- 1. What is operating system?
 - <u>A.</u> collection of programs that manages hardware resources
 - <u>B.</u> system service provider to the application programs
 - <u>C.</u> link to interface the hardware and application programs
 - D. all of the mentioned
- 2. To access the services of operating system, the interface is provided by the:
 - A. system calls
 - **B**. API
 - C. library
 - <u>D.</u> assembly instructions
- 3. Which one of the following is not true?
 - A. kernel is the program that constitutes the central core of the operating system
 - <u>B.</u> kernel is the first part of operating system to load into memory during booting
 - <u>C.</u> kernel is made of various modules which can not be loaded in running operating system
 - D. kernel remains in the memory during the entire computer session
- 4. Which one of the following error will be handle by the operating system?
 - A. power failure
 - B. lack of paper in printer
 - C. connection failure in the network
 - D. all of the mentioned
- 5. The main function of the command interpreter is:
 - A. to get and execute the next user-specified command
 - B. to provide the interface between the API and application program
 - C. to handle the files in operating system
 - D. none of the mentioned
- 6. By operating system, the resource management can be done via:
 - A. time division multiplexing
 - <u>B.</u> space division multiplexing
 - C. both (a) and (b)
 - D. none of the mentioned
- 7. If a process fails, most operating system write the error information to a:
 - A. log file

- <u>B.</u> another running process
- C. new file
- <u>D.</u> none of the mentioned
- 8. The systems which allows only one process execution at a time, are called:
 - <u>A.</u> uniprogramming systems
 - <u>B.</u> uniprocessing systems
 - <u>C.</u> unitasking systems
 - D. none of the mentioned
- 9. In operating system, each process has its own:
 - A. address space and global variables
 - B. open files
 - <u>C.</u> pending alarms, signals and signal handlers
 - D. all of the mentioned
- 10. In Unix, Which system call creates the new process?
 - <u>A.</u> fork
 - B. create
 - <u>C.</u> new
 - <u>D.</u> none of the mentioned
- 11. A process can be terminated due to:
 - A. normal exit
 - B. fatal error
 - <u>C.</u> killed by another process
 - D. all of the mentioned
- 12. What is the ready state of a process?
 - A. when process is scheduled to run after some execution
 - <u>B.</u> when process is unable to run until some task has been completed
 - C. when process is using the CPU
 - D. none of the mentioned
- 13. What is interprocess communication?
 - <u>A.</u> communication within the process
 - B. communication between two process
 - <u>C.</u> communication between two threads of same process
 - D. none of the mentioned

 A. each process is blocked and will remain so forever B. each process is terminated C. all processes are trying to kill each other D. none of the mentioned 	
15. A process stack does not contain:	
 A. function parameters B. local variables C. return addresses D. PID of child process 	
16. Which system call returns the process identifier of a terminated child?	
 A. wait B. exit C. fork D. get 	
17. The address of the next instruction to be executed by the current process is provided by the:	
 A. CPU registers B. program counter C. process stack D. pipe 	
18. A Process Control Block(PCB) does not contain which of the following :	
 A. code B. stack C. Process State D. I/O status information E. bootstrap program 	
19. The number of processes completed per unit time is known as	
 A. output B. Throughput C. Efficiency D. Capacity 	
20. The state of a process is defined by :	
• <u>A.</u> the final activity of the process	

14. A set of processes is deadlock if:

- <u>B.</u> the activity just executed by the process
- <u>C.</u> the activity to next be executed by the process
- <u>D.</u> the current activity of the process
- 21. Which of the following is not the state of a process?
 - A. new
 - <u>B.</u> old
 - <u>C.</u> Waiting
 - D. Running
 - E. Terminated
- 22. The Process Control Block is:
 - A. Process type variable
 - B. Data Structure
 - <u>C.</u> a secondary storage section
 - <u>D.</u> a Block in memory
- 23. The entry of all the PCBs of the current processes is in:
 - A. Process Register
 - B. Program Counter
 - C. Process Table
 - D. Process Unit
- 24. The degree of multi-programming is:
 - A. the number of processes executed per unit time
 - B. the number of processes in the ready queue
 - C. the number of processes in the I/O queue
 - D. the number of processes in memory
- 25. A single thread of control allows the process to perform:
 - A. only one task at a time
 - B. multiple tasks at a time
 - C. All of these
- 26. Which of the following do not belong to queues for processes?
 - A. Job Queue
 - B. PCB queue
 - <u>C.</u> Device Queue
 - D. Ready Queue

