

آخر معاينة ميكانيكا

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* أوجد المؤثر التفاضلي "Nabla" بدلالة الإحداثيات القطبية

$$\vec{\nabla} = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}$$

$$\text{Curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

الإحداثيات
انكاسية

$$= \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \hat{i} - \left(\frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z} \right) \hat{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \hat{k}$$

لوال $\text{Curl } \vec{F}$ يساوي Zero يبقى القوة محافظة ويمكن إيجاد دالة جهد لها

$$\vec{\nabla} = \boxed{} \underline{e_r} + \boxed{} \underline{e_\theta}$$

$$x = r \cos(\theta)$$

$$y = r \sin(\theta)$$

$$r = \sqrt{x^2 + y^2}$$

$$\theta = \tan^{-1}\left(\frac{y}{x}\right)$$

$$\frac{\partial \theta}{\partial x} = \frac{\left(-\frac{y}{x^2}\right)}{1 + \left(\frac{y^2}{x^2}\right)} = \frac{-y}{x^2 + y^2}$$

$$\frac{\partial \theta}{\partial y} = \frac{\frac{1}{x}}{1 + \frac{y^2}{x^2}} = \frac{x}{x^2 + y^2}$$

$$\vec{\nabla} = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j}$$

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \cdot \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \cdot \frac{\partial}{\partial \theta}$$

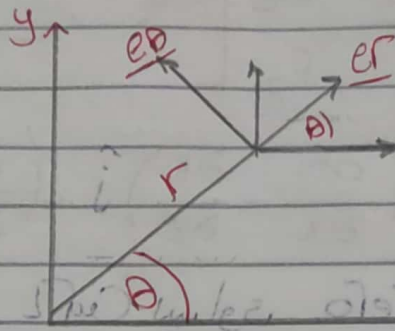
$$\frac{\partial}{\partial x} = \frac{2x}{2\sqrt{x^2 + y^2}} \frac{\partial}{\partial r} + \frac{-y}{x^2 + y^2} \frac{\partial}{\partial \theta}$$

$\underbrace{2\sqrt{x^2 + y^2}}_{r} \quad \underbrace{2x}_{r \cos(\theta)} \quad \underbrace{-y}_{-r \sin(\theta)}$

$$\ast \frac{\partial}{\partial x} = \cos(\theta) \frac{\partial}{\partial r} - \frac{\sin(\theta)}{r} \frac{\partial}{\partial \theta}$$

$$\ast \frac{\partial}{\partial y} = \sin(\theta) \frac{\partial}{\partial r} + \frac{\cos(\theta)}{r} \frac{\partial}{\partial \theta}$$

إيجاد متجهات الوحدة \underline{i} , \underline{j} في المركبات الكارتيزية
بدلالة r, θ



$$\underline{e_r} = \cos(\theta) \underline{i} + \sin(\theta) \underline{j} \rightarrow (1)$$

$$\underline{e_\theta} = -\sin(\theta) \underline{i} + \cos(\theta) \underline{j} \rightarrow (2)$$

بضرب (1) في $\sin(\theta)$ و (2) في $\cos(\theta)$ وبالجمع

$$\sin(\theta) \underline{e_r} + \cos(\theta) \underline{e_\theta} = (\sin^2(\theta) + \cos^2(\theta)) \underline{j}$$

$$\ast \underline{j} = \sin(\theta) \underline{e_r} + \cos(\theta) \underline{e_\theta}$$

بضرب (1) في $\cos(\theta)$ و (2) في $-\sin(\theta)$ وبالجمع

$$\cos(\theta) \underline{e_r} - \sin(\theta) \underline{e_\theta} = (\cos^2(\theta) + \sin^2(\theta)) \underline{i}$$

$$\ast \underline{i} = \cos(\theta) \underline{e_r} - \sin(\theta) \underline{e_\theta}$$

$$\begin{aligned}\vec{\nabla} &= \frac{\partial}{\partial x} \underline{i} + \frac{\partial}{\partial y} \underline{j} \\ \vec{\nabla} &= \left(\cos(\theta) \frac{\partial}{\partial r} - \frac{\sin(\theta)}{r} \frac{\partial}{\partial \theta} \right) \cdot \left(\sin(\theta) \underline{e}_r + \cos(\theta) \underline{e}_\theta \right) \\ &+ \left(\sin(\theta) \frac{\partial}{\partial r} + \frac{\cos(\theta)}{r} \frac{\partial}{\partial \theta} \right) \cdot \left(\cos(\theta) \underline{e}_r + \sin(\theta) \underline{e}_\theta \right)\end{aligned}$$

$$\vec{\nabla} = \frac{\partial}{\partial r} \underline{e}_r + \frac{1}{r} \frac{\partial}{\partial \theta} \underline{e}_\theta + \frac{\partial}{\partial z} \underline{k}$$

