

Design file:

```
module ALSU(A, B, cin, serial_in, red_op_A, red_op_B, opcode, bypass_A,
bypass_B, clk, rst, direction, leds, out);
parameter INPUT_PRIORITY = "A";
parameter FULL_ADDER = "ON";
input clk, cin, rst, red_op_A, red_op_B, bypass_A, bypass_B, direction,
serial_in;
input [2:0] opcode;
input signed [2:0] A, B;
output reg [15:0] leds;
output reg signed [5:0] out;

reg red_op_A_reg, red_op_B_reg, bypass_A_reg, bypass_B_reg, direction_reg,
serial_in_reg;
reg cin_reg;
reg [2:0] opcode_reg;
reg signed [2:0] A_reg, B_reg;

wire invalid_red_op, invalid_opcode, invalid;

//Invalid handling
assign invalid_red_op = (red_op_A_reg | red_op_B_reg) & (opcode_reg[1] |
opcode_reg[2]);
assign invalid_opcode = opcode_reg[1] & opcode_reg[2];
assign invalid = invalid_red_op | invalid_opcode;

//Registering input signals
always @(posedge clk or posedge rst) begin
    if(rst) begin
        cin_reg <= 0;
        red_op_B_reg <= 0;
        red_op_A_reg <= 0;
        bypass_B_reg <= 0;
        bypass_A_reg <= 0;
        direction_reg <= 0;
        serial_in_reg <= 0;
        opcode_reg <= 0;
        A_reg <= 0;
        B_reg <= 0;
    end else begin
        cin_reg <= cin;
        red_op_B_reg <= red_op_B;
        red_op_A_reg <= red_op_A;
        bypass_B_reg <= bypass_B;
        bypass_A_reg <= bypass_A;
        direction_reg <= direction;
        serial_in_reg <= serial_in;
        opcode_reg <= opcode;
```

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        A_reg <= A;
        B_reg <= B;
    end
end

//leds output blinking
always @(posedge clk or posedge rst) begin
    if(rst) begin
        leds <= 0;
    end else begin
        if (invalid)
            leds <= ~leds;
        else
            leds <= 0;
    end
end

//ALSU output processing
always @(posedge clk or posedge rst) begin
    if(rst) begin
        out <= 0;
    end
    else begin
        if (bypass_A_reg && bypass_B_reg)
            out <= (INPUT_PRIORITY == "A")? A_reg: B_reg;
        else if (bypass_A_reg)
            out <= A_reg;
        else if (bypass_B_reg)
            out <= B_reg;
        else if (invalid)
            out <= 0;
        else begin
            case (opcode_reg)
                3'h0: begin
                    if (red_op_A_reg && red_op_B_reg)
                        out <= (INPUT_PRIORITY == "A")? |A_reg: |B_reg;
                    else if (red_op_A_reg)
                        out <= |A_reg;
                    else if (red_op_B_reg)
                        out <= |B_reg;
                    else
                        out <= A_reg | B_reg;
                end
                3'h1: begin
                    if (red_op_A_reg && red_op_B_reg)
                        out <= (INPUT_PRIORITY == "A")? ^A_reg: ^B_reg;
                    else if (red_op_A_reg)
                        out <= ^A_reg;
                end
            endcase
        end
    end
end

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        else if (red_op_B_reg)
            out <= ^B_reg;
        else
            out <= A_reg ^ B_reg;
        end
3'h2: out <= (FULL_ADDER == "ON")? A_reg + B_reg + cin : A_reg +
B_reg;
3'h3: out <= A_reg * B_reg;
3'h4: begin
    if (direction_reg)
        out <= {out[4:0], serial_in_reg};
    else
        out <= {serial_in_reg, out[5:1]};
    end
3'h5: begin
    if (direction_reg)
        out <= {out[4:0], out[5]};
    else
        out <= {out[0], out[5:1]};
    end
endcase
end
end
end

endmodule

```

Verification plan:

Label	Design Requirement Description	Stimulus Generation	Functional Coverage	Functionality Check
ALSU1	When rst is asserted high, out should be 0 and leds should be 0.	Directed at the start of simulation then randomized with - constraint (most of the time low).		Checker ensures out = 0, leds = 0.
ALSU2	when opcode is ADD, then out should perform addition on ports A and B taking cin.	Randomized under constraints on the A and B	Cover MAXPOS, MAXNEG, ZERO as well as default for all other values	Checker ensures out = A + B + cin
ALSU3	when opcode is MUL, then out should perform the multiplication on ports A and B	Randomized under constraints on the A and B	Cover MAXPOS, MAXNEG, ZERO as well as default for all other values	Checker ensures out = A * B
ALSU4	when opcode is OR, then out should perform the OR operation on ports A and B if reduction_A, reduction B are low	Randomized without constraints on A or B.	-	Checker ensures out = A B
ALSU5	when opcode is OR & any of the inputs reduction_A or reduction_B is high.	Randomized under constraints on the A and B	Cover the walking ones values for A and B	Checker ensures out = (INPUT_PRIORITY == 'A') ? A : B
ALSU6	when opcode is XOR, then out should perform the XOR operation on ports A and B if reduction_A, reduction B are low.	Randomized without constraints on A or B	-	Checker ensures out = A ^ B

Label	Design Requirement Description	Stimulus Generation	Functional Coverage	Functionality Check
ALSU7	when opcode is XOR & any of the inputs reduction_A or reduction_B is high.	Randomized under constraints on the A and B	Cover the walking ones values for A and B	Checker ensures out = (INPUT_PRIORITY == 'A') ? ^A : ^B
ALSU8	when opcode is SHIFT then the output will shift right or left based on the direction input	Randomized without constraints on A or B	Cover the SHIFT opcode	Checker ensures out = (Direction == 'left') ? out << : out >>
ALSU9	when opcode is ROTATE then the output will rotate right or left based on the direction input	Randomized without constraints on A or B.	Cover the ROTATE opcode	Checker ensures out = (Direction == 'left') ? out << : out >>
ALSU10	When invalid cases exist without bypass, out should be low and leds should blink	Randomized under constraints (valid cases Happen frequently)	Cover the illegal opcode	Checker ensures out = 0, leds blinking
ALSU11	If the bypass inputs are high, then the output will bypass port A or B	Randomized under constraints	-	Checker ensures out = A or B

Interface:

```
interface alsu_if(clk);  
    input bit clk;  
    logic rst;  
    logic cin;  
    logic red_op_A;  
    logic red_op_B;  
    logic bypass_A;  
    logic bypass_B;  
    logic direction;  
    logic serial_in;  
    logic [2:0] opcode;  
    logic signed [2:0] A;  
    logic signed [2:0] B;  
    logic [15:0] leds;  
    logic signed [5:0] out;  
endinterface: alsu_if
```

Testbench file:

