1}$ ,  $z(t) \in \mathbb{R}$  (16-state, 1-output):

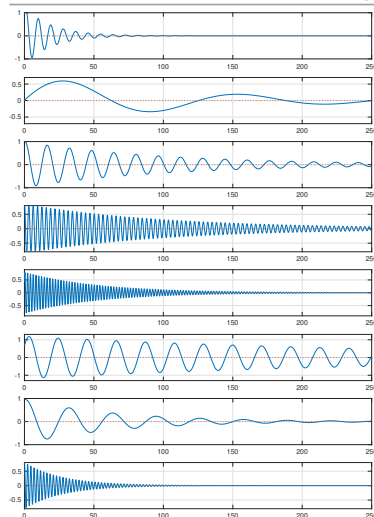
$$\dot{x}(t) = Ax(t)$$

$$z(t) = Cx(t).$$

- A lightly damped system, for which typical output to initial conditions is shown.
- Waveform is complicated. Appears random.



## Now we see the underlying simplicity



- However, the solution can be decomposed into much simpler modal components.
- The waveforms to the left show  $e^{-\lambda_i t}$  for complex-conjugate pairs  $\{\lambda_i, \lambda_i^*\}$  summed together.
- All are decaying sinusoids with different magnitudes, frequencies, and phase shifts.
- When summed together, the result appears complicated; but the individual components of the response are simple.



## Summary

- The matrix exponential is key to understanding the response of a state-space model.
- Since it is likely an unfamiliar concept to you until this point, it is valuable to develop intuition regarding what it looks like.
- You have learned that we can (almost always)<sup>1</sup> write  $e^{At} = Te^{\Lambda t}T^{-1}$ , where the columns of  $T$  are the eigenvectors of  $A$ .
- All the dynamics are contained in  $e^{\Lambda t}$ , which turn out to be the standard scalar exponentials of (possibly complex)  $\lambda_i t$  terms.
- So, the matrix exponential is a linear sum of exponentially-enveloped sinusoids.
- The frequencies of the sinusoids are the eigenvalues of  $A$ . The eigenvectors specify the relative weighting of each component to the overall output.

<sup>1</sup> If we cannot diagonalize  $A$ , there is a more general “Jordan form” for which the ideas presented in this lesson apply with a few modifications. . . basically multiplying the sinusoids by polynomials.