27. When the process issues an I/O request:

- A. It is placed in an I/O queue
- <u>B.</u> It is placed in a waiting queue
- <u>C.</u> It is placed in the ready queue
- D. It is placed in the Job queue

28. Which one of the following is not shared by threads?

- A. program counter
- B. stack
- <u>C.</u> both (a) and (b)
- D. none of the mentioned

29. A process can be:

- A. single threaded
- B. multithreaded
- C. both (a) and (b)
- D. none of the mentioned

30. If one thread opens a file with read privileges then:

- A. other threads in the another process can also read from that file
- B. other threads in the same process can also read from that file
- <u>C.</u> any other thread can not read from that file
- D. all of the mentioned

31. The time required to create a new thread in an existing process is:

- A. greater than the time required to create a new process
- B. less than the time required to create a new process
- <u>C.</u> equal to the time required to create a new process
- D. none of the mentioned

32. When the event for which a thread is blocked occurs,

- A. thread moves to the ready queue
- B. thread remains blocked
- C. thread completes
- D. a new thread is provided

33. Termination of the process terminates:

- A. first thread of the process
- <u>B.</u> first two threads of the process

- <u>C.</u> all threads within the process
- <u>D.</u> no thread within the process
- 34. Which one of the following is not a valid state of a thread?
 - <u>A.</u> running
 - <u>B.</u> parsing
 - <u>C.</u> ready
 - D. blocked
- 35. The register context and stacks of a thread are deallocated when the thread:
 - A. terminated
 - B. blocks
 - C. unblocks
 - <u>D.</u> spawns
- 36. Thread synchronization is required because:
 - A. all threads of a process share the same address space
 - B. all threads of a process share the same global variables
 - C. all threads of a process can share the same files
 - D. all of the mentioned
- 37. Which module gives control of the CPU to the process selected by the short-term scheduler?
 - A. dispatcher
 - B. interrupt
 - <u>C.</u> scheduler
 - D. none of the mentioned
- 38. The processes that are residing in main memory and are ready and waiting to execute are kept on a list called:
 - A. job queue
 - <u>B.</u> ready queue
 - C. execution queue
 - <u>D.</u> process queue
- 39. The interval from the time of submission of a process to the time of completion is termed as:
 - <u>A.</u> waiting time
 - B. turnaround time
 - <u>C.</u> response time
 - D. throughput

- 40. Which scheduling algorithm allocates the CPU first to the process that requests the CPU first?
 - <u>A.</u> first-come, first-served scheduling
 - <u>B.</u> shortest job scheduling
 - <u>C.</u> priority scheduling
 - D. none of the mentioned
- 41. In priority scheduling algorithm:
 - A. CPU is allocated to the process with highest priority
 - <u>B.</u> CPU is allocated to the process with lowest priority
 - <u>C.</u> equal priority processes can not be scheduled
 - <u>D.</u> none of the mentioned
- 42. In priority scheduling algorithm, when a process arrives at the ready queue, its priority is compared with the priority of:
 - A. all process
 - B. currently running process
 - <u>C.</u> parent process
 - D. init process
- 43. Time quantum is defined in:
 - A. shortest job scheduling algorithm
 - B. round robin scheduling algorithm
 - C. priority scheduling algorithm
 - D. multilevel queue scheduling algorithm
- 44. Process are classified into different groups in:
 - A. shortest job scheduling algorithm
 - B. round robin scheduling algorithm
 - C. priority scheduling algorithm
 - D. multilevel queue scheduling algorithm
- 45. In multilevel feedback scheduling algorithm:
 - A. a process can move to a different classified ready queue
 - B. classification of ready queue is permanent
 - C. processes are not classified into groups
 - D. none of the mentioned
- 46. Which one of the following can not be scheduled by the kernel?