```
import uvm_pkg::*;
import alsu_test_pkg::*;
import alsu_shared_pkg::*;
`include "uvm_macros.svh"

module alsu_tb();
    // Clock generation
    bit clk;

    initial begin
        forever begin
            #1 clk = ~clk;
        end
    end

    // Instantiate the interface
    alsu_if alsuif(clk);

    // Instantiate the DUT
    ALSU #(
        .INPUT_PRIORITY(INPUT_PRIORITY),
        .FULL_ADDER(FULL_ADDER)
    ) DUT (
        .clk(clk),
        .rst(alsuif.rst),
        .cin(alsuif.cin),
        .red_op_A(alsuif.red_op_A),
        .red_op_B(alsuif.red_op_B),
        .bypass_A(alsuif.bypass_A),
        .bypass_B(alsuif.bypass_B),
        .direction(alsuif.direction),
        .serial_in(alsuif.serial_in),
        .opcode(alsuif.opcode),
        .A(alsuif.A),
        .B(alsuif.B),
        .leds(alsuif.leds),
        .out(alsuif.out)
    );

    bind ALSU alsu_sva #(
        .INPUT_PRIORITY(INPUT_PRIORITY),
        .FULL_ADDER(FULL_ADDER)
    ) ASSERT (
        .clk(clk),
        .rst(alsuif.rst),
        .cin(alsuif.cin),
        .red_op_A(alsuif.red_op_A),
```

```

        .red_op_B(alsuif.red_op_B),
        .bypass_A(alsuif.bypass_A),
        .bypass_B(alsuif.bypass_B),
        .direction(alsuif.direction),
        .serial_in(alsuif.serial_in),
        .opcode(alsuif.opcode),
        .A(alsuif.A),
        .B(alsuif.B),
        .leds(alsuif.leds),
        .out(alsuif.out)
    );

    // Run the test
    initial begin
        uvm_config_db #(virtual alsu_if)::set(null, "uvm_test_top",
"ALSU_VIF", alsuif);
        run_test("alsu_test");
    end

endmodule

```


Test package:

```
package alsu_test_pkg;
import uvm_pkg::*;
import alsu_env_pkg::*;
import alsu_config_pkg::*;
import alsu_reset_seq_pkg::*;
import alsu_main_seq_pkg::*;
`include "uvm_macros.svh"

class alsu_test extends uvm_test;
    `uvm_component_utils(alsu_test)

    alsu_env env;
    alsu_config alsu_cfg;
    alsu_reset_seq reset_seq;
    alsu_main_seq main_seq;

    function new(string name = "alsu_test", uvm_component parent = null);
        super.new(name, parent);
    endfunction

    function void build_phase(uvm_phase phase);
        super.build_phase(phase);

        env = alsu_env::type_id::create("env", this);
        alsu_cfg = alsu_config::type_id::create("alsu_cfg");
        reset_seq = alsu_reset_seq::type_id::create("reset_seq");
        main_seq = alsu_main_seq::type_id::create("main_seq");

        if (!uvm_config_db #(virtual alsu_if)::get(this, "", "ALSU_VIF",
alsu_cfg.alsu_vif)) begin
            `uvm_fatal("BUILD_PHASE", "Test - Unable to get virtual interface
of the ALSU")
        end

        uvm_config_db #(alsu_config)::set(this, "*", "CFG", alsu_cfg);
    endfunction

    task run_phase(uvm_phase phase);
        super.run_phase(phase);
        phase.raise_objection(this);

        // reset sequence
        reset_seq.start(env.agent.sequencer);
        `uvm_info("RUN_PHASE", "Reset Asserted", UVM_LOW)
        `uvm_info("RUN_PHASE", "Reset Deasserted", UVM_LOW)

        // main sequence
```

```
`uvm_info("RUN_PHASE", "Stimulus Generation Started", UVM_LOW)
main_seq.start(env.agent.sequencer);
`uvm_info("RUN_PHASE", "Stimulus Generation Ended", UVM_LOW)

    phase.drop_objection(this);
endtask
endclass: alsu_test

endpackage: alsu_test_pkg
```

Env. package:

```
package alsu_env_pkg;
import uvm_pkg::*;
import alsu_agent_pkg::*;
import alsu_scoreboard_pkg::*;
import alsu_coverage_pkg::*;
`include "uvm_macros.svh"

class alsu_env extends uvm_env;
    `uvm_component_utils(alsu_env)

    alsu_agent agent;
    alsu_scoreboard scoreboard;
    alsu_coverage coverage;

    function new(string name = "alsu_env", uvm_component parent = null);
        super.new(name, parent);
    endfunction

    function void build_phase(uvm_phase phase);
        super.build_phase(phase);

        agent = alsu_agent::type_id::create("agent", this);
        scoreboard = alsu_scoreboard::type_id::create("scoreboard", this);
        coverage = alsu_coverage::type_id::create("coverage", this);
    endfunction

    function void connect_phase(uvm_phase phase);
        agent.analysis_port.connect(scoreboard.analysis_export);
        agent.analysis_port.connect(coverage.analysis_export);
    endfunction
endclass: alsu_env

endpackage: alsu_env_pkg
```

Agent package:

```
package alsu_agent_pkg;
import uvm_pkg::*;
import alsu_sequencer_pkg::*;
import alsu_seq_item_pkg::*;
import alsu_driver_pkg::*;
import alsu_monitor_pkg::*;
import alsu_config_pkg::*;
`include "uvm_macros.svh"

class alsu_agent extends uvm_agent;
    `uvm_component_utils(alsu_agent)

    alsu_sequencer sequencer;
    alsu_driver driver;
    alsu_monitor monitor;
    alsu_config alsu_cfg;
    uvm_analysis_port #(alsu_seq_item) analysis_port;

    function new(string name = "alsu_agent", uvm_component parent = null);
        super.new(name, parent);
    endfunction

    function void build_phase(uvm_phase phase);
        super.build_phase(phase);

        if (!uvm_config_db #(alsu_config)::get(this, "", "CFG", alsu_cfg))
begin
            `uvm_fatal("BUILD_PHASE", "Agent - Unable to get the configuration
object")
        end

        sequencer = alsu_sequencer::type_id::create("sequencer", this);
        driver = alsu_driver::type_id::create("driver", this);
        monitor = alsu_monitor::type_id::create("monitor", this);

        analysis_port = new("analysis_port", this);
    endfunction

    function void connect_phase(uvm_phase phase);
        driver.alsu_vif = alsu_cfg.alsu_vif;
        monitor.alsu_vif = alsu_cfg.alsu_vif;

        driver.seq_item_port.connect(sequencer.seq_item_export);
        monitor.analysis_port.connect(analysis_port);
    endfunction
endclass: alsu_agent
endpackage: alsu_agent_pkg
```

Driver package:

