

## Work & Energy

$$W_{\text{net}} = F_{\text{net}} \times d \quad \text{used when } (F_{\text{net}}) \text{ constant}$$

$$W_{\text{net}} = \int F_{\text{net}} \cdot dx \quad \Rightarrow \quad W_{\text{net}} = \frac{1}{2} m (\Delta V)^2 = \Delta H$$

$$W_{\text{net}} = W_g = -mg \Delta y = -\Delta U_g$$

$$F = -\frac{dU}{dx}$$

it means that objects experience a force that pushes them toward regions of lower potential energy...

$$\Delta E = \Delta H + \Delta U = 0$$

$$W_{\text{net}} = W_g = -\Delta U = \Delta H$$

$$E_{\text{total}} = H + U = \text{constant}$$

\* ((Energy conserved)) ((no change of energy))

\* Unit:  $\text{kg} \cdot \text{m}^2/\text{s}^2 = \text{Joule}$

\*  $U \leq H$

\*  $H = \text{always positive (velocity squared)}$

$$\Delta E = \Delta H + \Delta U = W_{\text{nc}}$$

$W_{\text{nc}} < 0$  ... negative, meaning that energy was released from the system in form of thermal energy (heat)...

## Hooke's Law & Spring's Potential Energy

negative sign implies that the force of spring is opposite to the direction of the displaced object...

$$F_{\text{Hooke}} = -k(x - x_0)$$

restoring force      spring constant      position of object

equilibrium length: position where the spring is not stretched nor compressed...

$$F_{\text{Hooke}} = -\frac{dU_{\text{Hooke}}}{dx}$$

Via integration  
→  
 $F_{\text{Hooke}}$  Substitution

$$U_{\text{Hooke}} = \frac{1}{2} k (x - x_0)^2 + C$$

Our universe approximately behaves like a spring when it's near the minimum potential energy which also means energy is (Conserved)

$$U(x) \approx \frac{1}{2} k (x - x_0)^2, \text{ where } k = U''(x_0) \dots$$

Combining Springs

Opposing connected spring:

$$k_{\text{eff}} = k_1 + k_2$$

where  $k_{\text{eff}} > k_1$  &  $k_2$

Directly connected spring:

$$k_{\text{eff}} = \frac{k_1 \cdot k_2}{k_1 + k_2}$$

where  $k_{\text{eff}} < k_1$  &  $k_2$

## Simple Harmonic Oscillator (SHO)

$$x(t) = A \cdot \cos(\omega t + \phi) + x_0 \quad \text{or} \quad x(t) = A \cdot \sin(\omega t + \phi) + x_0$$

$$V(t) = -W x(t)$$

\* ( $V_m = x_m = W E_m$ )  $m$ : maximized

$$a(t) = -\omega^2 x(t)$$

\* ( $a_m = x_m = W_m = F_m$ )

$$\omega = \sqrt{\frac{k}{m}}$$

$$T = \frac{2\pi}{\omega}$$

$$f = \frac{\omega}{2\pi}$$

$$f = \frac{1}{T} \quad (\text{Hz})$$

$$E_{\text{total}} = \frac{1}{2} \cdot k \cdot A^2 \Rightarrow$$

$$U + KE = \frac{1}{2} \cdot k \cdot A^2$$

$$\omega = \sqrt{\frac{g}{l}}$$

$$\theta(t) = A \cdot \cos(\omega t + \phi) + \theta_0$$

$$r(t) = A \cdot l \cdot \cos(\omega t + \phi) + r_0$$

$$V(t) = -l \cdot \omega \cdot \theta \quad \text{or} \quad -\omega \cdot r$$

$$a(t) = -l \cdot \omega^2 \cdot \theta \text{ or } -\omega^2 r$$

## Damped & Driven Harmonic Oscillator

$$\frac{d^2 x}{dt^2} + \left( \beta \frac{dx}{dt} + \omega_0^2 x = 0 \right)$$

equation for  
exponential decay

$$x(t) = A_0 e^{\frac{-\beta}{2}t} \cos(\omega t + \phi_0) + x_0$$

$$a + \beta v + \omega_0^2 x = 0$$

$$A(t) = A_0 e^{\frac{-\beta}{2}t}$$

$$\beta = \frac{\gamma}{2\omega_0}$$

$$v(t) = - \left( \frac{\beta}{2} + \omega \right) \cdot x(t)$$

$$Q = \frac{1}{2\beta} = \frac{\omega_0}{\beta}$$

$$a(t) = \left( \frac{\beta^2}{4} - \omega^2 + \beta\omega \right) \cdot x(t)$$

$$\frac{d^2 x}{dt^2} + \beta \cdot \frac{dx}{dt} + \omega_0^2 x = \sin(\omega_p t)$$

$$\omega = \sqrt{\omega_0^2 - \frac{\beta^2}{4}}$$

$$x(t) = A \sin(\omega_p t) + B \cos(\omega_p t)$$

$$\sqrt{A^2 + B^2} = \frac{1}{\sqrt{(\omega_0^2 - \omega_p^2)^2 + \beta^2 \omega_p^2}}$$

(Total Amplitude)

## Momentum & Collision

$$\vec{p} = m \cdot \vec{v}$$

$$\Delta p = \int F_{\text{net}} \cdot dt$$

$$p_{01} + p_{02} = p_{p1} + p_{p2}$$

$$F_{\text{net}} = \frac{d\vec{p}}{dt}$$

$$KE_{01} + KE_{02} = KE_{p1} + KE_{p2}$$

$$KE = \frac{p^2}{2m}$$

$$v_{p2} = \frac{m_1 (v_{01} - v_{p1})}{m_2}$$

$$(m_1 + m_2) v_{p1}^2 - 2 m_1 v_{01} v_{p1} + (m_1 - m_2) v_{01}^2 = 0$$

$$v_{p2} = \frac{2 m_1}{m_1 + m_2} \cdot v_{01}$$

$$v_{p1} = \frac{m_1 - m_2}{m_1 + m_2} \cdot v_{01}$$

Elastic  
Collisions

$v_{02} = 0 \text{ m/s}$

## Momentum in 2D & Explosions

x-component

$$p_{01,x} + p_{02,x} = p_{11,x} + p_{12,x}$$

y-component

$$p_{01,y} + p_{02,y} = p_{11,y} + p_{12,y}$$

$$p_{01} + p_{02} = p_{\text{system}}$$

$$\left[ \begin{array}{l} p_{01,x} + p_{02,x} = p_{\text{system}}(x) \\ p_{01,y} + p_{02,y} = p_{\text{system}}(y) \end{array} \right\} \text{Inelastic Collisions...}$$

$$p_{\text{system}} = p_{11} + p_{12}$$

Explosions...

## Thermal Energy, Heat, & Power

$$\Delta E_{\text{sys}} = \Delta H E + \Delta U + \Delta E_{\text{th}} \\ = Q - W$$

$$P = \frac{dE}{dt} = \frac{Q}{t}$$

unit: watt = J/s

$$Q = C \cdot \Delta T$$

$$Q = m \cdot \Delta H$$

$$P = h \cdot A \cdot \frac{T_1 - T_2}{(h)}$$

((Insulator))

↑ mole

$$C = (n) \cdot C_n \Rightarrow \text{specific heat}$$

↓ mass

$$C = (m) \cdot C_m$$

$$Q_{\text{sys}} + Q_{\text{surrounding}} = 0 \Rightarrow \text{Thermal Equilibrium...}$$