حيث K يعبر عن الارتفاع

مسألة ① أوجد القوة المحافظة الناشئة من دالة الجهد

$$\phi = 2r \sin(\theta)$$

حيث \vec{F} هي القوة المحافظة

$$\vec{F} = -\vec{\nabla} \times \phi = - \left[\frac{\partial \phi}{\partial r} \underline{e}_r + \frac{1}{r} \frac{\partial \phi}{\partial \theta} \underline{e}_\theta \right]$$

$$\frac{\partial \phi}{\partial r} = 2 \sin(\theta), \quad \frac{\partial \phi}{\partial \theta} = 2r \cos(\theta)$$

$$\vec{F} = - \left[2 \sin(\theta) \underline{e}_r + \frac{1}{r} 2r \cos(\theta) \underline{e}_\theta \right]$$

$$\vec{F} = -2 \sin(\theta) \cos(\theta) \underline{i} - 2 \sin^2(\theta) \underline{j} + 2 \sin(\theta) \cos(\theta) \underline{i} - 2 \cos^2(\theta) \underline{j}$$

$$\vec{F} = -2 (\sin^2(\theta) + \cos^2(\theta)) \underline{j}$$

$$\vec{F} = -2 \underline{j}$$

مثال ٥ يدور كوكب حول الشمس تحت تأثير قوة مركزية جاذبية تتناسب عكسياً مع مربع المسافة بين الكوكب والشمس. أثبت أن تلك القوة هي قوة محافظة ثم أوجد دالة الجهد.

الحل

$$\vec{F} = -\frac{\mu}{r^2} \hat{e}_r$$

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{e}_r & \hat{e}_\theta & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ -\frac{\mu}{r^2} & 0 & 0 \end{vmatrix} = \vec{0}$$

القوة محافظة

$$\vec{F} = -\vec{\nabla} \phi \quad \frac{-\mu}{r^2} = -\frac{\partial \phi}{\partial r}$$

$$\phi = \int \mu r^{-2} dr = -\frac{\mu}{r}$$

* وإذا كانت سرعة الكوكب عندما كان على بعد r_A تساوي v_A أو جد سرعته عند r_B

$$\phi_A + T_A = \phi_B + T_B \quad \text{باستخدام قانون بقاء الطاقة}$$

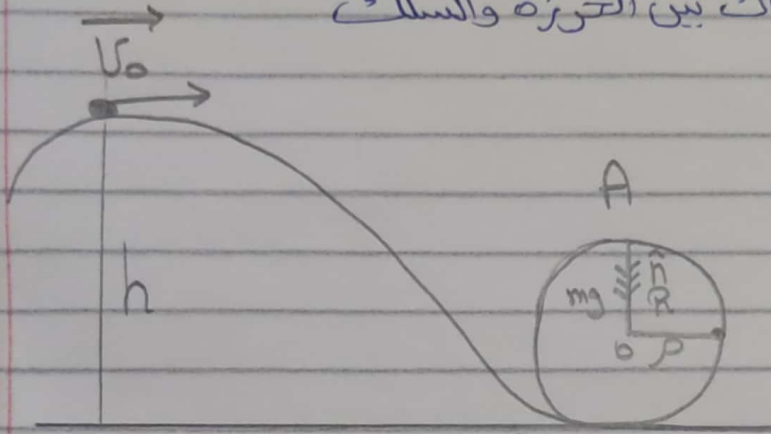
$$\frac{-\mu}{r_A} + \frac{1}{2} m v_A^2 = \frac{-\mu}{r_B} + \frac{1}{2} m v_B^2$$

$$v_B^2 = \frac{1}{m} \left(\frac{2\mu}{r_B} - \frac{2\mu}{r_A} + m v_A^2 \right)$$

$$v_B^2 = v_A^2 + K \left(\frac{1}{r_B} - \frac{1}{r_A} \right) \quad \Rightarrow K = \frac{2\mu}{m}$$

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مثال ٣ تتحرك خزانة على سلك أملس في مستوى رأسي كما هو موضح بالشكل . أوجد أقل سرعة ابتدائية v_0 بحيث تقوم بالكاد بعمل دورة كاملة بدون ترك السلك بفرض أنه لا يوجد احتكاك بين الخزانة والسلك



