

# 1. Mean Filter

In [20]:

```
import numpy as np
import cv2
from matplotlib import pyplot as plt
# from PIL import Image, ImageFilter

NOISE_IMG_PATH = 'img_train/noise/'
```

## 1.1 Gaussian Noise

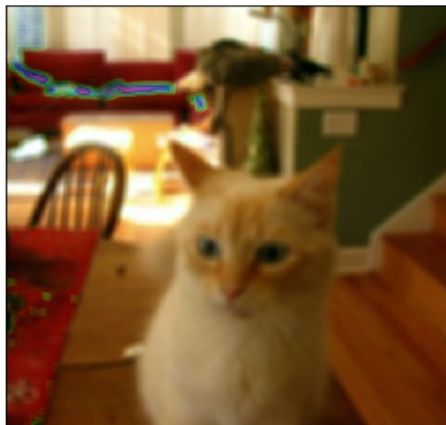
In [21]:

```
%matplotlib inline
image = cv2.imread(NOISE_IMG_PATH + 'kocenglucu/gaussian_kocenglucu.jpg') # reads the image
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV) # convert to HSV
figure_size = 9 # the dimension of the x and y axis of the kernel.
new_image = cv2.blur(image, (figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(cv2.cvtColor(image, cv2.COLOR_HSV2RGB)),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_HSV2RGB)),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



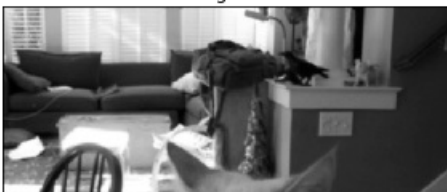
Mean filter



In [22]:

```
# The image will first be converted to grayscale
image2 = cv2.cvtColor(image, cv2.COLOR_HSV2BGR)
image2 = cv2.cvtColor(image2, cv2.COLOR_BGR2GRAY)
figure_size = 9
new_image = cv2.blur(image2, (figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(image2, cmap='gray'),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(new_image, cmap='gray'),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



Mean filter





## 1.2 Salt-Pepper Noise

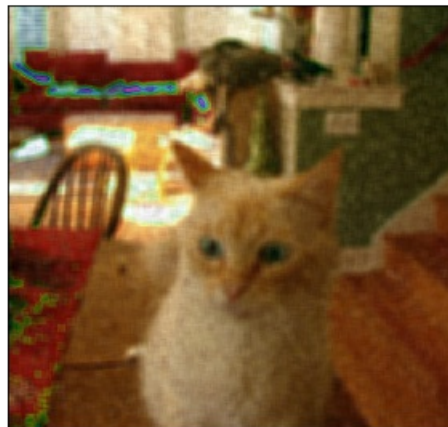
In [23]:

```
%matplotlib inline
image = cv2.imread(NOISE_IMG_PATH + 'kocenglucu/salt-pepper_kocenglucu.jpg') # reads the image
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV) # convert to HSV
figure_size = 9 # the dimension of the x and y axis of the kernel.
new_image = cv2.blur(image,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(cv2.cvtColor(image, cv2.COLOR_HSV2RGB)),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_HSV2RGB)),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



Mean filter



In [24]:

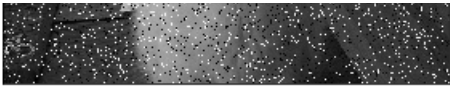
```
# The image will first be converted to grayscale
image2 = cv2.cvtColor(image, cv2.COLOR_HSV2BGR)
image2 = cv2.cvtColor(image2, cv2.COLOR_BGR2GRAY)
figure_size = 9
new_image = cv2.blur(image2,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(image2, cmap='gray'),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(new_image, cmap='gray'),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



Mean filter





## 1.3 Salt Noise

In [25]:

```
%matplotlib inline
image = cv2.imread(Noise_IMG_PATH + 'kocenglucu/salt_kocenglucu.jpg') # reads the image
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV) # convert to HSV
figure_size = 9 # the dimension of the x and y axis of the kernel.
new_image = cv2.blur(image,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(cv2.cvtColor(image, cv2.COLOR_HSV2RGB)),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_HSV2RGB)),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



Mean filter



In [26]:

```
# The image will first be converted to grayscale
image2 = cv2.cvtColor(image, cv2.COLOR_HSV2BGR)
image2 = cv2.cvtColor(image2, cv2.COLOR_BGR2GRAY)
figure_size = 9
new_image = cv2.blur(image2,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(image2, cmap='gray'),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(new_image, cmap='gray'),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



