Problem 3

Use this notebook to write your code for problem 3.

```
In [4]: import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
```

3D - Convolutional network

As in problem 2, we have conveniently provided for your use code that loads and preprocesses the MNIST data.

```
In [5]: # load MNIST data into PyTorch format
        import torch
        import torchvision
        import torchvision.transforms as transforms
        # set batch size
        batch size = 32
        # load training data downloaded into data/ folder
        mnist training data = torchvision.datasets.MNIST('data/', train=True, download=Tru
        e,
                                                         transform=transforms.ToTensor())
        # transforms.ToTensor() converts batch of images to 4-D tensor and normalizes 0-25
        5 to 0-1.0
        training data loader = torch.utils.data.DataLoader(mnist training data,
                                                           batch size=batch size,
                                                           shuffle=True)
        # load test data
        mnist_test_data = torchvision.datasets.MNIST('data/', train=False, download=True,
                                                         transform=transforms.ToTensor())
        test_data_loader = torch.utils.data.DataLoader(mnist_test_data,
                                                           batch_size=batch_size,
                                                           shuffle=False)
```

```
In [6]: # look at the number of batches per epoch for training and validation
    print(f'{len(training_data_loader)} training batches')
    print(f'{len(training_data_loader) * batch_size} training samples')
    print(f'{len(test_data_loader)} validation batches')
```

1875 training batches 60000 training samples 313 validation batches

```
In [65]: # sample model
         import torch.nn as nn
         class ConvNet(nn.Module):
             def __init__(self):
                 super(ConvNet, self).__init__()
                 self.first = nn.Sequential(
                      nn.Conv2d(1, 16, kernel_size=5, stride=1, padding=2),
                     nn.BatchNorm2d(16),
                     nn.ReLU(),
                     nn.MaxPool2d(kernel_size=2, stride=2))
                 self.second = nn.Sequential(
                     nn.Conv2d(16, 32, kernel_size=5, stride=1, padding=2),
                     nn.BatchNorm2d(32),
                     nn.ReLU(),
                     nn.MaxPool2d(kernel_size=2, stride=2))
                 self.Dropout = nn.Dropout()
                 # 7 * 7 * 32
                 self.fc1 = nn.Linear(7*7*32, 600)
                 self.fc2 = nn.Linear(600, 10)
             def forward(self, data):
                 out = self.first(data)
                 out = self.second(out)
                 # reshape
                 out = out.reshape(out.size(0), -1)
                 out = self.Dropout(out)
                 out = self.fc1(out)
                 out = self.fc2(out)
                 return out
         model = ConvNet()
In [66]: # why don't we take a look at the shape of the weights for each layer
         for p in model.parameters():
             print(p.data.shape)
         torch.Size([16, 1, 5, 5])
         torch.Size([16])
         torch.Size([16])
         torch.Size([16])
         torch.Size([32, 16, 5, 5])
         torch.Size([32])
         torch.Size([32])
         torch.Size([32])
         torch.Size([600, 1568])
         torch.Size([600])
         torch.Size([10, 600])
         torch.Size([10])
In [67]: # our model has some # of parameters:
         count = 0
         for p in model.parameters():
             n_params = np.prod(list(p.data.shape)).item()
             count += n_params
         print(f'total params: {count}')
         total params: 960754
```

```
In [68]: # For a multi-class classification problem
#import torch.optim as optim
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=.001)
```

```
In [69]: # Train the model for 10 epochs, iterating on the data in batches
         n_{epochs} = 10
         # store metrics
         training_accuracy_history = np.zeros([n_epochs, 1])
         training_loss_history = np.zeros([n_epochs, 1])
         validation_accuracy_history = np.zeros([n_epochs, 1])
         validation_loss_history = np.zeros([n_epochs, 1])
         for epoch in range(n_epochs):
             print(f'Epoch {epoch+1}/10:', end='')
             train_total = 0
             train_correct = 0
             # train
             model.train()
             for i, data in enumerate(training_data_loader):
                 images, labels = data
                 optimizer.zero_grad()
                 # forward pass
                 output = model(images)
                 # calculate categorical cross entropy loss
                 loss = criterion(output, labels)
                 # backward pass
                 loss.backward()
                 optimizer.step()
                 # track training accuracy
                  _, predicted = torch.max(output.data, 1)
                 train total += labels.size(0)
                 train correct += (predicted == labels).sum().item()
                 # track training loss
                 training loss history[epoch] += loss.item()
                 # progress update after 180 batches (~1/10 epoch for batch size 32)
                 if i % 180 == 0: print('.',end='')
             training_loss_history[epoch] /= len(training_data_loader)
             training_accuracy_history[epoch] = train_correct / train_total
             print(f'\n\tloss: {training_loss_history[epoch,0]:0.4f}, acc: {training_accura
         cy_history[epoch,0]:0.4f}',end='')
             # validate
             test total = 0
             test correct = 0
             with torch.no grad():
                 model.eval()
                 for i, data in enumerate(test data loader):
                     images, labels = data
                     # forward pass
                     output = model(images)
                     # find accuracy
                      _, predicted = torch.max(output.data, 1)
                     test_total += labels.size(0)
                     test correct += (predicted == labels).sum().item()
                     # find loss
                     loss = criterion(output, labels)
                     validation loss history[epoch] += loss.item()
                 validation loss history[epoch] /= len(test data loader)
                 validation_accuracy_history[epoch] = test_correct / test_total
             print(f', val loss: {validation_loss_history[epoch,0]:0.4f}, val acc: {validat
         ion_accuracy_history[epoch,0]:0.4f}')
```

```
Epoch 1/10:....
       loss: 0.2103, acc: 0.9369, val loss: 0.0465, val acc: 0.9843
Epoch 2/10:....
       loss: 0.0968, acc: 0.9709, val loss: 0.0462, val acc: 0.9848
Epoch 3/10:....
       loss: 0.0722, acc: 0.9785, val loss: 0.0308, val acc: 0.9896
Epoch 4/10:....
       loss: 0.0634, acc: 0.9807, val loss: 0.0355, val acc: 0.9889
Epoch 5/10:....
       loss: 0.0582, acc: 0.9825, val loss: 0.0327, val acc: 0.9886
Epoch 6/10:....
       loss: 0.0504, acc: 0.9847, val loss: 0.0305, val acc: 0.9905
Epoch 7/10:....
       loss: 0.0477, acc: 0.9854, val loss: 0.0318, val acc: 0.9896
Epoch 8/10:....
       loss: 0.0441, acc: 0.9859, val loss: 0.0301, val acc: 0.9909
Epoch 9/10:....
       loss: 0.0431, acc: 0.9870, val loss: 0.0314, val acc: 0.9902
Epoch 10/10:....
       loss: 0.0390, acc: 0.9881, val loss: 0.0232, val acc: 0.9925
```

Above, we output the training loss/accuracy as well as the validation loss and accuracy. Not bad! Let's see if you can do better.