```
package alsu_driver_pkg;
import uvm_pkg::*;
import alsu_seq_item_pkg::*;
import alsu_shared_pkg::*;
`include "uvm_macros.svh"

class alsu_driver extends uvm_driver #(alsu_seq_item);
    `uvm_component_utils(alsu_driver)

    virtual alsu_if alsu_vif;
    alsu_seq_item seq_item;

    function new(string name = "alsu_driver", uvm_component parent = null);
        super.new(name, parent);
    endfunction

    task run_phase(uvm_phase phase);
        super.run_phase(phase);
        forever begin
            seq_item = alsu_seq_item::type_id::create("seq_item");
            seq_item_port.get_next_item(seq_item);
            alsu_vif.rst = seq_item.rst;
            alsu_vif.A = seq_item.A;
            alsu_vif.B = seq_item.B;
            alsu_vif.opcode = opcode_e'(seq_item.opcode);
            alsu_vif.cin = seq_item.cin;
            alsu_vif.red_op_A = seq_item.red_op_A;
            alsu_vif.red_op_B = seq_item.red_op_B;
            alsu_vif.bypass_A = seq_item.bypass_A;
            alsu_vif.bypass_B = seq_item.bypass_B;
            alsu_vif.direction = direction_e'(seq_item.direction);
            alsu_vif.serial_in = seq_item.serial_in;
            @(negedge alsu_vif.clk);
            seq_item_port.item_done();
            `uvm_info("RUN_PHASE", seq_item.convert2string_stimulus(),
UVM_HIGH)
                end
            endtask
        endclass: alsu_driver

endpackage: alsu_driver_pkg
```

Monitor package:

```
package alsu_monitor_pkg;
import uvm_pkg::*;
import alsu_seq_item_pkg::*;
import alsu_shared_pkg::*;
`include "uvm_macros.svh"

class alsu_monitor extends uvm_monitor;
    `uvm_component_utils(alsu_monitor)

    virtual alsu_if alsu_vif;
    alsu_seq_item seq_item;
    uvm_analysis_port #(alsu_seq_item) analysis_port;

    function new(string name = "alsu_monitor", uvm_component parent = null);
        super.new(name, parent);
    endfunction

    function void build_phase(uvm_phase phase);
        super.build_phase(phase);
        analysis_port = new("analysis_port", this);
    endfunction

    task run_phase(uvm_phase phase);
        super.run_phase(phase);
        forever begin
            seq_item = alsu_seq_item::type_id::create("seq_item");
            @(negedge alsu_vif.clk);
            seq_item.rst = alsu_vif.rst;
            seq_item.A = alsu_vif.A;
            seq_item.B = alsu_vif.B;
            seq_item.opcode = opcode_e'(alsu_vif.opcode);
            seq_item.cin = alsu_vif.cin;
            seq_item.red_op_A = alsu_vif.red_op_A;
            seq_item.red_op_B = alsu_vif.red_op_B;
            seq_item.bypass_A = alsu_vif.bypass_A;
            seq_item.bypass_B = alsu_vif.bypass_B;
            seq_item.direction = direction_e'(alsu_vif.direction);
            seq_item.serial_in = alsu_vif.serial_in;
            seq_item.out = alsu_vif.out;
            seq_item.leds = alsu_vif.leds;

            analysis_port.write(seq_item);
            `uvm_info("RUN_PHASE", seq_item.convert2string(), UVM_HIGH)
        end
    endtask
endclass: alsu_monitor
endpackage: alsu_monitor_pkg
```

Sequencer package:

```
package alsu_sequencer_pkg;
import uvm_pkg::*;
import alsu_seq_item_pkg::*;

`include "uvm_macros.svh"

class alsu_sequencer extends uvm_sequencer #(alsu_seq_item);
    `uvm_component_utils(alsu_sequencer)

    function new(string name = "alsu_sequencer", uvm_component parent = null);
        super.new(name, parent);
    endfunction
endclass: alsu_sequencer

endpackage: alsu_sequencer_pkg
```

Coverage collector package:

```
package alsu_coverage_pkg;
import uvm_pkg::*;
import alsu_seq_item_pkg::*;
import alsu_shared_pkg::*;
`include "uvm_macros.svh"

class alsu_coverage extends uvm_component;
    `uvm_component_utils(alsu_coverage)

    uvm_analysis_export #(alsu_seq_item) analysis_export;
    uvm_tlm_analysis_fifo #(alsu_seq_item) analysis_fifo;
    alsu_seq_item seq_item;

    covergroup cvg;
        ADD_MULT_A_cp: coverpoint seq_item.A{
            bins A_data_0 = {0};
            bins A_data_max = {MAXPOS};
            bins A_data_min = {MAXNEG};
            bins A_data_default = default;
        }

        RED_A_cp: coverpoint seq_item.A iff (seq_item.red_op_A){
            bins A_data_walkingones[] = {3'sb001,3'sb010,3'sb100};
        }

        ADD_MULT_B_cp: coverpoint seq_item.B{
            bins B_data_0 = {0};
            bins B_data_max = {MAXPOS};
            bins B_data_min = {MAXNEG};
            bins B_data_default = default;
        }

        RED_B_cp: coverpoint seq_item.B iff (seq_item.red_op_B &&
(!seq_item.red_op_A)){
            bins B_data_walkingones[] = {3'sb001,3'sb010,3'sb100};
        }

        opcode_cp: coverpoint seq_item.opcode{
            bins bins_shift[] = {SHIFT, ROTATE};
            bins bins_arith[] = {ADD, MULT};
            bins bins_bitwise[] = {OR, XOR};
            illegal_bins bins_invalid = {INVALID_6, INVALID_7};
        }

