Final Exam Applied Computational Intelligence -7650

SA Embedded Within PSO Algorithm

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Abstract:

Sometimes Particle swarm optimization (PSO) reaches a local optimal solution prematurely, and all particles gather around it. Escaping from these local optima becomes difficult. To avoid premature convergence of PSO, some parts of simulated annealing can be used with it and a hybrid algorithm can be generated called SA embedded within PSO to escape premature local minima and obtain global optimal solution. Two standard benchmark functions (Rastrigin and Griewank) have been used here to evaluate the performance of this algorithm.

Introduction:

Particle swarm optimization (PSO) is a swarm intelligent optimization technique where all the particles in the swarm communicate with each other and tend to move towards the global optima updating their position through the velocity. The velocity helps them to update their positions in every iteration. Though PSO is an intelligent optimization technique but it sometimes get stuck into local minima and failed to reach the global optimal solution. Simulated annealing can play a very important role here to not get stuck in any local minima, as it is a probabilistic technique that employs a degree of randomness as part of its logic. So if Simulated annealing (SA) is embedded within Particle swarm optimization (PSO) then the PSO will not stuck in any local minima rather it aims to reach the global minima with better performance.

To compare and check the performance of the simulated annealing (SA) embedded within Particle Swarm optimization (PSO) algorithm, Travelling Salesman problem and two standard benchmark functions (Rastrigin and Griewank) were implemented through this algorithm.

Related Work:

There is a good number of optimization algorithms have been developed over last few decades. Among them, there are many heuristics like Simulated Annealing (SA) [1] and other optimization algorithms, which make use of social or evolutionary behaviors like Particle Swarm Optimization (PSO) [2, 3]. Particle Swarm Optimization (PSO) has been developed on the basis of social behavior of each particle living together in groups. Each particle aims to improve itself by observing other group members and imitating the better ones. This way, the particles of the group are performing an optimization procedure.

Particle Swarm Optimization (PSO) was introduced in 1995 by social psychologist James Kennedy and professor and chairman of electrical and computer engineering Russell C. Eberhart [4]. Their purpose was to simulate the natural swarming behavior of birds as they search for food. They developed a simulation of multiple particles flying around a cornfield with the goal of determining if the swarm of particles would flock towards the food.

As the PSO has a pretty good probability to get stuck in local minima, so simulated annealing (SA) is added which significantly reduces the chances of early convergence [5]using a temperature ramping schedule which prevents swarm particles from only relying on improved evaluations of the objective function [6].

Modified particle swarm optimization was previously used to find the travelling salesman problem [8]. To evaluate the performance of the algorithm (SA embedded within PSO), benchmark functions were used [7]. These functions play a very important role for testing the credibility of an optimization algorithm. Among a good number of benchmarks, the newly generated algorithm has been tested with two of them.

System description:

The PSO updates the position of each particle through updating their velocity (v_i) . If vector of the particles is $X_i = (x_{i,1}, x_{i,2}, x_{i,3}, \dots, x_{i,n})$ then their velocity vector will be $V_i = (v_{i,1}, v_{i,2}, v_{i,3}, \dots, v_{i,n})$ respectively for a N dimensional space. The personal best (p_{best}) and global best (g_{best}) are found among the particles. The value of the parameters ω , c_1 , c_2 are 0.5, c_1 and c_2 are randomly distributed in the range [0,1] and then the velocity becomes

$$v_{i,j}(m+1) = \omega_m v_{i,j}(m) + c_{1,m} r_1 \left(p_{i,j}^{best} - x_{i,j}(m) \right) + c_{2,m} r_2 \left(g_{best} - x_{i,j}(m) \right)$$

The updated position of each particle becomes

$$x_{i,i}(m+1) = x_{i,i}(m) + v_{i,i}(m)$$

Particle swarm optimization (PSO) updates the position with the above-mentioned process and reaches the global optima. But to compare the basic PSO with the SA embedded within PSO travelling salesman problem (TSP) has been developed besides benchmark functions. Here everything was same but the velocity has been calculated by swapping instead of arithmetic operations.

Suppose there are 5 cities in 2-d space (Euclidean space). The cities are numbered from 1,2,3,4,5. Now let a particle P be [2,4,5,1,3] and Q be [3,1,2,5,4]. In the velocity equation there are (-) operator and (+) operators. So the meaning of the (-) operator has been changed as follows.

To determine (P - Q), the concept of Swap Sequence has been introduced where S meaning that S=P - Q by which it mean the swapping sequence to go from the particle Q to P. S will be

- 1 3 \Rightarrow meaning to swap between the 1st and 3rd element in Q \Rightarrow [2,1,3,5,4]
- 2.5 \Rightarrow meaning to swap between the 2nd and 5th element in Q \Rightarrow [2,4,3,5,1]
- 3.4 \Rightarrow meaning to swap between the 3rd and 4th element in Q \Rightarrow [2,1,5,3,4]
- $4.5 \Rightarrow$ meaning to swap between the 4th and 5th element in Q \Rightarrow [2,1,5,4,3] = P

Thus applying the swap sequence S to Q, P from Q can be got.

