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الجامعة الإسلامية
جامعة حلب

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$$1) n(t) = \cos \frac{rt}{\pi} \sin \frac{rt}{\pi}$$

$$\cos \theta = \frac{1}{2}(e^{j\theta} + e^{-j\theta}) \quad \sin \theta = \frac{1}{2j}(e^{j\theta} - e^{-j\theta})$$

$$\sin \theta = \frac{1}{2j}(e^{j\theta} - e^{-j\theta})$$

$$\frac{1}{2j}(e^{j\frac{rt}{\pi}} - e^{-j\frac{rt}{\pi}})$$

$$= \frac{1}{2j} (e^{\frac{rt+j\pi}{\pi}} - e^{\frac{rt-j\pi}{\pi}} + e^{\frac{-rt+j\pi}{\pi}} + e^{\frac{-rt-j\pi}{\pi}})$$

$$\Rightarrow n(t) \rightarrow \frac{1}{2j} \cdot a_j - \frac{1}{2j} \cdot a_{-j} + \frac{1}{2} \cdot a_0 - \frac{1}{2j} \cdot a_{-r}$$

$$\Rightarrow a_r = 0 \quad K_0 = 0 \quad n(t) = \sum_{n=-\infty}^{\infty} a_n \sin\left(\frac{n\pi}{L}\right)t$$

$$X) f(n) \begin{cases} 1 & -1 \leq n \leq 0 \\ 0 & 0 < n \leq 1 \end{cases}$$

$$n(t) = \begin{cases} 1 & -1 \leq t \leq 0 \\ 0 & 0 < t \leq 1 \end{cases} \quad f(n) = \sum_{n=-\infty}^{\infty} a_n \sin\left(\frac{n\pi}{L}\right)t$$

$$T_1 = 1/0 \quad T_2 = 1 - (-1) = 2$$

$$a_0 = \frac{\pi T_1}{T} = \frac{\pi}{2} \quad a_n = \frac{\sin(n(\frac{\pi}{L})T_1)}{n\pi} = \frac{\sin(k\pi)}{n\pi}$$

$$\Rightarrow f(t) = \sum_{n=-\infty}^{\infty} a_n \sin\left(\frac{n\pi}{L}\right)t - \sum_{n=-\infty}^{\infty} \frac{\sin(k\pi)}{n\pi} e^{-jk\frac{\pi}{L}t} \quad k \neq 0$$

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$$1) n(t) = \sum_{n=0}^{\infty} b_n e^{jn\omega_0 t} = \sum_{n=0}^{\infty} e^{jn\omega_0 t}$$

$$n_s(t) = \sum_{n=0}^{\infty} s(t-nT) = \sum_{n=0}^{\infty} a_n e^{jn\omega_0 t} = \sum_{n=0}^{\infty} \frac{1}{T} e^{jn\omega_0 t}$$

$$\begin{aligned} n_s(t) &= \sum_{n=0}^{\infty} s(t-nT) + s(t-nT-KT) - \sum_{n=0}^{\infty} \frac{1}{T} e^{jn\omega_0 t} \\ &+ \sum_{n=0}^{\infty} \frac{r_s(t-nT-KT)}{T} = \sum_{n=0}^{\infty} \frac{1}{T} e^{jn\omega_0 t} (1 + e^{jnk}) \\ &= \sum_{n=0}^{\infty} r_s(t-nT) \end{aligned}$$

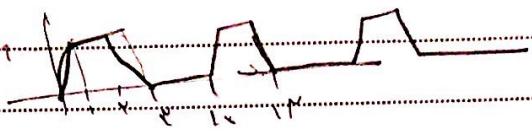
$$r_s(t) = n(t) - T n_s(t) = n(t) - T r_s(t)$$

$$\Rightarrow n(t) = s(t) - r_s(t - T) - r_s(t - 2T - T)$$

$$\Rightarrow r_s(t) = r_s(t-T) = n(t)$$

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1) $n_r(t) \rightarrow n_r(t+1)$



2) $T = 1 \Rightarrow$ $\alpha_n = \frac{1}{T} \int_T^\infty n(t) e^{-j\omega_n t} dt$

3) $\int_0^1 n(t) e^{-j\omega_n t} dt = \int_0^1 e^{j\omega_n t} dt + \int_1^\infty e^{-j\omega_n t} dt$

4) $= \int_0^1 e^{-j\omega_n t} dt + \int_{\omega_n}^{\omega_n + 1} e^{-j\omega_n t} dt + \int_{\omega_n + 1}^\infty e^{-j\omega_n t} dt$

5) $= \int_0^1 e^{-j\omega_n t} dt + \int_{\omega_n - 1}^{\omega_n} e^{-j\omega_n t} dt$