        opcode_shift_cp: coverpoint seq_item.opcode{
            option.weight = 0;
            bins bins_shift[] = {SHIFT, ROTATE};
        }
    endcovergroup
endclass
```



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}

opcode_arith_cp: coverpoint seq_item.opcode{
    option.weight = 0;
    bins bins_arith[] = {ADD, MULT};
}

opcode_bitwise_cp: coverpoint seq_item.opcode{
    option.weight = 0;
    bins bins_arith[] = {OR, XOR};
}

opcode_not_bitwise_cp: coverpoint seq_item.opcode{
    option.weight = 0;
    bins bins_not_bitwise[] = {[ADD:$]};
}

cin_cp: coverpoint seq_item.cin{
    option.weight = 0;
}

direction_cp: coverpoint seq_item.direction{
    option.weight = 0;
}

serial_in_cp: coverpoint seq_item.serial_in{
    option.weight = 0;
}

red_op_A_cp: coverpoint seq_item.red_op_A{
    option.weight = 0;
}

red_op_B_cp: coverpoint seq_item.red_op_B{
    option.weight = 0;
}

ADD_MULT_cross: cross ADD_MULT_A_cp, ADD_MULT_B_cp, opcode_arith_cp;

ADD_cin_cross: cross cin_cp, opcode_arith_cp{
    ignore_bins bins_MULT = binsof(opcode_arith_cp) intersect {MULT};
}

SHIFT_direction_cross: cross direction_cp, opcode_shift_cp{
    ignore_bins bins_ROTATE = binsof(opcode_shift_cp) intersect
{ROTATE};
}

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        SHIFT_serial_in_cross: cross serial_in_cp, opcode_shift_cp{
            ignore_bins bins_ROTATE = binsof(opcode_shift_cp) intersect
{ROTATE};
        }

        red_op_A_cross: cross RED_A_cp, ADD_MULT_B_cp, opcode_bitwise_cp iff
(seq_item.red_op_A){
            ignore_bins B_data_max = binsof(ADD_MULT_B_cp.B_data_max);
            ignore_bins B_data_min = binsof(ADD_MULT_B_cp.B_data_min);
        }

        red_op_B_cross: cross RED_B_cp, ADD_MULT_A_cp, opcode_bitwise_cp iff
(seq_item.red_op_B && (!seq_item.red_op_A)){
            ignore_bins A_data_max = binsof(ADD_MULT_A_cp.A_data_max);
            ignore_bins A_data_min = binsof(ADD_MULT_A_cp.A_data_min);
        }

        invalid_red_op_A_cross: cross red_op_A_cp, opcode_not_bitwise_cp{
            ignore_bins red_op_A_0 = binsof(red_op_A_cp) intersect {0};
            illegal_bins red_op_A_1 = binsof(red_op_A_cp) intersect {1};
        }

        invalid_red_op_B_cross: cross red_op_B_cp, opcode_not_bitwise_cp{
            ignore_bins red_op_B_0 = binsof(red_op_B_cp) intersect {0};
            illegal_bins red_op_B_1 = binsof(red_op_B_cp) intersect {1};
        }
    endgroup

    function new(string name = "alsu_coverage", uvm_component parent = null);
        super.new(name, parent);
        cvg = new();
    endfunction

    function void build_phase(uvm_phase phase);
        super.build_phase(phase);

        analysis_export = new("analysis_export", this);
        analysis_fifo = new("analysis_fifo", this);
    endfunction

    function void connect_phase(uvm_phase phase);
        super.connect_phase(phase);

        analysis_export.connect(analysis_fifo.analysis_export);
    endfunction

    task run_phase(uvm_phase phase);
        super.run_phase(phase);

```

```
        forever begin
            analysis_fifo.get(seq_item);
            sample_cvg(seq_item);
        end
    endtask

    task sample_cvg(alsu_seq_item seq_item);
        if((!seq_item.rst) || (!seq_item.bypass_A) || (!seq_item.bypass_B))
begin
            cvg.sample();
        end
    endtask
endclass: alsu_coverage

endpackage: alsu_coverage_pkg
```

Scoreboard package:

```
package alsu_scoreboard_pkg;
import uvm_pkg::*;
import alsu_seq_item_pkg::*;
import alsu_shared_pkg::*;
`include "uvm_macros.svh"

class alsu_scoreboard extends uvm_scoreboard;
    `uvm_component_utils(alsu_scoreboard)

    uvm_analysis_export #(alsu_seq_item) analysis_export;
    uvm_tlm_analysis_fifo #(alsu_seq_item) analysis_fifo;
    alsu_seq_item seq_item;

    logic cin_reg;
    logic red_op_A_reg;
    logic red_op_B_reg;
    logic bypass_A_reg;
    logic bypass_B_reg;
    direction_e direction_reg;
    logic serial_in_reg;
    opcode_e opcode_reg;
    logic signed [2:0] A_reg;
    logic signed [2:0] B_reg;
    logic [15:0] leds_ref;
    logic signed [5:0] out_ref;

    int error_count = 0;
    int correct_count = 0;

    function new(string name = "alsu_scoreboard", uvm_component parent =
null);
        super.new(name, parent);
    endfunction

    function void build_phase(uvm_phase phase);
        super.build_phase(phase);

        analysis_export = new("analysis_export", this);
        analysis_fifo = new("analysis_fifo", this);
    endfunction

    function void connect_phase(uvm_phase phase);
        super.connect_phase(phase);

        analysis_export.connect(analysis_fifo.analysis_export);
    endfunction
```

```

task run_phase(uvm_phase phase);
    super.run_phase(phase);
    forever begin
        seq_item = alsu_seq_item::type_id::create("seq_item");
        analysis_fifo.get(seq_item);
        ref_model(seq_item);
        check_result(seq_item);
    end
endtask

task check_result(alsu_seq_item seq_item);
    if ((out_ref != seq_item.out) || (leds_ref != seq_item.leds)) begin
        `uvm_error("RUN_PHASE", $sformatf("Comparsion failed, Transaction
received from DUT: %s While the reference out = 0b%0b, leds = 0x%0h ",
seq_item.convert2string(), out_ref, leds_ref));
        error_count++;
    end else begin
        `uvm_info("RUN_PHASE", $sformatf("Comparsion succeeded,
Transaction received from DUT: %s ", seq_item.convert2string()), UVM_HIGH);
        correct_count++;
    end
endtask

task ref_model(alsu_seq_item seq_item);
    logic invalid_red_op, invalid_opcode, invalid;

    invalid_red_op = (red_op_A_reg | red_op_B_reg) & (opcode_reg[1] |
opcode_reg[2]);
    invalid_opcode = opcode_reg[1] & opcode_reg[2];
    invalid        = invalid_red_op | invalid_opcode;

    if (seq_item.rst) begin
        leds_ref = 16'h0;
    end else begin
        if (invalid) begin
            leds_ref = ~leds_ref;
        end else begin
            leds_ref = 16'h0;
        end
    end

    if (seq_item.rst) begin
        out_ref = 0;
    end else begin
        if (bypass_A_reg && bypass_B_reg) begin
            out_ref = (INPUT_PRIORITY == "A") ? A_reg : B_reg;
        end else if (bypass_A_reg) begin
            out_ref = A_reg;
        end
    end
endtask