الحل
 $a_n = \frac{v^2}{R}$

$R = 0 \rightarrow$ عند A

$$\sum F_n = ma_n$$

$$mg = m \frac{v_A^2}{R}$$

$$v_A^2 = gR$$

$$T_0 + v_0^2 = T_A + v_A^2$$

$$\frac{1}{2} m v_0^2 + mgh = \frac{1}{2} m v_A^2 + mg(2R)$$

$$v_0^2 = v_A^2 + 2g(2R - h)$$

$$v_0^2 = g(R + 4R - 2h)$$

$$v_0^2 = g(5R - 2h)$$

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$$\vec{F} = -\vec{\nabla} \phi$$

$$= \left(-\frac{\partial \phi}{\partial x}, -\frac{\partial \phi}{\partial y}, -\frac{\partial \phi}{\partial z} \right)$$

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(0) أوجد دالة الجهد لجال القوة

$$\vec{F} = (ay(y^2 - 3z^2), 3ax(y^2 - z^2) - baxyz)$$

$$\frac{-\partial \phi}{\partial x} = F_x, \quad \frac{-\partial \phi}{\partial y} = F_y, \quad \frac{-\partial \phi}{\partial z} = F_z$$

$$\phi = -\int ay(y^2 - 3z^2) dx = -axy(y^2 - 3z^2) + C_1(y, z)$$

$$\frac{\partial \phi}{\partial y} = -3axy^2 + 3axz^2 + \frac{\partial C_1}{\partial y} = -3ax(y^2 - z^2)$$

$$= -3ax(y^2 - z^2) + \frac{\partial C_1}{\partial y} = -3ax(y^2 - z^2)$$

$$\frac{\partial C_1}{\partial y} = 0 \Rightarrow C_1 = C_1(z)$$

$$\frac{\partial \phi}{\partial z} = \underbrace{baxyz} + \frac{\partial C_1}{\partial z} = -F_z = \underbrace{baxyz}$$

$$\frac{\partial C_1}{\partial z} = 0 \Rightarrow C_1 = \text{Constant}$$

$$\phi = -axy(y^2 - 3z^2) + C$$

* أوجد دالة الجهد لجال القوة ،

1) $\vec{F} = (yz, xz, xy + 2z)$

2) $\vec{F} = (\sin(y), x \cos(y) + \cos(z), -y \sin(z))$

3) $\vec{F} = (y^2z + xz^2, 2xyz, xy^2 + 2x^2z)$

$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix} = 0$ هنجيب

علشان اتأكد انها قوة كافظت ولو مش قوة كافظت يبقى ملهاش دالة جهد

1)

$(x-x)\hat{i} - (y-y)\hat{j} + (z-z)\hat{k} = 0$ بعقل المحدد =

$\Phi = \vec{F} = (yz, xz, xy + 2z)$

$= - \int yz \, dx = -xyz + C_1(y, z)$ $\rightarrow z^2$

$= - \int xz \, dy = -xyz + C_2(x, z)$ $\rightarrow z^2$

$= - \int xy + 2z \, dz = - (xyz + z^2) + C_3(x, y)$ $\rightarrow z^2$

$\Phi = - (xyz + z^2)$

$$2) \vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \sin(y) & x \cos(y) + \cos(z) & -y \sin(z) \end{vmatrix}$$

$$= (-\sin(z) + \sin(z))\hat{i} - (0)\hat{j} + (\cos(y) - \cos(y))\hat{k}$$

$$\vec{\Phi} = (\sin(y), x \cos(y) + \cos(z), -y \sin(z))$$

$$= -\int \sin(y) dx = -x \sin(y) + C_1(y, z)$$

$$= -\int x \cos(y) + \cos(z) dy = -x \sin(y) + y \cos(z) + C_2(x, z)$$

$$= -\int y \sin(z) dz = -y \cos(z) + C_3(y, z)$$

$C_3 = \text{Constant}$ $\vec{\Phi} = -x \sin(y) - y \cos(z) + C_3$

$$3) \vec{\nabla} \times \vec{F} = \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y^2 z + x z^2 & 2xy z & xy^2 + 2x^2 z \end{vmatrix}$$

$$= (2xy - 2xy)\hat{i} - (2xz)\hat{j} + (2yz - 2yz)\hat{k}$$

$$= -2xz\hat{j} \neq 0$$

∴ القوة غير محافظة
∴ لا يوجد دالة جهد

$$\vec{F} = \left(-\frac{\partial \phi}{\partial x}, -\frac{\partial \phi}{\partial y}, -\frac{\partial \phi}{\partial z} \right)$$

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* أوجد القوة الناشئة عن دالة الجهد