6) $= \frac{\omega_n (-\omega_n - \omega)}{\pi \omega_n^2} + \left(-\frac{j\omega_n}{\pi \omega_n^2} \right) + \omega_n \pi \omega_n \frac{-\omega}{\pi \omega_n^2} = -\omega_n j \frac{\pi}{\omega_n}$

7) $\frac{\omega_n}{\pi \omega_n^2} = \frac{\omega_n}{\pi \omega_n^2} \left(-\frac{j\omega_n}{\pi} + \frac{\omega}{\pi} + 1 \right)$

8) $+ \frac{\omega_n}{\pi \omega_n^2} \left(e^{-j\omega_n \pi} - e^{j\omega_n \pi} \right) + \left(-\omega_n \pi \frac{-\omega}{\pi} \right) \frac{-\omega}{\pi} = -\omega_n j \frac{\pi}{\omega_n}$

9) $- \frac{\omega_n}{\pi \omega_n^2} = \left(-\omega_n \pi \frac{-\omega}{\pi} - \frac{\omega}{\pi} - \omega \right) \frac{-\omega}{\pi}$

10) $\boxed{\omega_n = \frac{-\omega}{\pi}}$

11) $\alpha_n = \frac{1}{\pi} \int_0^\infty n(t) h_{\omega_n}(t) dt$

12) $\int_0^\infty n(t) h_{\omega_n}(t) dt = \int_0^\infty n(t) \left(1 - e^{-j\omega_n t} \right) \left(1 - e^{-j\omega_n t} \right) dt$

13) $= \frac{1}{\pi} \int_0^\infty n(t) \sin(\omega_n t) \sin(\omega_n t) dt$

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1) مجموعه ای از اتصالات $n(t)$ با خروجی

$$n(t) = \sum_{k=-\infty}^{\infty} \delta(t-k)$$

$$a_n = \frac{1}{T} \int_{-\infty}^{\infty} n(t) dt$$

$$(R) y(t) = \sum_{k=-\infty}^{\infty} n(t-k)$$

$$\Rightarrow y(t) e^{-jkn\omega_0 T} = -e^{-jkn\omega_0 T}$$

سری خودی خواهی داشت بدون راداردی

$$g(t) = n(t) + y(t) \Rightarrow a_n + b_n = Y e^{-jkn\omega_0 T}$$

$$P_{avg} = \sum_{k=-\infty}^{\infty} |a_k|^2$$

(R)

$$n(t) = \frac{\pi R}{2} (\cos(\frac{\pi R}{4}t + \pi) \sin(\frac{\pi R}{4}t + \frac{\pi}{4}))$$

$$= \frac{\pi R}{2} \cos(\frac{\pi R}{4}t) \sin(\frac{\pi R}{4}t)$$

$$= \frac{\pi R}{2} \times \frac{1}{2} [e^{j\frac{\pi R}{4}t} + e^{-j\frac{\pi R}{4}t} + e^{-j\frac{\pi R}{4}t} + e^{j\frac{\pi R}{4}t}] \times \frac{1}{2} [e^{\frac{j\pi R}{4}t} - e^{-\frac{j\pi R}{4}t}]$$

$$= \frac{\pi R}{2} (e^{\frac{4\pi R}{4}st} + e^{\frac{-4\pi R}{4}st} - e^{\frac{-4\pi R}{4}st} - e^{\frac{4\pi R}{4}st})$$

$$\Rightarrow K_4 = \frac{\pi R}{4} \quad K_1 = \frac{\pi R}{4} \quad K_2 = \frac{\pi R}{4} \quad K_3 = \frac{\pi R}{4} \quad K \rightarrow \text{row}$$

$$P_{avg} = \frac{9}{16} \pi^2 R^2 = \frac{9}{16} \pi^2$$

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1 $a_{n-k} \rightarrow n(t) \rightarrow n(-t)$ جذر مملي (٤)

2 $n - n$ جذري

3 $a_n = a_{n+k} \rightarrow n(t) \cdot n(t) \leftarrow e^{-\int \frac{dt}{n(t)}} \cdot t$

4 $n(t) \cdot n(t) \leftarrow e^{-\int \frac{dt}{n(t)}} \cdot t \leftarrow e^{-\int \frac{dt}{n(t)}} \cdot t$ حل داروغان ويزير ويزير

5 $n(t) \cdot n(t) \leftarrow e^{-\int \frac{dt}{n(t)}} \cdot t \leftarrow e^{-\int \frac{dt}{n(t)}} \cdot t$