```

```

end else if (bypass_B_reg) begin
    out_ref = B_reg;
end else if (invalid) begin
    out_ref = 0;
end else begin
    case (opcode_reg)
        OR: begin
            if (red_op_A_reg && red_op_B_reg) begin
                out_ref = (INPUT_PRIORITY == "A") ? (|A_reg) :
(|B_reg);

            end else if (red_op_A_reg) begin
                out_ref = |A_reg;
            end else if (red_op_B_reg) begin
                out_ref = |B_reg;
            end else begin
                out_ref = A_reg | B_reg;
            end
        end
        XOR: begin
            if (red_op_A_reg && red_op_B_reg) begin
                out_ref = (INPUT_PRIORITY == "A") ? (^A_reg) :
(^B_reg);

            end else if (red_op_A_reg) begin
                out_ref = ^A_reg;
            end else if (red_op_B_reg) begin
                out_ref = ^B_reg;
            end else begin
                out_ref = A_reg ^ B_reg;
            end
        end
        ADD: begin
            if (FULL_ADDER == "ON") begin
                out_ref = A_reg + B_reg + cin_reg;
            end else begin
                out_ref = A_reg + B_reg;
            end
        end
        MULT: out_ref = A_reg * B_reg;
        SHIFT: begin
            if (direction_reg) begin
                out_ref = {out_ref[4:0], serial_in_reg};
            end else begin
                out_ref = {serial_in_reg, out_ref[5:1]};
            end
        end
        ROTATE: begin
            if (direction_reg) begin
                out_ref = {out_ref[4:0], out_ref[5]};

```

```

        end else begin
            out_ref = {out_ref[0], out_ref[5:1]};
        end
    end
    default: out_ref = out_ref;
endcase
end
end

if (seq_item.rst) begin
    cin_reg = 0;
    red_op_A_reg = 0;
    red_op_B_reg = 0;
    bypass_A_reg = 0;
    bypass_B_reg = 0;
    direction_reg = direction_e'(0);
    serial_in_reg = 0;
    opcode_reg = opcode_e'(0);
    A_reg = 0;
    B_reg = 0;
end else begin
    cin_reg = seq_item.cin;
    red_op_A_reg = seq_item.red_op_A;
    red_op_B_reg = seq_item.red_op_B;
    bypass_A_reg = seq_item.bypass_A;
    bypass_B_reg = seq_item.bypass_B;
    direction_reg = seq_item.direction;
    serial_in_reg = seq_item.serial_in;
    opcode_reg = seq_item.opcode;
    A_reg = seq_item.A;
    B_reg = seq_item.B;
end
endtask

function void report_phase(uvm_phase phase);
    super.report_phase(phase);
    `uvm_info("REPORT_PHASE", $sformatf("Total successful transactions:
%d ", correct_count), UVM_MEDIUM);
    `uvm_info("REPORT_PHASE", $sformatf("Total failed transactions: %d ",
error_count), UVM_MEDIUM);
endfunction

endclass: alsu_scoreboard

endpackage: alsu_scoreboard_pkg

```

Configuration package:

```
package alsu_config_pkg;
import uvm_pkg::*;
`include "uvm_macros.svh"

class alsu_config extends uvm_object;
    `uvm_object_utils(alsu_config)

    virtual alsu_if alsu_vif;

    function new(string name = "alsu_config");
        super.new(name);
    endfunction
endclass: alsu_config

endpackage: alsu_config_pkg
```


Sequence item package:

```
package alsu_seq_item_pkg;
import uvm_pkg::*;
import alsu_shared_pkg::*;
`include "uvm_macros.svh"

class alsu_seq_item extends uvm_sequence_item;
    `uvm_object_utils(alsu_seq_item)

    rand bit rst;
    rand bit cin;
    rand bit red_op_A;
    rand bit red_op_B;
    rand bit bypass_A;
    rand bit bypass_B;
    rand direction_e direction;
    rand bit serial_in;
    rand opcode_e opcode;
    rand bit signed [2:0] A;
    rand bit signed [2:0] B;
    logic [15:0] leds;
    logic signed [5:0] out;

    function new(string name = "alsu_seq_item");
        super.new(name);
    endfunction

    function string convert2string();
        return $sformatf("%s rst = %0b, A = 0b%0b, B = 0b%0b, opcode = %0s,
cin = %0b, red_op_A = %0b, red_op_B = %0b, bypass_A = %0b, bypass_B = %0b,
direction = %s, serial_in = %0b, out = 0b%0b, leds = 0x%0h ",
        super.convert2string(), rst, A, B, opcode, cin, red_op_A,
red_op_B, bypass_A, bypass_B, direction, serial_in, out, leds);
    endfunction

    function string convert2string_stimulus();
        return $sformatf("rst = %0b, A = 0b%0b, B = 0b%0b, opcode = %0s, cin =
%0b, red_op_A = %0b, red_op_B = %0b, bypass_A = %0b, bypass_B = %0b, direction
= %s, serial_in = %0b",
            rst, A, B, opcode, cin, red_op_A, red_op_B, bypass_A,
bypass_B, direction, serial_in);
    endfunction

    constraint c_rst {
        rst dist {0 := 95, 1 := 5};
    }

    constraint c_ADD_MULT {
```

```

        if (opcode == ADD || opcode == MULT) {
            A dist {MAXNEG := 30, ZERO := 30, MAXPOS := 30, [-3:-1] := 5,
[1:2] := 5};
            B dist {MAXNEG := 30, ZERO := 30, MAXPOS := 30, [-3:-1] := 5,
[1:2] := 5};
        }
    }

    constraint c_OR_XOR_A {
        if ((opcode inside {OR, XOR}) && red_op_A && !red_op_B) {
            A dist {3'b001 := 30, 3'b010 := 30, 3'b100 := 30, [3'b000:3'b111]
:= 10};
            B == 3'b000;
        }
    }

    constraint c_OR_XOR_B {
        if ((opcode inside {OR, XOR}) && red_op_B && !red_op_A) {
            B dist {3'b001 := 30, 3'b010 := 30, 3'b100 := 30, [3'b000:3'b111]
:= 10};
            A == 3'b000;
        }
    }

    constraint c_opcode {
        opcode dist {[OR:ROTATE] := 80, [INVALID_6:INVALID_7] := 20};
    }

    constraint c_bypass {
        bypass_A dist {0 := 95, 1 := 5};
        bypass_B dist {0 := 95, 1 := 5};
    }

    constraint c_red_op {
        red_op_A dist {0 := 50, 1 := 50};
        red_op_B dist {0 := 50, 1 := 50};
    }
endclass

endpackage: alsu_seq_item_pkg