1)

$$\phi = axy^2z^3$$

$$2) \phi = \frac{1}{2}ax^2 - \frac{1}{2}by^2 - \frac{1}{2}cz^2$$

$$3) \phi = a(x^2 + y^2 + z^2)^{-\frac{1}{2}}$$

$$1) \frac{\partial \phi}{\partial x} = -(ay^2z^3)$$

$$\frac{\partial \phi}{\partial y} = -(2axyz^3)$$

$$\frac{\partial \phi}{\partial z} = -(3axy^2z^2)$$

\vec{F} وجمعهم في

$$2) \frac{\partial \phi}{\partial x} = -ax, \frac{\partial \phi}{\partial y} = -by, \frac{\partial \phi}{\partial z} = -cz$$

$$\vec{F} = (-ax, -by, -cz)$$

$$3) \frac{\partial \phi}{\partial x} = ax(x^2 + y^2 + z^2)^{-\frac{3}{2}}$$

$$\frac{\partial \phi}{\partial y} = ay(x^2 + y^2 + z^2)^{-\frac{3}{2}}$$

$$\frac{\partial \phi}{\partial z} = az(x^2 + y^2 + z^2)^{-\frac{3}{2}}$$

$$\vec{F} = \left(-\frac{\partial \phi}{\partial x}, -\frac{\partial \phi}{\partial y}, -\frac{\partial \phi}{\partial z} \right)$$

finish

$$\square \vec{F} = (-x^2 y z) \underline{i} - (x y z^2) \underline{k}$$

$$\text{Curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -xyz & 0 & -xyz \end{vmatrix}$$

$$(-xz^2 - 0) - (-yz^2 + xy) + (-xz) \neq 0$$

هذه القوة ليست قوة محافظة

$$\text{Curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 y - z^2 & (3xyz + xz^2) & 2x^2 y z + yz^4 \end{vmatrix}$$

$$(2xz^2 + z^4 - 3xy - 2xz) \quad \text{ليست قوة محافظة}$$

$$\vec{F} = -K r^2 \underline{r}$$

{أوجد دالة الجهد}

$K \rightarrow \text{Constant}$

بالضرب $\times r$

$$\vec{F} = -K r^3 \underline{e_r}$$

$$\text{Curl } \vec{F} = \begin{vmatrix} \hat{e_r} & \hat{e_\theta} & \hat{k} \\ \frac{\partial}{\partial r} & \frac{1}{r} \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ -Kr^3 & 0 & 0 \end{vmatrix} = \underline{0}$$

$$\frac{\underline{r}}{r} = \underline{e_r}$$

$$\Phi = - \int -K r^3 dr$$

$$\Phi = \frac{K}{4} r^4 + C \quad \rightarrow = \text{Zero}$$

$$\vec{F} = (x+2y+az) \hat{i} + (bx-3y-z) \hat{j} + (4x+cy+2z) \hat{k}$$

$$\text{curl } \vec{F} = \vec{0}$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (x+2y+az) & (bx-3y-z) & (4x+cy+2z) \end{vmatrix}$$

$$(c+1) \hat{i} - (4-a) \hat{j} + (b-2) \hat{k} = \vec{0}$$

to $\text{curl } \vec{F} = \vec{0}$ we should take

$$a = 4, b = 2 \text{ and } c = -1$$

أوجد الشغل المبذول لتحريك جسم دورة كاملة حول دائرة في المستوى (x, y) نصف قطرها 3 cm ومركزها نقطة الأصل

$$\vec{F} = (2x+y+z) \hat{i} + (x+y-z) \hat{j} + (x-2y+4z) \hat{k}$$

$$W = \oint \vec{F} \cdot d\vec{r}$$

$$W = \int_0^{2\pi} (6 \cos(\theta) + 3 \sin(\theta)) \cdot (-3 \sin(\theta) d\theta)$$

$$+ \int_0^{2\pi} (3 \cos(\theta) + 3 \sin(\theta)) \cdot (3 \cos(\theta) d\theta)$$

$$W = \int_0^{2\pi} -9 \sin(\theta) \cos(\theta) + 9 (\cos^2(\theta) - \sin^2(\theta)) d\theta$$

$$x = 3 \cos(\theta)$$

$$y = 3 \sin(\theta)$$

$$dx = -3 \sin(\theta) d\theta$$

$$dy = 3 \cos(\theta) d\theta$$

$$\theta = 0 \rightarrow 2\pi$$

$$W = \left[\frac{9}{2} (\cos \theta)^2 + \frac{9}{2} \sin(2\theta) \right]_0^{2\pi} = \text{Zero} \quad \neq$$