

# Mohammad Hasan Mokhtarabadi

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EDUCATION	M.Sc. Mechanical Engineering - Applied Mechanics <i>Oct. 2020 - Apr. 2023 (Expected)</i> University of Tehran (UT), Tehran, Iran, (ranked 1 <sup>st</sup> in <a href="#">Best Universities in Iran</a> ) <b>GPA: 17.89 / 20</b> Thesis Title: Design and Fabrication of a Fitness Machine Prototype with Visual Pose Estimation Using ANN for Adjusting Cable Tension Force <i>Supervisor: Dr. Farzad A. Shirazi, Dr. Mohsen Saadat</i>
	B.Sc. Mechanical Engineering <i>Sept. 2016 - Oct. 2020</i> University of Isfahan (UI), Isfahan, Iran, (ranked 33 <sup>rd</sup> in <a href="#">Best Universities in Iran</a> ) <b>GPA: 17.94 / 20</b> Thesis Title: Design and Fabrication of a Handheld Force-Feedback Device That Applies Forces with Two Jet-Propellers <i>Supervisor: Dr. Hossein Karimpour, Dr. Kourosh Hasanpour</i>

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RESEARCH INTERESTS	<ul style="list-style-type: none"><li>• Mechatronics Systems</li><li>• Haptic Interfaces and Devices</li><li>• Machine Learning and Deep Learning</li><li>• System Identification and Adaptive Control Systems</li></ul>
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PUBLICATIONS	<p><b>M. Mokhtarabadi</b>, A. Zaheri, M. Saadat, F. Shirazi. 2022. Power Transmission Gearbox-Clutch with One Input and Multiple Selectable Outputs. U.S. Patent 63398326, filed Aug. 16, 2022. Provisional Patent.</p> <p><b>A. Zaheri</b>, M. Mokhtarabadi, M. Saadat, F. Shirazi. 2022. Fully Active Closed-Loop Cable-Driven Multi-Degree-of-Freedom Mechanical Arm System. U.S. Patent 63401421, filed Aug. 26, 2022. Provisional Patent.</p>
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AWARDS & HONORS	<ul style="list-style-type: none"><li>• Ranked 50<sup>th</sup> among more than 7,000 participants in Iranian University Entrance Exam for Master's degree in Mechanical Engineering</li><li>• Ranked 36<sup>th</sup> in national Mechanics Olympiad, Iran, 2019</li><li>• Ranked 2<sup>nd</sup> GPA among undergraduate class of 2016 in the Bachelor program at University of Isfahan</li><li>• Ranked within the top 3% among more than 160,000 participants in Iranian University Entrance Exam for Bachelor's degree</li><li>• Received national graduate and undergraduate full scholarship</li></ul>
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## ACADEMIC PROJECTS

### **Design and Fabrication of a Fitness Machine Prototype (Master's Thesis)**

*Supervisor: Dr. Farzad A. Shirazi, Dr. Mohsen Saadat*

*Oct. 2021 - Present*

- Implementation of Field Oriented Control (FOC) algorithm on STM32 microprocessor for feed-forward torque control of brushless DC motor
- Implementation of 3D pose-estimation for adjusting cable torques according to participant's skeleton situation on Jetson Nano Developer Kit
- Design and implementation of front-end layer (Python) to interact with user, and back-end layer (C++) to communicate with hardware (STM32)
- Design and Fabrication of mechanical structure of machine containing two brushless motors, and driver circuits, magnetic rotary encoders, touch screen, camera, microphone, and etc.

### **Design and Fabrication of a Handheld Haptic Device (Bachelor's Thesis)**

*Supervisor: Dr. Hossein Karimpour, Dr. Kourosh Hasanpour*

*Mar. 2020 - Sept. 2020*

- Implementation of real-world dynamic equations on Arduino Nano board to adjust forces according to hand situation
- Design and Implementation of Virtual-Reality (VR) environment in SIMULINK, and wireless communication with hardware
- Design and Fabrication of mechanical structure of device containing Two jet-propellers, 3D printed parts, IMU sensor, servo motor, and etc.
- more details: <https://www.youtube.com/watch?v=s1AUNDxSRoE>

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## COURSE PROJECTS

- Design a Fuzzy Sliding mode controller for bodybuilding applications *Jan. 2022*
- Simulation of an article related to System Identification course, "Recursive Least Square Algorithm for Estimating Parameters of an Induction Motor" *Jan. 2022*
- Simulation of an Article related to Adaptive Control Systems course, "Design of direct MRAC augmented with 2 DoF PID controller: An application to speed control of a servo plant" *Jun. 2021*
- Simulation of an Article related to Advanced Control systems course, "RISE-based adaptive control for EICoSI exoskeleton to assist knee joint mobility" *Jun. 2021*
- Design a Robert mechanism that converts rotational motion in a specific range to linear motion in a specific length with this consideration that the linear motion becomes as straight as possible *Jan. 2021*

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## EXPERIENCE

### Research Assistant

- Mechatronics Lab, University of Tehran

*Oct. 2021 - Present*

### Teaching Assistant

- Advanced Control Systems

*Dr. Farzad A. Shirazi*

*Oct. 2021 - Jan. 2022*

- Measurement Systems and Laboratory

*Dr. Farzad A. Shirazi*

*Feb. 2021 - Jun. 2021*

### Work Experience

- Internship in Esfahan's Mobarakeh Steel Company

*Jul. 2019 - Sep. 2019*

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## SKILLS

**Programming Languages:** C++, Python, MATLAB, L<sup>A</sup>T<sub>E</sub>X  
**Applications:** SolidWorks, MATLAB & SIMULINK, Microsoft Office  
**Operating Systems:** Windows, Linux (Ubuntu)  
**Hardware:** STM32 Microprocessors, Arduino Boards, NVIDIA Jetson Nano Developer Kit, Raspberry PI

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## LANGUAGES

Persian: Native  
English: High-Intermediate  
- *TOEFL iBT Score: 100 (Reading: 28, Listening: 28, Speaking: 20, Writing: 24)*

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## REFERENCES

1. Dr. Farzad A. Shirazi: fshirazi@ut.ac.ir
2. Dr. Mohsen Saadat: saad0021@umn.edu
3. Dr. Hossein Karimpour: h.karimpour@eng.ui.ac.ir