Garbage Collection Routing Based on Traveling Salesman Problem

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Outline

Introduction

Garbage Collection Routing Traveling Salesman Problem Problem Formulation

Motivation

Related Work

Our Approach

Dynamic Programming Christofide's Heuristic

Comparison

Proposal

Future Work

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Garbage Collection Routing

- Route garbage trucks to optimal tour
- Similar to Traveling Salesman Problem (TSP)

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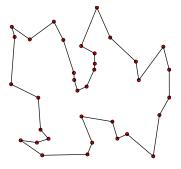


Figure: An example tour

► A salesman needs to visit some number of cities to sell his goods

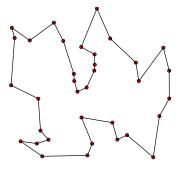


Figure: An example tour

- ▶ A salesman needs to visit some number of cities to sell his goods
- ▶ He wants to visit each city exactly once

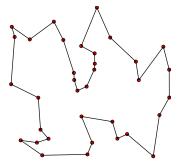


Figure: An example tour

- ▶ A salesman needs to visit some number of cities to sell his goods
- ▶ He wants to visit each city exactly once
- ▶ And come back to starting city



- ► Finding shortest route for the salesman is *NP-hard*
- ▶ No polynomial-time solution
- Approximation or heuristic based solutions

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Problem Formulation

- Garbage bins are cities
- Edges are the path between any two bins
- ► Each edge has some cost
- ► We want optimal tour for each truck

Motivation

▶ 7 billion people producing wastes, every single day

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- ▶ 1.65 million metric ton of strong waste in Dhaka per year

Motivation

- ▶ 7 billion people producing wastes, every single day
- ▶ 1.65 million metric ton of strong waste in Dhaka per year
- ► Small improvement in collection implies large contribution to the whole system

► Approach with objective function - simulation

- ► Approach with objective function simulation
- ► Minimum Spanning Tree

- Approach with objective function simulation
- Minimum Spanning Tree
- ► Chinese Postman Problem

- Approach with objective function simulation
- Minimum Spanning Tree
- Chinese Postman Problem
- Genetic Algorithms

Our Approach

Dynamic Programming (DP)

Our Approach

- Dynamic Programming (DP)
- Christofide's Heuristic

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Dynamic Programming

► A well known DP technique - DP with bitmasks

Dynamic Programming

- ► A well known DP technique DP with bitmasks
- ▶ Optimal for small cases roughly for 20-22 nodes

Dynamic Programming

- ▶ A well known DP technique DP with bitmasks
- ▶ Optimal for small cases roughly for 20-22 nodes
- ▶ Still exponential $\mathcal{O}(2^n n^2)$

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► Prerequisite - triangle inequality

- ► Prerequisite triangle inequality
- Reconstruct input graph

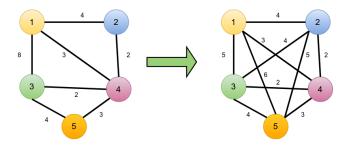


Figure: Reconstruction of input graph based on APSP algorithm.

- Prerequisite triangle inequality
- Reconstruct input graph
- ▶ Build *Minimum Spanning Tree*

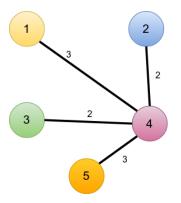


Figure: MST of the reconstructed graph.

- Prerequisite triangle inequality
- Reconstruct input graph
- ▶ Build *Minimum Spanning Tree*
- Minimum Weight Matching using odd degree nodes and combine with MST

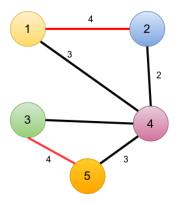


Figure: Combined graph

- ▶ 1.5*OPT heuristic
- ▶ Complexity $\mathcal{O}(n^3)$

Comparison of Output

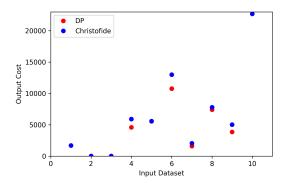


Figure: Comparison based on the output cost.

Comparison of Execution Time

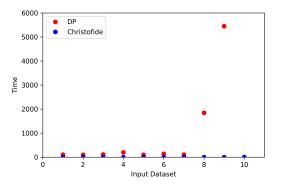


Figure: Comparison based on the execution time in miliseconds.

Proposal

► Small cases (20-22 nodes roughly) - DP with bitmasks

Proposal

- ► Small cases (20-22 nodes roughly) DP with bitmasks
- Christofide's heuristic for larger cases

Future Work

► Field work like developing maps of garbage bins

Future Work

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- ▶ More complex cost function

Future Work

- ► Field work like developing maps of garbage bins
- More complex cost function
- Genetic Algorithm to improve tour

Thank you.