
Continuous-time solution – Laplace Techniques

- The general linear Single Input Single Output (SISO) continuous-time state-space model is given by:

$$\begin{aligned}\frac{d\mathbf{x}(t)}{dt} &= \mathbf{A}\mathbf{x}(t) + \mathbf{B}u(t) \\ y(t) &= \mathbf{C}\mathbf{x}(t) + \mathbf{D}u(t)\end{aligned}$$

An alternative approach to the time-domain methods is to use of the Laplace Transform.

Remember

$$L\left[\frac{d}{dt} f(t)\right] = sF(s) - f(0), \quad L\left[\frac{d^2}{dt^2} f(t)\right] = s^2 F(s) - sf(0) - \frac{df}{dt}(0), \quad \text{etc.}$$

The solution to the state-space equation with the Laplace Transform is calculated as follows:

$$\begin{aligned}s\mathbf{I}\mathbf{X}(s) - \mathbf{x}(0) &= \mathbf{A}\mathbf{X}(s) + \mathbf{B}U(s) \\ (s\mathbf{I} - \mathbf{A})\mathbf{X}(s) &= \mathbf{x}(0) + \mathbf{B}U(s) \\ \mathbf{X}(s) &= (s\mathbf{I} - \mathbf{A})^{-1} \mathbf{x}(0) + (s\mathbf{I} - \mathbf{A})^{-1} \mathbf{B}U(s)\end{aligned}$$

So

$$Y(s) = \mathbf{C}(s\mathbf{I} - \mathbf{A})^{-1} \mathbf{x}(0) + \mathbf{C}(s\mathbf{I} - \mathbf{A})^{-1} \mathbf{B}U(s) + \mathbf{D}U(s)$$

- Example:** Determine the unit-step response for the system:

$$\begin{aligned}\frac{d\mathbf{x}(t)}{dt} &= \begin{bmatrix} 0 & 2 \\ -3 & -5 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u(t) \\ y(t) &= [1 \quad 0] \mathbf{x}(t)\end{aligned}$$

if the input $u(t)$ is a step and the initial value of the states is

$$\mathbf{x}(0) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

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Solution

The input is a unit step so

$$U(s) = \frac{1}{s}$$

The initial state is given

$$\mathbf{x}(0) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$Y(s) = \mathbf{C}(s\mathbf{I} - \mathbf{A})^{-1}\mathbf{x}(0) + \mathbf{C}(s\mathbf{I} - \mathbf{A})^{-1}\mathbf{B}U(s) + \mathbf{D}U(s)$$

$$Y(s) = [1 \quad 0] \left(\begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 2 \\ -3 & -5 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \\ + [1 \quad 0] \left(\begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 2 \\ -3 & -5 \end{bmatrix} \right)^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \frac{1}{s}$$

$$Y(s) = [1 \quad 0] \left(\begin{bmatrix} s & -2 \\ 3 & s+5 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + [1 \quad 0] \left(\begin{bmatrix} s & -2 \\ 3 & s+5 \end{bmatrix} \right)^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \frac{1}{s}$$

$$Y(s) = [1 \quad 0] \frac{1}{s^2 + 5s + 6} \begin{bmatrix} s+5 & 2 \\ -3 & s \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \\ + [1 \quad 0] \frac{1}{s^2 + 5s + 6} \begin{bmatrix} s+5 & 2 \\ -3 & s \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \frac{1}{s}$$

$$Y(s) = \frac{s+3}{s^2 + 5s + 6} + \frac{2}{s^2 + 5s + 6} \frac{1}{s} \\ = \left(\frac{s^2 + 3s}{s^2 + 5s + 6} \right) \frac{1}{s} + \left(\frac{2}{s^2 + 5s + 6} \right) \frac{1}{s} \\ = \left(\frac{s^2 + 3s + 2}{s^2 + 5s + 6} \right) \frac{1}{s} \\ = \frac{A}{s} + \frac{B}{s+2} + \frac{C}{s+3}$$

$$s^2 + 3s + 2 = A(s^2 + 5s + 6) + Bs(s + 3) + Cs(s + 2)$$

Equate coefficients of powers of s

$$1 = A + B + C$$

$$3 = 5A + 3B + 2C$$

$$2 = 6A$$

$$A = \frac{1}{3}, B = 0, C = 2/3$$

$$Y(s) = \frac{A}{s} + \frac{B}{s+2} + \frac{C}{s+3} = \frac{1}{3s} + \frac{2}{3(s+3)}$$

$$y(t) = \frac{1}{3}(1 + 2e^{-3t})u(t)$$

Note that as should be the case, this matches the result in example 5.3.

- **Example:** Determine the unit-impulse response for the system:

$$\begin{aligned}\frac{dx(t)}{dt} &= \begin{bmatrix} 0 & 2 \\ -3 & -5 \end{bmatrix} x(t) + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u(t) \\ y(t) &= [1 \quad 0] x(t)\end{aligned}$$

and the initial values of the states are zero.

$$\begin{aligned}Y(s) &= \mathbf{C}(s\mathbf{I} - \mathbf{A})^{-1}\mathbf{B} \\ &= [1 \quad 0] \frac{1}{s^2 + 5s + 6} \begin{bmatrix} s+5 & 2 \\ -3 & s \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \\ &= \frac{2}{s^2 + 5s + 6}\end{aligned}$$

Now use partial fractions

$$\begin{aligned}\frac{2}{s^2 + 5s + 6} &= \frac{A}{s+2} + \frac{B}{s+3} \\ 2 &= A(s+3) + B(s+2) \\ 2 &= 3A + 2B \\ 3A + 2B &= 0 \\ A = 2, B &= -2 \\ \frac{2}{s^2 + 5s + 6} &= \frac{2}{s+2} - \frac{2}{s+3} \\ y(t) &= (2e^{-2t} - 2e^{-3t})u(t)\end{aligned}$$

Note that as should be the case, this matches the result in example 5.2.