```

Reset sequence package:

```
package alsu_reset_seq_pkg;
import uvm_pkg::*;
import alsu_seq_item_pkg::*;
import alsu_shared_pkg::*;
`include "uvm_macros.svh"

class alsu_reset_seq extends uvm_sequence #(alsu_seq_item);
    `uvm_object_utils(alsu_reset_seq)

    alsu_seq_item seq_item;

    function new(string name = "alsu_reset_seq");
        super.new(name);
    endfunction

    task body();
        seq_item = alsu_seq_item::type_id::create("seq_item");
        start_item(seq_item);
        seq_item.rst = 1;
        seq_item.A = 0;
        seq_item.B = 0;
        seq_item.opcode = opcode_e'(0);
        seq_item.cin = 0;
        seq_item.red_op_A = 0;
        seq_item.red_op_B = 0;
        seq_item.bypass_A = 0;
        seq_item.bypass_B = 0;
        seq_item.direction = direction_e'(0);
        seq_item.serial_in = 0;
        finish_item(seq_item);
    endtask
endclass: alsu_reset_seq

endpackage: alsu_reset_seq_pkg
```

Main sequence package:

```
package alsu_main_seq_pkg;
import uvm_pkg::*;
import alsu_seq_item_pkg::*;
`include "uvm_macros.svh"

class alsu_main_seq extends uvm_sequence #(alsu_seq_item);
    `uvm_object_utils(alsu_main_seq)

    alsu_seq_item seq_item;

    function new(string name = "alsu_main_seq");
        super.new(name);
    endfunction

    task body();
        repeat (100) begin
            seq_item = alsu_seq_item::type_id::create("seq_item");
            start_item(seq_item);
            assert (seq_item.randomize());
            finish_item(seq_item);
        end
    endtask
endclass: alsu_main_seq
endpackage: alsu_main_seq_pkg
```

Assertions file:

```
import alsu_shared_pkg::*;

module alsu_sva #(
    parameter INPUT_PRIORITY = "A",
    parameter FULL_ADDER = "ON"
) (
    input logic clk,
    input logic rst,
    input logic cin,
    input logic red_op_A,
    input logic red_op_B,
    input logic bypass_A,
    input logic bypass_B,
    input logic direction,
    input logic serial_in,
    input logic [2:0] opcode,
    input logic signed [2:0] A,
    input logic signed [2:0] B,
    input logic [15:0] leds,
    input logic signed [5:0] out
);

    logic invalid_red_op, invalid_opcode, invalid;

    assign invalid_red_op = (red_op_A | red_op_B) & (opcode[1] | opcode[2]);
    assign invalid_opcode = opcode[1] & opcode[2];
    assign invalid = invalid_red_op | invalid_opcode;

    always_comb begin
        if (rst) begin
            assert_reset_leds: assert final(leds == 16'b0);
        end
    end

    property invalid_leds_p;
        @(posedge clk) disable iff (rst) (invalid) |-> ##2 (leds ==
~$past(leds));
    endproperty

    property valid_leds_p;
        @(posedge clk) disable iff (rst) (!invalid) |-> ##2 (leds == 16'b0);
    endproperty

    always_comb begin
        if (rst) begin
            assert_reset_out: assert final(out == 6'b0);
        end
    end
```

```

end
property priority_bypass_A_p;
    @(posedge clk) disable iff (rst)
        (bypass_A && bypass_B && INPUT_PRIORITY == "A") |-> ##2 (out ==
$past(A, 2));
endproperty

property priority_bypass_B_p;
    @(posedge clk) disable iff (rst)
        (bypass_A && bypass_B && INPUT_PRIORITY == "B") |-> ##2 (out ==
$past(B, 2));
endproperty

property bypass_A_p;
    @(posedge clk) disable iff (rst)
        (bypass_A && !bypass_B) |-> ##2 (out == $past(A, 2));
endproperty

property bypass_B_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && bypass_B) |-> ##2 (out == $past(B, 2));
endproperty

property invalid_out_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && invalid) |-> ##2 (out == 6'b0);
endproperty

property red_or_priority_A_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == OR && red_op_A &&
red_op_B && INPUT_PRIORITY == "A") |-> ##2
        (out == |$past(A, 2));
endproperty

property red_or_priority_B_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == OR && red_op_A &&
red_op_B && INPUT_PRIORITY == "B") |-> ##2
        (out == |$past(B, 2));
endproperty

property red_or_A_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == OR && red_op_A &&
!red_op_B) |-> ##2
        (out == |$past(A, 2));
endproperty

```

```

property red_or_B_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == OR && !red_op_A
&& red_op_B) |-> ##2
        (out == |$past(B, 2));
endproperty

property or_opcode_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == OR && !red_op_A
&& !red_op_B) |-> ##2
        (out == $past(A, 2) | $past(B, 2));
endproperty

property red_xor_priority_A_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == XOR && red_op_A
&& red_op_B && INPUT_PRIORITY == "A") |-> ##2
        (out == ^$past(A, 2));
endproperty

property red_xor_priority_B_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == XOR && red_op_A
&& red_op_B && INPUT_PRIORITY == "B") |-> ##2
        (out == ^$past(B, 2));
endproperty

property red_xor_A_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == XOR && red_op_A
&& !red_op_B) |-> ##2
        (out == ^$past(A, 2));
endproperty

property red_xor_B_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == XOR && !red_op_A
&& red_op_B) |-> ##2
        (out == ^$past(B, 2));
endproperty

property xor_opcode_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == XOR && !red_op_A
&& !red_op_B) |-> ##2
        (out == $past(A, 2) ^ $past(B, 2));
endproperty

```

```

property full_add_opcode_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == ADD && FULL_ADDER
== "ON") |-> ##2
        (out == $past(A, 2) + $past(B, 2) + $past(cin, 2));
endproperty

property half_add_opcode_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == ADD && FULL_ADDER
== "OFF") |-> ##2
        (out == $past(A, 2) + $past(B, 2));
endproperty

property mult_opcode_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == MULT) |-> ##2
        (out == $past(A, 2) * $past(B, 2));
endproperty

property right_shift_opcode_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == SHIFT &&
direction == RIGHT) |-> ##2
        (out == {$past(serial_in, 2), $past(out[5:1])});
endproperty

property left_shift_opcode_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == SHIFT &&
direction == LEFT) |-> ##2
        (out == {$past(out[4:0]), $past(serial_in, 2)});
endproperty

property right_rotate_opcode_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == ROTATE &&
direction == RIGHT) |-> ##2
        (out == {$past(out[0]), $past(out[5:1])});
endproperty

property left_rotate_opcode_p;
    @(posedge clk) disable iff (rst)
        (!bypass_A && !bypass_B && !invalid && opcode == ROTATE &&
direction == LEFT) |-> ##2
        (out == {$past(out[4:0]), $past(out[5])});
endproperty

