Cabin - Ping both ways()

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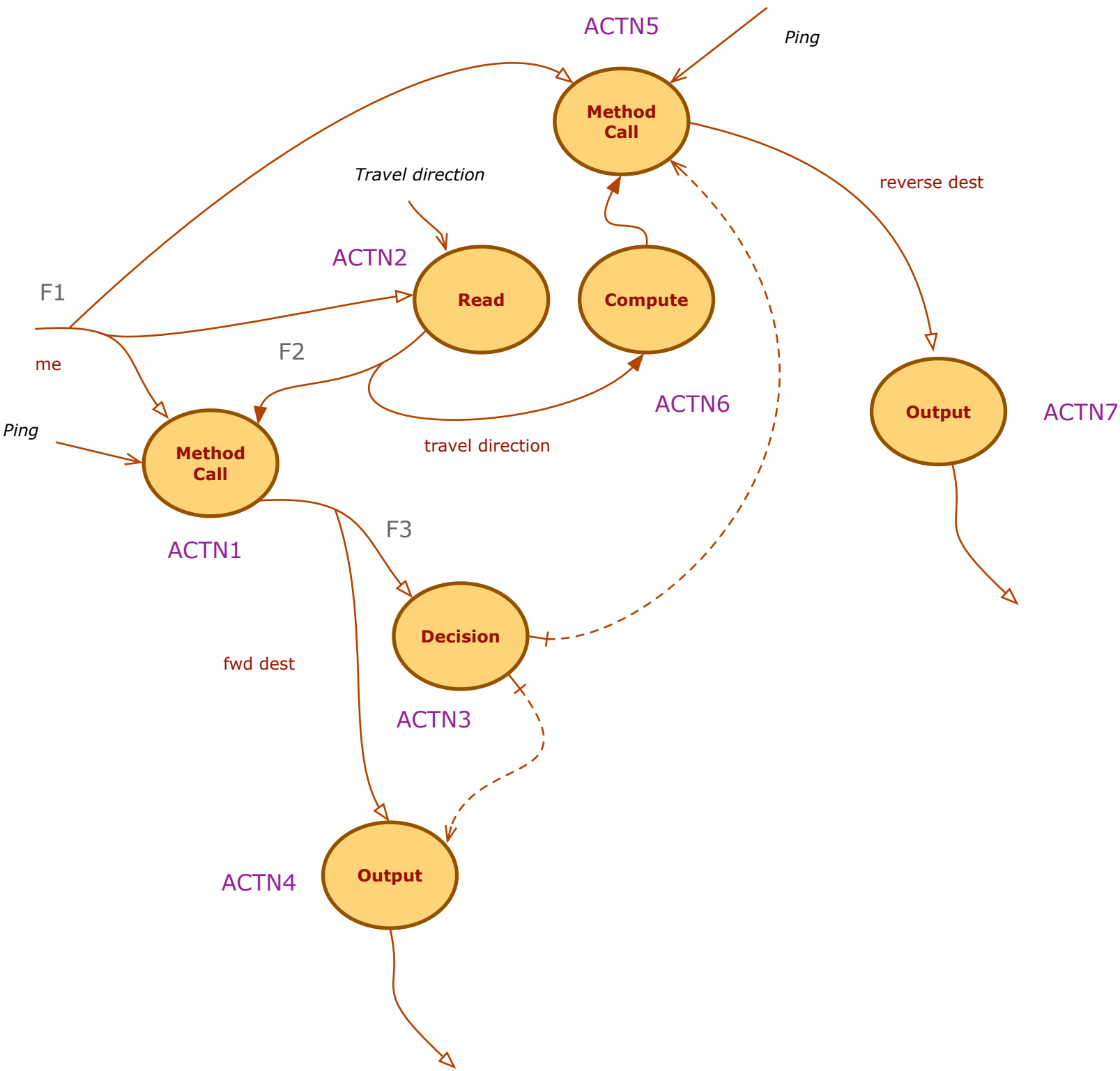
A6

ACTN5

Ping

Travel direction

ACTN2

Read

Compute

Method Call

F1

me

Ping

F2

ACTN6

travel direction

reverse dest

Output

ACTN7

Method Call

ACTN1

F3

Decision

ACTN3

fwd dest

Output

ACTN4

```
Cabin.Ping both ways() : Acessible Shaft Level

// Search in the Cabin's current travel direction
fwd dest .= .Ping( dir: Travel direction )
fwd dest? =>> fwd dest : {
    rev dest .= .Ping( dir: Travel direction.opposite )
    !rev dest? Travel direction.toggle
    =>> rev dest
// Empty if there is no destination in either direction
}
```