1. Let V be a vector space, let $\alpha \in \mathbb{R}$ be non-zero, and let $x, y \in V$ be such that $\alpha x = \alpha y$. Prove that x = y.

Proof. As $\alpha \neq 0$, we have access to $1/\alpha = \alpha^{-1}$ and thus

$$x = 1x = (\alpha^{-1}\alpha)x = \alpha^{-1}(\alpha x) = \alpha^{-1}(\alpha y) = (\alpha^{-1}\alpha)y = 1y = y$$

Question – What if we replaced 1x = x with something else? How about $\gamma x = x$ for *some* $\gamma \in \mathbb{R}$?

Answer.

$$x = \gamma x = (\gamma.1)x = (1.\gamma)x = (1)(\gamma x) = 1.x$$

2. Let $A \in \mathbb{R}^{n \times n}$, and let $\lambda \in \mathbb{R}$. Prove that $M = \{\mathbf{x} \in \mathbb{R}^n : A\mathbf{x} = \lambda \mathbf{x}\}$ is a subspace.

Proof. First, we note that $A\mathbf{0} = \mathbf{0} = \lambda \mathbf{0}$ and so $\mathbf{0} \in M$.

Now, let $\alpha, \beta \in \mathbb{R}$ and $\mathbf{x}, \mathbf{y} \in M$. Then

$$A(\alpha \mathbf{x} + \beta \mathbf{y}) = \alpha A \mathbf{x} + \beta A \mathbf{y} = \alpha \lambda \mathbf{x} + \beta \lambda \mathbf{y} = \lambda(\alpha \mathbf{x} + \beta \mathbf{y})$$

and therefore, $\alpha \mathbf{x} + \beta \mathbf{y} \in M$.

3. Determine if the following polynomials are linearly independent or linearly dependent:

$$2 + x - 3x^2 - 8x^3$$
, $1 + x + x^2 + 5x^3$, $3 - 4x^2 - 7x^3$

Solution. Let $\alpha, \beta, \gamma \in \mathbb{R}$ be such that

$$\alpha(2+x-3x^2-8x^3)+\beta(1+x+x^2+5x^3)+\gamma(3-4x^2-7x^3)=0$$

This yields

$$(2\alpha + \beta + 3\gamma) + (\alpha + \beta)x + (-3\alpha + \beta - 4\gamma)x^{2} + (-8\alpha + 5\beta - 7\gamma)x^{3} = 0$$

and so

$$2\alpha + \beta + 3\gamma = 0$$
$$\alpha + \beta = 0$$
$$-3\alpha + \beta - 4\gamma = 0$$
$$-8\alpha + 5\beta - 7\gamma = 0$$

This yields $\alpha = \beta = \gamma = 0$, and thus we have linear independence.

Recall $-M = \{p \in \mathbb{R}_2[x] : p(0) = 0\}$ is a subspace of $\mathbb{R}_2[x]$ with a basis of x, x^2 . What if we replace "p(0) = 0" with something else? Note that p(0) = 1 doesn't work. How about p(1) = 0? Can prove that $N = \{p \in \mathbb{R}_2[x] : p(1) = 0\}$ is a subspace and find a basis for it?

- (a) Let $N = \{p \in \mathbb{R}_2[x] : p(1) = 0\}$. Prove that N is a subspace of $\mathbb{R}_2[x]$
- (b) Find a basis for N.

Answer.

