## **Problem 3**

Use this notebook to write your code for problem 3.

```
In [4]: import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
```

## 3D - Convolutional network

As in problem 2, we have conveniently provided for your use code that loads and preprocesses the MNIST data.

```
In [5]: # load MNIST data into PyTorch format
        import torch
        import torchvision
        import torchvision.transforms as transforms
        # set batch size
        batch size = 32
        # load training data downloaded into data/ folder
        mnist training data = torchvision.datasets.MNIST('data/', train=True, download=Tru
        e,
                                                         transform=transforms.ToTensor())
        # transforms.ToTensor() converts batch of images to 4-D tensor and normalizes 0-25
        5 to 0-1.0
        training data loader = torch.utils.data.DataLoader(mnist training data,
                                                           batch size=batch size,
                                                           shuffle=True)
        # load test data
        mnist_test_data = torchvision.datasets.MNIST('data/', train=False, download=True,
                                                         transform=transforms.ToTensor())
        test_data_loader = torch.utils.data.DataLoader(mnist_test_data,
                                                           batch_size=batch_size,
                                                           shuffle=False)
```

```
In [6]: # look at the number of batches per epoch for training and validation
    print(f'{len(training_data_loader)} training batches')
    print(f'{len(training_data_loader) * batch_size} training samples')
    print(f'{len(test_data_loader)} validation batches')
```

1875 training batches 60000 training samples 313 validation batches

```
In [29]: # sample model
         import torch.nn as nn
         class ConvNet(nn.Module):
             def __init__(self):
                 super(ConvNet, self).__init__()
                 self.layer1 = nn.Sequential(
                     nn.Conv2d(1, 32, kernel_size=5, stride=1, padding=2),
                     nn.ReLU(),
                     nn.MaxPool2d(kernel_size=2, stride=2))
                 self.layer2 = nn.Sequential(
                     nn.Conv2d(32, 64, kernel_size=5, stride=1, padding=2),
                     nn.ReLU(),
                     nn.MaxPool2d(kernel_size=2, stride=2))
                 self.drop_out = nn.Dropout()
                 self.fc1 = nn.Linear(7 * 7 * 64, 1000)
                 self.fc2 = nn.Linear(1000, 10)
             def forward(self, x):
                 out = self.layer1(x)
                 out = self.layer2(out)
                 out = out.reshape(out.size(0), -1)
                 out = self.drop out(out)
                 out = self.fc1(out)
                 out = self.fc2(out)
                 return out
         model = ConvNet()
In [30]: | # why don't we take a look at the shape of the weights for each layer
         for p in model.parameters():
             print(p.data.shape)
         torch.Size([32, 1, 5, 5])
         torch.Size([32])
         torch.Size([64, 32, 5, 5])
         torch.Size([64])
         torch.Size([1000, 3136])
         torch.Size([1000])
         torch.Size([10, 1000])
         torch.Size([10])
In [31]: # our model has some # of parameters:
         count = 0
         for p in model.parameters():
             n_params = np.prod(list(p.data.shape)).item()
             count += n_params
         print(f'total params: {count}')
         total params: 3199106
In [32]: # For a multi-class classification problem
         #import torch.optim as optim
         criterion = nn.CrossEntropyLoss()
         optimizer = optim.Adam(model.parameters(), lr=.001)
```

```
In [33]: # Train the model for 10 epochs, iterating on the data in batches
         n_{epochs} = 10
         # store metrics
         training_accuracy_history = np.zeros([n_epochs, 1])
         training_loss_history = np.zeros([n_epochs, 1])
         validation_accuracy_history = np.zeros([n_epochs, 1])
         validation_loss_history = np.zeros([n_epochs, 1])
         for epoch in range(n_epochs):
             print(f'Epoch {epoch+1}/10:', end='')
             train_total = 0
             train_correct = 0
             # train
             model.train()
             for i, data in enumerate(training_data_loader):
                 images, labels = data
                 optimizer.zero_grad()
                 # forward pass
                 output = model(images)
                 # calculate categorical cross entropy loss
                 loss = criterion(output, labels)
                 # backward pass
                 loss.backward()
                 optimizer.step()
                 # track training accuracy
                  _, predicted = torch.max(output.data, 1)
                 train total += labels.size(0)
                 train correct += (predicted == labels).sum().item()
                 # track training loss
                 training loss history[epoch] += loss.item()
                 # progress update after 180 batches (~1/10 epoch for batch size 32)
                 if i % 180 == 0: print('.',end='')
             training_loss_history[epoch] /= len(training_data_loader)
             training_accuracy_history[epoch] = train_correct / train_total
             print(f'\n\tloss: {training_loss_history[epoch,0]:0.4f}, acc: {training_accura
         cy_history[epoch,0]:0.4f}',end='')
             # validate
             test total = 0
             test correct = 0
             with torch.no grad():
                 model.eval()
                 for i, data in enumerate(test data loader):
                     images, labels = data
                     # forward pass
                     output = model(images)
                     # find accuracy
                      _, predicted = torch.max(output.data, 1)
                     test_total += labels.size(0)
                     test_correct += (predicted == labels).sum().item()
                     # find loss
                     loss = criterion(output, labels)
                     validation loss history[epoch] += loss.item()
                 validation loss history[epoch] /= len(test data loader)
                 validation_accuracy_history[epoch] = test_correct / test_total
             print(f', val loss: {validation_loss_history[epoch,0]:0.4f}, val acc: {validat
         ion_accuracy_history[epoch,0]:0.4f}')
```

```
Epoch 1/10:....
       loss: 0.1395, acc: 0.9559, val loss: 0.0378, val acc: 0.9877
Epoch 2/10:....
       loss: 0.0665, acc: 0.9795, val loss: 0.0470, val acc: 0.9838
Epoch 3/10:....
       loss: 0.0560, acc: 0.9823, val loss: 0.0339, val acc: 0.9888
Epoch 4/10:....
       loss: 0.0514, acc: 0.9846, val loss: 0.0361, val acc: 0.9881
Epoch 5/10:....
       loss: 0.0472, acc: 0.9857, val loss: 0.0305, val acc: 0.9919
Epoch 6/10:....
       loss: 0.0432, acc: 0.9869, val loss: 0.0288, val acc: 0.9902
Epoch 7/10:....
       loss: 0.0416, acc: 0.9874, val loss: 0.0292, val acc: 0.9910
Epoch 8/10:....
       loss: 0.0370, acc: 0.9886, val loss: 0.0290, val acc: 0.9908
Epoch 9/10:....
       loss: 0.0370, acc: 0.9883, val loss: 0.0318, val acc: 0.9906
Epoch 10/10:....
       loss: 0.0334, acc: 0.9901, val loss: 0.0272, val acc: 0.9920
```

Above, we output the training loss/accuracy as well as the validation loss and accuracy. Not bad! Let's see if you can do better.