Now for the (+) operator, ordered union of Swap Sequence is made. Let T be another sequence where

T is

15

2 4

Then V = S+T will be

13

25

3 4

4 5

1 5

24

Now let X = [4,2,5,1,3].

To to determine a new particle [as updating the particle position by $X \leftarrow X+V$], Applying V being the whole Swap Sequence to determine the new X. Thus applying

1 3 \Rightarrow meaning to swap between the 1st and 3rd element in X \Rightarrow [5,2,4,1,3]

 $2.5 \Rightarrow$ meaning to swap between the 2nd and 5th element in X \Rightarrow [5,3,4,1,2]

 $3.4 \Rightarrow$ meaning to swap between the 3rd and 4th element in $X \Rightarrow [5,3,1,4,2]$

 $4.5 \Rightarrow$ meaning to swap between the 4th and 5th element in $X \Rightarrow [5,3,1,2,4]$

1.5 \Rightarrow meaning to swap between the 1st and 5th element in X \Rightarrow [4,3,1,2,5]

 $2.4 \Rightarrow$ meaning to swap between the 2nd and 4th element in $X \Rightarrow [4,2,1,3,5]$

The new X is created as [4,2,1,3,5].

Thus the velocity equation works and update position of PSO in case of TSP problem.

But PSO sometimes gets stuck in a local optimal solution prematurely. To avoid it SA has been added. The cost of the vector X was sent to SA. The Boltzmann probability function has been used here

$$P = \exp\left(\frac{\Delta f}{T}\right)$$

After adding the SA with PSO the new algorithm has become able to not get stuck in a premature local minima and reach a global optimal solution.

Algorithm:

d = Dimension as the size of the set of values for the benchmark function

 $value_{min} = Minimum$ value of the range of the benchmark function

 $value_{max} = Maximum value of the range of the benchmark function$

p = Number of particles

 $M = Maximum number of iterations, M \ge 10$

 $\omega = \text{Inertial constant of the velocity}$

P_S=Probability of accepting worse solution at the start

P_F=Probability of accepting worse solution at the end

$$T_{S} = \frac{-1}{\ln P_{S}}$$

$$T_{R} = \frac{-1}{-1}$$

$$\begin{split} T_F &= \frac{\ln P_S}{\ln P_F} \\ \mu &= \left(\frac{T_F}{T_S}\right)^{\frac{1}{M-1}} \\ T_{k+1} &= \mu T_k; \ k \geq 0 \end{split}$$

$$T_{k+1} = \mu T_k; \ k \ge 0$$

```
1: procedure PSOwithSA(d, value<sub>min</sub>, value<sub>max</sub>, p, M, \omega, c<sub>1</sub>, c<sub>2</sub>, T)
 2: Initialize P<sub>S</sub>, P<sub>F</sub> with proper values
 T_S \leftarrow \frac{-1}{\ln P_S}
 4: T_F \leftarrow \frac{-1}{\ln P_F}
 5: \mu \leftarrow \left(\frac{T_F}{T_S}\right)^{\frac{1}{M-1}}
 6: Let x, pBest be p particles each having d dimension.
 7: Let sBest be the swarm's best particle having d dimension.
 8: Let v be the velocity of p particles each having d dimension.
 9:
10: for i = 1, 2, ..., p do
          for j = 1, 2, ..., d do
11:
             \mathbf{x}_{i,j} \leftarrow \text{rand}[\text{value}_{\min}, \text{value}_{\max}]
12:
13:
             pBest_{i,j} \leftarrow x_{i,j}
          end for
14:
         if i = 1 then
15:
             sBest \leftarrow pBest_i, Cost\_sBest \leftarrow Cost(pBest_i)
16:
17:
          end if
         if Cost(x_i) < Cost\_sBest then
18:
             sBest \leftarrow x_i, Cost\_sBest \leftarrow Cost(x_i)
19:
          end if
20:
21: end for
22:
23: for k = 1, 2, ..., M do
24:
          for i = 1, 2, ..., p do
             r_p \leftarrow rand[0,1], \, r_g \leftarrow rand[0,1]
25:
             \mathbf{v}_i \leftarrow \omega \mathbf{v}_i + \mathbf{c}_1 \mathbf{r}_p \left( \mathbf{pBest}_i - \mathbf{x}_i \right) + \mathbf{c}_2 \mathbf{r}_g \left( \mathbf{sBest} - \mathbf{x}_i \right)
26:
27:
             \text{newX} \leftarrow \mathbf{x}_i + \mathbf{v}_i
             x_i \leftarrow \text{newX}
28:
             pX \leftarrow Perturb(d, value_{min}, value_{max}, newX)
29:
30:
             D_b \leftarrow Cost(x_i)
             D_i \leftarrow Cost(pX)
31:
             \Delta \leftarrow |D_b - D_i|
32:
             if D_i > D_b then
33:
                 if k = 1 and i = 1 then
34:
                     \Delta_{average} = \Delta
35:
                 end if
36:
                 p \leftarrow e^{-\frac{\Delta}{\Delta_{average}T}}
37:
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```
if p > rand[0, 1] then
38:
                     accept \leftarrow true
39:
                 else
40:
                     accept \leftarrow false
41:
                 end if
42:
             else
43:
                 accept \leftarrow true
44:
             end if
45:
46:
47:
             if accept = true then
                 \mathbf{x}_i \leftarrow \mathbf{p}\mathbf{X}
48:
                 D_b = D_i
49:
                 \begin{array}{l} \text{numAcceptedSolutions} = \text{numAcceptedSolutions} + 1 \\ \Delta_{\text{average}} \leftarrow \frac{\Delta_{\text{average}}(\text{numAcceptedSolutions} - 1) + \Delta}{\text{numAcceptedSolutions}} \end{array}
50:
51:
             end if
52:
53:
             if Cost(x_i) < Cost(pBest_i) then
54:
                 pBest_i \leftarrow x_i
55:
                 Cost(pBest_i) \leftarrow Cost(x_i)
56:
57:
                 if Cost(pBest_i) < Cost\_sBest then
58:
59:
                     sBest \leftarrow pBest_i
                     Cost\_sBest \leftarrow Cost(pBest_i)
60:
                 end if
61:
             end if
62:
63:
         end for
64:
         T \leftarrow \mu T
65: end for
66: end procedure
```

