

# Linearly Constrained Separable Optimization using PiecewiseQuadratics.jl and LCSO.jl

Nicholas Moehle   **Ellis Brown**   Mykel Kochenderfer

BlackRock AI Labs

JuliaCon JuMP-dev Workshop

July 2021

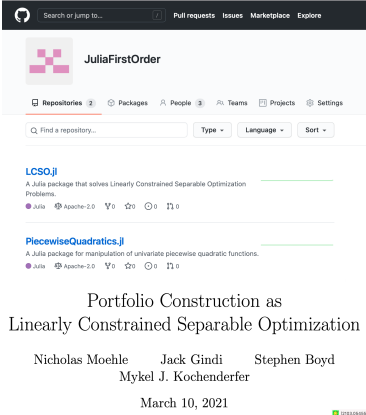
# Outline

PiecewiseQuadratics.jl

LCISO.jl

JuliaFirstOrder

Portfolio Optimization



The screenshot shows the GitHub repository page for JuliaFirstOrder. The repository is owned by JuliaFirstOrder and is categorized as a Package. It has 2 repositories, 0 packages, 0 people, 0 teams, 0 projects, and 0 settings. The repository is written in Julia and is licensed under the Apache-2.0 license. It has 0 stars, 0 forks, and 0 issues. The repository is described as a Julia package that solves Linearly Constrained Separable Optimization Problems. The repository is also linked to PiecewiseQuadratics.jl, which is described as a Julia package for manipulation of univariate piecewise quadratic functions. The repository is also linked to Portfolio Construction as Linearly Constrained Separable Optimization, which is a paper by Nicholas Moehle, Jack Gindi, Stephen Boyd, and Mykel J. Kochenderfer, published on March 10, 2021.

JuliaFirstOrder

Repositories 2 Packages People 0 Teams Projects Settings

Find a repository... Type Language Sort

[LCISO.jl](#)  
A Julia package that solves Linearly Constrained Separable Optimization Problems.  
Julia Apache-2.0 0 0 0 0 0

[PiecewiseQuadratics.jl](#)  
A Julia package for manipulation of univariate piecewise quadratic functions.  
Julia Apache-2.0 0 0 0 0 0

Portfolio Construction as  
Linearly Constrained Separable Optimization

Nicholas Moehle Jack Gindi Stephen Boyd  
Mykel J. Kochenderfer

March 10, 2021

# Outline

PiecewiseQuadratics.jl

LCSO.jl

JuliaFirstOrder

Portfolio Optimization

# PiecewiseQuadratics.jl

- Represent and manipulate univariate quadratic functions of the form  $f(x) = px^2 + qx + r, \forall x \in [l, u]$

# PiecewiseQuadratics.jl

- Represent and manipulate univariate quadratic functions of the form  $f(x) = px^2 + qx + r, \forall x \in [l, u]$
- Implements several methods useful for optimization
  - sum
  - derivative
  - convex envelope
  - proximal operator
  - ...

# PiecewiseQuadratics.jl

- Represent and manipulate univariate quadratic functions of the form  $f(x) = px^2 + qx + r, \forall x \in [l, u]$
- Implements several methods useful for optimization
  - sum
  - derivative
  - convex envelope
  - proximal operator
  - ...
- Applications to cost functions
  - Higher fidelity XXX(What does this mean? -Nick)
  - Computationally tractable

## Example

$$f(x) = \begin{cases} x^2 - 3x - 3 & \text{if } x \in [-\infty, 3] \\ -x + 3 & \text{if } x \in [3, 4] \\ 2x^2 - 20x + 47 & \text{if } x \in [4, 6] \\ x - 7 & \text{if } x \in [6, 7.5] \\ 4x - 29 & \text{if } x \in [7.5, \infty] \end{cases}$$

XXX As a formatting issue, can terms of the same order be aligned?

-Nick

## Example

$$f(x) = \begin{cases} x^2 - 3x - 3 & \text{if } x \in [-\infty, 3] \\ -x + 3 & \text{if } x \in [3, 4] \\ 2x^2 - 20x + 47 & \text{if } x \in [4, 6] \\ x - 7 & \text{if } x \in [6, 7.5] \\ 4x - 29 & \text{if } x \in [7.5, \infty] \end{cases}$$

XXX As a formatting issue, can terms of the same order be aligned?

