

Fig. 1. Sensor Model

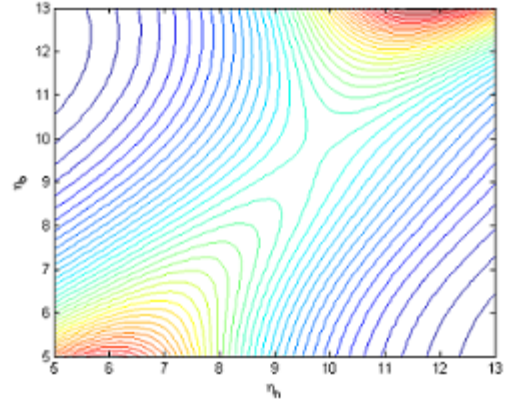


Fig. 4. Plot of contour of the surface of $\text{tr}(\text{PCRLB})$ shown in Fig. 2.

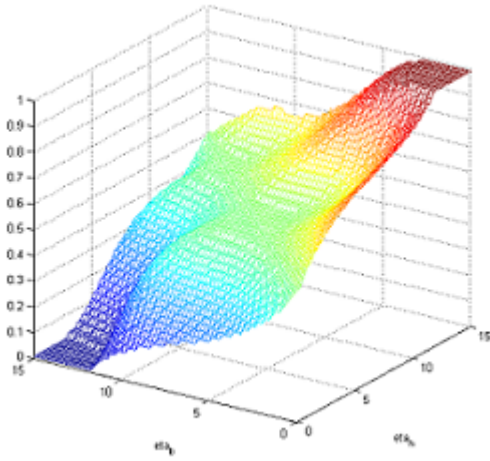


Fig. 2. Plot of α_{blind} versus honest and Byzantine sensor's threshold η_h and η_b

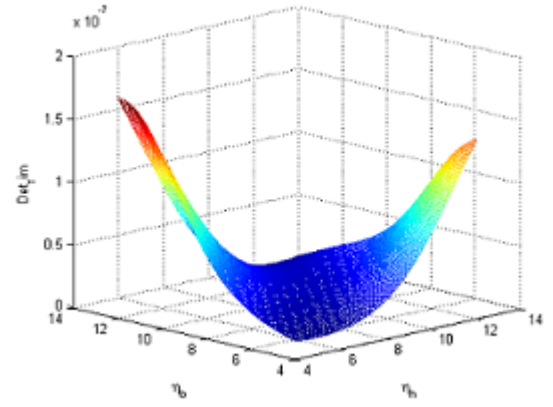


Fig. 5. Plot of $|FIM|$ versus honest and Byzantine sensor's threshold, η_h and η_b , we can see that saddle point exist

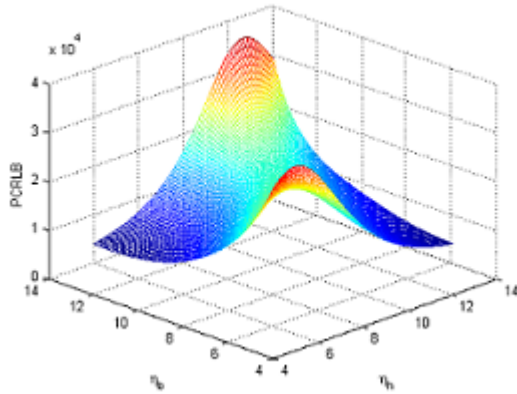


Fig. 3. Plot of $\text{tr}(\text{PCRLB})$ versus honest and Byzantine sensor's threshold, η_h and η_b , we can see that saddle point exist

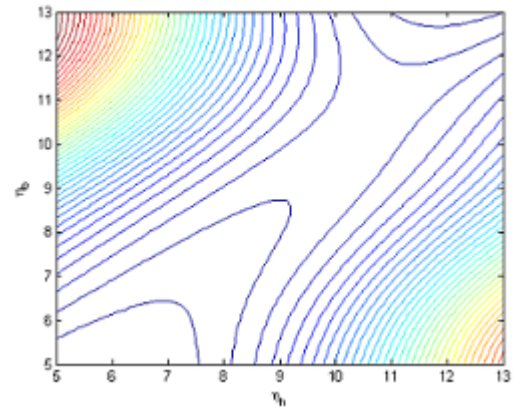


Fig. 6. Plot of contour of the surface of $|FIM|$ shown in Fig. 4.