```



```

assert_invalid_leds_p: assert property(invalid_leds_p);
assert_valid_leds_p: assert property(valid_leds_p);
assert_priority_bypass_A_p: assert property(priority_bypass_A_p);
assert_priority_bypass_B_p: assert property(priority_bypass_B_p);
assert_invalid_out_p: assert property(invalid_out_p);
assert_red_or_priority_A_p: assert property(red_or_priority_A_p);
assert_red_or_priority_B_p: assert property(red_or_priority_B_p);
assert_red_or_A_p: assert property(red_or_A_p);
assert_red_or_B_p: assert property(red_or_B_p);
assert_or_opcode_p: assert property(or_opcode_p);
assert_red_xor_priority_A_p: assert property(red_xor_priority_A_p);
assert_red_xor_priority_B_p: assert property(red_xor_priority_B_p);
assert_red_xor_A_p: assert property(red_xor_A_p);
assert_red_xor_B_p: assert property(red_xor_B_p);
assert_xor_opcode_p: assert property(xor_opcode_p);
assert_full_add_opcode_p: assert property(full_add_opcode_p);
assert_half_add_opcode_p: assert property(half_add_opcode_p);
assert_mult_opcode_p: assert property(mult_opcode_p);
assert_right_shift_opcode_p: assert property(right_shift_opcode_p);
assert_left_shift_opcode_p: assert property(left_shift_opcode_p);
assert_right_rotate_opcode_p: assert property(right_rotate_opcode_p);
assert_left_rotate_opcode_p: assert property(left_rotate_opcode_p);

```

```

cover_invalid_leds_p: cover property(invalid_leds_p);
cover_valid_leds_p: cover property(valid_leds_p);
cover_priority_bypass_A_p: cover property(priority_bypass_A_p);
cover_priority_bypass_B_p: cover property(priority_bypass_B_p);
cover_invalid_out_p: cover property(invalid_out_p);
cover_red_or_priority_A_p: cover property(red_or_priority_A_p);
cover_red_or_priority_B_p: cover property(red_or_priority_B_p);
cover_red_or_A_p: cover property(red_or_A_p);
cover_red_or_B_p: cover property(red_or_B_p);
cover_or_opcode_p: cover property(or_opcode_p);
cover_red_xor_priority_A_p: cover property(red_xor_priority_A_p);
cover_red_xor_priority_B_p: cover property(red_xor_priority_B_p);
cover_red_xor_A_p: cover property(red_xor_A_p);
cover_red_xor_B_p: cover property(red_xor_B_p);
cover_xor_opcode_p: cover property(xor_opcode_p);
cover_full_add_opcode_p: cover property(full_add_opcode_p);
cover_half_add_opcode_p: cover property(half_add_opcode_p);
cover_mult_opcode_p: cover property(mult_opcode_p);
cover_right_shift_opcode_p: cover property(right_shift_opcode_p);
cover_left_shift_opcode_p: cover property(left_shift_opcode_p);
cover_right_rotate_opcode_p: cover property(right_rotate_opcode_p);
cover_left_rotate_opcode_p: cover property(left_rotate_opcode_p);

```

```

endmodule

```

Do file:

```
vlib work
```

```
vlog -f src_files.list +cover -covercells
```

```
vsim -voptargs=+acc work.alsu_tb -cover -classdebug -uvmcontrol=all
```

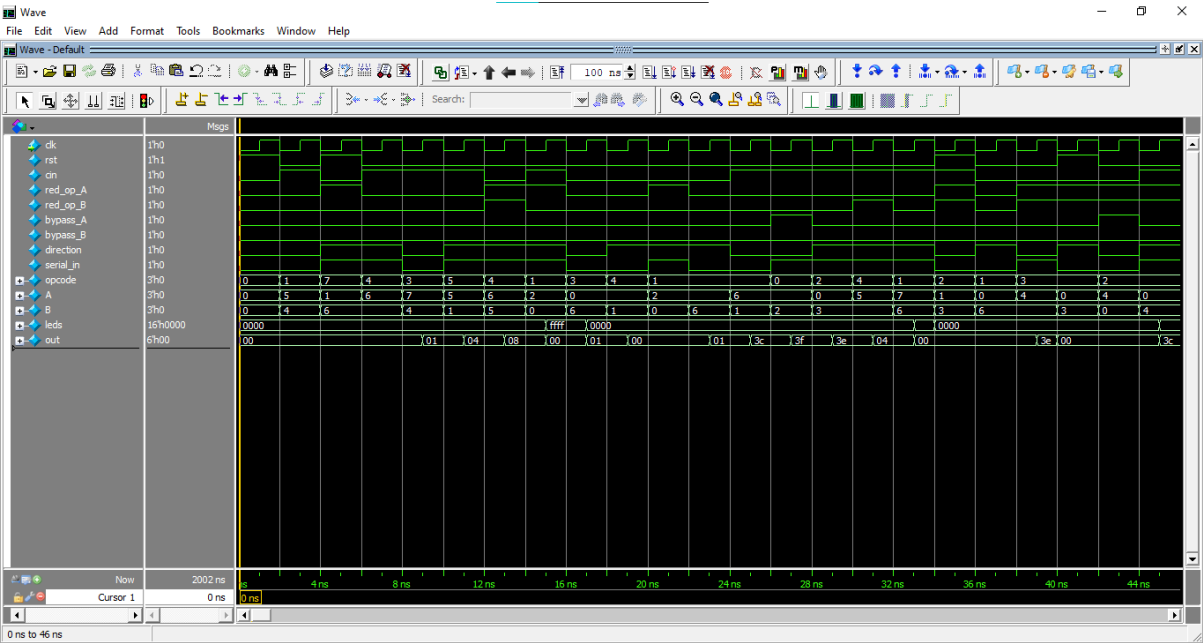
```
add wave /alsu_tb/alsuif/*
```

```
coverage save ALSU_tb.ucdb -onexit
```

```
run -all
```

```
quit -sim
```

Simulation snippet:



