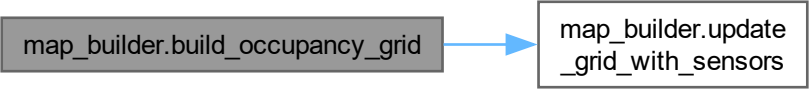


map_builder.build_occupancy_grid



```
graph LR; A[map_builder.build_occupancy_grid] --> B[map_builder.update_grid_with_sensors]
```

A flow diagram consisting of two rectangular boxes connected by a blue arrow. The first box on the left is gray and contains the text 'map_builder.build_occupancy_grid'. A blue arrow points from the right side of this box to the left side of a second box on the right. The second box is white with a black border and contains the text 'map_builder.update_grid_with_sensors'.

map_builder.update
_grid_with_sensors