-Nick

---

```
using PiecewiseQuadratics
f = PiecewiseQuadratic([
    # BoundedQuadratic( l,    u,    p,    q,    r),
    BoundedQuadratic(-Inf, 3.0, 1.0, -3.0, 3.0),
    BoundedQuadratic( 3.0, 4.0, 0.0, -1.0, 3.0),
    BoundedQuadratic( 4.0, 6.0, 2.0, -20.0, 47.0),
    BoundedQuadratic( 6.0, 7.5, 0.0, 1.0, -7.0),
    BoundedQuadratic( 7.5, Inf, 0.0, 4.0, -29.0)
]);
```

PiecewiseQuadratics.jl



# Plot

---

```
using Plots
plot(get_plot(f); ...)
plot!(get_plot(simplify(envelope(f)))); ...
```

---

# Plot

---

```
using Plots
plot(get_plot(f); ...)
plot!(get_plot(simplify(envelope(f)))); ...)
```

---

XXX We would make the font size larger to match the font size of the rest of the slide. (Basically, print out a smaller image.) -Nick XXX  
Change 'piece-wise' to 'piecewise'

# Outline

PiecewiseQuadratics.jl

LCSO.jl

JuliaFirstOrder

Portfolio Optimization

# Linearly Constrained Separable Optimization

A *linearly constrained separable optimization* (LCSO) problem:

$$\begin{aligned} \text{minimize} \quad & f(x) = \sum_{i=1}^n f_i(x_i) \\ \text{subject to} \quad & Ax = b, \end{aligned} \tag{1}$$

where

- the decision variable is  $x \in \mathbf{R}^n$
- the parameters are  $A \in \mathbf{R}^{m \times n}$ ,  $b \in \mathbf{R}^m$ , and the functions  $f_i$ .

---

<sup>1</sup>See: arXiv:2103.05455

# Linearly Constrained Separable Optimization

A *linearly constrained separable optimization* (LCSO) problem:

$$\begin{aligned} \text{minimize} \quad & f(x) = \sum_{i=1}^n f_i(x_i) \\ \text{subject to} \quad & Ax = b, \end{aligned} \tag{1}$$

where

- the decision variable is  $x \in \mathbf{R}^n$
- the parameters are  $A \in \mathbf{R}^{m \times n}$ ,  $b \in \mathbf{R}^m$ , and the functions  $f_i$ .

*LCSO problems can be solved using ADMM.*<sup>1</sup>

- Exactly, if the  $f_i$  are convex
- Approximately, if they aren't

---

<sup>1</sup>See: arXiv:2103.05455

## Extended-Form LCSO Problems

An extended-form LCSO problem:

$$\begin{aligned} & \text{minimize} && \frac{1}{2}x^T Px + q^T x + \sum_{i=1}^n f_i(x_i) \\ & \text{subject to} && Ax = b, \end{aligned} \tag{2}$$

where

- $q \in \mathbf{R}^n$ ,  $P \in \mathbf{S}_+^n$  is a symmetric positive semidefinite matrix

---

<sup>2</sup>See: arXiv:2103.05455

## Extended-Form LCSO Problems

An extended-form LCSO problem:

$$\begin{aligned} & \text{minimize} && \frac{1}{2}x^T Px + q^T x + \sum_{i=1}^n f_i(x_i) \\ & \text{subject to} && Ax = b, \end{aligned} \tag{2}$$

where

- $q \in \mathbf{R}^n$ ,  $P \in \mathbf{S}_+^n$  is a symmetric positive semidefinite matrix
- Extended-form LCSO problems can be reduced to standard LCSO problem (using an eigendecomposition)<sup>2</sup>

---

<sup>2</sup>See: arXiv:2103.05455

# LCSO.jl

- Solves LCSO problems using ADMM (more later...)



# LCSO.jl

- Solves LCSO problems using ADMM (more later...)
- Works with either standard- or extended-form problems

# LCSO.jl

- Solves LCSO problems using ADMM (more later...)
- Works with either standard- or extended-form problems
- Can be used to solve convex and non-convex problems (convergence is only guaranteed for convex problems)

# LCSO.jl

- Solves LCSO problems using ADMM (more later...)
- Works with either standard- or extended-form problems
- Can be used to solve convex and non-convex problems (convergence is only guaranteed for convex problems)
- In practice, converges to a moderately accurate solution quickly (even if the  $f_i$  are very complicated)

# LCSO.jl

- Solves LCSO problems using ADMM (more later...)
- Works with either standard- or extended-form problems
- Can be used to solve convex and non-convex problems (convergence is only guaranteed for convex problems)
- In practice, converges to a moderately accurate solution quickly (even if the  $f_i$  are very complicated)
- The separable functions  $f_i$  must be piecewise quadratic (see `PiecewiseQuadratics.jl`)

# LCSO.jl

- Solves LCSO problems using ADMM (more later...)
- Works with either standard- or extended-form problems
- Can be used to solve convex and non-convex problems (convergence is only guaranteed for convex problems)
- In practice, converges to a moderately accurate solution quickly (even if the  $f_i$  are very complicated)
- The separable functions  $f_i$  must be piecewise quadratic (see `PiecewiseQuadratics.jl`)
- (In theory, could be extended to any  $f_i$  that support a prox method)