Experiments and Results:

Let the number of particles t=15, ω =0.5, c_1 = 0.5, c_2 = 0.5, maximum number of iterations = 1000 and got results with the following experiments.

1. PSO and SA embedded within PSO (Solving Travelling salesman problem):

The Travelling salesman problem has been solved through the particle swarm optimization (PSO) and Simulated annealing (SA) embedded within particle swarm optimization (PSO) and the below results were found:

Travelling salesman problem	Results
Solved by PSO	17074.4102
Solved by PSO-SA	7838.7712

Table 1: Travelling Salesman Problem by PSO and SA embedded within PSO

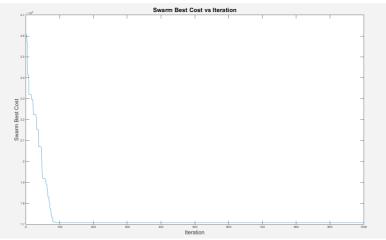


Figure 1: Swarm Best Cost vs. Iteration (Travelling salesman problem solved by PSO)

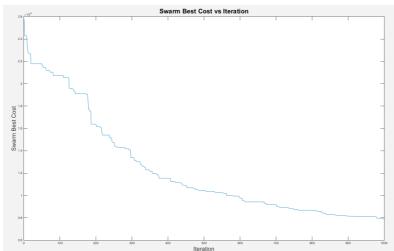


Figure 2: Swarm Best Cost vs. Iteration (Travelling salesman problem solved by SA embedded within PSO)

2. PSO and SA embedded within PSO (with benchmark functions):

To check the performance of the algorithm two benchmark functions were used for both PSO and SA embedded within PSO and the below results were found:

Serial No.	Function	Range	Results		
			Dimension	Dimension	Dimension
			n=2	n=10	n=30
1.	Basic PSO	-5.12 to 5.12	$2.6802e^{-5}$	$4.2633e^{-14}$	$7.2677e^{-10}$
	with Rastrigin				
2.	PSO-SA with	-5.12 to 5.12	0	0	0
	Rastrigin				
3.	Basic PSO	-600 to 600	1.4163 e ⁻⁵	2.7613	43.9708
	with Griewank				
4.	PSO-SA with	-600 to 600	$3.3307e^{-16}$	0.168	1.0269
	Griewank				

Table 2: PSO and SA embedded within PSO through Benchmark functions

After getting all the results of the above experiments it can be declared that Simulated annealing (SA) embedded within particle swarm optimization (PSO) works better than

the basic PSO algorithm as the this algorithm helps the particles not to stuck in the local minima and tend to obtain global optimal solution.

Conclusion and Future work:

Both basic PSO algorithm and SA embedded within PSO algorithm have been tested along with the benchmark functions in various dimensions and also a comparison is made through the travelling salesman problem. After comparing them we can conclude that the SA embedded within PSO algorithm provides better performance.

In future a dampening strategy can be applied on inertial coefficients to achieve better performance. More benchmark functions other than Rastrigin and Griewank can be used to check the performance of this algorithm.

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