Mean filter



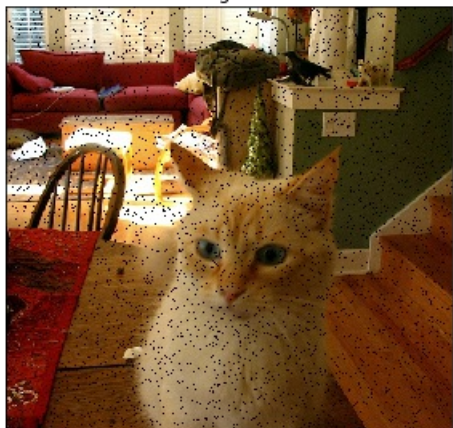


## 1.4 Pepper Noise

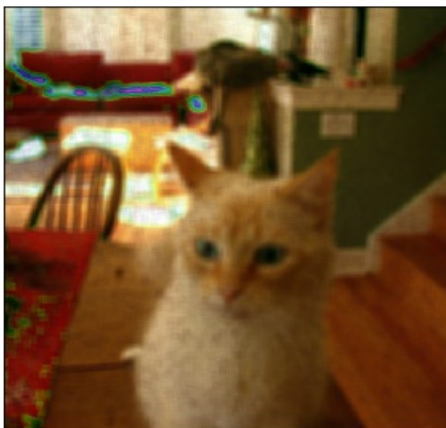
In [27]:

```
%matplotlib inline
image = cv2.imread(NOISE_IMG_PATH + 'kocenglucu/pepper_kocenglucu.jpg') # reads the image
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV) # convert to HSV
figure_size = 9 # the dimension of the x and y axis of the kernel.
new_image = cv2.blur(image,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(cv2.cvtColor(image, cv2.COLOR_HSV2RGB)),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_HSV2RGB)),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



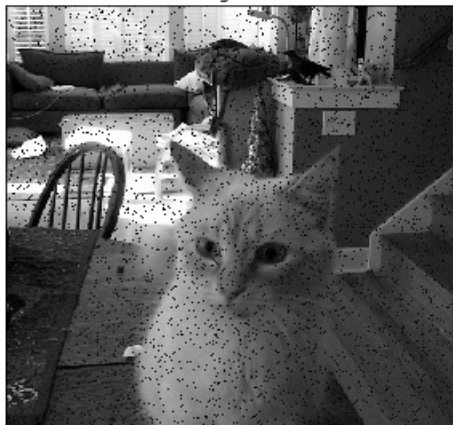
Mean filter



In [28]:

```
# The image will first be converted to grayscale
image2 = cv2.cvtColor(image, cv2.COLOR_HSV2BGR)
image2 = cv2.cvtColor(image2, cv2.COLOR_BGR2GRAY)
figure_size = 9
new_image = cv2.blur(image2,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(image2, cmap='gray'),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(new_image, cmap='gray'),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



Mean filter

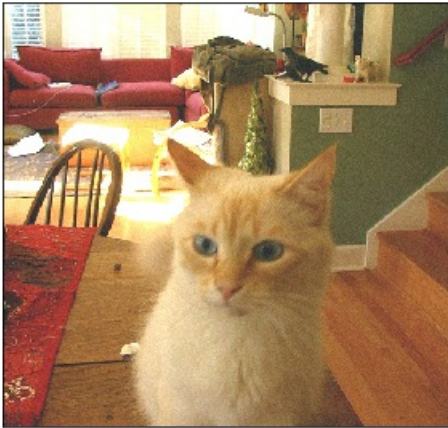


## 1.5 Poisson Noise

In [29]:

```
%matplotlib inline
image = cv2.imread(NOISE_IMG_PATH + 'kocenglucu/poisson_kocenglucu.jpg') # reads the image
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV) # convert to HSV
figure_size = 9 # the dimension of the x and y axis of the kernel.
new_image = cv2.blur(image,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(cv2.cvtColor(image, cv2.COLOR_HSV2RGB)),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_HSV2RGB)),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



Mean filter



In [30]:

```
# The image will first be converted to grayscale
image2 = cv2.cvtColor(image, cv2.COLOR_HSV2BGR)
image2 = cv2.cvtColor(image2, cv2.COLOR_BGR2GRAY)
figure_size = 9
new_image = cv2.blur(image2,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(image2, cmap='gray'),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(new_image, cmap='gray'),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



Mean filter



## 1.3 Speckle Noise

In [31]:

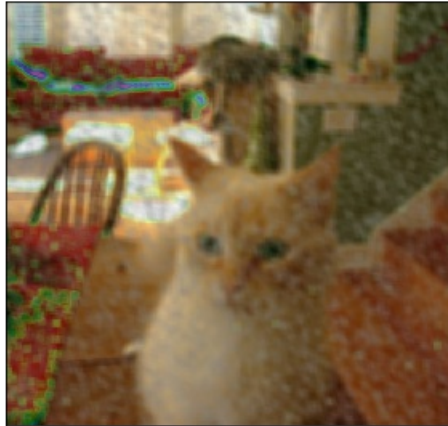
```
%matplotlib inline
image = cv2.imread(NOISE_IMG_PATH + 'kocenglucu/speckle_kocenglucu.jpg') # reads the image
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV) # convert to HSV
figure_size = 9 # the dimension of the x and y axis of the kernel.
new_image = cv2.blur(image,(figure_size, figure_size))
plt.figure(figsize=(11,6))
```

```
plt.subplot(121), plt.imshow(cv2.cvtColor(image, cv2.COLOR_HSV2RGB)),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_HSV2RGB)),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



Mean filter



In [32]:

```
# The image will first be converted to grayscale
image2 = cv2.cvtColor(image, cv2.COLOR_HSV2BGR)
image2 = cv2.cvtColor(image2, cv2.COLOR_BGR2GRAY)
figure_size = 9
new_image = cv2.blur(image2,(figure_size, figure_size))
plt.figure(figsize=(11,6))
plt.subplot(121), plt.imshow(image2, cmap='gray'),plt.title('Original')
plt.xticks([], plt.yticks([]))
plt.subplot(122), plt.imshow(new_image, cmap='gray'),plt.title('Mean filter')
plt.xticks([], plt.yticks([]))
plt.show()
```

Original



Mean filter