- A. kernel level thread
- B. user level thread
- <u>C.</u> process
- D. none of the mentioned

47. What is the reusable resource?

- A. that can be used by one process at a time and is not depleted by that use
- B. that can be used by more than one process at a time
- C. that can be shared between various threads
- <u>D.</u> none of the mentioned
- 48. Which of the following condition is required for deadlock to be possible?
 - A. mutual exclusion
 - <u>B.</u> a process may hold allocated resources while awaiting assignment of other resources
 - C. no resource can be forcibly removed from a process holding it
 - D. all of the mentioned
- 49. A system is in the safe state if:
 - A. the system can allocate resources to each process in some order and still avoid a deadlock
 - <u>B.</u> there exist a safe sequence
 - <u>C.</u> both (a) and (b)
 - D. none of the mentioned
- 50. The circular wait condition can be prevented by:
 - A. defining a linear ordering of resource types
 - B. using thread
 - <u>C.</u> using pipes
 - D. all of the mentioned
- 51. Which one of the following is the deadlock avoidance algorithm?
 - A. banker's algorithm
 - B. round-robin algorithm
 - C. elevator algorithm
 - D. karn's algorithm

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1. The main memory accommodates	:		
a) operating system	b) cpu		
c) user processes	d) all of the mentioned		
2. In contiguous memory allocation:			
a) each process is contained in a sing	e contiguous section of memory		
b) all processes are contained in a sin	gle contiguous section of memory		
c) the memory space is contiguous			
d) none of the mentioned			
3. The relocation (base) register help	s in :		
a) providing more address space to processes			
b) a different address space to proces	sses		
c) to protect the address spaces of processes			
d) none of the mentioned			
4. With relocation and limit registers, each logical address must be the limit register.			
a) <mark>less than</mark> b) eq	ual to		
c) greater than d) no	ne of the mentioned		
5. The operating system and the other processes are protected from being modified by an already running process because :			
a) they are in different memory spaces			
b) they are in different logical addresses			
c) they have a protection algorithm			
d) every address generated by the CP	U is being checked against the relocation and limit registers		
6. When memory is divided into several fixed sized partitions, each partition may contain			
a) exactly one process	b) <mark>at least one process</mark>		
c) multiple processes at once	d) none of the mentioned		
7. In fixed size partition, the degree of multiprogramming is bounded by			
a) <mark>the number of partitions</mark>	b) the CPU utilization		
c) the memory size	d) all of the mentioned		
8. The first fit, best fit and worst fit are strategies to select a			

a) process from a queue to put	a) process from a queue to put in memory			
b) processor to run the next pro	ocess			
c) free hole from a set of availal	ble holes			
d) all of the mentioned				
9. In internal fragmentation, m	emory is internal to a partition and:			
a) is being used	b) <mark>is not being used</mark>			
c) is always used	d) none of the mentioned			
10. A solution to the problem of	of external fragmentation is:			
a) <mark>compaction</mark>	b) larger memory space			
c) smaller memory space	d) none of the mentioned			
11. Another solution to the pro	oblem of external fragmentation problem is to:			
a) permit the logical address space of a process to be noncontiguous				
b) permit smaller processes to b	pe allocated memory at last			
c) permit larger processes to be	allocated memory at last			
d) all of the mentioned				
12. If relocation is static and is done at assembly or load time, compaction				
a) <mark>cannot be done</mark>	b) must be done			
c) must not be done	d) can be done			
13. The disadvantage of moving all process to one end of memory and all holes to the other direction, producing one large hole of availablaae memory is:				
a) the cost incurred	b) the memory used			
c) the CPU used	d) all of the mentioned			
14 is generally fast	er than and			
a) first fit, best fit, worst fit.	b) best fit , first fit, worst fit			
c) worst fit, best fit, first fit	d) none of the mentioned			
15. External fragmentation exists when:				
a) enough total memory exists to satisfy a request but not contiguous				
b) the total memory is insufficient to satisfy a request				
c) a request cannot be satisfied even when the total memory is free				

d) none of the mentioned			
16. External fragmentation will not o	occur when:		
a) first fit is used	b) best fit is used		
c) worst fit is used	d) no matter which algorithm used, it always occur		
17. Sometimes the overhead of keeping track of a hole might be:			
a) larger than the memory	b) <mark>larger than the hole itself</mark>		
c) very small	d) all of the mentioned		
18. When the memory allocated to a	a process is slightly larger than the process, then:		
a) internal fragmentation occurs	b) external fragmentation occurs		
c) both internal and external fragmentation occurs			
d) neither internal nor external fragmentation occurs			
19. Address Binding is:			
a) going to an address in memory			
b) locating an address with the help of	of another address		
c) binding two addresses together to	form a new address in a different memory space		
d) a mapping from one address space	e to another		
20. Binding of instructions and data	to memory addresses can be done at :		
a) Compile time b) Lo	b) Load time		
c) Execution time d) Al	I of the mentioned		
21. If the process can be moved duri binding must be :	ing its execution from one memory segment to another		
a) <mark>delayed until run time</mark>	b) preponed to compile time		
c) preponed to load time	d) none of the mentioned		
22. Dynamic loading is:			
a) loading multiple routines dynamical	ally b) loading a routine only when it is		
c) loading multiple routines randomly	y d) none of the mentioned		
cy loading matapic roddines randomi			
23. The advantage of dynamic loading	ng is that :		