Transcript:

```
# UVM_INFO ALSU_test.sv(42) @ 2: uvm_test_top [RUN_PHASE] Reset Asserted
# UVM_INFO ALSU_test.sv(43) @ 2: uvm_test_top [RUN_PHASE] Reset Deasserted
# UVM_INFO ALSU_test.sv(46) @ 2: uvm_test_top [RUN_PHASE] Stimulus Generation
Started
# UVM_INFO ALSU_test.sv(48) @ 2002: uvm_test_top [RUN_PHASE] Stimulus Generation
Ended
# UVM_INFO ALSU_scoreboard.sv(173) @ 2002: uvm_test_top.env.scoreboard
[REPORT_PHASE] Total successful transactions: 1001
# UVM_INFO ALSU_scoreboard.sv(174) @ 2002: uvm_test_top.env.scoreboard
[REPORT_PHASE] Total failed transactions: 0
#
# --- UVM Report Summary ---
#
# ** Report counts by severity
# UVM_INFO :    10
# UVM_WARNING :    0
# UVM_ERROR :    0
# UVM_FATAL :    0
# ** Report counts by id
# [Questa UVM]      2
# [REPORT_PHASE]    2
# [RNTST]           1
# [RUN_PHASE]       4
# [TEST_DONE]       1
#
# ** Note: $finish      : C:/questasim64_2021.1/win64/../../verilog_src/uvm-
1.1d/src/base/uvm_root.svh(430)
#
#   Time: 2002 ns  Iteration: 61  Instance: /alsu_tb
```

Code coverage:

```
> vcover report ALSU_tb.ucdb -details -annotate -all -output coverage_rpt.txt
```

=====

Branch Coverage:

Enabled Coverage	Bins	Hits	Misses	Coverage
-----	----	----	-----	-----
Branches	32	32	0	100.00%

=====

Statement Coverage:

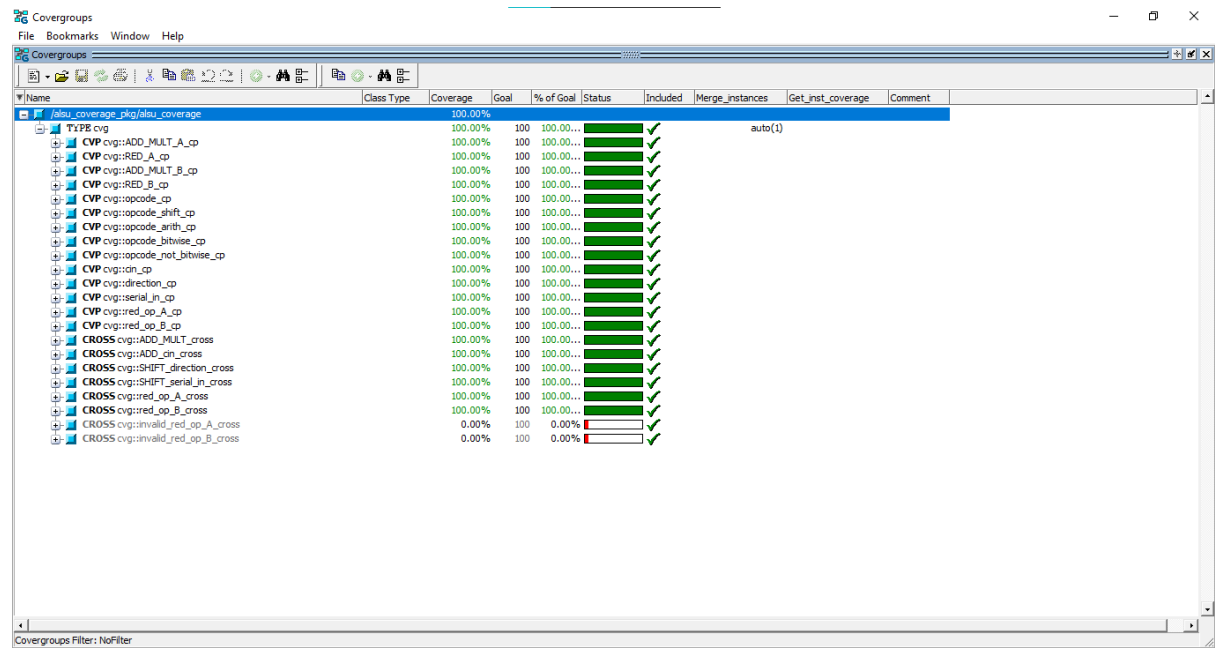
Enabled Coverage	Bins	Hits	Misses	Coverage
-----	----	----	-----	-----
Statements	48	48	0	100.00%

=====

Toggle Coverage:

Enabled Coverage	Bins	Hits	Misses	Coverage
-----	----	----	-----	-----
Toggles	118	118	0	100.00%

Functional coverage:



The screenshot shows the Covergroups tool interface. The main window displays a list of coverage groups under the path `/alsu_coverage_pkg/alsu_coverage`. The table columns are: Name, Class Type, Coverage, Goal, % of Goal, Status, Included, Merge_instances, Get_unst_coverage, and Comment. The status column uses a green bar and a checkmark to indicate 100% coverage, while a red bar and a checkmark indicate 0.00% coverage.

Name	Class Type	Coverage	Goal	% of Goal	Status	Included	Merge_instances	Get_unst_coverage	Comment
/alsu_coverage_pkg/alsu_coverage		100.00%	100	100.00...					
T1P8 cvg		100.00%	100	100.00...					auto[1]
CVP cvg::ADD_MULT_A_cp		100.00%	100	100.00...					
CVP cvg::RED_A_cp		100.00%	100	100.00...					
CVP cvg::ADD_MULT_B_cp		100.00%	100	100.00...					
CVP cvg::RED_B_cp		100.00%	100	100.00...					
CVP cvg::opcode_cp		100.00%	100	100.00...					
CVP cvg::opcode_shift_cp		100.00%	100	100.00...					
CVP cvg::opcode_arith_cp		100.00%	100	100.00...					
CVP cvg::opcode_bitwise_cp		100.00%	100	100.00...					
CVP cvg::opcode_not_bitwise_cp		100.00%	100	100.00...					
CVP cvg::cn_cp		100.00%	100	100.00...					
CVP cvg::direction_cp		100.00%	100	100.00...					
CVP cvg::serial_in_cp		100.00%	100	100.00...					
CVP cvg::red_op_A_cp		100.00%	100	100.00...					
CVP cvg::red_op_B_cp		100.00%	100	100.00...					
CROSS cvg::ADD_MULT_cross		100.00%	100	100.00...					
CROSS cvg::ADD_cn_cross		100.00%	100	100.00...					
CROSS cvg::SHIFT_direction_cross		100.00%	100	100.00...					
CROSS cvg::SHIFT_serial_in_cross		100.00%	100	100.00...					
CROSS cvg::red_op_A_cross		100.00%	100	100.00...					
CROSS cvg::red_op_B_cross		100.00%	100	100.00...					
CROSS cvg::invalid_red_op_A_cross		0.00%	100	0.00%					
CROSS cvg::invalid_red_op_B_cross		0.00%	100	0.00%					

Covergroups Filter: NoFilter

Assertions Filter: NoFilter