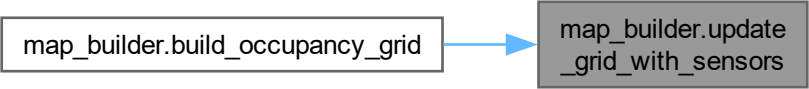


map\_builder.build\_occupancy\_grid



```
graph LR; A[map_builder.build_occupancy_grid] --> B[map_builder.update_grid_with_sensors]
```

A flow diagram consisting of two rectangular boxes connected by a blue arrow. The first box on the left is white with a black border and contains the text 'map\_builder.build\_occupancy\_grid'. A blue arrow points from the right side of this box to the left side of a second box on the right. The second box is gray with a black border and contains the text 'map\_builder.update\_grid\_with\_sensors'.

map\_builder.update  
\_grid\_with\_sensors