24. The	swaps processes in and out of the memory.			
a) <mark>Memory manager</mark>	b) CPU			
c) CPU manager	d) User			
25. If a higher priority process arrives and wants service, the memory manager can swap out the lower priority process to execute the higher priority process. This swapping is called:				
a) priority swapping	b) pull out, push in			
c) <mark>roll out, roll in</mark>	d) none of the mentioned			
26. If binding is done at assembly or load time, then the process be moved to different locations after being swapped out and in again.				
a) can	b) must			
c) <mark>can never</mark>	d) may			
27. In a system that do	oes not support swapping,			
a) the compiler normally binds symbolic addresses to relocatable addresses				
b) the compiler normally binds symbolic addresses to physical addresses				
c) the loader binds relocatable addresses to physical addresses				
d) binding of symbolic addresses to physical addresses normally takes place during execution				
28. The address generated by the CPU is referred to as:				
a) Physical address	b) <mark>Logical address</mark>			
c) Neither physical nor	d) None of the mentioned			
29. The address loaded into the memory address register of the memory is referred to as:				
a) <mark>Physical address</mark>	b) Logical address			
c) Neither physical nor	logical d) None of the mentioned			
30. The run time mapping from virtual to physical addresses is done by a hardware device called the :				
a) Virtual to physical m	napper b) Memory management unit			
c) Memory mapping u	nit d) None of the mentioned			
31. The base register is also known as the :				
a) basic register	b) regular register			
c) relocation register	d) delocation register			
32. The size of a process is limited to the size of :				

a) physical memory	b) external storage			
c) secondary storage	d) none of the mentioned			
33. If execution time binding is being used, then a process be swapped to a different memory space.				
a) has to be	b) can never			
c) must	d) <mark>may</mark>			
34. Swapping requires a				
a) motherboard	b) keyboard			
c) monitor	d) <mark>backing store</mark>			
35. The backing store is genera	lly a :			
a) fast disk				
b) disk large enough to accomm	nodate copies of all memory images for all users			
c) disk to provide direct access	to the memory images			
d) all of the mentioned				
36. The consists of all processes whose memory images are in the backing store or in memory and are ready to run.				
	b) ready queue			
memory and are ready to run.				
memory and are ready to run. a) wait queue c) cpu	b) <mark>ready queue</mark>			
memory and are ready to run. a) wait queue c) cpu 37. The time in a sw	b) ready queue d) secondary storage			
memory and are ready to run. a) wait queue c) cpu 37. The time in a sw memory is very high.	b) ready queue d) secondary storage vap out of a running process and swap in of a new process into the			
memory and are ready to run. a) wait queue c) cpu 37. The time in a sw memory is very high. a) context – switch	b) ready queue d) secondary storage vap out of a running process and swap in of a new process into the b) waiting d) all of the mentioned			
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a) <mark>as a chunk of disk</mark>	b) separate from a file s	system		
c) into a file system				
42. CPU fetches the instruction from memory according to the value of				
a) <mark>program counter</mark>	b) status register			
c) instruction register	d) program status word			
43. A memory buffer used to accommodate a speed differential is called				
a) stack pointer	b) <mark>cache</mark>			
c) accumulator	d) disk buffer			
44. Which one of the following	is the address generated by CPI	U?		
a) physical address	b) absolute address			
c) logical address	d) none of the mentioned			
45. Run time mapping from virtual to physical address is done by				
a) Memory management unit	b) CPU			
c) PCI	d) None of the mention	ed		
46. Memory management technique in which system stores and retrieves data from secondary storage for use in main memory is called				
a) fragmentation	b) <mark>paging</mark>			
c) mapping	d) none of the mention	ed		
47. The address of a page table in memory is pointed by				
a) stack pointer	b) page table base register			
c) page register	d) program counter			
48. Program always deals with				
a) logical address	b) absolute address			
c) physical address	d) relative address			
49. The page table contains				
a) base address of each page in	physical memory	b) page offset		
c) page size		d) none of the mentioned		