

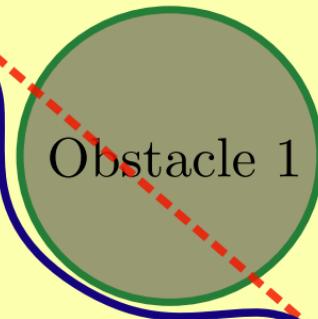
Target point



Obstacle 2



Obstacle 1



Starting point

