تكليف سرى اول (بروزرسانى اول) درس دينامبك سيالات محاسباتى پيشرفته محمد يوسفى 402126084 https://github.com/mohamadusefi

```
import numpy as np
import matplotlib.pyplot as plt
from scipy.sparse import diags
from scipy.sparse.linalg import gcrotmk

def S(x):
    return x * (1 - x) # definition of source term

K2, K3, H = [], [], []
i = 1
N = 4 # Starting value for N
increment = 3 # Initial increment
```

الگوریتم انتخاب نقاط به نحوی طراحی شده که نقاط ثابت برای مقایسه خطا با کاهش گام طولی وجود داشته باشد.

```
while N \leq 1000:
    L = 1 # length of the bar
    h = L / (N - 1) # step size
    x = np.linspace(0, L, N)
    Phi left = 0
    Phi right = 0
    diagonals = \begin{bmatrix} -2 * np.ones(N), 1*np.ones(N-1), 1*np.ones(N-1) \end{bmatrix}
    A = diags(diagonals, [0, -1, 1], format='csr')
    A[0, 0] = 1
    A[0, 1] = 0
    A[N-1, N-2] = 0
    A[N-1, N-1] = 1
    b = -S(x) * h**2
    b[0] = Phi left
    b[-1] = Phi right
    initial guess = np.zeros(N)
    Phi, info = gcrotmk(A, b, x0=initial guess)
    Phi[0] = Phi left
    Phi[-1] = Phi right
    print(f"N={N}, Solution={Phi}, CG Info={info}")
    K2.append(Phi[1*i]) # values of Phi in x = L/4
    K3.append(Phi[2*i]) # Values of Phi in x = 3L/4
    H.append(h) # storing values of h into H for log-log plot
```

```
N += increment
    increment *= 2
    i *= 2
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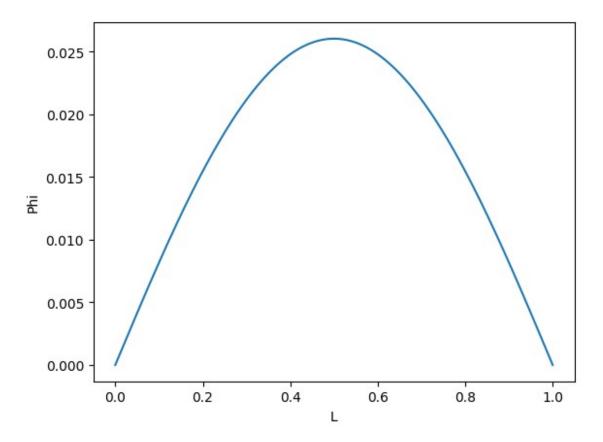
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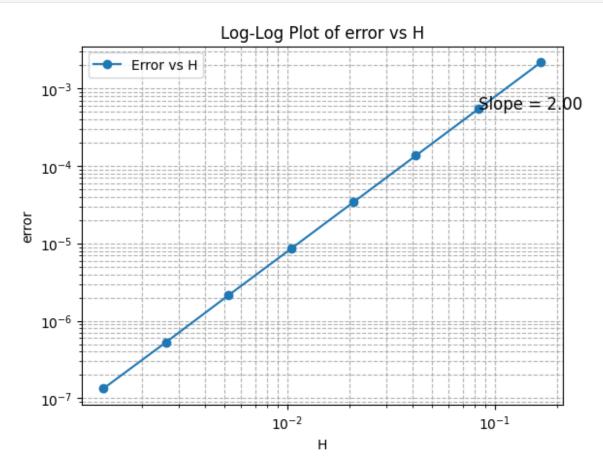
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0.02542576 0.02540281 0.02537945 0.02535568 0.02533149 0.02530688
0.02528187 0.02525643 0.02523059 0.02520433 0.02517766 0.02515058
0.02512309 \ 0.02509518 \ 0.02506687 \ 0.02503814 \ 0.02500901 \ 0.02497946
           0.02491914 0.02488837 0.02485719 0.0248256
0.0249495
                                                       0.0247936
           0.02472839 0.02469517 0.02466155 0.02462753 0.0245931
0.0247612
0.02455826 0.02452303 0.02448739 0.02445134 0.0244149
                                                       0.02437805
0.02410892\ 0.02406888\ 0.02402844\ 0.02398761\ 0.02394638\ 0.02390475
0.02386273 \ 0.02382032 \ 0.02377751 \ 0.02373431 \ 0.02369072 \ 0.02364674
0.02360236 0.0235576 0.02351245 0.0234669
                                            0.02342097 0.02337465
0.02332794 0.02328085 0.02323337 0.02318551 0.02313726 0.02308863
0.02303961 \ 0.02299021 \ 0.02294043 \ 0.02289027 \ 0.02283973 \ 0.02278881
0.02273751 0.02268583 0.02263378 0.02258134 0.02252854 0.02247535
0.02242179 0.02236786 0.02231356 0.02225888 0.02220383 0.02214841
0.02209262 0.02203646 0.02197994 0.02192304 0.02186578 0.02180816
0.02175016 0.02169181 0.02163309 0.02157401 0.02151456 0.02145476
0.02139459 \ 0.02133407 \ 0.02127319 \ 0.02121195 \ 0.02115035 \ 0.0210884
0.02102609\ 0.02096343\ 0.02090042\ 0.02083705\ 0.02077333\ 0.02070927
0.02064485 \ 0.02058008 \ 0.02051497 \ 0.02044951 \ 0.02038371 \ 0.02031756
0.02025106 0.02018423 0.02011705 0.02004953 0.01998167 0.01991348
0.01984494 0.01977607 0.01970686 0.01963732 0.01956745 0.01949724
           0.01935582 0.01928462 0.01921309 0.01914124 0.01906905
0.0194267
0.01899654 0.01892371 0.01885055 0.01877707 0.01870327 0.01862915
0.01855471 0.01847996 0.01840488 0.01832949 0.01825379 0.01817777
```

```
0.01810144 \ 0.0180248 \ 0.01794785 \ 0.01787059 \ 0.01779302 \ 0.01771514
