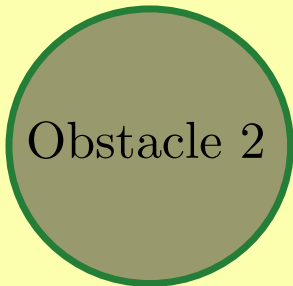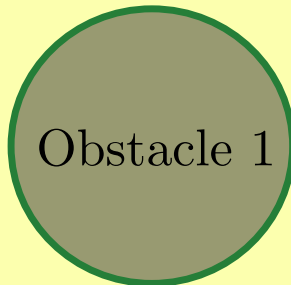Target point

Obstacle 2

Obstacle 1

Starting point