- (a) Since $x^2 1, x 1 \in N$, N is not empty.
 - Suppose $p \in N$. Then for $\alpha \in \mathbb{R}$ we have:

$$(\alpha p)(1) = \alpha p(1)$$
$$= \alpha 0$$
$$= 0$$

• Suppose $p, q \in N$. Then we have:

$$(p+q)(1) = p(1) + q(1)$$

= 0 + 0
= 0

(b) Find a basis for N. We'll show that $B = \{x - 1, x^2 - 1\}$ is a basis for N. To show such, we have to show x - 1 and $x^2 - 1$ are linearly independent. Suppose:

$$0 = \alpha_1(x - 1) + \alpha_2(x^2 - 1)$$

= $(-\alpha_1 - \alpha_2) + (\alpha_1)x + \alpha_2(x^2)$

Since 1, x, and x^2 are linearly independent, the only way for the following linear combination to be zero is

$$-\alpha_1 - \alpha_2 = 0$$
$$\alpha_1 = 0$$
$$\alpha_2 = 0$$

Which results is $\alpha_1 = 0$ and $\alpha_2 = 0$. Now we have to show $N = \text{span}(x - 1, x^2 - 1)$. We already know $x - 1, x^2 - 1 \in N$, hence $\text{span}(x - 1, x^2 - 1) \subset N$. Now, to show $N \subset \text{span}(x - 1, x^2 - 1)$, suppose $p = a + bx + cx^2 \in N$. We know:

$$p(1) = 0 \rightarrow a + b + c = 0$$

Now, in order for $p \in \text{span}(x-1, x^2-1)$, the following has to hold:

$$a + bx + cx^{2} = \alpha(x - 1) + \gamma(x^{2} - 1)$$

= $(-\alpha - \gamma) + (\alpha)x + (\gamma)x^{2}$

Which results in

$$-\alpha - \gamma = a$$
$$\alpha = b$$
$$\gamma = c$$

4. Find a basis for the row space of

$$A = \begin{bmatrix} 1 & -2 & 3 \\ 4 & -8 & 6 \\ -7 & 14 & -9 \\ -2 & 4 & 0 \end{bmatrix}$$

Solution. The RREF of A is

$$\begin{bmatrix} 1 & -2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

and so a basis for the row space is

$$\begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

NOTE – the rank of A is 2 and dim N(A) = 1

- 5. Let $A \in \mathbb{R}^{m \times n}$.
 - (a) Prove that $\dim(N(A^{\top})) = m \operatorname{rank}(A)$
 - (b) Prove that if A^{\top} is nonsingular if and only if $col(A) = \mathbb{R}^m$

Answer.

(a) Since $A \in \mathbb{R}^{m \times n}$ then $A^{\top} \in \mathbb{R}^{n \times m}$, and:

$$\dim(N(A^{\top})) = m - \operatorname{rank}(A^{\top})$$

$$= m - \dim(\operatorname{row}(A))$$

$$= m - \operatorname{rank}(A) \quad (\operatorname{since} \dim(\operatorname{row}(A)) = \operatorname{rank}(A))$$

(b) If A^{\top} is non-singular, we have $\dim(N(A^{\top})) = 0$, which means we have $\operatorname{rank}(A)^{\top} = m$.

$$m = \operatorname{rank}(A)^{\top}$$

= $\operatorname{dim}(\operatorname{row}(A))$
= $\operatorname{rank}(A)$ (since $\operatorname{dim}(\operatorname{row}(A)) = \operatorname{rank}(A)$)

which leads to $col(A) = \mathbb{R}^m$.

6. Let $T \colon \mathbb{R}^2 \to \mathbb{R}^2$ be a linear transformation such that

$$T\left(\begin{bmatrix}2\\1\end{bmatrix}\right) = \begin{bmatrix}8\\9\end{bmatrix}$$
 and $T\left(\begin{bmatrix}1\\-3\end{bmatrix}\right) = \begin{bmatrix}3\\2\end{bmatrix}$

Find the matrix A for T.

Solution. Let

$$B = \begin{bmatrix} 8 & 3 \\ 9 & 2 \end{bmatrix}, \quad P = \begin{bmatrix} 2 & 1 \\ 1 & -3 \end{bmatrix}, \quad P^{-1} = \frac{1}{-7} \begin{bmatrix} -3 & -1 \\ -1 & 2 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 3 & 1 \\ 1 & -2 \end{bmatrix}$$

Then

$$A = BP^{-1} = \frac{1}{7} \begin{bmatrix} 8 & 3 \\ 9 & 2 \end{bmatrix} \begin{bmatrix} 3 & 1 \\ 1 & -2 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 27 & 2 \\ 29 & 5 \end{bmatrix}$$

7. Let $T: \mathbb{R}^n \to \mathbb{R}$ be linear. Prove that there exists a unique $\mathbf{v} \in \mathbb{R}^n$ such that $T(\mathbf{x}) = \mathbf{v} \cdot \mathbf{x}$.