6 $n(t) \cdot n(t) \leftarrow e^{-\int \frac{dt}{n(t)}} \cdot t \leftarrow e^{-\int \frac{dt}{n(t)}} \cdot t$

7 $\int n(t) dt = \ln n(t) + C$ و $\int \frac{dt}{n(t)} = \ln n(t) + C$

8 $\int n(t) dt = \ln n(t) + C$ و $\int \frac{dt}{n(t)} = \ln n(t) + C$

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10 $\int n(t) dt = \ln n(t) + C$ برابر با $n(t) = e^{\ln n(t) + C}$

11 $n(t) = e^{\ln n(t) + C}$ برابر با $n(t) = e^{\ln n(t)} \cdot e^C$

12 $n(t) = n(t) \cdot e^C$ جذري

13 $\int n(t) dt = \ln n(t) + C$ برابر با $t = \ln n(t) + C$

14 $\int n(t) dt = \ln n(t) + C$ برابر با $t = \ln n(t) + C$

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16 $n(t) = e^{\ln n(t) + C}$ جذري

17 $n(t) = \sum_{k=0}^{\infty} S(t - kT) + \sum_{k=0}^{\infty} S(t - kT - T)$ $n(t) = \sum_{k=0}^{\infty} S(t - kT)$

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(F)

$$1) z(t) = n^*(t) + n(-t)$$

$$n(t) \xrightarrow{FS} a_n \text{ gives } n^* \xrightarrow{FS} a_{-n}$$

$n(-t)$ $\xrightarrow{FS} a_{-n}$ passing unit time delay
Reversal

$$a^*(t) \xrightarrow{FS} a_{-n}$$

Timescaling - multiplying by ω

$$\Rightarrow z(t) = a_{-n} + a_{-n}$$

$$2) n(t) \xrightarrow{FS} a_n \text{ time shifting, to } a_{t+k}$$

$$n(t+k) \xrightarrow{FS} e^{j\omega t} a_{t+k} \Rightarrow w.t \xrightarrow{\omega} n(t+k) \xrightarrow{e^{j\omega t}} a_{t+k}$$

$$n(t) \xrightarrow{FS} a_n \text{ - time shifting}$$

$$\delta r n(t) \xrightarrow{FS} j\omega n(t) \Rightarrow \delta r n(t) \xrightarrow{FS} j\omega n(t) \xrightarrow{\omega} n(t) \xrightarrow{e^{j\omega t}} a_{t+k}$$

$$z(t) = e^{-\frac{j\omega t}{K}} a_{t+k} \xrightarrow{\omega} a_{t+k}$$

$$e^{\frac{j\omega t}{K}} a_{t+k} \xrightarrow{\omega} a_{t+k}$$

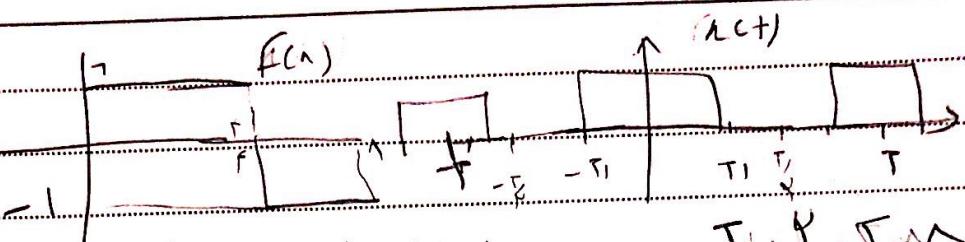
(+) - time shifting is a cause of delay in output

- in Z(t) \Rightarrow delay is due to delay in $n(t)$ by $\frac{1}{K}$ units

$$z(t) = n(t) S(t+1) + n(t) S(t-1)$$

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1 $n(t) =$

2 $H(j\omega) = \frac{\sin(\omega n)}{n}$

3 $f(n) = K \cdot \delta(t - \tau) + 1$

4 $T_1 + \gamma / T$

5 $a_n = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} f(n) dn$

6 $a_n = \frac{\sin(\omega n)}{n}$

7 $f(n) = \sum a_n e^{jn\omega n}$

8 $f(n) \leftarrow \begin{cases} 0 & n \neq 0 \\ \frac{\sin(\omega n)}{n} e^{-jn\omega n} & n \neq 0 \end{cases}$

9 $H(j\omega) = H(j\omega R) \rightarrow H(j\omega R) = \frac{\sin(\omega R)}{\omega R}$

10 $y(t) = \sum a_n H(j\omega R) e^{jn\omega R t}$

11 $y(t) = \sum \frac{\sin(\omega n)}{n} \times \frac{\sin(\omega R t)}{\omega R} \times e^{jn\omega R t}$

12 $\omega = \omega_0$