## Example

```
using LCSO
using PiecewiseQuadratics

n = 4 # num features
m = 2 # num constraints

# construct problem data
x0 = rand(n)
X = rand(n, n)

# ensure P is PSD
P = X'X
q = rand(n)
A = rand(m, n)
b = A * x0
```

```
# x1 has to be  $\in [-1, 2] \cup [2.5, 3.5]$ 
#   with quadratic penalty  $\in [-1, 2]$ 
#   and linear penalty  $\in [2.5, 3.5]$ 
g1 = PiecewiseQuadratic([
    BoundedQuadratic(-1, 2, 1, 0, 0),
    BoundedQuadratic(2.5, 3.5, 0, 1, 0)
])

# x2 has to be  $\in [-20, 10]$ 
g2 = indicator(-20, 10)

# x3 has to be  $\in [-5, 10]$ 
g3 = indicator(-5, 10)

# x4 has to be exactly 1.2318
g4 = indicator(1.2318, 1.2318)
```

## Example

```
g = [g1, g2, g3, g4]

# solve
params = AdmmParams(P, q, A, b, g)
vars, stats = optimize(params)

print(vars.x) # optimal x
# [-0.04933, 1.2180, -1.9325, 1.2318]
```

---

# Applications

- Portfolio optimization
- Radiation treatment planning
- Dynamic energy management
- ...



# Outline

PiecewiseQuadratics.jl

LCSO.jl

**JuliaFirstOrder**

Portfolio Optimization

# JuliaFirstOrder

- GitHub organization for first-order methods in Julia
  - <https://github.com/JuliaFirstOrder>
- Plan to migrate several related packages
  - ProximalOperators.jl
  - ProximalAlgorithms.jl
  - StructuredOptimization.jl
  - ...
- Thank you to Miles Lubin for the introductions!

# Outline

PiecewiseQuadratics.jl

LCSO.jl

JuliaFirstOrder

Portfolio Optimization

# Portfolio Optimization

- The original mean–variance portfolio optimization problem of Markowitz, *i.e.*, "Risk Minimization"

$$\begin{array}{ll} \text{minimize} & \gamma x^T \Sigma x - \mu^T x \\ \text{subject to} & \mathbf{1}^T x = 1. \end{array} \quad (3)$$

- The decision variable  $x \in \mathbf{R}^n$  is the fraction of the portfolio value in each of  $n$  assets.
- The vector  $\mu \in \mathbf{R}^n$  is the expected return forecast for the  $n$  assets, meaning  $\mu^T x$  is the expected portfolio return.
- The matrix  $\Sigma \in \mathbf{S}_{++}^n$  is the asset return covariance matrix, meaning  $x^T \Sigma x$  is the variance of the portfolio return.
- $\gamma \in \mathbf{R}_{\geq 0}$  is the risk aversion parameter

## ...With Separable Costs!

- The portfolio optimization problem with separable costs:

$$\begin{array}{ll}\text{minimize} & x^T \Sigma x - \gamma_{\text{risk}} \mu^T x + \sum_{i=1}^n f_i(x_i) \\ \text{subject to} & \mathbf{1}^T x = 1\end{array}\tag{4}$$

- $f_i$  are asset-level penalties, like taxes and trading costs, and are piecewise quadratic (more later)

## Separable cost examples

- Trading costs:

$$f_i^{\text{trd}}(x_i) = s_i |x_i - x_{\text{init},i}| + \begin{cases} 0 & x_i = x_{\text{init},i} \\ c_i^{\text{trd}} & \text{otherwise} \end{cases}$$

- Holding cost:

$$f_i^{\text{hold}}(x_i) = \begin{cases} 0 & x_i = 0 \\ c_i^{\text{hold}} & \text{otherwise} \end{cases}$$

- Position limits:

$$f_i^{\text{lim}}(x_i) = \begin{cases} 0 & h_{\text{lb},i} \leq x_i \leq h_{\text{ub},i} \\ \infty & \text{otherwise} \end{cases}$$

- Combinations of these:

$$f_i(x_i) = f_i^{\text{trd}}(x_i) + f_i^{\text{hold}}(x_i) + f_i^{\text{lim}}(x_i)$$

# Relaxation

- Problems are often nonconvex
- One way to handle this: **Relax** the problem by replacing  $f_i$  with its **convex envelope**

$$f_i^{**}(x) = \sup\{g(x) \mid g \text{ is convex and } g(x) \leq f_i(x), x \in \mathbf{dom}(f_i)\},$$

then use the result to recover a solution to the original problem

- Easy to compute when  $f_i$  are piecewise quadratic

Questions?