Proof. Define $\mathbf{v} \in \mathbb{R}^n$ by $\mathbf{v}_k = T(\mathbf{e}_k)$. Then

$$T(\mathbf{x}) = T(\mathbf{x}_1 \mathbf{e}_1 + \ldots + \mathbf{x}_n \mathbf{e}_n) = \mathbf{x}_1 T(\mathbf{e}_1) + \ldots + \mathbf{x}_n T(\mathbf{e}_n) = \mathbf{x}_1 \mathbf{v}_1 + \ldots + \mathbf{x}_n \mathbf{v}_n = \mathbf{x} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{x}$$

holds for all $\mathbf{x} \in \mathbb{R}^n$. Suppose that there is a $\mathbf{w} \in \mathbb{R}^n$ with $T(\mathbf{x}) = \mathbf{w} \cdot \mathbf{x}$ for each $\mathbf{x} \in \mathbb{R}^n$. Then

$$\mathbf{v}_k = T(\mathbf{e}_k) = \mathbf{w} \cdot \mathbf{e}_k = \mathbf{w}_1 \cdot 0 + \ldots + \mathbf{w}_k \cdot 1 + \ldots + \mathbf{w}_n \cdot 0 = \mathbf{w}_k$$

holds for all $1 \le k \le n$ and so $\mathbf{v} = \mathbf{w}$.

Note – This is a special case of the *Riesz Representation Theorem*.

MOREOVER – Possible that $T(v_1), \ldots, T(v_n)$ are linearly dependent for a linear $T: V \to W$ even if v_1, \ldots, v_n are linearly independent. What if we knew $T(v_1), \ldots, T(v_n)$ are linearly independent? What can we say about the linear independence/dependence of v_1, \ldots, v_n ? **Answer**. We will show if $T(v_1), \ldots, T(v_n)$ are linearly independent then v_1, \ldots, v_n have to be also linearly independent.

Prove by contradiction. Assume v_1, \ldots, v_n are linearly dependent. Then $\exists \alpha_1, \alpha_2, \cdots \alpha_n$ such that

$$\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = 0_V$$

with at least one of the α_i s being non-zero. Now:

$$0_W = T(0_V)$$
= $T(\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n)$
= $T(\alpha_1 v_1) + T(\alpha_2 v_2) + \dots + T(\alpha_n v_n)$
= $\alpha_1 T(v_1) + \alpha_2 T(v_2) + \dots + \alpha_n T(v_n)$

Which contradicts the assumption of $T(v_1), \ldots, T(v_n)$ being linearly independent. Hence v_1, \ldots, v_n are linearly independent.

8. Verify that

$$W = \left\{ \begin{bmatrix} 5r - s + 2t \\ 16t - 3r + 7s \\ t \end{bmatrix} \in \mathbb{R}^3 \colon r, s, t \in \mathbb{R}, \right\}$$

is a subspace of \mathbb{R}^3 .

Answer. Consider the following matrix A:

$$\mathbf{A} = \begin{bmatrix} 5 & -1 & 2 \\ -3 & 7 & 16 \\ 0 & 0 & 1 \end{bmatrix}$$

Now note that:

$$\begin{bmatrix} 5 & -1 & 2 \\ -3 & 7 & 16 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} r \\ s \\ t \end{bmatrix} = \begin{bmatrix} 5r - s + 2t \\ 16t - 3r + 7s \\ t \end{bmatrix}$$

Hence $W = \operatorname{col}(A)$ which is a subspace of \mathbb{R}^3 .