 0.01763696 0.01755848 0.01747969 0.0174006
                                              0.01732121 0.01724153
 0.01716154 0.01708125 0.01700067 0.0169198
                                              0.01683863 0.01675717
 0.01667542 0.01659337 0.01651104 0.01642843 0.01634552 0.01626234
 0.01617886 0.01609511 0.01601108 0.01592676 0.01584217 0.0157573
 0.01567216 0.01558674 0.01550104 0.01541508 0.01532884 0.01524234
 0.01515557 \ 0.01506853 \ 0.01498122 \ 0.01489366 \ 0.01480583 \ 0.01471774
 0.01462939 0.01454078 0.01445191 0.01436279 0.01427341 0.01418379
 0.01409391 0.01400378 0.0139134 0.01382278 0.0137319
                                                          0.01364079
 0.01354943 0.01345783 0.013366
                                   0.01327392 0.0131816
                                                          0.01308905
 0.01299627 0.01290326 0.01281001 0.01271653 0.01262283 0.0125289
 0.01243474 0.01234036 0.01224576 0.01215094 0.0120559
                                                          0.01196064
 0.01186516 \ 0.01176947 \ 0.01167357 \ 0.01157746 \ 0.01148114 \ 0.01138461
 0.01128787 0.01119093 0.01109378 0.01099644 0.01089889 0.01080115
 0.0107032 \quad 0.01060507 \quad 0.01050673 \quad 0.01040821 \quad 0.0103095
                                                          0.0102106
 0.01011151 \ 0.01001223 \ 0.00991277 \ 0.00981313 \ 0.00971331 \ 0.00961331
 0.00951314 0.00941278 0.00931226 0.00921156 0.00911069 0.00900965
 0.00890845 0.00880708 0.00870555 0.00860385 0.008502
                                                          0.00839999
 0.00829782 0.0081955 0.00809302 0.00799039 0.00788761 0.00778469
 0.00768162 0.00757841 0.00747505 0.00737155 0.00726792 0.00716414
 0.00706024 0.0069562
                        0.00685202 0.00674772 0.00664329 0.00653874
 0.00643406 0.00632926 0.00622434 0.0061193
                                              0.00601414 0.00590887
 0.00580349 0.00569799 0.00559239 0.00548668 0.00538086 0.00527494
 0.00516892 0.0050628 0.00495659 0.00485027 0.00474387 0.00463737
 0.00453078 0.00442411 0.00431735 0.00421051 0.00410358 0.00399658
 0.00388949 \ 0.00378233 \ 0.0036751 \ 0.0035678 \ 0.00346042 \ 0.00335298
 0.00324547 0.0031379 0.00303027 0.00292258 0.00281483 0.00270702
 0.00259916 \ 0.00249125 \ 0.00238329 \ 0.00227529 \ 0.00216724 \ 0.00205914
 0.00195101 \ 0.00184283 \ 0.00173462 \ 0.00162638 \ 0.0015181 \ 0.00140979
 0.00130145 0.00119309 0.00108471 0.0009763
                                              0.00086787 0.00075942
 0.00065096 0.00054249 0.000434
                                   0.00032551 0.00021701 0.00010851
           1, CG Info=0
fig, ax = plt.subplots()
ax.plot(x, Phi)
plt.xlabel('L')
plt.ylabel('Phi')
plt.show()
```



```
dif1 = []
dif2 = []
error = []
j = 0
for i in range(1, len(H)):
    dif1.append(abs(K2[i] - K2[i-1]))
    dif2.append(abs(K3[i] - K3[i-1]))
    error.append(np.linalg.norm([dif1[j], dif2[j]])) # compute norm
of errors at K2 and K3 points in each step-size
    j += 1
del H[0]
plt.loglog(H, error, 'o-', label='Error vs H')
plt.xlabel('H')
plt.ylabel('error')
plt.title('Log-Log Plot of error vs H')
plt.legend()
plt.grid(True, which="both", ls="--")
log H = np.log(H)
log_error = np.log(error)
slope, intercept = np.polyfit(log_H, log_error, 1)
```

```
plt.text(H[1], error[1], f'Slope = {slope:.2f}', fontsize=12)
plt.show()
```



.شکل بالا شیب کلی نمودار خطا در برابر گام طولی را نشان میدهد